JOURNAL OF THE CHUNGCHEONG MATHEMATICAL SOCIETY Volume **36**, No. 2, May 2023 http://dx.doi.org/10.14403/jcms.2023.36.2.125

# VOLUME PROPERTIES AND A CHARACTERIZATION OF ELLIPTIC PARABOLOIDS

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ABSTRACT. We establish a characterization theorem of elliptic paraboloids in the (n+1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$  with extrinsic properties such as the (n+1)-dimensional volumes of regions enclosed by the hyperplanes and hypersurfaces, and the *n*-dimensional areas of projections of the sections of hypersurfaces cut off by hyperplanes.

### 1. Introduction

Suppose that M is a smooth convex hypersurface in the (n + 1)dimensional Euclidean space  $\mathbb{E}^{n+1}$ . For a fixed point  $p \in M$  and a sufficiently small t > 0, let us denote by  $\Phi$  a hyperplane which intersects M and is parallel to the tangent hyperplane  $\Psi$  of M at p with distance t. We aim to characterize elliptic paraboloids in the (n + 1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$  by using the *n*-dimensional areas of projections of the sections cut off by hyperplanes and the (n + 1)-dimensional volumes of regions enclosed by the hyperplanes and hypersurfaces. In order to do so, we denote by  $A_p(t)$  and  $V_p(t)$  the *n*-dimensional area of the section in  $\Phi$  enclosed by  $\Phi \cap M$  and the (n+1)-dimensional volume of the region bounded by the hypersurface M and the hyperplane  $\Phi$ , respectively.

If M is a smooth convex hypersurface in the (n + 1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function f:  $\mathbb{R}^n \to \mathbb{R}$ , for a fixed point  $p = (x, f(x)) \in M$  and a real number k > 0, we put  $\Phi$  the hyperplane through v = (x, f(x) + k) which is parallel to the tangent hyperplane  $\Psi$  of M at p. We denote by  $A_p^*(k)$ ,  $V_p^*(k)$  and  $D_p^*(k)$  the *n*-dimensional area of the section in  $\Phi$  enclosed by  $\Phi \cap M$ , the (n + 1)-dimensional volume of the region of  $\mathbb{E}^{n+1}$  bounded by M and

Received January 31, 2023; Accepted May 15, 2023.

<sup>2020</sup> Mathematics Subject Classification: 53A07.

Key words and phrases: Elliptic paraboloid; (n + 1)-dimensional volume; *n*-dimensional surface area; Gauss-Kronecker curvature.

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FIGURE 1.  $A_p^*(1)$  and  $V_p^*(1)$  for p = (1, 1) and  $f(x) = x^2$ .



FIGURE 2.  $D_p^*(1)$  for p = (1, 1) and  $f(x) = x^2$ .

the hyperplane  $\Phi$  and the *n*-dimensional area of the projection of the section in  $\Phi$  enclosed by  $\Phi \cap M$  onto  $\mathbb{R}^n$ , respectively. In this case, for a fixed point  $p \in M$  and a sufficiently small t > 0 we may define  $D_p(t)$  as the area of the projection of the section in  $\Phi$  enclosed by  $\Phi \cap M$  onto  $\mathbb{R}^n$ , where  $\Phi$  is the hyperplane which intersects M and is parallel to the tangent hyperplane  $\Psi$  of M at p with distance t. See Figures 1 and 2.

Let us denote  $W(p) = \sqrt{1 + |\nabla f(x)|^2}$ , where  $p = (x, f(x)) \in M$  and  $\nabla f$  is the gradient of f. Then we have

(1.1) 
$$D_p^*(k) = A_p^*(k)/W(p).$$

For details, see Section 2.

For elliptic paraboloids in the (n + 1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$ , the following characterization theorem has been established ([10, 11]).

**Proposition 1.** Let M be a smooth convex hypersurface in the (n+1)dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function  $f : \mathbb{R}^n \to \mathbb{R}$ . Suppose that the Gauss-Kronecker curvature K(p) of M at p with respect to the upward unit normal to M is positive at some point  $p \in M$ . Then M is an elliptic paraboloid if and only if it satisfies one of the following conditions:

 $(V^*)$ :  $V_p^*(k)$  is a positive function, which depends only on k.  $(D^*)$ :  $D_p^*(k)$  in (1.1) is a positive function, which depends only on k.

On the other hand, the following characterization theorem of parabolas was established (Theorem 1 of [21]).

**Proposition 2.** Suppose that f(x) is a differentiable function and for all real numbers a and h with h > 0, l(a, h, x) is the secant line determined by the two points (a, f(a)) and (a + h, f(a + h)) on the graph of f(x), separated horizontally by h units. Then f(x) is a parabola if and only if the signed area

$$A(a,h) = \int_{a}^{a+h} l(a,h,x)dx - \int_{a}^{a+h} f(x)dx$$

between the line l(a, h, x) and the function f(x) over the interval [a, a+h] is a nonzero function of h alone, not dependent on a.

In the convex cases, Proposition 2 can be rewritten as follows:

**Proposition 3.** Suppose that  $f : \mathbb{R} \to \mathbb{R}$  is a convex differentiable function and M is its graph. Then M is a parabola if and only if it satisfies

 $(V^*D): V_p^*(k)$  is a positive function  $\phi(D)$ , which depends only on  $D = D_p^*(k)$ .

Hence, it is quite reasonable to ask whether the above condition  $(V^*D)$  also characterize the elliptic paraboloids in the (n+1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$ .

In this paper, in Section 3 we prove the following characterization theorem of elliptic paraboloids, which is an n-dimensional analogue of Proposition 3.

**Theorem 4.** Let M be a smooth convex hypersurface in the (n + 1)dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function  $f : \mathbb{R}^n \to \mathbb{R}$ . Suppose that the Gauss-Kronecker curvature K(p) of M at p with respect to the upward unit normal to M is positive at some point  $p \in M$ . Then M is an elliptic paraboloid if and only if it satisfies the following condition:

 $(V^*D)$ :  $V_p^*(k)$  is a positive function  $\phi(D)$ , which depends only on  $D = D_p^*(k)$ .

Various properties of conic sections (especially, parabolas) have been proved to be characteristic ones ([1, 2, 4, 7, 8, 12, 14, 15, 17, 19, 21, 24]).

Some characterization theorems for hyperplanes, circular hypercylinders, hyperspheres, ellipsoids, elliptic paraboloids and elliptic hyperboloids in the Euclidean space  $\mathbb{E}^{n+1}$  were established in [3, 4, 6, 9, 10, 11, 13, 18, 22]. For a characterization of hyperbolic space in the Minkowski space  $\mathbb{E}_1^{n+1}$ , we refer to [16].

Throughout this article, all objects are smooth  $(C^2)$  and connected, unless otherwise mentioned.

#### 2. Preliminaries

Suppose that M is a smooth convex hypersurface in the (n + 1)dimensional Euclidean space  $\mathbb{E}^{n+1}$ . For a fixed point  $p \in M$  and a sufficiently small t > 0, we make use of notations:  $A_p(t), V_p(t)$  and  $D_p(t)$ defined in Section 1. We may introduce a coordinate system (x, z) = $(x_1, x_2, \dots, x_n, z)$  of  $\mathbb{E}^{n+1}$  with the origin p, the tangent space of M at pis the hyperplane z = 0. Furthermore, we may assume that M is locally the graph of a non-negative convex function  $f : \mathbb{R}^n \to \mathbb{R}$ .

Then, for a sufficiently small t > 0 we have

$$A_p(t) = \iint_{f(x) < t} 1 dx$$

and

$$V_p(t) = \iint_{f(x) < t} \{t - f(x)\} dx,$$

where  $x = (x_1, x_2, \dots, x_n), dx = dx_1 dx_2 \cdots dx_n$ . Since we also have

$$V_p(t) = \iint_{f(x) < t} \{t - f(x)\} dx$$
$$= \int_{z=0}^t \{\iint_{f(x) < z} 1 dx\} dz,$$

the fundamental theorem of calculus shows that

(2.1) 
$$V'_p(t) = \iint_{f(x) < t} 1 dx = A_p(t).$$

We have the following ([11]).

**Lemma 5.** Suppose that the Gauss-Kronecker curvature K(p) of M at p is positive with respect to the upward unit normal to M. Then we have the following:

(2.2) 
$$\lim_{t \to 0} \frac{1}{(\sqrt{t})^n} A_p(t) = \frac{(\sqrt{2})^n \omega_n}{\sqrt{K(p)}},$$

(2.3) 
$$\lim_{t \to 0} \frac{1}{(\sqrt{t})^{n+2}} V_p(t) = \frac{(\sqrt{2})^{n+2} \omega_n}{(n+2)\sqrt{K(p)}},$$

where  $\omega_n$  denotes the volume of the *n*-dimensional unit ball.

Now, suppose that M is a smooth convex hypersurface in the (n+1)dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function  $f : \mathbb{R}^n \to \mathbb{R}$ . For a fixed point  $p = (x, f(x)) \in M$  and a positive number k, we adopt the following notations:  $A_p^*(k), V_p^*(k), D_p^*(k)$  and  $D_p(t)$  defined in Section 1.

If we denote by  $\theta$  the angle between the tangent hyperplane  $\Psi$  of M at p and  $\mathbb{R}^n$ , then we have

(2.4) 
$$\cos\theta = \frac{1}{W(p)},$$

where we put for the gradient  $\nabla f$  of f

$$W(p) = \sqrt{1 + |\nabla f(x)|^2}.$$

For a positive number t with k = tW(p), we have  $\cos \theta = 1/W(p) = t/k$ . Hence we get

(2.5) 
$$V_p^*(k) = V_p(t), \quad A_p^*(k) = A_p(t) \text{ and } D_p^*(k) = D_p(t).$$

Furthermore, it follows from (2.5) that

(2.6) 
$$D_p^*(k) = A_p^*(k)/W(p),$$

(2.7) 
$$D_p(t) = A_p(t)/W(p).$$

Using k = tW(p), together with (2.5) and (2.6), Lemma 5 implies the following.

**Lemma 6.** Suppose that M is a smooth convex hypersurface in the (n + 1)-dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function  $f : \mathbb{R}^n \to \mathbb{R}$ . For a fixed point  $p = (x, f(x)) \in M$ , we suppose that the Gauss-Kronecker curvature K(p) of M at p with respect to the upward unit normal to M is positive. Then we have the following:

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(2.8) 
$$\lim_{k \to 0} \frac{1}{(\sqrt{k})^n} A_p^*(k) = \frac{(\sqrt{2})^n \omega_n}{\sqrt{K(p)}} \times \frac{1}{(\sqrt{W(p)})^n},$$

(2.9) 
$$\lim_{k \to 0} \frac{1}{(\sqrt{k})^{n+2}} V_p^*(k) = \frac{(\sqrt{2})^{n+2} \omega_n}{(n+2)\sqrt{K(p)}} \times \frac{1}{(\sqrt{W(p)})^{n+2}},$$

(2.10) 
$$\lim_{k \to 0} \frac{1}{(\sqrt{k})^n} D_p^*(k) = \frac{(\sqrt{2})^n \omega_n}{\sqrt{K(p)}} \times \frac{1}{(\sqrt{W(p)})^{n+2}},$$

where  $\omega_n$  denotes the volume of the *n*-dimensional unit ball.

### 3. Proof of Theorem 4

In this section, we give a proof of Theorem 4 stated in Section 1.

Let us denote by M a smooth convex hypersurface in the (n + 1)dimensional Euclidean space  $\mathbb{E}^{n+1}$  defined by the graph of a convex function  $f : \mathbb{R}^n \to \mathbb{R}$ .

First, suppose that the hypersurface M satisfies  $(V^*D)$ . Then  $V_p^*(k)$  is a positive function  $\phi(D)$ , which depends only on  $D = D_p^*(k)$ . Hence we have

(3.1) 
$$\frac{V_p^*(k)}{(\sqrt{k})^{n+2}} = \frac{\phi(D)}{D^{(n+2)/n}} \times \frac{(D_p^*(k))^{(n+2)/n}}{(\sqrt{k})^{n+2}}.$$

It follows from (2.10) in Lemma 6 that (3.2)

$$\lim_{k \to 0} \frac{(D_p^*(k))^{(n+2)/n}}{(\sqrt{k})^{n+2}} = \lim_{k \to 0} \{\frac{D_p^*(k)}{(\sqrt{k})^n}\}^{(n+2)/n} = \frac{(\sqrt{2})^{n+2}\omega_n^{(n+2)/n}}{(\sqrt{K(p)})^{(n+2)/n}} \times \frac{1}{(\sqrt{W(p)})^{(n+2)^2/n}}$$

By the assumption, we have

$$\lim_{D \to 0} \frac{\phi(D)}{D^{(n+2)/n}} = \delta,$$

where  $\delta$  is a constant independent of p. Hence together with (2.9),(3.1), and (3.2) we obtain

$$\frac{(\sqrt{2})^{n+2}\omega_n}{(n+2)\sqrt{K(p)}} \times \frac{1}{(\sqrt{W(p)})^{n+2}} = \delta \times \frac{(\sqrt{2})^{n+2}\omega_n^{(n+2)/n}}{(\sqrt{K(p)})^{(n+2)/n}} \times \frac{1}{(\sqrt{W(p)})^{(n+2)^2/n}}$$

from which we get

(3.3) 
$$K(p) = (n+2)^n \delta^n \omega_n^2 \frac{1}{W(p)^{n+2}}$$

Note that the Gauss-Kronecker curvature K(p) of M at p is given by ([23], p.93)

(3.4) 
$$K(p) = \frac{\det D^2 f(x)}{W(p)^{n+2}}.$$

It follows from (3.3) and (3.4) that the determinant det  $D^2 f(x)$  of the Hessian of the function f is a positive constant. Thus f(x) is a globally defined quadratic polynomial ([5, 20]), and hence M is an elliptic paraboloid. This completes the proof of the if part of Theorem 4.

Conversely, let us consider an elliptic paraboloid defined by

$$M: z = f(x) = \sum_{i=1}^{n} a_i^2 x_i^2, a_i > 0,$$

a tangent hyperplane  $\Psi$  to M at a fixed point  $p = (x, z) \in M$  and a hyperplane  $\Phi$  through v = (x, z + k), k > 0 which is parallel to the tangent hyperplane  $\Psi$  to M at p. Then the proof of Theorem 5 of [11] shows that

(3.5) 
$$V_p^*(k) = \alpha_n k^{(n+2)/2}, \quad \alpha_n = \frac{2\sigma_{n-1}}{n(n+2)a_1a_2\cdots a_n},$$

where  $\sigma_{n-1}$  denotes the surface area of the (n-1)-dimensional unit sphere. Hence, from (2.5) with k = tW(p) we have

$$V_p(t) = \alpha_n W(p)^{(n+2)/2} t^{(n+2)/2}$$

It follows from (2.1) that

$$A_p(t) = \beta_n W(p)^{(n+2)/2} t^{n/2}, \quad \beta_n = \frac{n+2}{2} \alpha_n$$

and hence we get from k = tW(p)

$$A_n^*(k) = \beta_n W(p) k^{n/2}.$$

Using (2.6), we have

(3.6) 
$$D_p^*(k) = \frac{1}{W(p)} A_p^*(k) = \beta_n k^{n/2}.$$

Together with (3.6), (3.5) implies

$$V_p^*(k) = \gamma_n D_p^*(k)^{(n+2)/n}, \quad \gamma_n = \frac{\alpha_n}{(\beta_n)^{(n+2)/n}}.$$

This completes the proof of the only if part of Theorem 4.

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