

DIRICHLET EIGENVALUE PROBLEMS UNDER MUSIELAK-ORLICZ GROWTH

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ABSTRACT. This paper studies the eigenvalues of the $G(\cdot)$ -Laplacian Dirichlet problem

$$\begin{cases} -\operatorname{div} \left(\frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \right) = \lambda \left(\frac{g(x, |u|)}{|u|} u \right) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where Ω is a bounded domain in \mathbb{R}^N and g is the density of a generalized Φ -function $G(\cdot)$. Using the Lusternik-Schnirelmann principle, we show the existence of a nondecreasing sequence of nonnegative eigenvalues.

1. Introduction

In the fields of partial differential equations and the calculus of variations, there has been much research on non-standard growth problems, such as the eigenvalue problems [5]. The study of eigenvalue problems relies on the Lusternik-Schnirelmann (L-S) theory of critical points for an even functional on a manifold. The presentations of this theory, in both finite and infinite-dimensional spaces, can be found in [1, 4, 14, 15].

A mathematical prototype for nonlinear elliptic eigenvalue problems is expressible by involving the p -Laplacian operator

$$(1.1) \quad \begin{cases} -\operatorname{div} (|\nabla u|^{p-2} \nabla u) = \lambda (|u|^{p-2} u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where $1 < p < \infty$ and Ω is a bounded domain of \mathbb{R}^N . The problem (1.1) has attracted much attention and has been extensively studied in the literature (see for examples [2, 7, 9]). One of the important consequences of the Lusternik-Schnirelmann principle is the existence, exactly as for the classical Laplace

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operator ($p = 2$), of an increasing sequence of eigenvalues

$$\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_i \leq \dots, \quad \lambda_i \rightarrow \infty.$$

Later on, this result has been generalized to variable exponent and Orlicz cases

$$\begin{cases} -\operatorname{div} \left(|\nabla u|^{p(x)-2} \nabla u \right) = \lambda \left(|u|^{p(x)-2} u \right) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

and

$$\begin{cases} -\operatorname{div} \left(\frac{g(|\nabla u|)}{|\nabla u|} \nabla u \right) = \lambda \left(\frac{g(|u|)}{|u|} u \right) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where $x \rightarrow p(x)$ is a continuous function on $\bar{\Omega}$ such that $1 < p(x) < \infty$ and $t \rightarrow g(t)$ is the density of a Φ -function G (see [6, 12, 13]).

One naturally asks whether a similar result holds in the Musielak-Orlicz case. For this, we consider the following eigenvalue problem under generalized Orlicz growth

$$(1.2) \quad \begin{cases} -\operatorname{div} \left(\frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \right) = \lambda \left(\frac{g(x, |u|)}{|u|} u \right) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where $g(x, \cdot)$ is the right-hand derivative of a Φ -function $G(x, \cdot)$. This situation covers not only the variable exponent $G(x, t) = t^{p(x)}$ and Orlicz case $G(x, t) = G(t)$, but also the variable exponent perturbation $G(x, t) = t^{p(x)} \ln(e + t)$, the double phase $G(x, t) = t^p + a(x)t^q$ and their various combinations (see [8]). Note that, some particular vector inequalities are helpful in the study of the eigenvalue problem for the p -Laplacian. In our situation, a lack of these inequalities and homogeneity are a major source of difficulties. To overcome these problems, we developed a method inspired by Lieberman's pioneering article [10], which allows us to apply the L-S principle for establish the existence of a nondecreasing sequence of nonnegative eigenvalue tending to infinity of the problem (1.2) (see Theorem 3.7).

2. Musielak-Orlicz-Sobolev spaces

To deal with the problem (1.2), we need Musielak-Orlicz-Sobolev spaces. Most of the results concerning these spaces are given in Musielak's monograph [11], hence the alternative name of Musielak-Orlicz spaces.

Definition 2.1. A function $G : \Omega \times [0, \infty) \rightarrow [0, \infty]$ is called a generalized Φ -function, denoted by $G(\cdot) \in \Phi(\Omega)$, if the following conditions hold:

- For each $t \in [0, \infty)$, the function $G(\cdot, t)$ is measurable.
- For a.e. $x \in \Omega$, the function $G(x, \cdot)$ is a Φ -function, i.e.,
 - (1) $G(x, 0) = \lim_{t \rightarrow 0^+} G(x, t) = 0$ and $\lim_{t \rightarrow \infty} G(x, t) = \infty$;
 - (2) $G(x, \cdot)$ is increasing and convex.

Note that, a generalized Φ -function can be represented as

$$G(x, t) = \int_0^t g(x, s) \, ds,$$

where $g(x, \cdot)$ is the right-hand derivative of $G(x, \cdot)$. Furthermore for each $x \in \Omega$, the function $g(x, \cdot)$ is right-continuous and nondecreasing.

Assumptions. We say that $G(\cdot)$ satisfies

(SC) : If for a.e. $x \in \Omega$, the function $t \rightarrow g(x, t)$ is a $C^1(\mathbb{R}^+)$ and there exist two constants $g_0, g^0 > 0$ such that,

$$g_0 \leq \frac{tg'(x, t)}{g(x, t)} \leq g^0.$$

(A₀) : If there exists a constant $c_0 > 1$ such that,

$$\frac{1}{c_0} \leq G(x, 1) \leq c_0 \text{ for a.e. } x \in \Omega.$$

(A₁) : If there exists $C > 0$ such that, for every $x, y \in B_R \subset \Omega$ with $R \leq 1$, we have

$$G_{B_R}(x, t) \leq CG_{B_R}(y, t) \text{ when } G_{B_R}^-(t) \in \left[1, \frac{1}{R^N}\right],$$

where $G_{B_R}^-(t) := \inf_{B_R} G(x, t)$.

Remark 2.2. 1) Note that (A₁) corresponds to local log-Holder continuity in the variable exponent case (see Proposition 7.1.2 in [8]). In the double phase case $G(x, t) = t^P + a(x)t^q$, condition (A₁) is equivalent to $a(y) - a(x) \leq C|y - x|^{\frac{N}{p}(q-p)}$ (see Proposition 7.2.2 in [8]).

2) The condition (SC) implies

$$g_0 + 1 \leq \frac{tg(x, t)}{G(x, t)} \leq g^0 + 1.$$

So, we have the following inequalities [3]

$$(2.1) \quad \sigma^{g_0+1}G(x, t) \leq G(x, \sigma t) \leq \sigma^{g^0+1}G(x, t) \text{ for } x \in \Omega, t \geq 0 \text{ and } \sigma \geq 1.$$

$$(2.2) \quad \sigma^{g^0+1}G(x, t) \leq G(x, \sigma t) \leq \sigma^{g_0+1}G(x, t) \text{ for } x \in \Omega, t \geq 0 \text{ and } \sigma \leq 1.$$

Definition 2.3. We define $G^*(\cdot)$ the conjugate Φ -function of $G(\cdot)$, by

$$G^*(x, s) := \sup_{t \geq 0} (st - G(x, t)) \text{ for } x \in \Omega \text{ and } s \geq 0.$$

Note that $G^*(\cdot)$ is also a generalized Φ -function and can be represented as

$$G^*(x, t) = \int_0^t g^{-1}(x, s) \, ds,$$

with $g^{-1}(x, s) := \sup\{t \geq 0 : g(x, t) \leq s\}$.

Remark 2.4. If $G(\cdot)$ satisfies (SC) , then $G^*(\cdot)$ satisfies also (SC) , as follows

$$(2.3) \quad \frac{g^0 + 1}{g^0} \leq \frac{tg^{-1}(x, t)}{G^*(x, t)} \leq \frac{g_0 + 1}{g_0}.$$

The functions $G(\cdot)$ and $G^*(\cdot)$ satisfies the following Young inequality

$$st \leq G(x, t) + G^*(x, s) \text{ for } x \in \Omega \text{ and } s, t \geq 0.$$

Further, we have the equality if $s = g(x, t)$ or $t = g^{-1}(x, s)$.

Definition 2.5. Let $G(\cdot) \in \Phi(\mathbb{R}^N)$, the generalized Orlicz space, also called Musielak-Orlicz space, is defined as the set

$$L^{G(\cdot)}(\Omega) := \{u \in L^0(\Omega) : \lim_{\lambda \rightarrow 0} \int_{\Omega} G(x, \lambda|u|) dx = 0\},$$

where $L^0(\Omega)$ is the set of measurable functions in Ω . If $G(\cdot)$ satisfies (SC) , then

$$L^{G(\cdot)}(\Omega) = \{u \in L^0(\Omega) : \int_{\Omega} G(x, |u|) dx < \infty\}.$$

Remark 2.6. On the generalized Orlicz space, we define the following norms:

- Luxembourg norm: $\|u\|_{G(\cdot)} = \inf\{\lambda > 0 : \int_{\Omega} G(x, \frac{|u|}{\lambda}) dx \leq 1\}$.
- Orlicz norm: $\|u\|_{G(\cdot)}^0 = \sup\{|\int_{\Omega} u(x)v(x) dx| : \int_{\Omega} G^*(x, |v|) dx \leq 1\}$.

These norms are equivalent, precisely, we have

$$\|u\|_{G(\cdot)} \leq \|u\|_{G(\cdot)}^0 \leq 2\|u\|_{G(\cdot)}.$$

The functions $G(\cdot)$ and $G^*(\cdot)$ satisfy the Hölder inequality

$$\left| \int_{\Omega} u(x)v(x) dx \right| \leq 2\|u\|_{G(\cdot)}\|v\|_{G^*(\cdot)} \text{ for } u \in L^{G(\cdot)}(\Omega) \text{ and } v \in L^{G^*(\cdot)}(\Omega).$$

The following lemmas establish properties of convergent sequences in generalized Orlicz spaces (see [8]).

Lemma 2.7. Let $G(\cdot) \in \Phi(\Omega)$. For any sequence $\{u_i\}_i$ in $L^{G(\cdot)}(\Omega)$, we have the following properties: If $G(\cdot)$ satisfies (SC) , then

$$\|u_i\|_{G(\cdot)} \rightarrow 0 \text{ (resp. } 1; \infty) \iff \int_{\Omega} G(x, |u_i(x)|) dx \rightarrow 0 \text{ (resp. } 1; \infty).$$

Lemma 2.8. Let $G(\cdot) \in \Phi(\Omega)$ and $\{u_i\}_i$ be a sequence of measurable functions u_i . Assume the sequence $\{u_i\}_i$ converges almost everywhere to a measurable function u , and is dominated by a function $h \in L^{G(\cdot)}(\Omega)$. Then all u_i as well as u are in $L^{G(\cdot)}(\Omega)$ and the sequence $\{u_i\}_i$ converges to u in $L^{G(\cdot)}(\Omega)$.

Lemma 2.9. Let $G(\cdot) \in \Phi(\Omega)$ satisfies (SC) and $\{u_i\}_i$ be a sequence in $L^{G(\cdot)}(\Omega)$. If $u_i \rightarrow u$ in $L^{G(\cdot)}(\Omega)$, then there exist a subsequence $\{u_{i_j}\}_j$ and a function $h \in L^{G(\cdot)}(\Omega)$ such that $u_{i_j} \rightarrow u$, for a.e. in Ω and for all j , $|u_{i_j}(x)| \leq h(x)$ for a.e. in Ω .

Proof. Since $u_i \rightarrow u$ in $L^{G(\cdot)}(\Omega)$, then by Lemma 2.7, we have

$$\int_{\Omega} G(x, |u_i(x) - u(x)|) dx \rightarrow 0.$$

So, for any $\delta > 0$, let $A_{\delta,i} := \{x \in \Omega : |u_i(x) - u(x)| > \delta\}$. Using the inequalities (2.1), (2.2) and the condition (A_0) , we get

$$\begin{aligned} \frac{1}{c_0} \min(\delta^{g_0}, \delta^{g^0}) |A_{\delta,i}| &\leq \int_{A_{\delta,i}} G(x, \delta) dx \\ &\leq \int_{A_{\delta,i}} G(x, |u_i - u|) dx \\ &\leq \int_{\Omega} G(x, |u_i - u|) dx. \end{aligned}$$

Hence, $|A_{\delta,i}| \rightarrow 0$, and $u_i \rightarrow u$ in measure. Therefore, there exists a subsequence (u_{i_j}) of (u_i) which converge to u , for a.e. in Ω .

Then we can define

$$h := \sum_{j=1}^{\infty} |u_{i_j} - u|$$

and it can be seen that $h \in L^{G(\cdot)}(\Omega)$ and h is a dominating function of (u_{i_j}) for all j . □

Definition 2.10. We define the generalized Orlicz-Sobolev space by

$$W^{1,G(\cdot)}(\Omega) := \{u \in L^{G(\cdot)}(\Omega) \cap L^1_{loc}(\Omega) : |\nabla u| \in L^{G(\cdot)}(\Omega) \text{ in the distribution sense}\},$$

equipped with the norm

$$\|u\|_{1,G(\cdot)} = \|u\|_{G(\cdot)} + \|\nabla u\|_{G(\cdot)}.$$

Definition 2.11. $W_0^{1,G(\cdot)}(\Omega)$ is the closure of $C_0^\infty(\Omega)$ in $W^{1,G(\cdot)}(\Omega)$.

Next, we recall the norm version of the Poincare inequality, which will be investigated in this work (see [8]).

Theorem 2.12. *Let Ω be a bounded set of \mathbb{R}^N and $G(\cdot) \in \Phi(\Omega)$ satisfy (SC), (A_0) and (A_1) . For every $u \in W_0^{1,G(\cdot)}(\Omega)$, we have*

$$\|u\|_{G(\cdot)} \leq C \|\nabla u\|_{G(\cdot)}.$$

In particular, $\|\nabla u\|_{G(\cdot)}$ is a norm on $W_0^{1,G(\cdot)}(\Omega)$ and it is equivalent to the norm $\|u\|_{1,G(\cdot)}$.

The following compact embedding theorem for Musielak-Sobolev spaces is given by P. Hasto [8].

Theorem 2.13. *Let $G(\cdot) \in \Phi(\mathbb{R}^N)$ satisfy (SC), (A_0) and (A_1) and let Ω be bounded. Then*

$$W_0^{1,G(\cdot)}(\Omega) \hookrightarrow\hookrightarrow L^{G(\cdot)}(\Omega).$$

3. Eigenvalue problems for the $G(\cdot)$ -Laplacian

3.1. Lusternik-Schnirelmann principle (L-S principle)

We recall here a version of the Lusternik-Schnirelmann principle, which Browder discussed in [4] and Zeidler in [14, 15].

Theorem 3.1. *Let X be a real reflexive Banach space. If A, B are two functionals on X satisfying the following properties:*

(LS_1): $A, B : X \rightarrow \mathbb{R}$ are even functionals and that $A, B \in C^1(X, \mathbb{R})$ with $A(0) = B(0) = 0$.

(LS_2): A' is strongly continuous (i.e., $u_i \rightarrow u$ in X implies $A'(u_i) \rightarrow A'(u)$) and,

$$\begin{aligned} \langle A'(u), u \rangle = 0, \quad u \in \overline{coS_B} \text{ implies } A(u) = 0, \\ A(u) = 0, \quad u \in \overline{coS_B} \text{ implies } u = 0, \end{aligned}$$

where $\overline{coS_B}$ is the closed convex hull of $S_B := \{u \in X, B(u) = 1\}$.

(LS_3): B' is continuous, bounded and satisfies (S_0), i.e., as $i \rightarrow \infty$,

$$u_i \rightarrow u, \quad B'(u_i) \rightarrow v, \quad \langle B'(u_i), u_i \rangle \rightarrow \langle v, u \rangle \text{ implies } u_i \rightarrow u.$$

(LS_4): The level set S_B is bounded and $u \neq 0$ implies

$$\langle B'(u), u \rangle > 0, \quad \lim_{t \rightarrow \infty} B(tu) = \infty, \quad \inf_{u \in S_B} \langle B'(u), u \rangle > 0.$$

Then the eigenvalue problem

$$(3.1) \quad A'(u) = \mu B'(u), \quad u \in S_B, \quad \mu \in \mathbb{R},$$

admits a sequence of eigenpairs $\{u_i, \mu_i\}$ such that $u_i \rightarrow u$, $\mu \rightarrow 0$ as $i \rightarrow \infty$ and $\mu_i \neq 0$ for all i .

3.2. Application of L-S principle in $W_0^{1,G(\cdot)}(\Omega)$

In the sequel, let $G(\cdot) \in \Phi(\mathbb{R}^N)$ satisfy (SC), (A_0), (A_1), $G(x, \cdot) \in C^1([0, \infty))$ for every $x \in \Omega$ and C a generic constant which may change from line to line. We consider the following eigenvalue problem

$$(3.2) \quad \begin{cases} -\operatorname{div} \left(\frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \right) = \lambda \left(\frac{g(x, |u|)}{|u|} u \right) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where $g(x, \cdot)$ is the derivative of $G(x, \cdot)$. The existence of a weak solution to the Dirichlet-Sobolev problem associated of (3.2) has been studied in [3].

Definition 3.2. Let $\lambda \in \mathbb{R}$ and $u \in W_0^{1,G(\cdot)}(\Omega)$. (u, λ) is called a solution of the problem (3.2) if

$$(3.3) \quad \int_{\Omega} \frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \cdot \nabla v \, dx = \lambda \int_{\Omega} \frac{g(x, |u|)}{|u|} uv \, dx, \quad \forall v \in W_0^{1,G(\cdot)}(\Omega).$$

If (u, λ) is a solution of the problem (3.2) and $u \neq 0$, as usual, we call λ and u an eigenvalue and an eigenfunction corresponding to λ of (3.2), respectively.

In what follows we use the previous version of the L-S principle in order to prove the existence of a sequence of eigenvalues for problem (3.2). For this reason, we define on $X = W_0^{1,G(\cdot)}(\Omega)$ the functionals

$$(3.4) \quad A(u) := \int_{\Omega} G(x, |u|) \, dx,$$

$$(3.5) \quad B(u) := \int_{\Omega} G(x, |\nabla u|) \, dx.$$

Lemma 3.3. *Let A and B be defined in (3.4), (3.5). Then A and B satisfies (LS_1) .*

Proof. Let $G(\cdot) \in \Phi(\mathbb{R}^N)$. By definition of a generalized Φ -function, we have $G(x, 0) = 0$ which implies $A(0) = B(0) = 0$. The C^1 -smooth regularity of the functionals A and B follows by computing the Gateaux derivatives of A and B at $u \in W_0^{1,G(\cdot)}(\Omega)$ in the direction $v \in W_0^{1,G(\cdot)}(\Omega)$. Precisely, for every $u, v \in W_0^{1,G(\cdot)}(\Omega)$, we have

$$(3.6) \quad \langle A'(u), v \rangle = \int_{\Omega} \frac{g(x, |u|)}{|u|} uv \, dx,$$

$$(3.7) \quad \langle B'(u), v \rangle = \int_{\Omega} \frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \cdot \nabla v \, dx.$$

Then A and B satisfies (LS_1) . □

Lemma 3.4. *Let A be defined in (3.4). Then A' satisfies (LS_2) .*

Proof. Let $u \in W_0^{1,G(\cdot)}(\Omega)$, by the condition (SC) , we have

$$A(u) = \int_{\Omega} G(x, |u|) \, dx \leq \frac{1}{g_0 + 1} \int_{\Omega} g(x, |u|)|u| \, dx \leq \langle A'(u), u \rangle.$$

Then, if $\langle A'(u), u \rangle = 0$ implies $A(u) = 0$.

Next, we assume $A(u) = 0$. By Proposition 2.2.7 in [8], there exists $\tilde{G}(\cdot) \in \Phi(\Omega)$ with $\tilde{G}(\cdot) \approx G(\cdot)$ which is a strictly increasing. So, we have

$$0 \leq \int_{\Omega} \tilde{G}(x, |u|) \, dx \leq C \int_{\Omega} G(x, |u|) \, dx = 0 \quad \text{implies} \quad u = 0.$$

To end the proof of Lemma 3.4, it remains for us to prove that A' is strongly continuous. Let $u_i \rightharpoonup u$ in $W_0^{1,G(\cdot)}(\Omega)$, we need to show that

$$A'(u_i) \longrightarrow A'(u) \quad \text{in} \quad W_0^{1,G(\cdot)}(\Omega)^*.$$

For every $v \in W_0^{1,G(\cdot)}(\Omega)$, using the Holder inequality, we get

$$(3.8) \quad \begin{aligned} & \left| \int_{\Omega} \frac{g(x, |u_i|)}{|u_i|} u_i v \, dx - \int_{\Omega} \frac{g(x, |u|)}{|u|} uv \, dx \right| \\ & \leq \int_{\Omega} \left| \frac{g(x, |u_i|)}{|u_i|} u_i - \frac{g(x, |u|)}{|u|} u \right| |v| \, dx \end{aligned}$$

$$\leq 2 \left\| \frac{g(x, |u_i|)}{|u_i|} u_i - \frac{g(x, |u|)}{|u|} u \right\|_{G^*(\cdot)} \|v\|_{G(\cdot)}.$$

Since $u_i \rightharpoonup u$ in $W_0^{1,G(\cdot)}(\Omega)$, then by the compact embedding Theorem 2.13, we have $u_i \rightarrow u$ in $L^{G(\cdot)}(\Omega)$. So, using the reverse dominate convergence theorem, Lemma 2.9, there are a subsequence $\{u_{i_j}\}_j$ and a function $h \in L^{G(\cdot)}(\Omega)$ such that $u_{i_j} \rightarrow u$ for a.e. in Ω and $|u_{i_j}| \leq h$.

As the function $t \rightarrow g(x, t)$ is continuous and increasing, we have

$$\frac{g(x, |u_{i_j}|)}{|u_{i_j}|} u_{i_j} \rightarrow \frac{g(x, |u|)}{|u|} u \text{ for a.e. in } \Omega \text{ and } \frac{g(x, |u_{i_j}|)}{|u_{i_j}|} u_{i_j} \leq \frac{g(x, |h|)}{|h|} h.$$

Note that $\frac{g(x, |h|)}{|h|} h \in L^{G^*(\cdot)}(\Omega)$. Indeed, by the Young equality and the condition (SC), we have

$$\begin{aligned} \int_{\Omega} G^*(x, \left| \frac{g(x, |h|)}{|h|} h \right|) dx &= \int_{\Omega} G^*(x, g(x, |h|)) dx \\ &= \int_{\Omega} g(x, |h|) |h| - G(x, |h|) dx \\ &\leq g^0 \int_{\Omega} G(x, |h|) dx \\ &< \infty. \end{aligned}$$

Then, by the dominate convergence theorem, Lemma 2.8, we have

$$\frac{g(x, |u_{i_j}|)}{|u_{i_j}|} u_{i_j} \rightarrow \frac{g(x, |u|)}{|u|} u \text{ in } L^{G^*(\cdot)}(\Omega).$$

Hence, by inequality (3.8), we have

$$\int_{\Omega} \frac{g(x, |u_{i_j}|)}{|u_{i_j}|} u_{i_j} v dx \rightarrow \int_{\Omega} \frac{g(x, |u|)}{|u|} uv dx.$$

Since the weak limit is independent of the choice of the subsequence, it follows that

$$\int_{\Omega} \frac{g(x, |u_i|)}{|u_i|} u_i v dx \rightarrow \int_{\Omega} \frac{g(x, |u|)}{|u|} uv dx.$$

Therefore $A'(u_i) \rightarrow A(u)$ in $W_0^{1,G(\cdot)}(\Omega)^*$. □

Inspired by the proof of Theorem 1.7 of Lieberman [10], we have:

Lemma 3.5. *Let B be defined in (3.5). Then B' satisfies (LS₃).*

Proof. Using the Hölder inequality, we have

$$\begin{aligned} (3.9) \quad \|B'\|_{(W_0^{1,G(\cdot)}(\Omega))^*} &= \sup\{\langle B'(u), v \rangle; \|v\|_{1,G(\cdot)} \leq 1\} \\ &\leq \sup \left| \int_{\Omega} \frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \cdot \nabla v dx \right| \\ &\leq 2 \|g(x, |\nabla u|)\|_{G^*(\cdot)} \|v\|_{1,G(\cdot)}. \end{aligned}$$

Using the equivalent between Luxembourg norm and Orlicz norm, and the Young inequality, we have

$$\|g(x, |\nabla u|)\|_{G^*(\cdot)} \leq \|g(x, |\nabla u|)\|_{G^*(\cdot)}^0 \leq 1 + \int_{\Omega} G^*(x, g(x, |\nabla u|)) \, dx.$$

Then, by the Young equality and the condition (SC), we obtain

$$\|g(x, |\nabla u|)\|_{G^*(\cdot)} \leq g^0 \int_{\Omega} G(x, |\nabla u|) \, dx.$$

So, by the inequality (3.9), we get

$$\|B'\|_{W_0^{1,G(\cdot)}(\Omega)^*} \leq C \left(g^0 \int_{\Omega} G(x, |\nabla u|) \, dx + 1 \right) \|v\|_{1,G(\cdot)}.$$

Hence B' is bounded. Moreover, a similar argument to the one we used to prove (LS₂), we get the continuity of B' .

Complete the proof of Lemma 3.5, that is, prove that B satisfies condition (S₀). Let $\{u_i\}_i$ be a sequence in $W_0^{1,G(\cdot)}(\Omega)$ such that

$$u_i \rightharpoonup u, \quad B'(u_i) \rightharpoonup v \quad \text{and} \quad \langle B'(u_i), u_i \rangle \rightarrow \langle v, u \rangle$$

for some $v \in W_0^{1,G(\cdot)}(\Omega)^*$ and $u \in W_0^{1,G(\cdot)}(\Omega)$. Then, we have

$$(3.10) \quad \begin{aligned} & \langle B'(u_i) - B'(u), u_i - u \rangle \\ &= \langle B'(u_i), u_i \rangle - \langle B'(u_i), u \rangle - \langle B'(u), u_i - u \rangle \rightarrow 0. \end{aligned}$$

On the other hand, from the condition (SC) and Cauchy-Schwarz inequality, we have for $\theta_t = tu + (1-t)u_i$, $t \in (0, 1)$

$$\begin{aligned} & \left(\frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u - \frac{g(x, |\nabla u_i|)}{|\nabla u_i|} \nabla u_i \right) \cdot (\nabla u - \nabla u_i) \\ &= \left(\int_0^1 \frac{\partial}{\partial t} \left(\frac{g(x, |\nabla \theta_t|)}{|\nabla \theta_t|} \nabla \theta_t \right) \, dt \right) \cdot (\nabla u - \nabla u_i) \\ &= |\nabla u - \nabla u_i|^2 \int_0^1 \frac{g(x, |\nabla \theta_t|)}{|\nabla \theta_t|} \, dt \\ & \quad + \int_0^1 g(x, |\nabla \theta_t|) \left(\frac{|\nabla \theta_t| g'(x, |\nabla \theta_t|)}{g(x, |\nabla \theta_t|)} - 1 \right) \frac{(\nabla \theta_t \cdot (\nabla u - \nabla u_i))^2}{|\nabla \theta_t|^3} \, dt \\ & \geq \min(1, g_0) |\nabla u - \nabla u_i|^2 \int_0^1 \frac{g(x, |\nabla \theta_t|)}{|\nabla \theta_t|} \, dt. \end{aligned}$$

Which implies

$$\langle B'(u_i) - B'(u), u_i - u \rangle \geq \min(1, g_0) \int_{\Omega} \int_0^1 \frac{g(x, |\nabla \theta_t|)}{|\nabla \theta_t|} |\nabla u - \nabla u_i|^2 \, dt \, dx.$$

Now we write $S_1 = \{x \in \Omega, |\nabla u - \nabla u_i| \leq 2|\nabla u|\}$ and $S_2 = \{x \in \Omega, |\nabla u - \nabla u_i| > 2|\nabla u|\}$. Then $S_1 \cup S_2 = \Omega$ and

$$\begin{aligned} \frac{1}{2}|\nabla u| &\leq |\nabla \theta_t| \leq 3|\nabla u| && \text{on } S_1 \text{ for } t \geq \frac{3}{4}, \\ \frac{1}{4}|\nabla u - \nabla u_i| &\leq |\nabla \theta_t| \leq 3|\nabla u - \nabla u_i| && \text{on } S_2 \text{ for } t \leq \frac{1}{4}. \end{aligned}$$

Therefore

$$(3.11) \quad \begin{aligned} &\langle B'(u_i) - B'(u), u_i - u \rangle \\ &\geq C \left(\int_{S_1} \frac{g(x, |\nabla u|)}{|\nabla u|} |\nabla u - \nabla u_i|^2 dx + \int_{S_2} G(x, |\nabla u - \nabla u_i|) dx \right). \end{aligned}$$

Hence

$$(3.12) \quad \int_{S_2} G(x, |\nabla u - \nabla u_i|) dx \leq C \langle B'(u_i) - B'(u), u_i - u \rangle.$$

To estimate the integrals over S_1 , using the condition (SC), $t \rightarrow g(x, t)$ is a nondecreasing function and the Hölder inequality in $L^2(S_1)$, we have

$$\begin{aligned} &\int_{S_1} G(x, |\nabla u - \nabla u_i|) dx \\ &\leq C \int_{S_1} g(x, |\nabla u - \nabla u_i|) |\nabla u - \nabla u_i| dx \\ &\leq C \int_{S_1} \left(\frac{g(x, |\nabla u|)}{|\nabla u|} |\nabla u| \right)^{\frac{1}{2}} |\nabla u - \nabla u_i| (g(x, |\nabla u - \nabla u_i|))^{\frac{1}{2}} dx \\ &\leq C \left(\int_{S_1} \frac{g(x, |\nabla u|)}{|\nabla u|} |\nabla u - \nabla u_i|^2 dx \right)^{\frac{1}{2}} \left(\int_{S_1} g(x, |\nabla u|) |\nabla u| dx \right)^{\frac{1}{2}} \\ &\leq C \left(\int_{S_1} \frac{g(x, |\nabla u|)}{|\nabla u|} |\nabla u - \nabla u_i|^2 dx \right)^{\frac{1}{2}} \left(\int_{S_1} G(x, |\nabla u|) dx \right)^{\frac{1}{2}}. \end{aligned}$$

Hence, using the inequality (3.11), we have

$$(3.13) \quad \begin{aligned} &\int_{S_1} G(|\nabla u - \nabla u_i|) dx \\ &\leq C (\langle B'(u_i) - B'(u), u_i - u \rangle)^{\frac{1}{2}} \left(\int_{\Omega} G(x, |\nabla u|) dx \right)^{\frac{1}{2}}. \end{aligned}$$

Collecting the inequalities (3.11), (3.12), (3.13), we have

$$\begin{aligned} &\int_{\Omega} G(|\nabla u - \nabla u_i|) dx \\ &\leq C \left((\langle B'(u_i) - B'(u), u_i - u \rangle)^{\frac{1}{2}} \left(\int_{\Omega} G(|\nabla u|) + G(x, |u|) dx \right)^{\frac{1}{2}} \right) \end{aligned}$$

$$+ \langle B'(u_i) - B'(u), u_i - u \rangle).$$

Therefore, by the inequality (3.10), Theorem 2.12 and Lemma 2.7, we have $u_i \rightarrow u$ in $W_0^{1,G(\cdot)}(\Omega)$. \square

Lemma 3.6. *Let B be defined in (3.5). Then B and B' satisfies (LS_4) .*

Proof. Let $u \neq 0$, by the inequalities (2.1) and (2.2), for all $t \in \mathbb{R}^+$ we have

$$B(tu) = \int_{\Omega} G(x, |\nabla tu|) \, dx \leq \max(t^{g_0+1}, t^{g_0+1}) \int_{\Omega} G(x, |\nabla u|) \, dx.$$

Then $\lim_{t \rightarrow +\infty} B(tu) = +\infty$.

Next, by the condition (SC) and Proposition 2.2.7 in [8], there exists $\tilde{G}(\cdot) \in \Phi(\Omega)$ with $\tilde{G}(\cdot) \approx G(\cdot)$ which is a strictly increasing. Then, we have

$$\begin{aligned} \langle B'(u), u \rangle &= \int_{\Omega} g(x, |\nabla u|) |\nabla u| \, dx \\ &\geq (g_0 + 1) \int_{\Omega} G(x, |\nabla u|) \, dx \\ &\geq C \int_{\Omega} \tilde{G}(x, |\nabla u|) \, dx \\ &\geq 0. \end{aligned}$$

Note that, the last inequality result from the fact if $u \in W_0^{1,G(\cdot)}$ and $\nabla u = 0$ then $u = 0$.

So, if $u \in S_B$, then, by the previous inequality, we have $\langle B'(u), u \rangle \geq g_0 + 1$. Therefore B and B' satisfies the hypothesis (LS_4) . \square

Theorem 3.7. *Let $G(\cdot) \in \Phi(\mathbb{R}^N)$ satisfy (SC) , (A_0) and (A_1) . Let A and B be the two functionals defined in (3.4), (3.5). Then there exists a nondecreasing sequence of nonnegative eigenvalues $\{\lambda_i\}_i$ of (3.2) such that $\lambda_i \rightarrow \infty$ as $i \rightarrow \infty$.*

Proof. By Lemmas 3.3-3.6 combined with Theorem 3.1, there exists a nonnegative nonincreasing sequence $\{\mu_i\}_i$ such that $\mu_i \rightarrow 0$ as $i \rightarrow \infty$ and each μ_i is an eigenvalue of $A'(u) = \mu B'(u)$ which means, for every $v \in W_0^{1,G(\cdot)}(\Omega)$, we have

$$\int_{\Omega} \frac{g(x, |u|)}{|u|} uv \, dx = \mu \int_{\Omega} \frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \cdot \nabla v \, dx.$$

Which is equivalent

$$\int_{\Omega} \frac{g(x, |\nabla u|)}{|\nabla u|} \nabla u \cdot \nabla v \, dx = \frac{1}{\mu} \int_{\Omega} \frac{g(x, |u|)}{|u|} uv \, dx.$$

Then $\lambda_i := \frac{1}{\mu_i} \rightarrow \infty$ as $i \rightarrow \infty$ is a nondecreasing sequence of nonnegative eigenvalues of (3.2). \square

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