

SOME RESULTS ON INVARIANT SUBMANIFOLDS OF LORENTZIAN PARA-KENMOTSU MANIFOLDS

MEHMET ATÇEKEN

ABSTRACT. The purpose of this paper is to study invariant submanifolds of a Lorentzian para Kenmotsu manifold. We obtain the necessary and sufficient conditions for an invariant submanifold of a Lorentzian para Kenmotsu manifold to be totally geodesic. Finally, a non-trivial example is built in order to verify our main results.

1. Introduction

The geometry of almost paracontact manifolds is a naturel extension of the almost para Hermitian manifolds. The study of almost paracontact metric manifolds started in [6]. After then, these manifolds were classified by many geometers(see references).

Let \widetilde{M} be an n -dimensional Lorentzian metric manifold. This means that it is endowed with a structure (φ, ξ, η, g) , where φ is a $(1,1)$ -type tensor field, ξ is a vector field, η is a 1-form on \widetilde{M} and g is a Lorentzian metric tensor satisfying;

$$\begin{aligned} (1) \quad \varphi^2 X &= X + \eta(X)\xi, \quad g(\varphi X, \varphi Y) = g(X, Y) + \eta(X)\eta(Y) \\ (2) \quad \eta(\xi) &= -1, \quad \eta(X) = g(X, \xi), \end{aligned}$$

for all vector fields X, Y on \widetilde{M} . Then $\widetilde{M}^n(\varphi, \xi, \eta, g)$ is said to be Lorentzian almost paracontact manifold [13].

A Lorentzian almost paracontact manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$ is called Lorentzian para Kenmotsu manifold if

$$(3) \quad (\widetilde{\nabla}_X \varphi)Y = -g(\varphi X, Y)\xi - \eta(Y)\varphi X,$$

for all $X, Y \in \Gamma(T\widetilde{M})$, where $\widetilde{\nabla}$ and $\Gamma(T\widetilde{M})$ denote the Levi-Civita connection and differentiable vector fields set on \widetilde{M} , respectively.

Received December 28, 2020. Revised December 27, 2021. Accepted December 29, 2021.

2010 Mathematics Subject Classification: 53C15, 53C40, 53C50.

Key words and phrases: Lorentzian Para Kenmotsu Manifold, Invarinat Submanifold, Pseudoparallel Submanifold, Ricci-Generalized Pseudoparallel Submanifold.

© The Kangwon-Kyungki Mathematical Society, 2022.

This is an Open Access article distributed under the terms of the Creative commons Attribution Non-Commercial License (<http://creativecommons.org/licenses/by-nc/3.0/>) which permits unrestricted non-commercial use, distribution and reproduction in any medium, provided the original work is properly cited.

In a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$, we have

$$(4) \quad \widetilde{\nabla}_X \xi = -\varphi^2 X = -X - \eta(X)\xi$$

$$(5) \quad (\widetilde{\nabla}_X \eta)Y = -g(X, Y) - \eta(X)\eta(Y),$$

for all $X, Y \in \Gamma(T\widetilde{M})$.

By \widetilde{R} and S , we denote the Riemannian curvature tensor and Ricci tensor of Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$, then we have

$$(6) \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$

$$(7) \quad \widetilde{R}(\xi, X)Y = g(X, Y)\xi - \eta(Y)X,$$

$$(8) \quad S(\xi, X) = (n-1)\eta(X),$$

The concircular curvature tensor of $\widetilde{M}^n(\varphi, \xi, \eta, g)$ is given by

$$(9) \quad \widetilde{C}(X, Y)Z = \widetilde{R}(X, Y)Z - \frac{\tau}{n(n-1)}\{g(Y, Z)X - g(X, Z)Y\},$$

for all $X, Y, Z \in \Gamma(T\widetilde{M})$, where τ is the scalar curvature of \widetilde{M} .

Now, let M be an immersed submanifold of a Lorentzian para Kenmotsu manifold \widetilde{M}^n . By $\Gamma(TM)$ and $\Gamma(T^\perp M)$, we denote the tangent and normal subspaces of M in \widetilde{M} . Then the Gauss and Weingarten formulae are, respectively, given by

$$(10) \quad \widetilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y),$$

and

$$(11) \quad \widetilde{\nabla}_X V = -A_V X + \nabla_X^\perp V,$$

for all $X, Y \in \Gamma(TM)$ and $V \in \Gamma(T^\perp M)$, where ∇ and ∇^\perp are the connections on M and $\Gamma(T^\perp M)$ and σ and A are called the second fundamental form and shape operator of M , respectively. They are related by

$$(12) \quad g(A_V X, Y) = g(\sigma(X, Y), V).$$

The covariant derivative of σ is defined by

$$(13) \quad (\widetilde{\nabla}_X \sigma)(Y, Z) = \nabla_X^\perp \sigma(Y, Z) - \sigma(\nabla_X Y, Z) - \sigma(Y, \nabla_X Z),$$

for all $X, Y, Z \in \Gamma(TM)$. If $\widetilde{\nabla} \sigma = 0$, then submanifold M is said to be its second fundamental form is parallel [6].

By R , we denote the Riemannian curvature tensor of the submanifold M , we have the following Gauss equation;

$$(14) \quad \begin{aligned} \widetilde{R}(X, Y)Z &= R(X, Y)Z + A_{\sigma(X, Z)}Y - A_{\sigma(Y, Z)}X + (\widetilde{\nabla}_X \sigma)(Y, Z) \\ &- (\widetilde{\nabla}_Y \sigma)(X, Z), \end{aligned}$$

for all $X, Y, Z \in \Gamma(T\widetilde{M})$, where if $(\widetilde{\nabla}_X \sigma)(Y, Z) - (\widetilde{\nabla}_Y \sigma)(X, Z) = 0$, then it is called curvature-invariant submanifold.

For a $(0, k)$ -type tensor field T , $k \geq 1$ and a $(0, 2)$ -type tensor field A on a Riemannian manifold (M, g) , $Q(A, T)$ -Tachibana tensor field is defined by

$$(15) \quad \begin{aligned} Q(A, T)(X_1, X_2, \dots, X_k; X, Y) &= -T((X \wedge_A Y)X_1, X_2, \dots, X_k) \dots \\ &- T(X_1, X_2, \dots, X_{k-1}, (X \wedge_A Y)X_k), \end{aligned}$$

for all $X_1, X_2, \dots, X_k, X, Y \in \Gamma(TM)$, where

$$(16) \quad (X \wedge_A Y)Z = A(Y, Z)X - A(X, Z)Y.$$

DEFINITION 1.1. A submanifold of a Riemannian manifold (M, g) is said to be pseudoparallel, 2-pseudoparallel, Ricci-generalized pseudoparallel and 2-Ricci-generalized pseudoparallel if

$$\begin{aligned} &\tilde{R} \cdot \sigma \text{ and } Q(g, \sigma) \\ &\tilde{R} \cdot \tilde{\nabla} \sigma \text{ and } Q(g, \tilde{\nabla} \sigma) \\ &\tilde{R} \cdot \sigma \text{ and } Q(S, \sigma) \\ &\tilde{R} \cdot \tilde{\nabla} \sigma \text{ and } Q(S, \tilde{\nabla} \sigma) \end{aligned}$$

are linearly dependent, respectively [1].

Equivalently, these can be formulated by the following equations;

$$(17) \quad \tilde{R} \cdot \sigma = L_1 Q(g, \sigma),$$

$$(18) \quad \tilde{R} \cdot \tilde{\nabla} \sigma = L_2 Q(g, \tilde{\nabla} \sigma),$$

$$(19) \quad \tilde{R} \cdot \sigma = L_3 Q(S, \sigma),$$

$$(20) \quad \tilde{R} \cdot \tilde{\nabla} \sigma = L_4 Q(S, \tilde{\nabla} \sigma),$$

where functions L_1, L_2, L_3 and L_4 are, respectively, defined on

$M_1 = \{x \in M : \sigma(x) \neq g(x)\}$, $M_2 = \{x \in M : \tilde{\nabla} \sigma(x) \neq g(x)\}$, $M_3 = \{x \in M : S(x) \neq \sigma(x)\}$ and $M_4 = \{x \in M : S(x) \neq \tilde{\nabla} \sigma(x)\}$.

Particularly, if $L_1 = 0$ (resp. $L_2 = 0$), then submanifold is said to be semiparallel (resp. 2-semiparallel) [11].

2. Some Results on Invariant Submanifolds of a Lorentzian Para Kenmotsu Manifold

Now, we will investigate the above cases for the invariant submanifold M of a para-Kenmotsu manifold $\tilde{M}^n(\varphi, \xi, \eta, g)$.

Now, let M be an immersed submanifold of a para-Kenmotsu manifold manifold $\tilde{M}^{2n+1}(\varphi, \xi, \eta, g)$. If $\varphi(T_x M) \subseteq T_x M$, for each point at $x \in M$, then M is said to be invariant submanifold. We note that all of the properties of an invariant submanifold inherit the ambient manifold.

In the rest of this paper, we will assume that M is invariant submanifold of a Lorentzian para Kenmotsu manifold $\tilde{M}^n(\varphi, \xi, \eta, g)$. Thus by using (3) and (10), we have

$$(21) \quad \sigma(X, \xi) = 0, \quad \sigma(\varphi X, Y) = \sigma(X, \varphi Y) = \varphi \sigma(X, Y),$$

and

$$(22) \quad \nabla_X \xi = -X - \eta(X)\xi,$$

for all $X, Y \in \Gamma(TM)$.

LEMMA 2.1. *Let M be an invariant submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. The second fundamental form σ of M is parallel if and only if M is totally geodesic.*

Proof. Let's assume that σ is parallel. Then (13) yields to

$$\nabla_X^\perp \sigma(Y, Z) - \sigma(\nabla_X Y, Z) - \sigma(Y, \nabla_X Z) = 0,$$

for all $X, Y, Z \in \Gamma(TM)$. Here, taking $Z = \xi$, by virtue of (21) and (22), we reach at

$$-\sigma(\nabla_X Y, \xi) - \sigma(Y, \nabla_X \xi) = -\sigma(Y, -X - \eta(X)\xi) = \sigma(Y, X) = 0$$

This proves our assertion. The converse is obvious. \square

Lemma 2.1 is important for later theorems and propositions.

THEOREM 2.2. *Let M be an invariant pseudoparallel submanifold of a Lorentzian para-Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is either totally geodesic or $L_1 = 1$.*

Proof. Let M be pseudoparallel submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}(\varphi, \xi, \eta, g)$, then from (17) we have

$$(\widetilde{R}(X, Y) \cdot \sigma)(U, V) = L_1 Q(g, \sigma)(U, V; X, Y),$$

for all $X, Y, U, V \in \Gamma(TM)$. This implies that

$$\begin{aligned} R^\perp(X, Y)\sigma(U, V) &= \sigma(R(X, Y)U, V) - \sigma(U, R(X, Y)V) \\ &= -L_1\{\sigma((X \wedge_g Y)U, V) + \sigma(U, (X \wedge_g Y)V)\} \\ &= -L_1\{\sigma(g(Y, U)X - g(X, U)Y, V) \\ &+ \sigma(U, g(Y, V)X - g(X, V)Y)\} \end{aligned} \quad (23)$$

for all $X, Y, U, V \in \Gamma(TM)$. Taking $V = \xi$ in (23) and taking into account of (21), we obtain

$$\begin{aligned} \sigma(R(X, Y)\xi, U) &= L_1\{\eta(Y)\sigma(X, U) - \eta(X)\sigma(U, Y)\} \\ \sigma(\eta(X)Y - \eta(Y)X, U) &= L_1\{\eta(Y)\sigma(X, U) - \eta(X)\sigma(U, Y)\} \end{aligned}$$

This completes the proof. \square

From the Theorem 2.2, we have the following proposition.

PROPOSITION 2.3. *Let M be an invariant pseudoparallel submanifold of a Lorentzian para-Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is semiparallel if and only if M is totally geodesic.*

THEOREM 2.4. *Let M be an invariant 2-pseudoparallel submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is either totally geodesic or $L_2 = 1$.*

Proof. Let M be 2-pseudoparallel of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then from (18), we have

$$(\widetilde{R}(X, Y) \cdot \widetilde{\nabla}\sigma)(U, V, Z) = L_2Q(g, \widetilde{\nabla}\sigma)(U, V, Z; X, Y),$$

for all $X, Y, U, V, Z \in \Gamma(TM)$. This means that

$$\begin{aligned} &R^\perp(X, Y)(\widetilde{\nabla}_U\sigma)(V, Z) - (\widetilde{\nabla}_{R(X, Y)U}\sigma)(V, Z) - (\widetilde{\nabla}_U\sigma)(R(X, Y)V, Z) \\ &- (\widetilde{\nabla}_U\sigma)(V, R(X, Y)Z) = -L_2\{(\widetilde{\nabla}_{(X \wedge_g Y)U}\sigma)(V, Z) + (\widetilde{\nabla}_U\sigma)((X \wedge_g Y)V, Z) \\ &+ (\widetilde{\nabla}_U\sigma)(V, (X \wedge_g Y)Z)\}, \end{aligned}$$

that is,

$$\begin{aligned} &R^\perp(X, Y)(\widetilde{\nabla}_U\sigma)(V, Z) - (\widetilde{\nabla}_{R(X, Y)U}\sigma)(V, Z) - (\widetilde{\nabla}_U\sigma)(R(X, Y)V, Z) \\ &- (\widetilde{\nabla}_U\sigma)(V, R(X, Y)Z) = -L_2\{g(Y, U)(\widetilde{\nabla}_X\sigma)(V, Z) - g(X, U)(\widetilde{\nabla}_Y\sigma)(V, Z) \\ &+ (\widetilde{\nabla}_U\sigma)(g(Y, V)X - g(X, V)Y, Z) + (\widetilde{\nabla}_U\sigma)(V, g(Y, Z)X - g(X, Z)Y)\}. \end{aligned}$$

In the last equality, taking $X = Z = \xi$ and the after necessary arrangements are made, we obtain

$$\begin{aligned} (24) \quad R^\perp(\xi, Y)(\widetilde{\nabla}_U\sigma)(V, \xi) &- (\widetilde{\nabla}_{R(\xi, Y)U}\sigma)(V, \xi) - (\widetilde{\nabla}_U\sigma)(R(\xi, Y)V, \xi) \\ &- (\widetilde{\nabla}_U\sigma)(V, R(\xi, Y)\xi) = -L_2\{g(Y, U)(\widetilde{\nabla}_\xi\sigma)(V, \xi) \\ &- \eta(U)(\widetilde{\nabla}_Y\sigma)(V, \xi) + (\widetilde{\nabla}_U\sigma)(g(Y, V)\xi - \eta(V)Y, \xi) \\ &+ (\widetilde{\nabla}_U\sigma)(V, \eta(Y)\xi + Y)\}. \end{aligned}$$

Now, let us calculate each of these expressions. Making use of (13), (21) and (22), we obtain

$$\begin{aligned} (25) \quad R^\perp(\xi, Y)(\widetilde{\nabla}_U\sigma)(V, \xi) &= R^\perp(\xi, Y)\{\nabla_U^\perp\sigma(V, \xi) - \sigma(\nabla_U V, \xi) \\ &- \sigma(V, \nabla_U \xi)\} \\ &= R^\perp(\xi, Y)\{-\sigma(V, \nabla_U \xi)\} \\ &= -R^\perp(\xi, Y)\sigma(V, -U - \eta(U)\xi) \\ &= R^\perp(\xi, Y)\sigma(V, U). \end{aligned}$$

Moreover, taking into account of (7) and (22), we have

$$\begin{aligned} (26) \quad (\widetilde{\nabla}_{R(\xi, Y)U}\sigma)(V, \xi) &= \nabla_{R(\xi, Y)U}^\perp\sigma(V, \xi) - \sigma(\nabla_{R(\xi, Y)U} V, \xi) \\ &- \sigma(\nabla_{R(\xi, Y)U} \xi, V) \\ &= -\sigma(-R(\xi, Y)U - \eta(R(\xi, Y)U)\xi, V) \\ &= \sigma(R(\xi, Y)U, V) = \sigma(g(Y, U)\xi - \eta(U)Y, V) \\ &= -\eta(U)\sigma(Y, V). \end{aligned}$$

$$\begin{aligned} (27) \quad (\widetilde{\nabla}_U\sigma)(R(\xi, Y)V, \xi) &= \nabla_U^\perp\sigma(R(\xi, Y)V, \xi) - \sigma(\nabla_U R(\xi, Y)V, \xi) \\ &- \sigma(R(\xi, Y)V, \nabla_U \xi) \\ &= -\sigma(R(\xi, Y)V, -U - \eta(U)\xi) \\ &= \sigma(g(Y, V)\xi - \eta(V)Y, U) = -\eta(V)\sigma(Y, U). \end{aligned}$$

$$\begin{aligned}
(\tilde{\nabla}_U \sigma)(V, R(\xi, Y)\xi) &= (\tilde{\nabla}_U \sigma)(V, Y + \eta(Y)\xi) \\
&= (\tilde{\nabla}_U \sigma)(V, Y) + (\tilde{\nabla}_U \sigma)(V, \eta(Y)\xi) \\
&= (\tilde{\nabla}_U \sigma)(V, Y) + \nabla_U^\perp \sigma(V, \eta(Y)\xi) \\
&\quad - \sigma(\nabla_U V, \eta(Y)\xi) - \sigma(V, \nabla_U \eta(Y)\xi) \\
&= (\tilde{\nabla}_U \sigma)(V, Y) - \sigma(V, U\eta(Y)\xi + \eta(Y)\nabla_U \xi) \\
(28) \qquad \qquad \qquad &= (\tilde{\nabla}_U \sigma)(V, Y) + \eta(Y)\sigma(V, U),
\end{aligned}$$

and

$$\begin{aligned}
(\tilde{\nabla}_{(\xi \wedge_g Y)U} \sigma)(V, \xi) &= \nabla_{(\xi \wedge_g Y)U}^\perp \sigma(V, \xi) - \sigma(\nabla_{(\xi \wedge_g Y)U} V, \xi) \\
&\quad - \sigma(V, \nabla_{(\xi \wedge_g Y)U} \xi) = -\sigma(V, \nabla_{g(Y,U)\xi - \eta(U)Y} \xi) \\
&= -\sigma(V, g(Y, U)\nabla_\xi \xi - \eta(U)\nabla_Y \xi) = \eta(U)\sigma(V, \nabla_Y \xi) \\
(29) \qquad \qquad \qquad &= \eta(U)\sigma(V, -Y - \eta(Y)\xi) = -\eta(U)\sigma(V, Y),
\end{aligned}$$

$$\begin{aligned}
(\tilde{\nabla}_U \sigma)((\xi \wedge_g Y)V, \xi) &= \nabla_U^\perp \sigma((\xi \wedge_g Y)V, \xi) - \sigma(\nabla_U ((\xi \wedge_g Y)V, \xi) \\
&\quad - \sigma((\xi \wedge_g Y)V, \nabla_U \xi) \\
&= -\sigma(g(Y, V)\xi - \eta(V)Y, -U - \eta(U)\xi) \\
(30) \qquad \qquad \qquad &= -\eta(V)\sigma(Y, U).
\end{aligned}$$

$$\begin{aligned}
(\tilde{\nabla}_U \sigma)(V, (\xi \wedge_g Y)\xi) &= (\tilde{\nabla}_U \sigma)(V, \eta(Y)\xi + Y) \\
&= (\tilde{\nabla}_U \sigma)(V, \eta(Y)\xi) + (\tilde{\nabla}_U \sigma)(V, Y) \\
&= \nabla_U^\perp \sigma(V, \eta(Y)\xi) - \sigma(\nabla_U V, \eta(Y)\xi) \\
&\quad - \sigma(V, \nabla_U \eta(Y)\xi) + (\tilde{\nabla}_U \sigma)(V, Y) \\
&= -\sigma(V, U\eta(Y)\xi + \eta(Y)\nabla_U \xi) + (\tilde{\nabla}_U \sigma)(V, Y) \\
&= -\eta(Y)\sigma(V, -U - \eta(U)\xi) + (\tilde{\nabla}_U \sigma)(V, Y) \\
(31) \qquad \qquad \qquad &= \eta(Y)\sigma(V, U) + (\tilde{\nabla}_U \sigma)(V, Y).
\end{aligned}$$

Consequently, if we put (25), (26), (27), (28), (29), (30) and (31) in (24), we reach at

$$\begin{aligned}
&R^\perp(\xi, Y)\sigma(V, U) + \eta(U)\sigma(Y, V) + \eta(V)\sigma(Y, U) - (\tilde{\nabla}_U \sigma)(V, Y) \\
&- \eta(Y)\sigma(U, V) = L_2\{\eta(U)\sigma(V, Y) + \eta(V)\sigma(Y, U) - \eta(Y)\sigma(V, U) \\
(32) \qquad \qquad \qquad &- (\tilde{\nabla}_U \sigma)(V, Y)\}
\end{aligned}$$

If taking $X = \xi$ in (32), considering (21) and (5), we get

$$(33) \qquad -\sigma(Y, U) - (\tilde{\nabla}_U \sigma)(Y, \xi) = -L_2\{\sigma(U, Y) + (\tilde{\nabla}_U \sigma)(Y, \xi)\},$$

where

$$\begin{aligned}
(\tilde{\nabla}_U \sigma)(\xi, Y) &= \nabla_U^\perp \sigma(Y, \xi) - \sigma(\nabla_U Y, \xi) - \sigma(Y, \nabla_U \xi) \\
(34) \qquad \qquad \qquad &= -\sigma(Y, -U - \eta(U)\xi) = \sigma(Y, U).
\end{aligned}$$

From (33) and (34), we conclude that

$$(L_2 - 1)\sigma(U, Y) = 0,$$

which is proves our assertions. \square

From Theorem 2.4, we have the following proposition.

PROPOSITION 2.5. *Let M be an invariant pseudoparallel submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is 2-semiparallel if and only if M is totally geodesic.*

THEOREM 2.6. *Let M be an invariant submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then $\widetilde{C} \cdot \sigma = 0$ if and only if M is either totally geodesic or the scalar curvature τ of \widetilde{M}^n is $\tau = n(n - 1)$.*

Proof. $\widetilde{C} \cdot \sigma = 0$ implies that

$$(35) \quad \begin{aligned} (\widetilde{C}(X, Y) \cdot \sigma)(U, V) &= R^\perp(X, Y)\sigma(U, V) - \sigma(\widetilde{C}(X, Y)U, V) \\ &- \sigma(U, \widetilde{C}(X, Y)V) = 0, \end{aligned}$$

for all $X, Y, U, V \in \Gamma(TM)$. On the other hand, from (6) and (9), we can derive

$$(36) \quad \widetilde{C}(X, Y)\xi = \left(1 - \frac{\tau}{n(n - 1)}\right)(\eta(Y)X - \eta(X)Y).$$

Thus, for $V = \xi$, from (35) and (36), we conclude that

$$\sigma(\widetilde{C}(X, Y)\xi, U) = \left(1 - \frac{\tau}{n(n - 1)}\right)\sigma(\eta(Y)X - \eta(X)Y, U) = 0.$$

The proof is completed. □

THEOREM 2.7. *Let M be an invariant Ricci-generalized pseudoparallel submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is either totally geodesic or the function $L_3 = \frac{1}{n-1}$.*

Proof. If M is Ricci-generalized pseudoparallel of a Lorentzian para Kenmotsu manifold $\widetilde{M}(\varphi, \xi, \eta, g)$, then from (15) and (19), we have

$$\begin{aligned} (\widetilde{R}(X, Y) \cdot \sigma)(U, V) &= L_3 Q(S, \sigma)(U, V; X, Y) \\ &= -L_3 \{ \sigma((X \wedge_S Y)U, V) + \sigma(U, (X \wedge_S Y)V) \}, \end{aligned}$$

for all $X, Y, U, V \in \Gamma(TM)$. This means that

$$\begin{aligned} R^\perp(X, Y)\sigma(U, V) &- \sigma(R(X, Y)U, V) - \sigma(U, R(X, Y)V) \\ &= -L_3 \{ \sigma(S(Y, U)X - S(X, U)Y, V) \\ &+ \sigma(S(V, Y)X - S(X, V)Y, U) \}. \end{aligned}$$

Here taking $X = V = \xi$ and by using (7) and (15), we reach at

$$(37) \quad \begin{aligned} R^\perp(\xi, Y)\sigma(U, \xi) &- \sigma(R(\xi, Y)U, \xi) - \sigma(U, R(\xi, Y)\xi) \\ &= -L_3 \{ \sigma(S(Y, U)\xi - S(\xi, U)Y, \xi) \\ &+ \sigma(S(\xi, Y)\xi - S(\xi, \xi)Y, U) \}. \end{aligned}$$

By using (8) and (21), we can infer

$$\begin{aligned} -\sigma(U, Y + \eta(Y)\xi) &= -L_3 \{ -S(\xi, \xi)\sigma(Y, U) \} \\ -\sigma(Y, U) &= -(n - 1)L_3\sigma(Y, U). \end{aligned}$$

This proves our assertion. □

THEOREM 2.8. *Let M be an invariant 2-Ricci-generalized pseudoparallel submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^n(\varphi, \xi, \eta, g)$. Then M is either totally geodesic or $L_4 = \frac{1}{n-1}$.*

Proof. Let us assume that M is 2-Ricci-generalized pseudoparallel submanifold. Then from (20), we have

$$(\tilde{R}(X, Y) \cdot \tilde{\nabla}\sigma)(U, V, Z) = L_4 Q(S, \tilde{\nabla}\sigma)(U, V, Z; X, Y),$$

for all $X, Y, U, V, Z \in \Gamma(TM)$. This implies that

$$\begin{aligned} R^\perp(X, Y)(\tilde{\nabla}_U\sigma)(V, Z) &= (\tilde{\nabla}_{R(X, Y)U}\sigma)(V, Z) - (\tilde{\nabla}_U\sigma)(R(X, Y)V, Z) \\ &= (\tilde{\nabla}_U\sigma)(V, R(X, Y)Z) = -L_4\{(\tilde{\nabla}_{(X \wedge_S Y)U}\sigma)(V, Z) \\ &+ (\tilde{\nabla}_U\sigma)((X \wedge_S Y)V, Z) + (\tilde{\nabla}_U\sigma)(V, (X \wedge_S Y)Z)\}. \end{aligned}$$

Here taking $X = V = \xi$, we have

$$\begin{aligned} R^\perp(\xi, Y)(\tilde{\nabla}_U\sigma)(\xi, Z) &= (\tilde{\nabla}_{R(\xi, Y)U}\sigma)(\xi, Z) - (\tilde{\nabla}_U\sigma)(R(\xi, Y)\xi, Z) \\ &= (\tilde{\nabla}_U\sigma)(\xi, R(\xi, Y)Z) = -L_4\{(\tilde{\nabla}_{(\xi \wedge_S Y)U}\sigma)(\xi, Z) \\ (38) \quad &+ (\tilde{\nabla}_U\sigma)((\xi \wedge_S Y)\xi, Z) + (\tilde{\nabla}_U\sigma)(\xi, (\xi \wedge_S Y)Z)\}. \end{aligned}$$

Now, let's calculate each of these expressions. Also taking into account of (21) and (22), we arrive at

$$\begin{aligned} R^\perp(\xi, Y)(\tilde{\nabla}_U\sigma)(\xi, Z) &= R^\perp(\xi, Y)\{\nabla_U^\perp\sigma(\xi, Z) - \sigma(\nabla_U Z, \xi) \\ &- \sigma(Z, \nabla_U \xi)\} = R^\perp(\xi, Y)\{-\sigma(Z, -U - \eta(U)\xi)\} \\ (39) \quad &= R^\perp(\xi, Y)\sigma(Z, U). \end{aligned}$$

On the other hand, by using (21) and (22), we have

$$\begin{aligned} (\tilde{\nabla}_{R(\xi, Y)U}\sigma)(\xi, Z) &= \nabla_{R(\xi, Y)U}^\perp\sigma(\xi, Z) - \sigma(\nabla_{R(\xi, Y)U}\xi, Z) \\ &- \sigma(\xi, \nabla_{R(\xi, Y)U}Z) \\ &= -\sigma(-R(\xi, Y)U - \eta(R(\xi, Y)U)\xi, Z) \\ &= \sigma(R(\xi, Y)U, Z) = \sigma(g(Y, U)\xi - \eta(U)Y, Z) \\ (40) \quad &= -\eta(U)\sigma(Y, Z), \end{aligned}$$

$$\begin{aligned} (\tilde{\nabla}_U\sigma)(R(\xi, Y)\xi, Z) &= (\tilde{\nabla}_U\sigma)(Y + \eta(Y)\xi, Z) = (\tilde{\nabla}_U\sigma)(Y, Z) \\ &+ (\tilde{\nabla}_U\sigma)(\eta(Y)\xi, Z) = (\tilde{\nabla}_U\sigma)(Y, Z) \\ &+ \nabla_U^\perp\sigma(\eta(Y)\xi, Z) - \sigma(\nabla_U\eta(Y)\xi, Z) \\ &- \sigma(\eta(Y)\xi, \nabla_U Z) \\ &= (\tilde{\nabla}_U\sigma)(Y, Z) - \sigma(U\eta(Y)\xi + \eta(Y)\nabla_U\xi, Z) \\ &= (\tilde{\nabla}_U\sigma)(Y, Z) - \sigma(U\eta(Y)\xi - \eta(Y)(U + \eta(U)\xi), Z) \\ (41) \quad &= (\tilde{\nabla}_U\sigma)(Y, Z) + \eta(Y)\sigma(U, Z). \end{aligned}$$

$$\begin{aligned} (\tilde{\nabla}_U\sigma)(\xi, R(\xi, Y)Z) &= \nabla_U^\perp\sigma(\xi, R(\xi, Y)Z) - \sigma(\nabla_U\xi, R(\xi, Y)Z) \\ &- \sigma(\xi, \nabla_U R(\xi, Y)Z) = -\sigma(-U - \eta(U)\xi, R(\xi, Y)Z) \\ (42) \quad &= -\sigma(-U, g(Y, Z)\xi - \eta(Z)Y) = -\eta(Z)\sigma(U, Y). \end{aligned}$$

Now, let's calculate the left side of (32). Making use of (13), (21) and (22), we have

$$\begin{aligned}
 (\tilde{\nabla}_{(\xi \wedge_S Y)U} \sigma)(\xi, Z) &= \nabla_{(\xi \wedge_S Y)U}^\perp \sigma(\xi, Z) - \sigma(\nabla_{(\xi \wedge_S Y)U} \xi, Z) \\
 &\quad - \sigma(\xi, \nabla_{(\xi \wedge_S Y)U} Z) \\
 &= -\sigma(\nabla_{S(Y,U)\xi - S(\xi,U)Y} \xi, Z) \\
 &= -S(Y, U)\sigma(\nabla_\xi \xi, Z) + S(\xi, U)\sigma(\nabla_Y \xi, Z) \\
 &= (n - 1)\eta(U)\sigma(-Y - \eta(Y)\xi, Z) \\
 (43) \qquad &= -(n - 1)\eta(U)\sigma(Y, Z),
 \end{aligned}$$

$$\begin{aligned}
 (\tilde{\nabla}_U \sigma)((\xi \wedge_S Y)\xi, Z) &= (\tilde{\nabla}_U \sigma)(S(Y, \xi)\xi - S(\xi, \xi)Y, Z) \\
 &= (\tilde{\nabla}_U \sigma)((n - 1)Y + (n - 1)\eta(Y)\xi, Z) \\
 &= (n - 1)\{(\tilde{\nabla}_U \sigma)(Y, Z) + (\tilde{\nabla}_U \sigma)(\eta(Y)\xi, Z)\} \\
 &= (n - 1)\{(\tilde{\nabla}_U \sigma)(Y, Z) + \nabla_U^\perp \sigma(\eta(Y)\xi, Z) \\
 &\quad - \sigma(\nabla_U \eta(Y)\xi, Z) - \sigma(\eta(Y)\xi, \nabla_U Z)\} \\
 &= (n - 1)\{(\tilde{\nabla}_U \sigma)(Y, Z) - \sigma(U\eta(Y)\xi + \eta(Y)\nabla_U \xi, Z)\} \\
 &= (n - 1)\{(\tilde{\nabla}_U \sigma)(Y, Z) - \eta(Y)\sigma(-U - \eta(U)\xi, Z)\} \\
 (44) \qquad &= (n - 1)\{(\tilde{\nabla}_U \sigma)(Y, Z) + \eta(Y)\sigma(U, Z)\}.
 \end{aligned}$$

Finally,

$$\begin{aligned}
 (\tilde{\nabla}_U \sigma)(\xi, (\xi \wedge_S Y)Z) &= (\tilde{\nabla}_U \sigma)(\xi, S(Y, Z)\xi - S(\xi, Z)Y) \\
 &= (\tilde{\nabla}_U \sigma)(\xi, S(Y, Z)\xi) - (n - 1)(\tilde{\nabla}_U \sigma)(\xi, \eta(Z)Y) \\
 &= \nabla_U^\perp \sigma(\xi, S(Y, Z)\xi) - \sigma(\nabla_U \xi, S(Y, Z)\xi) \\
 &\quad - \sigma(\xi, \nabla_U S(Y, Z)\xi) - (n - 1)\{\nabla_U^\perp \sigma(\xi, \eta(Z)Y) \\
 &\quad - \sigma(\nabla_U \xi, \eta(Z)Y) - \sigma(\xi, \nabla_U \eta(Z)Y)\} \\
 &= -(n - 1)\sigma(-U - \eta(U)\xi, Y)\eta(Z) \\
 (45) \qquad &= (n - 1)\eta(Z)\sigma(U, Y).
 \end{aligned}$$

By substituting (39), (40), (41), (42), (43), (44) and (45) into (38) we reach at

$$\begin{aligned}
 R^\perp(\xi, Y)\sigma(U, Z) + \eta(U)\sigma(Y, Z) - (\tilde{\nabla}_U \sigma)(Y, Z) - \eta(Y)\sigma(U, Z) \\
 + \eta(Z)\sigma(U, Y) &= (n - 1)L_4\{\eta(U)\sigma(Y, Z) - \eta(Y)\sigma(U, Z) \\
 (46) \qquad - (\tilde{\nabla}_U \sigma)(Y, Z) + \eta(Z)\sigma(U, Y)\}.
 \end{aligned}$$

Here if taking $Z = \xi$ in (46), we can easily to see that

$$(n - 1)L_4\{(\tilde{\nabla}_U \sigma)(Y, \xi) + \sigma(U, Y)\} = (\tilde{\nabla}_U \sigma)(Y, \xi) + \sigma(U, Y).$$

From (34), we conclude that

$$((n - 1)L_4 - 1)\sigma(U, Y) = 0,$$

which proves our assertion. □

EXAMPLE 2.9. Let us consider the 5-dimensional manifold

$$\widetilde{M}^5 = \{(x_1, x_2, x_3, x_4, z) : z > 0\},$$

where (x_1, x_2, x_3, x_4, z) denote the standard coordinates of \mathbb{R}^5 . Then let e_1, e_2, e_3, e_4, e_5 be vector fields on \widetilde{M}^5 by given

$$e_1 = z \frac{\partial}{\partial x_1}, e_2 = z \frac{\partial}{\partial x_2}, e_3 = z \frac{\partial}{\partial x_3}, e_4 = z \frac{\partial}{\partial x_4}, e_5 = z \frac{\partial}{\partial z}$$

which are linearly independent at each point at each point \widetilde{M}^5 and we define a Lorentzian metric tensor g on \widetilde{M}^5 as

$$\begin{aligned} g(e_i, e_i) &= 1, \quad 1 \leq i \leq 4 \\ g(e_i, e_j) &= 0, \quad 1 \leq i \neq j \leq 5 \\ g(e_5, e_5) &= -1. \end{aligned}$$

Let η be the 1-form defined by $\eta(X) = g(X, e_5)$ for all $X \in \Gamma(T\widetilde{M})$. Now, we define the tensor field (1,1)-type φ such that

$$\varphi e_1 = -e_2, \quad \varphi e_3 = -e_4, \quad \varphi e_5 = 0.$$

Then for $X = x_i e_i, Y = y_j e_j \in \Gamma(T\widetilde{M}), 1 \leq i, j \leq 5$, we can easily see that

$$\varphi^2 X = X + \eta(X)\xi, \quad \xi = e_5, \quad \eta(X) = g(X, \xi)$$

and

$$g(\varphi X, \varphi Y) = g(X, Y) + \eta(X)\eta(Y).$$

By direct calculations, only non-vanishing components are

$$[e_i, e_5] = -e_i, \quad 1 \leq i \leq 4.$$

From Kozsul's formula, we can compute

$$\widetilde{\nabla}_{e_i} e_5 = -e_i, \quad 1 \leq i \leq 4.$$

Thus for $X = x_i e_i, Y = y_j e_j \in \Gamma(T\widetilde{M})$, we have

$$\widetilde{\nabla}_X \xi = -X - \eta(X)\xi, \quad \text{and} \quad (\widetilde{\nabla}_X \varphi)Y = -g(\varphi X, Y)\xi - \eta(Y)\varphi X,$$

that is, $\widetilde{M}^5(\varphi, \xi, \eta, g)$ is a Lorentzian para Kenmotsu manifold.

Now, we consider the 3-dimensional submanifold M^3 of $\widetilde{M}^5(\varphi, \xi, \eta, g)$ given by ψ -immersion

$$\begin{aligned} \psi : M^3 &\longrightarrow \widetilde{M}^5(\varphi, \xi, \eta, g) \\ \psi(x_1, x_2, z) &= (zx_1, zx_2, zx_1, zx_2, \frac{1}{2}z^2). \end{aligned}$$

Then the tangent space of submanifold M is spanned by the vector fields

$$U = z \frac{\partial}{\partial x_1} + z \frac{\partial}{\partial x_3} = e_1 + e_3, \quad V = z \frac{\partial}{\partial x_2} + z \frac{\partial}{\partial x_4} = e_2 + e_4, \quad \xi = z \frac{\partial}{\partial z}.$$

Thus we can see that $\varphi U = \varphi(e_1 + e_3) = -e_2 - e_4 = -V$. This verifies M is a 3-dimensional invariant submanifold of a Lorentzian para Kenmotsu manifold $\widetilde{M}^5(\varphi, \xi, \eta, g)$. On the other hand, we can easily that $\widetilde{\nabla}_U V = \widehat{\nabla}_V U = 0, \widetilde{\nabla}_U \xi = -U, \widetilde{\nabla}_V \xi = -V$. Also this tells us that M is pseudoparallel, 2-pseudoparallel, Ricci-generalized pseudoparallel and 2-Ricci generalized pseudoparallel.

References

- [1] S. K. Hui., V. N. Mishra, T., Pal and Vandana, *Some Classes of Invariant Submanifolds of $(LCS)_n$ -Manifolds*, Italian J. of Pure and Appl. Math. **39** (2018), 359–372.
- [2] V. Venkatesha and S. Basavarajappa, *Invariant Submanifolds of LP-Sasakian Manifolds*, Khayyam J. Math. **6** (1) (2020), 16–26.
- [3] S. Sular., C. Özgür and C. Murathan, *Pseudoparallel Anti-Invariant Submanifolds of Kenmotsu Manifolds*, Hacettepe J. of Math. and Stat. **39** (4) (2010), 535–543.
- [4] B. C. Montano., L. D. Terlizzi and M.M Tripathi, *Invariant Submanifolds of Contact (κ, μ) -Manifolds*, Glasgow Math. J. **50** (2008), 499–507.
- [5] M. S., Siddesha and C. S Bagewadi, *Invariant Submanifolds of (κ, μ) -Contact Manifolds Admitting Quarter Symmetric Metric Connection*, International J. of Math. Trends and Tech(IJMTT). **34** (2) (2016), 48–53.
- [6] S. Koneyuki and F. L. Williams, *Almost paracontact and parahodge Structures on Manifolds*, Nagoya Math.J. **90** (1985), 173–187.
- [7] S. Zamkovay, *Canonical Connections on Paracontact Manifolds*, Ann. Global Geom. **36** (2009), 37–60.
- [8] B. C. Montano., I. K. Erken and C. Murathan, *Nullity Conditions in Paracontact Geometry*, Differential Geom. Appl. **30** (2010), 79–100.
- [9] D. G. Prakasha and K. Mirji, *On (κ, μ) -Paracontact Metric Manifolds*, Gen. Math. Notes. **25** (2) (2014), 68–77.
- [10] S. Zamkovay, *Canonical Connections on Paracontact Manifolds*, Ann. Glob. Anal. Geom. **36** (2009), 68–77.
- [11] M. Atçeken., Ü. Yıldırım and S. Dirik, *Semiparallel Submanifolds of a Normal Paracontact Metric Manifold*, Hacet. J. Math. Stat. **48** (2) (2019), 501–509.
- [12] D. E. Blair, T. Koufogiorgos, B. J. Papatoniou, *Contact Metric Manifolds Satisfying a Nullity Conditions*, Israel J. Math. **91** (1995), 189–214.
- [13] Venkatesha and D. M. Naik, *Certain Results on K-Paracontact and Para Sasakian Manifolds*, J. Geom. **108** (2017), 939–052.

Mehmet Atçeken

Department of Mathematics, Aksaray University, 68100, Aksaray Turkey.

E-mail: mehmet.atceken382@gmail.com