

## THE CONSTRUCTIONS AND DEFORMATIONS OF NIJENHUIS OPERATORS ON 3-HOM-LIE ALGEBRAS

YIZHENG LI AND DINGGUO WANG

**ABSTRACT.** In this paper, we study Nijenhuis operators on 3-Hom-Lie algebras and provide some examples. Next, we give various constructions of Nijenhuis operators according to constructions of 3-Hom-Lie algebras. Furthermore, we define a cohomology of Nijenhuis operators on 3-Hom-Lie algebras with coefficients in a suitable representation. Finally, as an application, we study formal deformations of Nijenhuis operators that are generated by the above-defined cohomology.

### 1. Introduction

The notion of Hom-Lie algebras was introduced by Hartwig, Larsson, and Silvestrov in [9] as part of a study of deformations of Witt and Virasoro algebras. Some  $q$ -deformations of the Witt and the Virasoro algebras have the structure of a Hom-Lie algebra [9]. Because of the close relation to discrete and deformed vector fields and differential calculus [14], many people paid special attention to this algebraic structure. In particular, the author studied representations and cohomologies of Hom-Lie algebras in [20], the authors introduced the notion of a Hom-Lie bialgebra and gave an equivalent description of the Hom-Lie bialgebras, the matched pairs and the Manin triples of Hom-Lie algebras in [21]. These provide a good starting point for discussion and further research.

The notion of  $n$ -Lie algebras was introduced by Filippov in [6]. The authors studied Nijenhuis operators on  $n$ -Lie algebras in [18]. Recently, the authors studied Reynolds operators on  $n$ -Lie algebras in [11]. 3-Lie algebras were special types of  $n$ -Lie algebras and played an important role in string theory [4]. Many more properties and structures of 3-Lie algebras have been developed, see [7, 10, 12, 13, 17, 22, 25, 26] and references cited therein. Hom-type generalizations of  $n$ -ary Nambu-Lie algebras, called  $n$ -ary Hom-Nambu-Lie algebras, were introduced by Arnlind, Makhlouf, and Silvestrov in [3]. Since then, the

---

Received November 26, 2023; Revised May 3, 2024; Accepted June 7, 2024.

2020 *Mathematics Subject Classification.* Primary 17A30, 17B60, 17B61.

*Key words and phrases.* Nijenhuis operator, Rota-Baxter operator, cohomology, formal deformation.

This work was financially supported by the NSF of China (No. 12271292).

authors studied the cohomologies adapted to central extensions and deformations in [1], the authors studied the constructions of 3-Hom-Lie algebras from Hom-Lie algebras in [2], the authors provided the constructions of Rota-Baxter multiplicative 3-ary Hom-Nambu-Lie algebras in [24], the authors constructed the representations and module-extensions of 3-Hom-Lie algebras in [16], and the authors introduced the notion of a 3-Hom-Lie bialgebra and gave an equivalent description of the 3-Hom-Lie bialgebras, the matched pairs and the Manin triples of 3-Hom-Lie algebras in [8]. Recently, we studied relative Rota-Baxter operators on 3-Hom-Lie algebras in [15]. See [23] for more details about deformations of  $n$ -Hom-Lie algebras.

Recently, Mishra and Naolekar [19] studied  $\mathcal{O}$ -operators, also known as relative or generalized Rota-Baxter operators on Hom-Lie algebras. Later, Das and Sen [5] studied Nijenhuis operators on Hom-Lie algebras. Motivated by the work of [5, 19], it is natural and meaningful to study Nijenhuis operators on 3-Hom-Lie algebras. This becomes our motivation for writing the present paper. This paper is organized as follows. In Section 2, we will recall some basic notions and facts about 3-Hom-Lie algebras. In Section 3, we study Nijenhuis operators on 3-Hom-Lie algebras and provide some examples. In Section 4, we give various constructions of Nijenhuis operators according to constructions of 3-Hom-Lie algebras. In Section 5, we define a cohomology of Nijenhuis operators on 3-Hom-Lie algebras with coefficients in a suitable representation. In Section 6, we study formal deformations of Nijenhuis operators that are generated by the above-defined cohomology.

Throughout this paper, all vector spaces, (multi)linear maps are over an algebraically closed field  $\mathbb{K}$  of characteristic 0.

## 2. Preliminaires

In this section, we will recall some basic notions and facts about 3-Hom-Lie algebras from [1, 16, 23].

**Definition.** A 3-Hom-Lie algebra is a triple  $(L, [\cdot, \cdot, \cdot], \alpha)$  consisting of a vector space  $L$ , a 3-ary skew-symmetric operation  $[\cdot, \cdot, \cdot] : \wedge^3 L \rightarrow L$  and an algebra morphism  $\alpha : L \rightarrow L$  satisfying the following 3-Hom-Jacobi identity

$$\begin{aligned} & [\alpha(x), \alpha(y), [u, v, w]] \\ &= [[x, y, u], \alpha(v), \alpha(w)] + [\alpha(u), [x, y, v], \alpha(w)] + [\alpha(u), \alpha(v), [x, y, w]], \end{aligned}$$

for any  $x, y, u, v, w \in L$ .

**Example 2.1.** Let  $(L, [\cdot, \cdot, \cdot])$  be a 3-Lie algebra and  $\alpha : L \rightarrow L$  a 3-Lie algebra morphism. Then  $(L, [\cdot, \cdot, \cdot]_\alpha = \alpha \circ [\cdot, \cdot, \cdot], \alpha)$  is a 3-Hom-Lie algebra induced by the 3-Lie algebra morphism  $\alpha$ .

**Definition.** A representation of a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  on the vector space  $V$  with respect to  $A \in \mathfrak{gl}(V)$  is a bilinear map  $\rho : \wedge^2 L \rightarrow \mathfrak{gl}(V)$ , such

that for any  $x, y, z, u \in L$ , the following equalities are satisfied:

$$\begin{aligned} \rho(\alpha(x), \alpha(y)) \circ A &= A \circ \rho(x, y), \\ \rho([x, y, z], \alpha(u)) \circ A &= \rho(\alpha(y), \alpha(z))\rho(x, u) \\ &\quad + \rho(\alpha(z), \alpha(x))\rho(y, u) + \rho(\alpha(x), \alpha(y))\rho(z, u), \\ \rho(\alpha(x), \alpha(y))\rho(z, u) &= \rho(\alpha(z), \alpha(u))\rho(x, y) \\ &\quad + \rho([x, y, z], \alpha(u)) \circ A + \rho(\alpha(z), [x, y, u]) \circ A. \end{aligned}$$

Then  $(V, A, \rho)$  is called a representation of  $L$ , or  $V$  is an  $L$ -module.

Define  $\text{ad} : \wedge^2 L \rightarrow \mathfrak{gl}(L)$  by

$$\text{ad}_{x,y}z = [x, y, z], \quad \forall x, y, z \in L.$$

Then  $(L, \text{ad}, \alpha)$  is a representation of the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  on  $L$  with respect to  $\alpha$ , which is called the adjoint representation.

Let  $(V, A, \rho)$  be a representation of a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$ . The cohomology of  $L$  with coefficients in  $V$  is the cohomology of the cochain complex  $\{C^*(L, V), \delta\}$ , where

$$\begin{aligned} C_{\alpha, A}^n(L, V) &= \{f \in \text{Hom}(\underbrace{\wedge^2 L \otimes \cdots \otimes \wedge^2 L}_{n-1} \wedge L, V), \quad (n \geq 1), \\ &\quad A \circ f = f \circ \alpha^{\otimes 2n-1}\} \end{aligned}$$

and the coboundary operator  $\delta : C_{\alpha, A}^n(L, V) \rightarrow C_{\alpha, A}^{n+1}(L, V)$  given by

$$\begin{aligned} &(\delta f)(\mathfrak{X}_1, \mathfrak{X}_2, \dots, \mathfrak{X}_n, x_{n+1}) \\ &= \sum_{1 \leq j < k \leq n} (-1)^j f(\alpha(\mathfrak{X}_1), \dots, \hat{\mathfrak{X}}_j, \dots, \alpha(\mathfrak{X}_{k-1}), [x_j, y_j, x_k] \wedge \alpha(y_k) \\ &\quad + \alpha(x_k) \wedge [x_j, y_j, y_k], \alpha(\mathfrak{X}_{k+1}), \dots, \alpha(\mathfrak{X}_n), \alpha(x_{n+1})) \\ &\quad + \sum_{j=1}^n (-1)^j f(\alpha(\mathfrak{X}_1), \dots, \hat{\mathfrak{X}}_j, \dots, \alpha(\mathfrak{X}_n), [x_j, y_j, x_{n+1}]) \\ &\quad + \sum_{j=1}^n (-1)^{j+1} \rho(\alpha^{n-1}(\mathfrak{X}_j)) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_n, x_{n+1}) \\ &\quad + (-1)^{n+1} (\rho(\alpha^{n-1}(y_n), \alpha^{n-1}(x_{n+1}))) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_{n-1}, x_n) \\ &\quad + \rho(\alpha^{n-1}(x_{n+1}), \alpha^{n-1}(x_n)) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_{n-1}, y_n) \end{aligned}$$

for  $\mathfrak{X}_i = x_i \wedge y_i \in L \wedge L, i = 1, \dots, n$  and  $x_{n+1} \in L$ . The corresponding cohomology groups are denoted by  $H_{3\text{HLie}}^*(L, V)$ .

### 3. Nijenhuis operators

In this section, we first recall Nijenhuis operators on a 3-Hom-Lie algebra in [15] and provide some new examples.

**Definition.** Let  $(L, [\cdot, \cdot, \cdot], \alpha)$  be a 3-Hom-Lie algebra. A linear operator  $N : L \rightarrow L$  is called a Nijenhuis operator if  $N$  satisfies: for any  $x, y, z \in L$ ,

$$(3.1) \quad N \circ \alpha = \alpha \circ N,$$

$$(3.2) \quad \begin{aligned} [Nx, Ny, Nz] &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz]) \\ &\quad - N[Nx, y, z] - N[x, Ny, z] - N[x, y, Nz] + N^2[x, y, z]. \end{aligned}$$

The vector space  $L$  carries a new 3-Hom-Lie algebra structure with bracket

$$\begin{aligned} [x, y, z]_N &:= [Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] - N[Nx, y, z] \\ &\quad - N[x, Ny, z] - N[x, y, Nz] + N^2[x, y, z], \text{ for } x, y, z \in L. \end{aligned}$$

We denote this deformed 3-Hom-Lie algebra by  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$ .

**Example 3.1.** The identity map  $\text{id} : L \rightarrow L$  is a Nijenhuis operator.

**Example 3.2.** Consider 3-dimensional 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  with basis  $\{e_1, e_2, e_3\}$  and the nonzero multiplication is given by

$$[e_1, e_2, e_3] = e_1, \quad \alpha(e_1) = -e_1, \quad \alpha(e_2) = e_2, \quad \alpha(e_3) = e_3.$$

Let  $N : L \rightarrow L$  be a linear map given by  $\begin{pmatrix} d & 0 & 0 \\ 0 & c & f \\ 0 & 0 & b \end{pmatrix}$  where  $dcf \neq 0$ . Then

we have

$$[Ne_1, Ne_2, Ne_3] = dcbe_1.$$

Further, we have

$$\begin{aligned} [Ne_1, Ne_2, e_3] &= dce_1, \quad [Ne_1, e_2, e_3] = de_1, \\ [Ne_1, e_2, Ne_3] &= db e_1, \quad [e_1, Ne_2, e_3] = ce_1, \\ [e_1, Ne_2, Ne_3] &= cbe_1, \quad [e_1, e_2, Ne_3] = be_1. \end{aligned}$$

It is easy to obtain that

$$\begin{aligned} &[Ne_1, Ne_2, Ne_3] \\ &= N([Ne_1, Ne_2, e_3] + [Ne_1, e_2, Ne_3] + [e_1, Ne_2, Ne_3]) \\ &\quad - N([Ne_1, e_2, e_3] + [e_1, Ne_2, e_3] + [e_1, e_2, Ne_3]) + N^2[e_1, e_2, e_3]. \end{aligned}$$

Thus,  $N$  is a Nijenhuis operator on  $(L, [\cdot, \cdot, \cdot], \alpha)$ .

**Example 3.3.** Let  $(L, [\cdot, \cdot, \cdot])$  be a 3-Lie algebra and  $\alpha : L \rightarrow L$  a 3-Lie algebra morphism. If  $N$  is a Nijenhuis operator on the 3-Lie algebra  $L$  commuting with  $\alpha$ , then  $N$  is also a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_\alpha, \alpha)$  in Example 2.2.

**Example 3.4.** A complex 3-Hom-Lie algebra is a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  together with a linear map  $J : L \rightarrow L$  commuting with  $\alpha$  that satisfies  $J^2 = -\text{id}$  and

$$J[x, y, z] = -[Jx, Jy, Jz] + [Jx, y, z] + [x, Jy, z] + [x, y, Jz]$$

$$+ J[Jx, Jy, z] + J[x, Jy, Jz] + J[Jx, y, Jz].$$

It follows from  $J^2 = -\text{id}$  and the last identity that  $J$  is a Nijenhuis operator.

**Definition.** A linear map  $T : L \rightarrow L$  is called a modified Rota-Baxter operator of weight  $\lambda \in \mathbb{K}$  on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  if  $T$  satisfies the following conditions

$$\begin{aligned} T \circ \alpha &= \alpha \circ T, \\ [Tx, Ty, Tz] &= T([Tx, Ty, z] + [x, Ty, Tz] + [Tx, y, Tz] - \lambda[x, y, z]) \\ &\quad + \lambda[Tx, y, z] + \lambda[x, Ty, z] + \lambda[x, y, Tz]. \end{aligned}$$

**Definition.** A linear map  $T : L \rightarrow L$  is called a Rota-Baxter operator of weight  $\lambda$  on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  if  $T$  satisfies the following conditions

$$\begin{aligned} T \circ \alpha &= \alpha \circ T, \\ [Tx, Ty, Tz] &= T([Tx, Ty, z] + [x, Ty, Tz] + [Tx, y, Tz] \\ &\quad + \lambda[Tx, y, z] + \lambda[x, Ty, z] + \lambda[x, y, Tz] + \lambda^2[x, y, z]). \end{aligned}$$

**Proposition 3.5.** *Let  $(L, [\cdot, \cdot, \cdot], \alpha)$  be a 3-Hom-Lie algebra and  $N : L \rightarrow L$  be a linear operator. Then*

- (a) *If  $N^2 = 0$ , then  $N$  is a Nijenhuis operator if and only if  $N$  is a Rota-Baxter operator.*
- (b) *If  $N^2 = N$ , then  $N$  is a Nijenhuis operator if and only if  $N$  is a Rota-Baxter operator of weight  $-1$ .*
- (c) *If  $N^2 = \pm \text{id}$ , then  $N$  is a Nijenhuis operator if and only if  $N$  is a modified Rota-Baxter operator of weight  $\mp 1$ .*

*Proof.* (a) Let  $N^2 = 0$ . Suppose  $N$  is a Nijenhuis operator. Then for any  $x, y, z \in L$ , we have

$$\begin{aligned} [Nx, Ny, Nz] &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] \\ &\quad - N([Nx, y, z] + [x, Ny, z] + [x, y, Nz] - N[x, y, z])) \\ &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz]). \end{aligned}$$

Hence,  $N$  is a Rota-Baxter operator. Proof of the converse part is similar.

(b) Let  $N^2 = N$ . Suppose  $N$  is a Nijenhuis operator. Then for any  $x, y, z \in L$ , we have

$$\begin{aligned} [Nx, Ny, Nz] &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] \\ &\quad - N([Nx, y, z] + [x, Ny, z] + [x, y, Nz] - N[x, y, z])) \\ &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] - [Nx, y, z] - [x, Ny, z] \\ &\quad - [x, y, Nz] + [x, y, z]). \end{aligned}$$

Hence,  $N$  is a Rota-Baxter operator of weight  $-1$ . Similarly, the converse can be shown.

(c) Let  $N^2 = \text{id}$ . Suppose  $N$  is a Nijenhuis operator. Then, for any  $x, y, z \in L$ , we have

$$\begin{aligned} & [Nx, Ny, Nz] \\ &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] \\ &\quad - N([Nx, y, z] + [x, Ny, z] + [x, y, Nz] - N[x, y, z])) \\ &= N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz] + [x, y, z]) - [Nx, y, z] \\ &\quad - [x, Ny, z] - [x, y, Nz]. \end{aligned}$$

Hence,  $N$  is a modified Rota-Baxter operator of weight  $-1$ . In a similar way the other cases can be shown.  $\square$

We recall the notion of relative Rota-Baxter operators on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  from [8].

**Definition.** Let  $(L, [\cdot, \cdot, \cdot], \alpha)$  be a 3-Hom-Lie algebra and  $(V, A, \rho)$  be a representation. A linear operator  $T : V \rightarrow L$  is called a relative Rota-Baxter operator associated to  $(V, A, \rho)$  if  $T$  satisfies: for any  $u, v, w \in V$ ,

$$\begin{aligned} \alpha \circ T &= T \circ A, \\ [Tu, Tv, Tw] &= T(\rho(Tu, Tv)w + \rho(Tv, Tw)u + \rho(Tw, Tu)v). \end{aligned}$$

**Definition.** Two relative Rota-Baxter operators  $T_1, T_2 : V \rightarrow L$  are said to be compatible if for all  $\mu, \nu \in \mathbb{K}$ , the sum  $\mu T_1 + \nu T_2 : V \rightarrow L$  is a relative Rota-Baxter operator.

The following result is straightforward.

**Lemma 3.6.** *Two relative Rota-Baxter operators  $T_1$  and  $T_2$  are compatible if and only if the following condition holds:*

$$\begin{aligned} & [T_i(u), T_i(v), T_j(w)] + [T_i(u), T_j(v), T_i(w)] + [T_j(u), T_i(v), T_i(w)] \\ &= T_i(\rho(T_i u, T_j v)w + \rho(T_j u, T_i v)w + \rho(T_i v, T_j w)u \\ &\quad + \rho(T_j v, T_i w)u + \rho(T_i w, T_j u)v + \rho(T_j w, T_i u)v) \\ &\quad + T_j(\rho(T_i u, T_i v)w + \rho(T_i v, T_i w)u + \rho(T_i w, T_i u)v), \quad (i, j = 1, 2). \end{aligned}$$

The following proposition shows that a pair of compatible relative Rota-Baxter operators with an invertible condition are connected by a Nijenhuis operator.

**Proposition 3.7.** *Let  $T_1$  and  $T_2$  be two compatible relative Rota-Baxter operators in which  $T_2$  (resp.  $T_1$ ) is invertible. Then  $N = T_1 \circ T_2^{-1}$  (resp.  $N = T_2 \circ T_1^{-1}$ ) is a Nijenhuis operator on  $L$ .*

*Proof.* We only prove the case in which  $T_2$  is invertible. The other case is similar. First observe that, for  $N = T_1 \circ T_2^{-1}$ , we have

$$\alpha \circ N = \alpha \circ T_1 \circ T_2^{-1} = T_1 \circ \alpha \circ T_2^{-1} = T_1 \circ T_2^{-1} \circ \alpha = N \circ \alpha.$$

Further, for any  $x, y, z \in L$ , there exists  $u, v, w \in V$  such that  $T_2(u) = x, T_2(v) = y, T_2(w) = z$ . Therefore, we have

$$\begin{aligned}
 [Nx, Ny, Nz] &= [NT_2(u), NT_2(v), NT_2(w)] \\
 &= [T_1(u), T_1(v), T_1(w)] \\
 (3.3) \quad &= T_1(\rho(T_1u, T_1v)w + \rho(T_1v, T_1w)u + \rho(T_1w, T_1u)v).
 \end{aligned}$$

On the other hand, we have

$$\begin{aligned}
 &N([Nx, Ny, z] + [x, Ny, Nz] + [Nx, y, Nz]) \\
 &\quad - N^2([Nx, y, z] + [x, Ny, z] + [x, y, Nz]) + N^3[x, y, z] \\
 &= T_1 \circ T_2^{-1}([T_1(u), T_1(v), T_2(w)] + [T_2(u), T_1(v), T_1(w)] \\
 &\quad + [T_1(u), T_2(v), T_1(w)]) - (T_1 \circ T_2^{-1})^2([T_1(u), T_2(v), T_2(w)] \\
 &\quad + [T_2(u), T_1(v), T_2(w)] + [T_2(u), T_2(v), T_1(w)]) \\
 &\quad + (T_1 \circ T_2^{-1})^3([T_2(u), T_2(v), T_2(w)]) \\
 &= T_1 \circ T_2^{-1}(T_1(\rho(T_1u, T_2v)w + \rho(T_2u, T_1v)w + \rho(T_1v, T_2w)u \\
 &\quad + \rho(T_2v, T_1w)u + \rho(T_1w, T_2u)v + \rho(T_2w, T_1u)v) + T_2(\rho(T_1u, T_1v)w \\
 &\quad + \rho(T_1v, T_1w)u + \rho(T_1w, T_1u)v)) - (T_1 \circ T_2^{-1})^2(T_2(\rho(T_1u, T_2v)w \\
 &\quad + \rho(T_2u, T_1v)w + \rho(T_1v, T_2w)u + \rho(T_2v, T_1w)u + \rho(T_1w, T_2u)v \\
 &\quad + \rho(T_2w, T_1u)v) + T_1(\rho(T_2u, T_2v)w + \rho(T_2v, T_2w)u \\
 &\quad + \rho(T_2w, T_2u)v)) + (T_1 \circ T_2^{-1})^3(T_2(\rho(T_2u, T_2v)w + \rho(T_2v, T_2w)u \\
 &\quad + \rho(T_2w, T_2u)v)) \\
 (3.4) \quad &= T_1(\rho(T_1u, T_1v)w + \rho(T_1v, T_1w)u + \rho(T_1w, T_1u)v).
 \end{aligned}$$

It follows from (3.3) and (3.4) that  $N$  is a Nijenhuis operator.  $\square$

#### 4. Constructions of Nijenhuis operators

In this section, according to constructions of 3-Hom-Lie algebras, we give various constructions of Nijenhuis operators. We also give some examples of Nijenhuis operators on 3-Hom-Lie algebras.

##### 4.1. Constructions of Nijenhuis operators on 3-Hom-Lie algebras from those on Hom-Lie algebras

**Lemma 4.1** ([2]). *Let  $(L, [\cdot, \cdot], \alpha)$  be a Hom-Lie algebra and  $L^*$  be the dual space of  $L$ . Suppose that  $f \in L^*$  satisfies  $f([x, y]) = 0$  and  $f(\alpha(x))f(y) = f(\alpha(y))f(x)$  for all  $x, y \in L$ . Then there is a 3-Hom-Lie algebra structure on  $L$  given by*

$$(4.1) \quad [x, y, z]_f = f(x)[y, z] + f(y)[z, x] + f(z)[x, y], \quad \forall x, y, z \in L.$$

**Theorem 4.2.** *Let  $N$  be a Nijenhuis operator on a Hom-Lie algebra  $(L, [\cdot, \cdot], \alpha)$ . Suppose that  $f \in L^*$  satisfies  $f([x, y]) = 0$  and  $f(\alpha(x))f(y) = f(\alpha(y))f(x)$  for*

all  $x, y \in L$ . Then  $N$  is also a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_f, \alpha)$ .

*Proof.* By Lemma 4.1,  $(L, \{\cdot, \cdot, \cdot\}_{f,D}, \alpha)$  is a 3-Hom-Lie algebra with the multiplication  $[\cdot, \cdot, \cdot]_f$  defined in (4.1). Now for any  $x, y, z \in L$ , we have  $\alpha \circ N = N \circ \alpha$  and

$$\begin{aligned} & [Nx, Ny, Nz]_f \\ &= f(Nx)[Ny, Nz] + f(Ny)[Nz, Nx] + f(Nz)[Nx, Ny] \\ &= f(Nx)([Ny, z] + [y, Nz] - N[y, z]) + f(Ny)([Nz, x] + [z, Nx] - N[z, x]) \\ & \quad + f(Nz)([Nx, y] + [x, Ny] - N[x, y]). \end{aligned}$$

Applying (3.2) and (4.1), we obtain

$$\begin{aligned} & N\left([Nx, Ny, z]_f + [x, Ny, Nz]_f + [Nx, y, Nz]_f\right. \\ & \quad \left. - N[Nx, y, z]_f - N[x, Ny, z]_f - N[x, y, Nz]_f + N^2[x, y, z]_f\right) \\ &= N\left(f(Nx)[Ny, z] + f(Ny)[z, Nx] + f(z)[Nx, Ny] + f(x)[Ny, Nz]\right. \\ & \quad + f(Ny)[Nz, x] + f(Nz)[x, Ny] + f(Nx)[y, Nz] + f(y)[Nz, Nx] \\ & \quad + f(Nz)[Nx, y] - N(f(Nx)[y, z] + f(y)[z, Nx] + f(z)[Nx, y]) \\ & \quad + f(x)[Ny, z] + f(Ny)[z, x] + f(z)[x, Ny] + f(x)[y, Nz] \\ & \quad \left. + f(y)[Nz, x] + f(Nz)[x, y] + N^2(f(x)[y, z] + f(y)[z, x] + f(z)[x, y])\right) \\ &= [Nx, Ny, Nz]_f + N(f(x)[Ny, Nz] + f(y)[Nz, Nx] + f(z)[Nx, Ny]) \\ & \quad - Nf(x)[Ny, Nz] - Nf(y)[Nz, Nx] - Nf(z)[Nx, Ny] \\ &= [Nx, Ny, Nz]_f. \end{aligned}$$

And the proof is finished.  $\square$

By Lemma 4.1 and Theorem 4.2, we have

**Example 4.3.** Let  $(L, [\cdot, \cdot])$  be a Lie algebra and  $\alpha : L \rightarrow L$  a Lie algebra morphism,  $N$  be a Nijenhuis operator on a Lie algebra  $(L, [\cdot, \cdot])$  with  $\alpha \circ N = N \circ \alpha$ . Suppose that  $f \in L^*$  satisfies  $f([x, y]_\alpha) = 0$  and  $f(\alpha(x))f(y) = f(\alpha(y))f(x)$  for all  $x, y \in L$ . Then  $N$  is also a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_f, \alpha)$ , where  $[\cdot, \cdot]_\alpha = \alpha \circ [\cdot, \cdot]$  and

$$[x, y, z]_f = f(x)[y, z]_\alpha + f(y)[z, x]_\alpha + f(z)[x, y]_\alpha, \quad \forall x, y, z \in L.$$

**Example 4.4.** Let  $(L, [\cdot, \cdot], \alpha)$  be the 3-dimensional Hom-Lie algebra given by

$$[e_1, e_2] = e_2, \quad \alpha(e_1) = e_1, \quad \alpha(e_2) = -e_2, \quad \alpha(e_3) = e_3,$$

where  $\{e_1, e_2, e_3\}$  is a basis of  $L$ . By Lemma 4.1, the trace function  $f \in L^*$ ,

where  $\begin{cases} f(e_1) = 1, \\ f(e_2) = 0, \\ f(e_3) = 1 \end{cases}$  induces a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_f, \alpha)$  defined with



the same basis by

$$[e_1, e_2, e_3] = e_2.$$

Consider a linear map  $N : L \rightarrow L$  defined by  $\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$  with respect to the basis  $\{e_1, e_2, e_3\}$ . Define

$$Ne_1 = a_{11}e_1 + a_{21}e_2 + a_{31}e_3,$$

$$Ne_2 = a_{12}e_1 + a_{22}e_2 + a_{32}e_3,$$

$$Ne_3 = a_{13}e_1 + a_{23}e_2 + a_{33}e_3.$$

In order to satisfy  $\alpha \circ N = N \circ \alpha$ , we need

$$a_{21} = a_{12} = a_{32} = a_{23} = 0.$$

In order to obtain that  $N$  is a Nijenhuis operator on the Hom-Lie algebra  $L$ , we need

$$[Ne_i, Ne_j] = N([Ne_i, e_j] + [e_i, Ne_j] - N[e_i, e_j]), \quad i, j = 1, 2, 3.$$

By a straightforward computation, we conclude that  $N$  is a Nijenhuis operator on the Hom-Lie algebra  $L$  if and only if

$$a_{21} = a_{12} = a_{32} = a_{23} = 0.$$

By Theorem 4.2,  $N = \begin{pmatrix} a_{11} & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & 0 & a_{33} \end{pmatrix}$  is also a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_f, \alpha)$ .

#### 4.2. Constructions of Nijenhuis operators on 3-Hom-Lie algebras from Nijenhuis operators on commutative Hom-associative algebras

**Lemma 4.5** ([24]). *Let  $(L, \cdot, \alpha)$  be a commutative Hom-associative algebra and  $D$  be a derivation and  $f \in L^*$  satisfies  $f(D(x) \cdot y) = f(x \cdot D(y))$  and  $f(\alpha(x))f(y) = f(\alpha(y))f(x)$  for all  $x, y \in L$ . Then  $(L, \{\cdot, \cdot, \cdot\}_{f,D}, \alpha)$  is a 3-Hom-Lie algebra, where the bracket is given*

$$(4.2) \quad \{x, y, z\}_{f,D} = \begin{vmatrix} f(x) & f(y) & f(z) \\ D(x) & D(y) & D(z) \\ x & y & z \end{vmatrix}$$

for any  $x, y, z \in L$ .

**Proposition 4.6.** *With the same assumptions as Lemma 4.5. Let  $N$  be a Nijenhuis operator on  $(L, \cdot, \alpha)$  satisfying  $D \circ N = N \circ D$ . Then  $N$  is a Nijenhuis operator on the 3-Lie algebra  $(L, \{\cdot, \cdot, \cdot\}_{f,D}, \alpha)$ , where the bracket is given by (4.2).*

*Proof.* For all  $x, y \in L$ , define  $[x, y]_D = D(x) \cdot y - D(y) \cdot x$ . By direct calculations, we can verify that  $(L, [\cdot, \cdot]_D, \alpha)$  is a Hom-Lie algebra. Furthermore, assume that  $N$  is a Nijenhuis operator on  $(L, \cdot, \alpha)$  satisfying  $D \circ N = N \circ D$ . Then we have  $\alpha \circ N = N \circ \alpha$  and

$$\begin{aligned} & [Nx, Ny]_D \\ &= D(Nx) \cdot Ny - D(Ny) \cdot Nx \\ &= ND(x) \cdot Ny - Nx \cdot ND(y) \\ &= N(Dx \cdot Ny + NDx \cdot y - N(Dx \cdot y)) - N(Nx \cdot Dy + x \cdot NDy - N(x \cdot Dy)) \\ &= N([Nx, y]_D + [x, Ny]_D - N[x, y]_D), \end{aligned}$$

which implies that  $N$  is a Nijenhuis operator on the Hom-Lie algebra  $(L, [\cdot, \cdot]_D, \alpha)$ . By Theorem 4.2,  $N$  is a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, \{\cdot, \cdot, \cdot\}_{f,D}, \alpha)$ .  $\square$

By Lemma 4.5 and Proposition 4.6, we have

**Example 4.7.** Let  $(L, \cdot)$  be a commutative algebra and  $\alpha : L \rightarrow L$  an algebra morphism,  $D$  be a derivation on a commutative algebra  $(L, \cdot)$  with  $\alpha \circ D = D \circ \alpha$  and  $N$  be a Nijenhuis operator on a commutative algebra  $(L, \cdot)$  with  $\alpha \circ N = N \circ \alpha$ . Suppose that  $f \in L^*$  satisfies  $f(D(x) \cdot_\alpha y) = f(x \cdot_\alpha D(y))$  and  $f(\alpha(x))f(y) = f(\alpha(y))f(x)$  for all  $x, y \in L$ . Then  $N$  is also a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, \{\cdot, \cdot, \cdot\}_{f,D}, \alpha)$ , where  $\cdot_\alpha = \alpha \circ \cdot$  and

$$\begin{aligned} [x, y]_{\alpha, D} &= D(x) \cdot_\alpha y - D(y) \cdot_\alpha x, \\ \{x, y, z\}_{f, D} &= f(x)[y, z]_{\alpha, D} + f(y)[z, x]_{\alpha, D} + f(z)[x, y]_{\alpha, D}, \quad \forall x, y, z \in L. \end{aligned}$$

Let  $(L, \cdot, \alpha)$  be a commutative Hom-associative algebra. For  $x_i, y_i, z_i \in L, i = 1, 2, 3$ , denote by

$$|\vec{x}, \vec{y}, \vec{z}| = \begin{vmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ x_3 & y_3 & z_3 \end{vmatrix},$$

where  $\vec{x}, \vec{y}$  and  $\vec{z}$  denote the column vectors.

The following lemma is easy to check and we omit the proof.

**Lemma 4.8.** Let  $N$  be a Nijenhuis operator on a commutative Hom-associative algebra  $(L, \cdot, \alpha)$  and  $N(\vec{x}), N(\vec{y}), N(\vec{z})$  denote the images of the column vectors. Then we have

$$\begin{aligned} & |N(\vec{x}), N(\vec{y}), N(\vec{z})| \\ &= N(|N(\vec{x}), N(\vec{y}), \vec{z}| + c.p.) - N^2(|N(\vec{x}), N(\vec{y}), \vec{z}| + c.p.) \\ &+ N^3(|\vec{x}, \vec{y}, \vec{z}|). \end{aligned}$$

**Definition ([16]).** Let  $(L, \cdot, \alpha)$  be a commutative Hom-associative algebra. If a linear map  $\omega : L \rightarrow L$  satisfying for every  $a, b \in L$ ,

$$\omega(a \cdot b) = \omega(a) \cdot \omega(b), \text{ and } \omega^2(a) = a,$$

then  $\omega$  is called an involution of  $L$ .

**Lemma 4.9** ([16]). *Let  $(L, \cdot, \alpha)$  be a commutative Hom-associative algebra,  $D$  be a derivation of  $L$  and  $\omega : L \rightarrow L$  be an involution of  $L$  satisfying*

$$\omega \circ D + D \circ \omega = 0, \text{ and } \alpha \circ \omega = \omega \circ \alpha.$$

*Then  $(L, [\cdot, \cdot, \cdot]_{\omega, D}, \alpha)$  is a 3-Hom-Lie algebra, where the bracket is given*

$$(4.3) \quad [x, y, z]_{\omega, D} = \begin{vmatrix} \omega(x) & \omega(y) & \omega(z) \\ x & y & z \\ D(x) & D(y) & D(z) \end{vmatrix},$$

for any  $x, y, z \in L$ .

**Theorem 4.10.** *With the same assumptions as Lemma 4.10. Let  $N$  be a Nijenhuis operator on a commutative Hom-associative algebra  $(L, \cdot, \alpha)$  satisfying  $N \circ D = D \circ N$  and  $N \circ \omega = \omega \circ N$ . Then  $N$  is a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_{\omega, D}, \alpha)$ , where the bracket is given by (4.3).*

*Proof.* For any  $x, y, z \in L$ , we have  $\alpha \circ N = N \circ \alpha$  and

$$\begin{aligned} & [Nx, Ny, Nz]_{\omega, D} \\ &= \begin{vmatrix} \omega N(x) & \omega N(y) & \omega N(z) \\ Nx & Ny & Nz \\ DN(x) & DN(y) & DN(z) \end{vmatrix} \\ &= \begin{vmatrix} N\omega(x) & N\omega(y) & N\omega(z) \\ Nx & Ny & Nz \\ ND(x) & ND(y) & ND(z) \end{vmatrix} \\ &= N \left( \begin{vmatrix} N\omega(x) & N\omega(y) & \omega(z) \\ Nx & Ny & z \\ ND(x) & ND(y) & D(z) \end{vmatrix} + c.p. \right) \\ &\quad - N^2 \left( \begin{vmatrix} N\omega(x) & \omega(y) & \omega(z) \\ Nx & y & z \\ ND(x) & D(y) & D(z) \end{vmatrix} + c.p. \right) \\ &\quad + N^3 \left( \begin{vmatrix} \omega(x) & \omega(y) & \omega(z) \\ x & y & z \\ D(x) & ND(y) & D(z) \end{vmatrix} \right) \\ &= N \left( \begin{vmatrix} \omega N(x) & \omega N(y) & \omega(z) \\ Nx & Ny & z \\ DN(x) & DN(y) & D(z) \end{vmatrix} + c.p. \right) \\ &\quad - N^2 \left( \begin{vmatrix} \omega N(x) & \omega(y) & \omega(z) \\ Nx & y & z \\ DN(x) & D(y) & D(z) \end{vmatrix} + c.p. \right) + N^3 \left( \begin{vmatrix} \omega(x) & \omega(y) & \omega(z) \\ x & y & z \\ D(x) & D(y) & D(z) \end{vmatrix} \right) \\ &= N ([Nx, Ny, z]_{\omega, D} + c.p.) - N^2 ([Nx, y, z]_{\omega, D} + c.p.) + N^3 ([x, y, z]_{\omega, D}). \end{aligned}$$

Thus,  $N$  is a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_{\omega, D}, \alpha)$ .  $\square$

### 5. Cohomology of Nijenhuis operators

In this section, we construct a representation of the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$  on the vector space  $L$ , and define the cohomology of Nijenhuis operators on 3-Hom-Lie algebras.

**Lemma 5.1.** *Let  $N : L \rightarrow L$  be a Nijenhuis operator on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$ . Define  $\rho_N : L \wedge L \rightarrow \mathfrak{gl}(L)$  by*

$$\begin{aligned} \rho_N(x_1, x_2)(x) &= [N(x_1), N(x_2), x] - N([N(x_1), x_2, x] \\ &\quad + [x_1, N(x_2), x] - N[x_1, x_2, x]), \end{aligned}$$

where  $x_1, x_2, x \in L$ . Then  $(L, \alpha, \rho_N)$  is a representation of the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$ .

*Proof.* For any  $x_1, x_2, x_3, x_4, x \in L$ , it is easy to check that  $\rho_N(\alpha(x_1), \alpha(x_2)) \circ \alpha = \alpha \circ \rho_N(x_1, x_2)$  holds. Further, we have

$$\begin{aligned} &\rho_N(\alpha(x_2), \alpha(x_3))\rho_N(x_1, x_4)(x) + \rho_N(\alpha(x_3), \alpha(x_1))\rho_N(x_2, x_4)(x) \\ &\quad + \rho_N(\alpha(x_1), \alpha(x_2))\rho_N(x_3, x_4)(x) \\ &= \rho_N(\alpha(x_2), \alpha(x_3))([N(x_1), N(x_4), x] \\ &\quad - N([N(x_1), x_4, x] + [x_1, N(x_4), x] - N[x_1, x_4, x])) \\ &\quad + \rho_N(\alpha(x_3), \alpha(x_1))([N(x_2), N(x_4), x] \\ &\quad - N([N(x_2), x_4, x] + [x_2, N(x_4), x] - N[x_2, x_4, x])) \\ &\quad + \rho_N(\alpha(x_1), \alpha(x_2))([N(x_3), N(x_4), x] \\ &\quad - N([N(x_3), x_4, x] + [x_3, N(x_4), x] - N[x_3, x_4, x])) \\ &= [N(x_2), N(x_3), [N(x_1), N(x_4), x]] \\ &\quad - N([N(x_2), x_3, [N(x_1), N(x_4), x]] + [x_2, N(x_3), [N(x_1), N(x_4), x]]) \\ &\quad - N[x_2, x_3, [N(x_1), N(x_4), x]]) - [N(x_2), N(x_3), N([N(x_1), x_4, x] \\ &\quad + [x_1, N(x_4), x] - N[x_1, x_4, x])] + N([N(x_2), x_3, N([N(x_1), x_4, x] \\ &\quad + [x_1, N(x_4), x] - N[x_1, x_4, x]) \\ &\quad + [x_1, N(x_4), x] - N[x_1, x_4, x]) + [x_2, N(x_3), N([N(x_1), x_4, x] + [x_1, N(x_4), x] \\ &\quad - N[x_1, x_4, x]) - N[x_2, x_3, N([N(x_1), x_4, x] + [x_1, N(x_4), x] - N[x_1, x_4, x])]) \\ &\quad + [N(x_3), N(x_1), [N(x_2), N(x_4), x]] - N([N(x_3), x_1, [N(x_2), N(x_4), x]]) \\ &\quad + [x_3, N(x_1), [N(x_2), N(x_4), x]] - N[x_3, x_1, [N(x_2), N(x_4), x]]) \\ &\quad - [N(x_3), N(x_1), N([N(x_2), x_4, x] + [x_2, N(x_4), x] - N[x_2, x_4, x])] \\ &\quad + N([N(x_3), x_1, N([N(x_2), x_4, x] + [x_2, N(x_4), x] - N[x_2, x_4, x])]) \\ &\quad + [x_3, N(x_1), N([N(x_2), x_4, x] + [x_2, N(x_4), x] - N[x_2, x_4, x])] \\ &\quad - N[x_3, x_1, N([N(x_2), x_4, x] + [x_2, N(x_4), x] - N[x_2, x_4, x])]) \\ &\quad + [N(x_1), N(x_2), [N(x_3), N(x_4), x]] - N([N(x_1), x_2, [N(x_3), N(x_4), x]]) \\ &\quad + [x_1, N(x_2), [N(x_3), N(x_4), x]] - N[x_1, x_2, [N(x_3), N(x_4), x]]) \\ &\quad - [N(x_1), N(x_2), N([N(x_3), x_4, x] + [x_3, N(x_4), x] - N[x_3, x_4, x])] \end{aligned}$$

$$\begin{aligned}
 & + N([N(x_1), x_2, N([N(x_3), x_4, x] + [x_3, N(x_4), x] - N[x_3, x_4, x])]) \\
 & + [x_1, N(x_2), N([N(x_3), x_4, x] + [x_3, N(x_4), x] - N[x_3, x_4, x])] \\
 & - N[x_1, x_2, N([N(x_3), x_4, x] + [x_3, N(x_4), x] - N[x_3, x_4, x])] \\
 = & [[N x_1, N x_2, N x_3], N \alpha(x_4), \alpha(x)] - N([[N x_1, N x_2, N x_3], \alpha(x_4), \alpha(x)] \\
 & + [[x_1, x_2, x_3]_N, N \alpha(x_4), \alpha(x)] - N[[x_1, x_2, x_3]_N, \alpha(x_4), \alpha(x)]) \\
 = & \rho_N([x_1, x_2, x_3]_N, \alpha(x_4)) \alpha(x).
 \end{aligned}$$

Similarly, we have

$$\begin{aligned}
 & \rho_N(\alpha(x_1), \alpha(x_2)) \rho_N(x_3, x_4) x \\
 = & \rho_N(\alpha(x_3), \alpha(x_4)) \rho_N(x_1, x_2) x + \rho_N([x_1, x_2, x_3]_N, \alpha(x)) \alpha(x) \\
 & + \rho_N(\alpha(x_3), [x_1, x_2, x_4]_N) \alpha(x).
 \end{aligned}$$

And the proof is finished.  $\square$

Let  $\delta_N : C_{\alpha, \alpha}^n(L, L) \rightarrow C_{\alpha, \alpha}^{n+1}(L, L)$  be the corresponding coboundary operator of the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$  with coefficients in the representation  $(L, \alpha, \rho_N)$ . More precisely,  $\delta_N : C_{\alpha, \alpha}^n(L, L) \rightarrow C_{\alpha, \alpha}^{n+1}(L, L)$  is given by

$$\begin{aligned}
 & (\delta_N f)(\mathfrak{X}_1, \mathfrak{X}_2, \dots, \mathfrak{X}_n, x_{n+1}) \\
 = & \sum_{1 \leq j < k \leq n} (-1)^j f(\alpha(\mathfrak{X}_1), \dots, \hat{\mathfrak{X}}_j, \dots, \alpha(\mathfrak{X}_{k-1}), [x_j, y_j, x_k]_N \wedge \alpha(y_k) \\
 & + \alpha(x_k) \wedge [x_j, y_j, y_k]_N, \alpha(\mathfrak{X}_{k+1}), \dots, \alpha(\mathfrak{X}_n), \alpha(x_{n+1})) \\
 & + \sum_{j=1}^n (-1)^j f(\alpha(\mathfrak{X}_1), \dots, \hat{\mathfrak{X}}_j, \dots, \alpha(\mathfrak{X}_n), [x_j, y_j, x_{n+1}]_N) \\
 & + \sum_{j=1}^n (-1)^{j+1} \rho_N(\alpha^{n-1}(\mathfrak{X}_j)) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_n, x_{n+1}) \\
 & + (-1)^{n+1} (\rho_N(\alpha^{n-1}(y_n), \alpha^{n-1}(x_{n+1})) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_{n-1}, x_n) \\
 & + \rho_N(\alpha^{n-1}(x_{n+1}), \alpha^{n-1}(x_n)) f(\mathfrak{X}_1, \dots, \hat{\mathfrak{X}}_j, \dots, \mathfrak{X}_{n-1}, y_n))
 \end{aligned}$$

for  $\mathfrak{X}_i = x_i \wedge y_i \in \wedge^2 L$ ,  $i = 1, \dots, n$  and  $x_{n+1} \in L$ .

For any  $\mathfrak{X} = x \wedge y \in \wedge^2 L$  with  $\alpha(x) = x, \alpha(y) = y$ , we define  $d_N(\mathfrak{X}) : L \rightarrow L$  by

$$d_N(\mathfrak{X})(z) = N[\mathfrak{X}, z] - [\mathfrak{X}, Nz], \quad \forall z \in L.$$

**Proposition 5.2.** *Let  $N$  be a Nijenhuis operator on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$ . Then  $d_N(\mathfrak{X})$  is a 1-cocycle on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot]_N, \alpha)$  with coefficients in  $(L, \alpha, \rho_N)$ .*

*Proof.* By direct calculation we can get the conclusion.  $\square$

**Theorem 5.3.** *Let  $N$  be a Nijenhuis operator on a 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$  with respect to a representation  $(L, \rho_N, \alpha)$ . Define the set of  $n$ -cochains by*

$$C_N^n(L, L) = \begin{cases} C_{\alpha, \alpha}^n(L, L), & n \geq 2, \\ L \wedge L, & n = 1. \end{cases}$$

Define  $D_N : C_N^n(L, L) \rightarrow C_N^{n+1}(L, L)$  by

$$D_N = \begin{cases} \delta_N, & n \geq 2, \\ d_N, & n = 1. \end{cases}$$

We denote by

$$Z_N^n(L, L) = \{f \in C_N^n(L, L) \mid D_N f = 0\}$$

and

$$B_N^n(L, L) = \{D_N g \mid g \in C_N^{n-1}(L, L)\}$$

the space of  $n$ -cocycles and  $n$ -coboundaries, respectively. The corresponding quotients

$$H_N^n(L, L) := Z_N^n(L, L) / B_N^n(L, L), \text{ for } n \geq 1$$

are called the  $n$ -th cohomology group, and the cohomology of the cochain complex  $(\oplus_{n=1}^{\infty} C_N^n(L, L), D_N)$  is taken to be the cohomology for the Nijenhuis operator  $N$ .

## 6. Formal deformations of Nijenhuis operators

In this section, we study formal deformations of Nijenhuis operators on 3-Hom-Lie algebras.

Let  $(L, [\cdot, \cdot, \cdot], \alpha)$  be a 3-Hom-Lie algebra and  $N : L \rightarrow L$  be a Nijenhuis operator on it. Consider the space  $L[[t]]$  of formal power series in  $t$  with coefficients from  $L$ . Then  $L[[t]]$  is a  $\mathbb{K}[[t]]$ -module. Moreover the trilinear bracket  $[\cdot, \cdot, \cdot]$  and the linear map  $\alpha$  can be extended to  $L[[t]]$  by  $\mathbb{K}[[t]]$ -linearity. We denote extended structures by the same notation. With these extensions,  $(L[[t]], [\cdot, \cdot, \cdot], \alpha)$  is a 3-Hom-Lie algebra over  $\mathbb{K}[[t]]$ .

**Definition.** A formal one-parameter deformation of  $N$  consists of a formal sum

$$N_t = N_0 + tN_1 + t^2N_2 + \cdots \in \text{Hom}(L, L)[[t]]$$

with  $N_0 = N$  such that the  $\mathbb{K}[[t]]$ -linear map  $N_t : L[[t]] \rightarrow L[[t]]$  is a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$ .

Thus it follows from the above definition that  $N_t$  satisfies:  $\alpha \circ N_t = N_t \circ \alpha$  and

$$\begin{aligned} & [N_t x, N_t y, N_t z] \\ &= N_t([N_t x, N_t y, z] + [x, N_t y, N_t z] + [N_t x, y, N_t z] - N_t[N_t x, y, z]) \end{aligned}$$

$$- N_t[x, N_t y, z] - N_t[x, y, N_t z] + N_t \circ N_t[x, y, z],$$

for all  $x, y, z \in L$ . These conditions are equivalent to  $\alpha \circ N_n = N_n \circ \alpha$  and

$$\begin{aligned} & \sum_{i+j+k=n} [N_i x, N_j y, N_k z] \\ = & \sum_{i+j+k=n} N_i([N_j x, N_k y, z] + [x, N_j y, N_k z] + [N_j x, y, N_k z] \\ & - N_j[N_k x, y, z] - N_j[x, N_k y, z] - N_j[x, y, N_k z] + N_j \circ N_k[x, y, z]), \end{aligned}$$

for  $n = 0, 1, 2, \dots$  and  $x, y, z \in L$ , the conditions hold automatically as  $N_0 = N$  is a Nijenhuis operator on the 3-Hom-Lie algebra  $(L, [\cdot, \cdot, \cdot], \alpha)$ . For  $n = 1$ , we get  $\alpha \circ N_n = N_n \circ \alpha$  and

$$\begin{aligned} & [N_1(z), N(y), N(z)] + [N(x), N_1(y), N(z)] + [N(x), N(y), N_1(z)] \\ = & N([x, N_1(y), N(z)] + [x, N(y), N_1(z)]) + N([N_1(z), y, N(z)] \\ & + [N(z), y, N_1(z)]) + N([N_1(x), N(y), z] + [N(x), N_1(y), z]) \\ (6.1) \quad & + N_1([x, N(y), N(z)] + [N(x), y, N(z)] + [N(x), N(y), z]) \\ & - N^2([N_1(x), y, z] + [x, N(y), z] + [x, y, N_1(z)]) \\ & - N \circ N_1([x, N(y), z] + [N(x), y, z] + [x, y, N(z)]) \\ & + N^2 \circ N_1([x, y, z]). \end{aligned}$$

Hence it follows from (6.1) that  $N_1$  is a 1-cocycle in the cohomology of  $N$ . This is called the infinitesimal of the deformation.

**Definition.** Two deformations  $N_t = \sum_{i=0}^{\infty} t^i N_i$  and  $N'_t = \sum_{i=0}^{\infty} t^i N'_i$  of a Nijenhuis operator  $N$  are said to be equivalent if there is an element  $\mathfrak{X} = x \wedge y \in \wedge^2 L$  with  $\alpha(x) = x, \alpha(y) = y$ , and linear maps  $\phi_i \in \text{Hom}(L, L)$  for  $i \geq 2$  such that

$$\phi_t = (\text{id} + t[\mathfrak{X}, \cdot] + \sum_{i \geq 2} t^i \phi_i) : L[[t]] \rightarrow L[[t]]$$

is a morphism of Nijenhuis operators from  $N_t$  to  $N'_t$ .

Let  $\phi_t$  be a morphism of Nijenhuis operators from  $N_t$  to  $N'_t$ . For any  $z \in L$ , we have

$$(N + tN'_1)(\text{id} + t[\mathfrak{X}, \cdot])(z) = (\text{id} + t[\mathfrak{X}, \cdot])(N + tN_1)(z) \pmod{t^2}.$$

By equating coefficients of  $t$ , we get

$$N_1(z) - N'_1(z) = N[\mathfrak{X}, z] - [\mathfrak{X}, Nz] = d_N(\mathfrak{X})(z).$$

As a consequence, we get the following

**Theorem 6.1.** *Let  $N_t = \sum_{i=0}^{\infty} t^i N_i$  be a formal one-parameter deformation of  $N$ . Then the linear term  $N_1$  is a 1-cocycle in the cohomology of  $N$ , whose cohomology class depends only on the equivalence class of the deformation.*

## References

- [1] F. Ammar, S. Mabrouk, and A. Makhlouf, *Representations and cohomology of  $n$ -ary multiplicative Hom-Nambu-Lie algebras*, J. Geom. Phys. **61** (2011), no. 10, 1898–1913. <https://doi.org/10.1016/j.geomphys.2011.04.022>
- [2] J. Arn Lind, A. Makhlouf, and S. Silvestrov, *Ternary Hom-Nambu-Lie algebras induced by Hom-Lie algebras*, J. Math. Phys. **51** (2010), no. 4, 043515, 11 pp. <https://doi.org/10.1063/1.3359004>
- [3] J. Arn Lind, A. Makhlouf, and S. Silvestrov, *Construction of  $n$ -Lie algebras and  $n$ -ary Hom-Nambu-Lie algebras*, J. Math. Phys. **52** (2011), no. 12, 123502, 13 pp. <https://doi.org/10.1063/1.3653197>
- [4] J. Bagger and N. Lambert, *Gauge symmetry and supersymmetry of multiple M2-branes*, Phys. Rev. D **77** (2008), no. 6, 065008, 6 pp. <https://doi.org/10.1103/PhysRevD.77.065008>
- [5] A. Das and S. Sen, *Nijenhuis operators on Hom-Lie algebras*, Comm. Algebra **50** (2022), no. 3, 1038–1054. <https://doi.org/10.1080/00927872.2021.1977942>
- [6] V. T. Filippov,  *$n$ -Lie algebras*, Sibirsk. Mat. Zh. **26** (1985), no. 6, 126–140, 191.
- [7] S. Guo, Y. Qin, K. Wang, and G. Zhou, *Deformations and cohomology theory of Rota-Baxter 3-Lie algebras of arbitrary weights*, J. Geom. Phys. **183** (2023), Paper No. 104704, 24 pp. <https://doi.org/10.1016/j.geomphys.2022.104704>
- [8] S. Guo, S. Wang, and X. Zhang, *3-Hom-Lie Yang-Baxter equation and 3-Hom-Lie bialgebras*, Mathematics **10** (2022), 2485.
- [9] J. T. Hartwig, D. Larsson, and S. D. Silvestrov, *Deformations of Lie algebras using  $\sigma$ -derivations*, J. Algebra **295** (2006), no. 2, 314–361. <https://doi.org/10.1016/j.jalgebra.2005.07.036>
- [10] S. Hou and Y. Sheng, *Generalized Reynolds operators on 3-Lie algebras and NS-3-Lie algebras*, Int. J. Geom. Methods Mod. Phys. **18** (2021), no. 14, Paper No. 2150223, 29 pp. <https://doi.org/10.1142/S0219887821502236>
- [11] S. Hou and Y. Sheng, *Cohomologies of Reynolds operators on  $n$ -Lie algebras*, Comm. Algebra **51** (2023), no. 2, 779–798. <https://doi.org/10.1080/00927872.2022.2113403>
- [12] S. Hou, Y. Sheng, and R. Tang, *Twilled 3-Lie algebras, generalized matched pairs of 3-Lie algebras and  $\mathcal{O}$ -operators*, J. Geom. Phys. **163** (2021), Paper No. 104148, 15 pp. <https://doi.org/10.1016/j.geomphys.2021.104148>
- [13] S. Hou, Y. Sheng, and Y. Zhou, *3-post-Lie algebras and relative Rota-Baxter operators of nonzero weight on 3-Lie algebras*, J. Algebra **615** (2023), 103–129. <https://doi.org/10.1016/j.jalgebra.2022.10.016>
- [14] N. H. Hu,  *$q$ -Witt algebras,  $q$ -Lie algebras,  $q$ -holomorph structure and representations*, Algebra Colloq. **6** (1999), no. 1, 51–70.
- [15] Y. Li and D. Wang, *Twisted Rota-Baxter operators on 3-Hom-Lie algebras*, Comm. Algebra **51** (2023), no. 11, 4662–4675. <https://doi.org/10.1080/00927872.2023.2215321>
- [16] Y. Liu, L. Chen, and Y. Ma, *Representations and module-extensions of 3-hom-Lie algebras*, J. Geom. Phys. **98** (2015), 376–383. <https://doi.org/10.1016/j.geomphys.2015.08.013>
- [17] J. Liu, A. Makhlouf, and Y. Sheng, *A new approach to representations of 3-Lie algebras and Abelian extensions*, Algebr. Represent. Theory **20** (2017), no. 6, 1415–1431. <https://doi.org/10.1007/s10468-017-9693-0>
- [18] J.-F. Liu, Y.-H. Sheng, Y.-Q. Zhou, and C.-M. Bai, *Nijenhuis operators on  $n$ -Lie algebras*, Commun. Theor. Phys. (Beijing) **65** (2016), no. 6, 659–670. <https://doi.org/10.1088/0253-6102/65/6/659>
- [19] S. K. Mishra and A. Naolekar,  *$\mathcal{O}$ -operators on hom-Lie algebras*, J. Math. Phys. **61** (2020), no. 12, 121701, 19 pp. <https://doi.org/10.1063/5.0026719>
- [20] Y. Sheng, *Representations of hom-Lie algebras*, Algebr. Represent. Theory **15** (2012), no. 6, 1081–1098. <https://doi.org/10.1007/s10468-011-9280-8>



- [21] Y.-H. Sheng and C. M. Bai, *A new approach to hom-Lie bialgebras*, J. Algebra **399** (2014), 232–250. <https://doi.org/10.1016/j.jalgebra.2013.08.046>
- [22] Y.-H. Sheng and R. Tang, *Symplectic, product and complex structures on 3-Lie algebras*, J. Algebra **508** (2018), 256–300. <https://doi.org/10.1016/j.jalgebra.2018.05.005>
- [23] L. Song and R. Tang, *Cohomologies, deformations and extensions of n-Hom-Lie algebras*, J. Geom. Phys. **141** (2019), 65–78. <https://doi.org/10.1016/j.geomphys.2019.03.003>
- [24] B. Sun and L. Chen, *Rota-Baxter multiplicative 3-ary Hom-Nambu-Lie algebras*, J. Geom. Phys. **98** (2015), 400–413. <https://doi.org/10.1016/j.geomphys.2015.08.011>
- [25] R. Tang, S. Hou, and Y. Sheng, *Lie 3-algebras and deformations of relative Rota-Baxter operators on 3-Lie algebras*, J. Algebra **567** (2021), 37–62. <https://doi.org/10.1016/j.jalgebra.2020.09.017>
- [26] J. Zhao, J. Liu, and Y. Sheng, *Cohomologies and relative Rota-Baxter-Nijenhuis structures of 3-LieRep pairs*, Linear Multilinear Algebra **70** (2022), no. 21, 6240–6264. <https://doi.org/10.1080/03081087.2021.1949428>

YIZHENG LI  
SCHOOL OF MATHEMATICAL SCIENCES  
QUFU NORMAL UNIVERSITY  
QUFU 273165, P. R. CHINA  
*Email address:* yzli1001@163.com

DINGGUO WANG  
SCHOOL OF MATHEMATICAL SCIENCES  
QUFU NORMAL UNIVERSITY  
QUFU 273165, P. R. CHINA  
*Email address:* dingguo95@126.com