

INVARIANT PSEUDOPARALLEL SUBMANIFOLDS OF AN ALMOST α -COSYMPLECTIC (κ, μ, ν) -SPACE

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Abstract. In this article, we research the conditions for invariant submanifolds in an almost α -cosymplectic (κ, μ, ν) space to be pseudo-parallel, Ricci-generalized pseudo-parallel and 2-Ricci-generalized pseudo-parallel. We think that the results for the relations among the functions will contribute to differential geometry.

1. Introduction

An almost contact manifold is an odd-dimensional manifold \widetilde{M}^{2n+1} which carries a field ϕ of endomorphism of the tangent space, a vector field ξ , called characteristic, and a 1-form η satisfying

$$(1) \quad \phi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1,$$

where I denotes the identity mapping of tangent space at each point of M . From (1), it follows

$$(2) \quad \phi\xi = 0, \quad \eta \circ \phi = 0 \quad \text{rank}(\phi) = 2n.$$

An almost contact manifold $\widetilde{M}^{2n+1}(\phi, \xi, \eta)$ is said to be normal if the tensor field $N = [\phi, \phi] + 2d\eta \otimes \xi = 0$, where $[\phi, \phi]$ denote the Nijenhuis tensor field of ϕ . It is well known that any almost contact manifold $\widetilde{M}^{2n+1}(\phi, \xi, \eta)$ has a Riemannian metric such that

$$(3) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$$

for any vector fields X, Y on \widetilde{M} [3]. Such metric g is called compatible metric and the manifold \widetilde{M}^{2n+1} together with the structure (ϕ, η, ξ, g) is called an almost contact metric manifold and is denoted by $\widetilde{M}^{2n+1}(\phi, \eta, \xi, g)$. The 2-form Φ of $\widetilde{M}^{2n+1}(\phi, \eta, \xi, g)$ is defined as $\Phi(X, Y) = g(\phi X, Y)$, and is called the

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fundamental form of $\widetilde{M}^{2n+1}(\phi, \eta, \xi, g)$. If the Nijenhuis tensor vanishes, defined by

$$N_\phi(X, Y) = [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y] - \phi^2[X, Y] + 2d\eta(X, Y)\xi,$$

then $\widetilde{M}^{2n+1}(\phi, \eta, \xi, g)$ is said to be normal. It is obvious that a normal almost Kenmotsu is said to be Kenmotsu manifold. On the other hand, an almost contact metric manifold is known as Kenmotsu if and only if $(\widetilde{\nabla}_X \phi)Y = g(\phi X, Y)\xi - \eta(Y)\phi X$. An almost contact metric structure is cosymplectic if and only if $\widetilde{\nabla}\eta$ and $\widetilde{\nabla}\Phi$ are closed.

In the light of the above definitions, the generalization of almost Kenmotsu manifold, $\widetilde{M}^{2n+1}(\phi, \eta, \xi, g)$ is called almost α -Kenmotsu manifold if $d\eta = 0$ and $d\Phi = 2\alpha\eta \wedge \Phi$, where α is a nonzero real constant[4].

As a generalization of these, a new notation has been introduced of an almost α -cosymplectic manifold which is defined $d\eta = 0$ and $d\Phi = 2\alpha\eta \wedge \Phi$ for a real number α . A normal almost α -cosymplectic manifold is said to be α -cosymplectic manifold, and it is either cosymplectic or α -Kenmotsu under the condition $\alpha = 0$ or $\alpha \neq 0$, respectively[6, 12].

It should be noted that almost α -cosymplectic manifolds are generalizations of almost α -Kenmotsu and almost cosymplectic manifolds.

It is well known that on a contact metric manifold $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$, the tensor h , defined by $2h = L_\xi \phi$, the following equalities are satisfied;

$$(4) \quad \widetilde{\nabla}_X \xi = -\phi X - \phi h X, \quad h\phi + \phi h = 0, \quad tr h = tr \phi h = 0, \quad h\xi = 0,$$

where $\widetilde{\nabla}$ is the Levi-Civita connection on \widetilde{M}^{2n+1} [4].

In [10], the authors studied the almost α -cosymplectic (κ, μ, ν) -spaces under different conditions and gave an example in dimension 3.

Going beyond generalized (κ, μ) -spaces, in [8], the notion of (κ, μ, ν) -contact metric manifold was introduced as follows[10];

$$(5) \quad \widetilde{R}(X, Y)\xi = \eta(Y)[\kappa I + \mu h + \nu \phi h]X - \eta(X)[\kappa I + \mu h + \nu \phi h]Y,$$

for some smooth functions κ, μ and ν on \widetilde{M}^{2n+1} , where \widetilde{R} denotes the Riemannian curvature tensor of \widetilde{M}^{2n+1} and X, Y are vector fields on \widetilde{M}^{2n+1} .

They proved that this type of manifold is intrinsically related to the harmonicity of the Reeb vector on contact metric 3-manifolds. Some authors have studied manifolds satisfying condition (5) but a non-contact metric structure. In this connection, P. Dacko and Z. Olszak defined an almost cosymplectic

(κ, μ, ν) -space as an almost cosymplectic manifold that satisfies (5), but with κ, μ and ν functions varying exclusively in the direction of ξ in [4]. Later examples have been given for this type manifold [5].

Pseudoparallel submanifolds have been studied in different structures and working on [2, 1, 11]. In the present paper, we generalize the ambient space and research cases of existence or non-existence of pseudoparallel submanifold in α -cosymplectic (κ, μ, ν) -space.

Proposition 1.1. *Given $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$ an almost α -cosymplectic (κ, μ, ν) -space, then*

$$\begin{aligned}
 (6) \quad h^2 &= (\kappa + \alpha^2)\phi^2, \\
 \widetilde{R}(\xi, X)Y &= \kappa[g(X, Y)\xi - \eta(Y)X] + \mu[g(hX, Y)\xi - \eta(Y)hX] \\
 (7) \quad &+ \nu[g(\phi hX, Y)\xi - \eta(Y)\phi hX] \\
 (8) \quad (\widetilde{\nabla}_X \phi)Y &= g(\alpha\phi X + hX, Y)\xi - \eta(Y)(\alpha\phi X + hX) \\
 (9) \quad \widetilde{\nabla}_X \xi &= -\alpha\phi^2 X - \phi hX,
 \end{aligned}$$

for all vector fields X, Y on \widetilde{M}^{2n+1} [3].

Proof. From (5), we obtain

$$(10) \quad \widetilde{R}(X, \xi)\xi = -\kappa\phi^2 X + \mu hX + \nu\phi hX.$$

Taking ϕX instead of X in (10), we have

$$(11) \quad \widetilde{R}(\phi X, \xi)\xi = \kappa\phi X + \mu h\phi X + \nu\phi h\phi X.$$

Applying ϕ to (11) and after the necessary revisions are made, we reach at

$$(12) \quad \phi\widetilde{R}(\phi X, \xi)\xi = \kappa\phi^2 X + \mu hX + \nu\phi hX.$$

(10) and (12) give us

$$(13) \quad \widetilde{R}(X, \xi)\xi - \phi\widetilde{R}(\phi X, \xi)\xi = -2\kappa\phi^2 X.$$

On the other hand, from ([13]) we know that

$$\begin{aligned}
 \widetilde{R}(X, \xi)\xi &= \alpha^2[\eta(X)\xi - X] + \alpha\phi hX + (\widetilde{\nabla}_\xi \phi h)X - (\widetilde{\nabla}_X \phi h)\xi \\
 (14) \quad &= \alpha^2\phi^2 X + 2\alpha\phi hX + \mu hX - h^2 X.
 \end{aligned}$$

This implies that

$$\widetilde{R}(\phi X, \xi)\xi = -\alpha^2\phi X + 2\alpha hX + \mu\phi h\phi X + \nu hX - h^2\phi X.$$

Applying ϕ to the last equality, one can easily see

$$(15) \quad \phi\widetilde{R}(\phi X, \xi)\xi = -\alpha^2\phi^2 X + 2\alpha\phi hX + \mu hX + \nu\phi hX + h^2 X.$$

From (14) and (15), we verify

$$(16) \quad \widetilde{R}(X, \xi)\xi - \phi\widetilde{R}(\phi X, \xi)\xi = 2[\alpha^2\phi^2 - h^2]X.$$

(13) and (18) give us (6).

Also, from (5), we have

$$g(\tilde{R}(X, Y)\xi, Z) = \kappa g(\eta(Y)X - \eta(X)Y, Z) + \mu g(\eta(Y)hX - \eta(X)hY, Z) + \nu g(\eta(Y)\phi hX - \eta(X)\phi hY, Z),$$

for all $X, Y, Z \in \Gamma(T\tilde{M})$. By using the properties of \tilde{R} and $\phi \circ h + h \circ \phi = 0$, we conclude that

$$(17) \quad \begin{aligned} g(\tilde{R}(\xi, Z)X, Y) &= \kappa\eta(Y)g(X, Z) - \kappa\eta(X)g(Y, Z) + \mu\eta(Y)g(hX, Z) \\ &- \mu\eta(X)g(Y, hZ) + \nu\eta(Y)g(\phi hX, Z) - \nu\eta(X)g(Y, \phi hZ). \end{aligned}$$

Here, one can easily see

$$\begin{aligned} \tilde{R}(\xi, Z)X &= \kappa[g(X, Z)\xi - \eta(X)Z] + \mu[g(hX, Z)\xi - \eta(X)hZ] \\ &+ \nu[g(\phi hX, Z)\xi - \eta(X)\phi hZ]. \end{aligned}$$

This completes the proof of (7).

Almost α -cosymplectic manifolds are special classes of almost α -cosymplectic f -manifolds, for the proof of (8), one can see [10]. So we do not need to give the proof here.

Taking $Y = \xi$ in (8), we observe

$$(18) \quad (\tilde{\nabla}_X \phi)\xi = -\phi\tilde{\nabla}_X \xi = -\alpha\phi X - hX.$$

Applying ϕ to (18) and after the necessary revisions are made, we can verify (9). Thus, the proof is completed. \square

Now, let M be an immersed submanifold of an almost α -cosymplectic (κ, μ, ν) -space \tilde{M}^{2n+1} . By $\Gamma(TM)$ and $\Gamma(T^\perp M)$, we denote the tangent and normal subspaces of M in \tilde{M} . Then, the Gauss and Weingarten formulae are, respectively, given by

$$(19) \quad \tilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y),$$

and

$$(20) \quad \tilde{\nabla}_X V = -A_V X + \nabla_X^\perp V,$$

for all $X, Y \in \Gamma(TM)$ and $V \in \Gamma(T^\perp M)$, where ∇ and ∇^\perp are the induced connections on M and $\Gamma(T^\perp M)$ and σ and A are called the second fundamental form and shape operator of M , respectively, $\Gamma(TM)$ denote the set differentiable vector fields on M . They are related by

$$(21) \quad g(A_V X, Y) = g(\sigma(X, Y), V).$$

The covariant derivative of σ is defined by

$$(22) \quad (\tilde{\nabla}_X \sigma)(Y, Z) = \nabla_X^\perp \sigma(Y, Z) - \sigma(\nabla_X Y, Z) - \sigma(Y, \nabla_X Z),$$

for all $X, Y, Z \in \Gamma(TM)$. If $\tilde{\nabla}\sigma = 0$, then the submanifold is called its second fundamental form parallel.

By R , we denote the Riemannian curvature tensor of the submanifold M , we have the following Gauss equation

$$(23) \quad \begin{aligned} \tilde{R}(X, Y)Z &= R(X, Y)Z + A_{\sigma(X, Z)}Y - A_{\sigma(Y, Z)}X + (\tilde{\nabla}_X\sigma)(Y, Z) \\ &- (\tilde{\nabla}_Y\sigma)(X, Z), \end{aligned}$$

for all $X, Y, Z \in \Gamma(TM)$.

For a $(0, k)$ -type tensor field T , $k \geq 1$ and a $(0, 2)$ -type tensor field A on a Riemannian manifold (M, g) , $Q(A, T)$ -tensor field is defined by

$$(24) \quad \begin{aligned} Q(A, T)(X_1, X_2, \dots, X_k; X, Y) &= -T((X \wedge_A Y)X_1, X_2, \dots, X_k) \dots \\ &- T(X_1, X_2, \dots, X_{k-1}, (X \wedge_A Y)X_k), \end{aligned}$$

for all $X_1, X_2, \dots, X_k, X, Y \in \Gamma(TM)$ [9], where

$$(25) \quad (X \wedge_A Y)Z = A(Y, Z)X - A(X, Z)Y.$$

Definition 1.2. A submanifold of a Riemannian manifold (M, g) is said to be pseudoparallel, 2-pseudoparallel, Ricci-generalized pseudoparallel and 2-Ricci-generalized pseudoparallel if

$$\begin{aligned} \tilde{R} \cdot \sigma \text{ and } Q(g, \sigma) \\ \tilde{R} \cdot \tilde{\nabla}\sigma \text{ and } Q(g, \tilde{\nabla}\sigma) \\ \tilde{R} \cdot \sigma \text{ and } Q(S, \sigma) \\ \tilde{R} \cdot \tilde{\nabla}\sigma \text{ and } Q(S, \tilde{\nabla}\sigma) \end{aligned}$$

are linearly dependent, respectively[11].

Equivalently, these cases can be explained by the following way;

$$(26) \quad \tilde{R} \cdot \sigma = L_1 Q(g, \sigma),$$

$$(27) \quad \tilde{R} \cdot \tilde{\nabla}\sigma = L_2 Q(g, \tilde{\nabla}\sigma),$$

$$(28) \quad \tilde{R} \cdot \sigma = L_3 Q(S, \sigma),$$

$$(29) \quad \tilde{R} \cdot \tilde{\nabla}\sigma = L_4 Q(S, \tilde{\nabla}\sigma),$$

where the functions L_1, L_2, L_3 and L_4 are, respectively, defined on $M_1 = \{x \in M : \sigma(x) \neq g(x)\}$, $M_2 = \{x \in M : \tilde{\nabla}\sigma(x) \neq g(x)\}$, $M_3 = \{x \in M : S(x) \neq \sigma(x)\}$ and $M_4 = \{x \in M : S(x) \neq \tilde{\nabla}\sigma(x)\}$ and S denotes the Ricci tensor of M .

Particularly, if $L_1 = 0$ (resp. $L_2 = 0$), the submanifold is said to be semi-parallel (resp. 2-semiparallel)[1].

2. Invariant Submanifolds of an almost α -cosymplectic (κ, μ, ν) Space

Now, let $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$ be an almost α -cosymplectic (κ, μ, ν) -space and M an immersed submanifold of \widetilde{M}^{2n+1} . If $\phi(T_x M) \subseteq T_x M$, for each point $x \in M$, then M is said to be an invariant submanifold of $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$ with respect to ϕ . Hence, we will easily see that an invariant submanifold with respect to ϕ is also invariant with respect to h .

Proposition 2.1. *Let M be an invariant submanifold of an almost α -cosymplectic (κ, μ, ν) -space $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$ such that ξ tangent to M . Then, the following equalities hold on M ;*

$$(30) \quad \begin{aligned} R(X, Y)\xi &= \kappa[\eta(Y)X - \eta(X)Y] + \mu[\eta(Y)hX - \eta(X)hY] \\ &+ \nu[\eta(Y)\phi hX - \eta(X)\phi hY] \end{aligned}$$

$$(31) \quad (\nabla_X \phi)Y = g(\alpha\phi X + hX, Y)\xi - \eta(Y)(\alpha\phi X + hX)$$

$$(32) \quad \nabla_X \xi = -\alpha\phi^2 X - \phi hX$$

$$(33) \quad \phi\sigma(X, Y) = \sigma(\phi X, Y) = \sigma(X, \phi Y), \quad \sigma(X, \xi) = 0,$$

where ∇ , σ and R denote the induced Levi-Civita connection, the shape operator and Riemannian curvature tensor of M , respectively.

Proof. Since M is an invariant submanifold, from (9) and (19), we have

$$\sigma(X, \xi) = 0, \quad \text{and} \quad A_V \xi = 0,$$

for all $X \in \Gamma(TM)$ and $V \in \Gamma(T^\perp M)$. Also by using (23), we obtain (30).

On the other hand, tangent and normal components of expanding

$$\begin{aligned} (\widetilde{\nabla}_X \phi)Y &= \widetilde{\nabla}_X Y - \phi \widetilde{\nabla}_X Y \\ &= \nabla_X \phi Y + \sigma(X, \phi Y) - \phi \nabla_X Y - \phi \sigma(X, Y) \\ &= (\nabla_X \phi)Y + \sigma(X, \phi Y) - \phi \sigma(X, Y) \end{aligned}$$

give us to (31) and (33), respectively.

Finally, the Gauss formulae and (9), we have

$$\widetilde{\nabla}_X \xi = \nabla_X \xi + \sigma(\xi, X) = -\alpha\phi^2 X - \phi hX,$$

for all $X \in \Gamma(TM)$. Also tangent components of this give (32).

Furthermore, by using (7), (23) and the last term of (33), we get (30). □

In the rest of this paper, we will assume that M is an invariant submanifold of an α -cosymplectic (κ, μ, ν) -space $\widetilde{M}^{2n+1}(\phi, \xi, \eta, g)$. In this case, from (4), we have

$$(34) \quad \phi hX = -h\phi X,$$

for all $X \in \Gamma(TM)$, that is, M is also invariant with respect to the tensor field h .

We need the following theorem to guarantee for the second fundamental form σ is not always identically zero.

Theorem 2.2. *Let M be an invariant submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, the second fundamental form σ of M is parallel M is totally geodesic provided $\kappa \neq 0$.*

Proof. Let us suppose that σ is parallel. From (22), we have

$$(35) \quad (\tilde{\nabla}_X \sigma)(Y, Z) = \nabla_X^\perp \sigma(Y, Z) - \sigma(\nabla_X Y, Z) - \sigma(Y, \nabla_X Z) = 0,$$

for all vector fields X, Y and Z on M^{2n+1} . Setting $Z = \xi$ in (35) and taking into account (32) and (33), we have

$$\sigma(\nabla_X \xi, Y) = -\sigma(\alpha\phi^2 X + \phi hX, Y) = 0,$$

that is,

$$(36) \quad -\alpha\sigma(X, Y) + \phi\sigma(hX, Y) = 0.$$

Writing hX of X in (36) and by using (6) and (33), we obtain

$$(37) \quad \begin{aligned} -\alpha\sigma(hX, Y) + \phi\sigma(h^2 X, Y) &= 0, \\ \alpha\sigma(hX, Y) + (\alpha^2 + \kappa)\phi\sigma(X, Y) &= 0. \end{aligned}$$

From (36) and (37), we conclude that $\kappa\sigma(X, Y) = 0$, which proves our assertion. \square

Theorem 2.3. *Let M be an invariant pseudoparallel submanifold of an almost α cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, M is either totally geodesic submanifold or the function L_1 satisfies $L_1 = \kappa \mp \sqrt{(\nu^2 - \mu^2)(\kappa + \alpha^2)}$, $\mu\nu(\kappa + \alpha^2) = 0$.*

Proof. We suppose that M is an invariant pseudoparallel submanifold of an almost α -cosymplectic $M^{2n+1}(\phi, \xi, \eta, g)$ -space. Then, there exists a function L_1 on M such that

$$(R(X, Y) \cdot \sigma)(U, V) = L_1 Q(g, \sigma)(U, V; X, Y),$$

for all vector fields X, Y, U, V on M . By means of (24) and (26), we have

$$(38) \quad \begin{aligned} R^\perp(X, Y)\sigma(U, V) &= \sigma(R(X, Y)U, V) - \sigma(U, R(X, Y)V) \\ &= -L_1\{\sigma((X \wedge_g Y)U, V) + \sigma(U, (X \wedge_g Y)V)\}. \end{aligned}$$

Here taking $Y = U = \xi$ in (38) and taking into account of Proposition 2.1, we obtain

$$\begin{aligned} R^\perp(X, \xi)\sigma(\xi, V) &= \sigma(R(X, \xi)\xi, V) - \sigma(\xi, R(X, \xi)V) \\ &= -L_1\{\sigma((X \wedge_g \xi)\xi, V) + \sigma(\xi, (X \wedge_g \xi)V)\} \\ &= -L_1\{\sigma(X - \eta(X)\xi, V) + \sigma(\xi, \eta(V)X - g(X, V)\xi)\}, \end{aligned}$$

that is,

$$(39) \quad \sigma(R(X, \xi)\xi, V) = L_1\sigma(X, V).$$

By means of Proposition 2.1 and (5), we conclude that

$$(40) \quad (L_1 - \kappa)\sigma(X, V) = \mu\sigma(hX, V) + \nu\sigma(\phi hX, V).$$

If hX is substituted for X at (40) and making use of (6) and (33), we obtain

$$(41) \quad (L - \kappa)\sigma(hX, V) = -(\kappa + \alpha^2)[\mu\sigma(X, V) + \nu\phi\sigma(X, V)].$$

From (40) and (41), we reach at

$$[(L_1 - \kappa)^2 + (\kappa + \alpha^2)(\mu^2 - \nu^2)]\sigma(X, V) = -2\mu\nu(\kappa + \alpha^2)\phi\sigma(X, V).$$

This yields to

$$(L_1 - \kappa)^2 + (\kappa + \alpha^2)(\mu^2 - \nu^2) = 0, \quad \mu\nu(\kappa + \alpha^2) = 0 \quad \text{or} \quad \sigma = 0.$$

This completes the proof. □

From the Theorem 2.3, we have the following corollary.

Corollary 2.4. *Let M be an invariant submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, M is semiparallel if and only if M is totally geodesic.*

Theorem 2.5. *Let M be an invariant submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. If M is a 2-pseudoparallel submanifold, then M is either totally geodesic or the functions α, κ, μ, ν and L_2 satisfy $L_2 = \kappa \mp \sqrt{(\kappa + \alpha^2)(\nu^2 - \nu^2)}$ and $\mu\nu(\kappa + \alpha^2) = 0$.*

Proof. Let us suppose that M is a 2-pseudoparallel submanifold of (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, by means of (27), there exists a function L_2 such that

$$(\tilde{R}(X, Y) \cdot \tilde{\nabla}\sigma)(U, V, Z) = L_2Q(g, \tilde{\nabla}\sigma)(U, V, Z; X, Y),$$

for all vector fields X, Y, Z, U, V on M . This implies that

$$(42) \quad \begin{aligned} R^\perp(X, Y)(\nabla_U\sigma)(V, Z) &= (\tilde{\nabla}_{R(X, Y)U}\sigma)(V, Z) - (\tilde{\nabla}_U\sigma)(R(X, Y)V, Z) \\ &= (\tilde{\nabla}_U\sigma)(V, R(X, Y)Z) = -L_2\{(\tilde{\nabla}_{(X \wedge_g Y)U}\sigma)(V, Z) \\ &+ (\tilde{\nabla}_U\sigma)((X \wedge_g Y)V, Z) \\ &+ (\tilde{\nabla}_U\sigma)(V, (X \wedge_g Y)Z)\}. \end{aligned}$$

Taking $X = Z = \xi$ in (42), we can infer

$$(43) \quad \begin{aligned} R^\perp(\xi, Y)(\tilde{\nabla}_U\sigma)(V, \xi) &= (\tilde{\nabla}_{R(\xi, Y)U}\sigma)(V, \xi) - (\nabla_U\sigma)(R(\xi, Y)V, \xi) \\ &= (\tilde{\nabla}_U\sigma)(V, R(\xi, Y)\xi) = -L_2\{(\tilde{\nabla}_{(\xi \wedge_g Y)U}\sigma)(V, \xi) \\ &+ (\tilde{\nabla}_U\sigma)((\xi \wedge_g Y)V, \xi) \\ &+ (\tilde{\nabla}_U\sigma)(V, (\xi \wedge_g Y)\xi)\}. \end{aligned}$$

Next, we will calculate each of these statements, respectively. Taking into account of (22), (32) and (33), we obtain

$$\begin{aligned}
 R^\perp(\xi, Y)(\widetilde{\nabla}_U\sigma)(V, \xi) &= R^\perp(\xi, Y)\{\nabla_U^\perp\sigma(V, \xi) - \sigma(\nabla_U V, \xi) - \sigma(\nabla_U \xi, V)\} \\
 &= -R^\perp(\xi, Y)\sigma(\nabla_U \xi, V) \\
 &= -R^\perp(\xi, Y)\sigma(-\alpha\phi^2 U - \phi h U, V) \\
 (44) \qquad &= -\alpha R^\perp(\xi, Y)\sigma(U, V) + R^\perp(\xi, Y)\phi\sigma(hU, V).
 \end{aligned}$$

On the other hand, from (5), (23) and (33), by a direct calculation, we can infer

$$\begin{aligned}
 R(\xi, X)Y &= \kappa[g(Y, X)\xi - \eta(Y)X] + \mu[g(hY, X)\xi - \eta(Y)hX] \\
 (45) \qquad &+ \nu[g(X, \phi h Y)\xi - \eta(Y)\phi h X].
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 (\widetilde{\nabla}_{R(\xi, Y)U}\sigma)(V, \xi) &= \nabla_{R(\xi, Y)U}^\perp\sigma(V, \xi) - \sigma(\nabla_{R(\xi, Y)U} V, \xi) - \sigma(\nabla_{R(\xi, Y)U} \xi, V) \\
 &= -\sigma(\nabla_{R(\xi, Y)U} \xi, V) \\
 &= \sigma(\alpha\phi^2 R(\xi, Y)U + \phi h R(\xi, Y)U, V) \\
 &= -\alpha\sigma(R(\xi, Y)U, V) + \sigma(\phi h R(\xi, Y)U, V) \\
 &= -\alpha\sigma(-\kappa\eta(U)Y - \mu\eta(U)hY - \nu\eta(U)\phi h Y, V) \\
 &+ \sigma(-\kappa\eta(U)\phi h Y - \mu\eta(U)\phi h^2 Y - \nu\eta(U)\phi h \phi h Y, V) \\
 &= \alpha\kappa\eta(U)\sigma(V, Y) + \alpha\mu\eta(U)\sigma(hY, V) \\
 &+ \alpha\nu\eta(U)\sigma(\phi h Y, V) - \kappa\eta(U)\sigma(\phi h Y, V) \\
 (46) \qquad &+ \mu(\kappa + \alpha^2)\eta(U)\sigma(\phi Y, V) + \nu(\kappa + \alpha^2)\sigma(V, Y).
 \end{aligned}$$

Furthermore, by using (32) and (45), we have

$$\begin{aligned}
 (\widetilde{\nabla}_U\sigma)(R(\xi, Y)V, \xi) &= \nabla_U^\perp\sigma(R(\xi, Y)V, \xi) - \sigma(\nabla_U R(\xi, Y)V, \xi) \\
 &- \sigma(\nabla_U \xi, R(\xi, Y)V) \\
 &= -\sigma(\nabla_U \xi, R(\xi, Y)V) = \sigma(\alpha\phi^2 U + \phi h U, R(\xi, Y)V) \\
 &= \alpha\sigma(\phi^2 U, R(\xi, Y)V) + \sigma(\phi h U, R(\xi, Y)V) \\
 &= -\alpha\sigma(U, -\kappa\eta(V)Y - \mu\eta(V)hY - \nu\eta(V)\phi h Y) \\
 &+ \sigma(\phi h U, -\kappa\eta(V)Y - \mu\eta(V)hY - \nu\eta(V)\phi h Y) \\
 &= \kappa\alpha\eta(V)\sigma(U, Y) + \mu\alpha\eta(V)\sigma(hY, U) \\
 &+ \alpha\nu\eta(V)\sigma(U, \phi h Y) - \kappa\eta(V)\sigma(\phi h U, Y) \\
 &- \mu\eta(V)\sigma(\phi h U, hY) + \nu\eta(V)\sigma(hU, hY) \\
 &= \kappa\alpha\eta(V)\sigma(U, Y) + \mu\alpha\eta(V)\sigma(hY, U) \\
 &+ \alpha\nu\eta(V)\sigma(U, \phi h Y) - \kappa\eta(V)\sigma(\phi h U, Y) \\
 &+ \mu(\kappa + \alpha^2)\eta(V)\sigma(\phi U, Y) \\
 (47) \qquad &- \nu(\kappa + \alpha^2)\eta(V)\sigma(U, Y).
 \end{aligned}$$

The fourth term gives us

$$(48) \quad \begin{aligned} & (\nabla_U \sigma)(V, R(\xi, Y)\xi) \\ &= (\nabla_U \sigma)(V, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu \phi hY). \end{aligned}$$

On the other hand, by the view of (25), (32) and (33), we obtain

$$(49) \quad \begin{aligned} (\tilde{\nabla}_{(\xi \wedge_g Y)U} \sigma)(V, \xi) &= \nabla_{(\xi \wedge_g Y)U}^\perp \sigma(V, \xi) - \sigma(\nabla_{(\xi \wedge_g Y)U} V, \xi) \\ &- \sigma(V, \nabla_{(\xi \wedge_g Y)U} \xi) \\ &= \sigma(V, \alpha \phi^2 (\xi \wedge_g Y)U + \phi h (\xi \wedge_g Y)U) \\ &= -\alpha \sigma(V, (\xi \wedge_g Y)U) + \sigma(V, (\xi \wedge_g Y)U) \\ &= \alpha \eta(U) \sigma(Y, V) - \eta(U) \sigma(\phi h Y, V), \end{aligned}$$

and

$$(50) \quad \begin{aligned} (\tilde{\nabla}_U \sigma)((\xi \wedge_g Y)V, \xi) &= \nabla_U^\perp \sigma((\xi \wedge_g Y)V, \xi) - \sigma(\nabla_U (\xi \wedge_g Y)V, \xi) \\ &- \sigma((\xi \wedge_g Y)V, \nabla_U \xi) \\ &= \sigma(\alpha \phi^2 U + \phi h U, g(Y, V)\xi - \eta(V)Y) \\ &= \alpha \eta(V) \sigma(Y, U) - \eta(V) \sigma(Y, \phi h U). \end{aligned}$$

Finally,

$$(51) \quad \begin{aligned} (\tilde{\nabla}_U \sigma)(V, \eta(Y)\xi - Y) &= -(\tilde{\nabla}_U \sigma)(V, Y) + (\tilde{\nabla}_U \sigma)(V, \eta(Y)\xi) \\ &= -(\tilde{\nabla}_U \sigma)(V, Y) + \nabla_U^\perp \sigma(V, \eta(Y)\xi) \\ &- \sigma(\nabla_U V, \eta(Y)\xi) - \sigma(V, \nabla_U \eta(Y)\xi) \\ &= -(\tilde{\nabla}_U \sigma)(V, Y) - \sigma(V, U[\eta(Y)]\xi + \eta(Y)\nabla_U \xi) \\ &= -(\tilde{\nabla}_U \sigma)(V, Y) + \eta(V) \sigma(\alpha \phi^2 U + \phi h U, V) \\ &= -(\tilde{\nabla}_U \sigma)(V, Y) - \alpha \eta(Y) \sigma(U, V) \\ &+ \eta(Y) \sigma(\phi h U, V). \end{aligned}$$

Substituting (44), (46), (47), (48), (49), (50) and (51) into (43), we reach at

$$\begin{aligned} & -\alpha R^\perp(\xi, Y) \sigma(U, V) + R^\perp(\xi, Y) \phi \sigma(U, V) - \kappa \alpha \eta(U) \sigma(V, Y) \\ & - \mu \alpha \eta(U) \sigma(V, hY) - \nu \alpha \eta(U) \sigma(V, \phi h Y) + \kappa \eta(U) \sigma(V, \phi h Y) \\ & - \mu(\kappa + \alpha^2) \eta(U) \sigma(\phi Y, V) - \nu(\kappa + \alpha^2) \eta(U) \sigma(V, Y) - \kappa \alpha \eta(V) \sigma(U, Y) \\ & - \alpha \mu \eta(V) \sigma(hY, U) - \alpha \nu \eta(V) \sigma(U, \phi h Y) + \kappa \eta(V) \sigma(\phi h U, Y) \\ & - \mu(\kappa + \alpha^2) \eta(V) \sigma(\phi U, Y) + \nu(\kappa + \alpha^2) \eta(V) \sigma(U, Y) \\ & - (\nabla_U \sigma)(V, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu \phi hY) = -L_2 \{ \alpha \eta(U) \sigma(V, Y) \\ & - \eta(U) \sigma(\phi h Y, V) + \alpha \eta(V) \sigma(Y, U) - \eta(V) \sigma(Y, \phi h U) \\ & - (\nabla_U \sigma)(V, Y) - \alpha \eta(Y) \sigma(U, V) + \eta(Y) \sigma(\phi h U, V) \}. \end{aligned}$$

Here, taking $V = \xi$ in the last equality and using (33), we conclude that

$$\begin{aligned}
 L_2\{\alpha\sigma(U, Y) &- \sigma(Y, \phi hU) - (\tilde{\nabla}_U\sigma)(Y, \xi)\} = \kappa\alpha\sigma(U, Y) + \alpha\mu\sigma(U, hY) \\
 &+ \alpha\nu\sigma(U, \phi hY) - \kappa\alpha\sigma(\phi hY, U) + \mu(\kappa + \alpha^2)\sigma(\phi U, Y) \\
 &- \nu(\kappa + \alpha^2)\sigma(U, Y) \\
 (52) \quad &+ (\tilde{\nabla}_U\sigma)(\xi, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY),
 \end{aligned}$$

where

$$\begin{aligned}
 (\tilde{\nabla}_U\sigma)(Y, \xi) &= -\sigma(\nabla_U\xi, Y) = \sigma(\alpha\phi^2U + \phi hU, Y) \\
 (53) \quad &= -\alpha\sigma(U, Y) + \phi\sigma(hU, Y)
 \end{aligned}$$

and

$$\begin{aligned}
 &(\tilde{\nabla}_U\sigma)(\xi, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
 &= -\sigma(\nabla_U\xi, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
 &= \sigma(\alpha\phi^2U + \phi hU, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
 &= -\alpha\sigma(U, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
 &+ \sigma(\phi hU, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
 &= \kappa\alpha\sigma(U, Y) + \alpha\mu\sigma(hY, U) + \alpha\nu\sigma(\phi hY, U) \\
 (54) \quad &- \kappa\sigma(\phi hU, Y) + \mu(\kappa + \alpha^2)\sigma(\phi U, Y) - \nu(\kappa + \alpha^2)\sigma(U, Y).
 \end{aligned}$$

Substituting (53) and (54) into (52), we get

$$\begin{aligned}
 &[\alpha L_2 - \kappa\alpha + \nu(\kappa + \alpha^2)]\sigma(U, Y) + [\kappa - L_2 - \alpha\nu]\phi\sigma(hU, Y) \\
 (55) \quad &- \mu(\kappa + \alpha^2)\phi\sigma(U, Y) - \alpha\mu\sigma(hU, Y) = 0.
 \end{aligned}$$

If hU is written instead of U in (55) and using (6), (9) and (33), we have

$$\begin{aligned}
 &[\alpha L_2 - \kappa\alpha + \nu(\kappa + \alpha^2)]\sigma(hU, Y) - (\kappa + \alpha^2)[\kappa - L_2 - \alpha\nu]\phi\sigma(U, Y) \\
 (56) \quad &- \mu(\kappa + \alpha^2)\phi\sigma(hU, Y) + \alpha\mu(\kappa + \alpha^2)\sigma(U, Y) = 0.
 \end{aligned}$$

From (55) and (56), for $\kappa \neq 0$, we obtain

$$[L_2 - \kappa]^2 - (\kappa + \alpha^2)(\nu^2 - \mu^2)]\sigma(U, Y) + 2\mu\nu(\kappa + \alpha^2)\phi\sigma(U, Y) = 0.$$

Since the vectors $\phi\sigma(U, Y)$ and $\sigma(U, Y)$ are orthogonal, we conclude that M is a totally geodesic or

$$\mu\nu(\kappa + \alpha^2) = 0,$$

and

$$L_2 = \kappa \mp \sqrt{(\kappa + \alpha^2)(\nu^2 - \mu^2)}.$$

Thus, the proof is completed. \square

From Theorem 2.5, we have the following corollary.

Corollary 2.6. *Let M be an invariant submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, M is 2-semiparallel if and only if M is totally geodesic.*

Theorem 2.7. *Let M be an invariant Ricci-generalized pseudoparallel submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, M is either totally geodesic submanifold or the functions L_3, κ, μ, ν and α satisfy the condition*

$$L_3 = \frac{1}{2n} \left(1 \mp \frac{1}{\kappa} \sqrt{(\kappa + \alpha^2)(\nu^2 - \mu^2)} \right), \quad \mu\nu(\kappa + \alpha^2) = 0.$$

Proof. We suppose that M is an invariant Ricci-generalized pseudoparallel. Then there exists a function L_3 on M such that

$$(\tilde{R}(X, Y) \cdot \sigma)(U, V) = L_3 Q(S, \sigma)(U, V; X, Y),$$

for all vector fields X, Y, U, V on M . This implies that

$$\begin{aligned} R^\perp(X, Y)\sigma(U, V) &= \sigma(R(X, Y)U, V) - \sigma(U, R(X, Y)V) \\ &= -L_3\{\sigma((X \wedge_S Y)U, V) + \sigma(U, (X \wedge_S Y)V)\} \\ &= -L_3\{\sigma(X, V)S(U, Y) - \sigma(Y, V)S(X, U) \\ &+ \sigma(U, X)S(Y, V) - \sigma(U, Y)S(X, V)\}. \end{aligned} \tag{57}$$

By a direct calculation, we obtain

$$S(X, \xi) = 2n\kappa\eta(X). \tag{58}$$

Taking $U = \xi$ in (57) and by view means of (5), (33) and (58), we have

$$\sigma(R(X, Y)\xi, V) = 2n\kappa L_2\{\sigma(X, V) - \sigma(Y, V)\},$$

that is,

$$\begin{aligned} 2n\kappa L_2\{\sigma(X, V) - \sigma(Y, V)\} &= \sigma(\kappa[\eta(Y)X - \eta(X)Y] + \mu[\eta(Y)hX \\ &- \eta(X)hY] + \nu[\eta(Y)\phi hX - \eta(X)\phi hY], V). \end{aligned}$$

This yields to

$$\kappa(2nL_3 - 1)\sigma(X, V) = \mu\sigma(hX, V) + \nu\phi\sigma(hX, V). \tag{59}$$

If hX is written instead of X and using (6) and (33), we get

$$\kappa(2nL_3 - 1)\sigma(hX, V) = -(\kappa + \alpha^2)\{\mu\sigma(X, V) - \nu\phi\sigma(X, V)\}. \tag{60}$$

From (59) and (60), we can derive

$$\begin{aligned} \{\kappa^2(2nL_3 - 1)^2 + (\kappa + \alpha^2)(\mu^2 - \nu^2)\}\sigma(X, V) \\ = -2\mu\nu(\kappa + \alpha^2)\phi\sigma(X, V). \end{aligned}$$

Since σ and $\phi\sigma$ are orthogonal vectors, it follows that

$$\kappa^2(2nL_3 - 1)^2 + (\kappa + \alpha^2)(\mu^2 - \nu^2) = 0, \quad \mu\nu(\kappa + \alpha^2) = 0,$$

which proves our assertions. □

Theorem 2.8. *Let M be an invariant 2-Ricci-generalized pseudoparallel submanifold of an almost α -cosymplectic (κ, μ, ν) -space $M^{2n+1}(\phi, \xi, \eta, g)$. Then, M is either totally geodesic submanifold or the function L_4 satisfies*

$$L_4 = \frac{1}{2n} \left(1 \mp \frac{1}{\kappa} \sqrt{(\kappa + \alpha^2)(\nu^2 - \mu^2)} \right) \quad \text{and} \quad \mu\nu(\kappa + \alpha^2) = 0.$$

Proof. Given M is an invariant 2-Ricci-generalized pseudoparallel submanifold, we have

$$(\tilde{R}(X, Y) \cdot \tilde{\nabla}\sigma)(U, V, W) = L_4 Q(S, \tilde{\nabla}\sigma)(U, V, W; X, Y)$$

for all vector fields X, Y, U, V, W on M . That means

$$\begin{aligned} R^\perp(X, Y)(\tilde{\nabla}_U\sigma)(V, W) &= (\tilde{\nabla}_{R(X, Y)U}\sigma)(V, W) - (\tilde{\nabla}_U\sigma)(R(X, Y)V, W) \\ &= (\tilde{\nabla}_U\sigma)(V, R(X, Y)W) = -L_4\{(\tilde{\nabla}_{(X \wedge_S Y)U}\sigma)(V, W) \\ &+ (\tilde{\nabla}_U\sigma)((X \wedge_S Y)V, W) \\ (61) \quad &+ (\tilde{\nabla}_U\sigma)(V, (X \wedge_S Y)W)\}. \end{aligned}$$

Taking $X = V = \xi$ in (61), we obtain

$$\begin{aligned} R^\perp(\xi, Y)(\tilde{\nabla}_U\sigma)(\xi, W) &= (\tilde{\nabla}_{R(\xi, Y)U}\sigma)(\xi, W) - (\tilde{\nabla}_U\sigma)(R(\xi, Y)\xi, W) \\ &= (\tilde{\nabla}_U\sigma)(\xi, R(\xi, Y)W) = -L_4\{(\tilde{\nabla}_{(\xi \wedge_S Y)U}\sigma)(\xi, W) \\ &+ (\tilde{\nabla}_U\sigma)(\xi \wedge_S Y, W) \\ (62) \quad &+ (\tilde{\nabla}_U\sigma)(\xi, (\xi \wedge_S Y)W)\}. \end{aligned}$$

Now, let us calculate each of these terms separately. First,

$$\begin{aligned} R^\perp(\xi, Y)\{-\sigma(\nabla_U\xi, W)\} &= R^\perp(\xi, Y)\sigma(\alpha\phi^2U + \phi hU, W) \\ &= -\alpha R^\perp(\xi, Y)\sigma(U, W) \\ (63) \quad &+ R^\perp(\xi, Y)\sigma(\phi hU, W). \end{aligned}$$

Making use of (6), (32) and (45), we can calculate the second term as

$$\begin{aligned} (\tilde{\nabla}_{R(\xi, Y)U}\sigma)(W, \xi) &= -\sigma(\nabla_{R(\xi, Y)U}\xi, W) = \alpha\sigma(\phi^2R(\xi, Y)U, W) \\ &+ \sigma(\phi h\nabla_{R(\xi, Y)U}\xi, W) \\ &= \alpha\kappa\eta(U)\sigma(Y, W) + \alpha\mu\eta(U)\sigma(hY, W) \\ &+ \alpha\nu\eta(U)\sigma(\phi hY, W) \\ &- \kappa\eta(U)\sigma(\phi hY, W) + \mu(\kappa + \alpha^2)\eta(U)\sigma(\phi Y, W) \\ &- \nu\eta(U)\sigma(\phi h\phi hY, W) \\ &= \alpha\kappa\eta(U)\sigma(Y, W) + \alpha\mu\eta(U)\sigma(hY, W) \\ &+ \alpha\nu\eta(U)\sigma(\phi hY, W) \\ &- \kappa\eta(U)\sigma(\phi hY, W) + \mu\eta(U)(\kappa + \alpha^2)\sigma(\phi Y, W) \\ (64) \quad &- \nu(\kappa + \alpha^2)\eta(U)\sigma(Y, W), \end{aligned}$$

In view of (9) and (22), we observe

$$(65) \quad \begin{aligned} & (\tilde{\nabla}_U \sigma)(R(\xi, Y)\xi, W) \\ &= (\tilde{\nabla}_U \sigma)(\kappa[\eta(Y)\xi - Y] - \mu hY - \nu \phi hY, W). \end{aligned}$$

In the same way,

$$(66) \quad \begin{aligned} (\tilde{\nabla}_U \sigma)(R(\xi, Y)W, \xi) &= -\sigma(\nabla_U \xi, R(\xi, Y)W) = \sigma(\alpha\phi^2 U + \phi hU, R(\xi, Y)W) \\ &= \alpha\kappa\eta(W)\sigma(U, Y) + \alpha\mu\eta(W)\sigma(hY, W) \\ &+ \alpha\nu\eta(W)\sigma(U, \phi hY) - \kappa\eta(W)\sigma(\phi hU, Y) \\ &- \mu\eta(W)\sigma(\phi h^2 U, Y) + \nu\eta(W)\sigma(h^2 U, Y) \\ &= \alpha\kappa\eta(W)\sigma(U, Y) + \alpha\mu\eta(W)\sigma(hY, W) \\ &+ \alpha\nu\eta(W)\sigma(U, \phi hY) - \kappa\eta(W)\sigma(\phi hU, Y) \\ &+ \mu(\kappa + \alpha^2)\eta(W)\sigma(\phi U, Y) \\ &+ \nu(\kappa + \alpha^2)\eta(W)\sigma(U, Y), \end{aligned}$$

$$(67) \quad \begin{aligned} (\tilde{\nabla}_{(\xi \wedge_S Y)U} \sigma)(\xi, W) &= -\sigma(\nabla_{(\xi \wedge_S Y)U} \xi, W) \\ &= \sigma(\alpha\phi^2 (\xi \wedge_S Y)U + \phi h(\xi \wedge_S Y)U, W) \\ &= -\alpha\sigma(S(Y, U)\xi - S(\xi, U)Y, W) \\ &+ \sigma(\phi h[S(Y, U)\xi - S(\xi, U)Y], W) \\ &= 2n\kappa\eta(U)\{\alpha\sigma(Y, W) - \sigma(\phi hY, W)\}, \end{aligned}$$

$$(68) \quad \begin{aligned} (\tilde{\nabla}_U \sigma)((\xi \wedge_S Y)\xi, W) &= -\sigma(\nabla_U (\xi \wedge_S Y)\xi, W) \\ &= (\tilde{\nabla}_U \sigma)(S(\xi, Y)\xi - S(\xi, \xi)Y, W) \\ &= 2n\{(\nabla_U \sigma)(\kappa\eta(Y)\xi, W) - (\nabla_U \sigma)(\kappa Y, W)\} \\ &= 2n\{-\sigma(U[\kappa\eta(Y)]\xi + \kappa\eta(Y)\nabla_U \xi, W) \\ &- (\nabla_U \sigma)(\kappa Y, W)\} \\ &= 2n\{-\kappa\alpha\eta(Y)\sigma(U, W) + \kappa\eta(Y)\sigma(\phi hU, W) \\ &- (\nabla_U \sigma)(\kappa Y, W)\}. \end{aligned}$$

Finally,

$$(69) \quad \begin{aligned} (\tilde{\nabla}_U \sigma)(\xi, (\xi \wedge_S Y)W) &= -\sigma(\nabla_U \xi, (\xi \wedge_S Y)W) \\ &= \sigma(\alpha\phi^2 U + \phi hU, S(Y, W)\xi - S(\xi, W)Y) \\ &= 2n\kappa\alpha\eta(W)\sigma(U, Y) \\ &- 2n\kappa\eta(W)\sigma(\phi hU, Y). \end{aligned}$$

Consequently, substituting (63), (64), (65), (66), (67), (68) and (69) into (62), we reach at

$$\begin{aligned}
& - \alpha R^\perp(\xi, Y)\sigma(U, W) + R^\perp(\xi, Y)\sigma(\phi hU, W) - \alpha\kappa\eta(U)\sigma(Y, W) \\
& - \alpha\mu\eta(U)\sigma(hY, W) - \alpha\nu\eta(U)\sigma(\phi hY, W) + \kappa\eta(U)\sigma(\phi hY, W) \\
& - \mu\eta(U)(\kappa + \alpha^2)\sigma(\phi Y, W) + \nu(\kappa + \alpha^2)\eta(U)\sigma(Y, W) \\
& - (\nabla_U\sigma)(\kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY, W) - \alpha\kappa\eta(W)\sigma(U, Y) \\
& - \alpha\mu\eta(W)\sigma(hY, W) - \alpha\nu\eta(W)\sigma(U, \phi hY) + \kappa\eta(W)\sigma(\phi hU, Y) \\
& - \mu(\kappa + \alpha^2)\eta(W)\sigma(\phi U, Y) + \nu(\kappa + \alpha^2)\eta(W)\sigma(U, Y) \\
& = -L_4\{2n\kappa\alpha\eta(U)\sigma(Y, W) - 2n\kappa\eta(U)\sigma(\phi hY, W) - 2n\kappa\alpha\eta(Y)\sigma(U, W) \\
& + 2n\kappa\eta(Y)\sigma(\phi hU, W) - 2n(\nabla_U\sigma)(\kappa Y, W) + 2n\alpha\kappa\eta(W)\sigma(U, Y) \\
& - 2n\kappa\eta(W)\sigma(\phi hU, Y)\}.
\end{aligned}$$

In the last equality, putting $W = \xi$, we have

$$\begin{aligned}
2nL_4\{(\nabla_U\sigma)(\kappa Y, \xi) & - \kappa\alpha\sigma(U, Y) + \kappa\sigma(\phi hU, Y)\} = \nu(\kappa + \alpha^2)\sigma(U, Y) \\
& - \alpha\kappa\sigma(U, Y) - \alpha\mu\sigma(hY, U) - \alpha\nu\sigma(\phi hU, Y) \\
& - \mu(\kappa + \alpha^2)\sigma(\phi U, Y) + \kappa\sigma(\phi hU, Y) \\
(70) \quad & - (\nabla_U\sigma)(\kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY, \xi),
\end{aligned}$$

where

$$\begin{aligned}
(\nabla_U\sigma)(\kappa Y, \xi) & = -\sigma(\nabla_U\xi, \kappa Y) = \sigma(\alpha\phi^2U + \phi hU, \kappa Y) \\
(71) \quad & = -\alpha\kappa\sigma(U, Y) + \kappa\sigma(\phi hU, Y),
\end{aligned}$$

and

$$\begin{aligned}
& (\nabla_U\sigma)(\kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY, \xi) \\
& = -\sigma(\nabla_U\xi, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
& = \sigma(\alpha\phi^2U + \phi hU, \kappa[\eta(Y)\xi - Y] - \mu hY - \nu\phi hY) \\
& = \alpha\kappa\sigma(U, Y) + \alpha\mu\sigma(U, hY) + \alpha\nu\sigma(U, \phi hY) \\
(72) \quad & - \kappa\sigma(\phi hU, Y) + \mu(\kappa + \alpha^2)\sigma(\phi U, Y) - \nu(\kappa + \alpha^2)\sigma(U, Y).
\end{aligned}$$

(71) and (72) are put in (70), we conclude that

$$\begin{aligned}
[\kappa\alpha(2nL_4 - 1) & + (\kappa + \alpha^2)(\nu - \mu\phi)]\sigma(U, Y) \\
(73) \quad & - [\kappa(2nL_4 - 1)\phi + \alpha(\nu\phi + \mu)]\sigma(hU, Y) = 0.
\end{aligned}$$

Here hU is written instead of U and taking into account of (6) and (33), we have

$$\begin{aligned}
[\kappa\alpha(2nL_4 - 1) & + (\kappa + \alpha^2)(\nu - \mu\phi)]\sigma(hU, Y) \\
(74) \quad & + [\kappa(2nL_4 - 1)\phi + \alpha(\nu\phi + \mu)](\kappa + \alpha^2)\sigma(U, Y) = 0.
\end{aligned}$$

From (73) and (74), it follows for $\kappa \neq 0$,

$$[\kappa^2(2nL_4 - 1)^2 + (\mu^2 - \nu^2)(\kappa + \alpha^2)]\sigma(U, V) + 2\mu\nu(\kappa + \alpha^2)\phi\sigma(U, V) = 0.$$

This proves our assertion. \square

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