

Nonlinear Functional Analysis and Applications

Vol. 27, No. 4 (2022), pp. 757-771

ISSN: 1229-1595(print), 2466-0973(online)

<https://doi.org/10.22771/nfaa.2022.27.04.05>

<http://nfaa.kyungnam.ac.kr/journal-nfaa>

Copyright © 2022 Kyungnam University Press



**SOME FIXED POINT THEOREMS FOR RATIONAL
 (α, β, Z) -CONTRACTION MAPPINGS UNDER
SIMULATION FUNCTIONS AND CYCLIC
 (α, β) -ADMISSIBILITY**

**Snehlata Mishra¹, Anil Kumar Dubey², Urmila Mishra³
and Ho Geun Hyun⁴**

¹Dr. C. V. Raman University, Kargi Road, Kota,
Bilaspur (Chhattisgarh), PIN-491001, India
e-mail: snehmis76@gmail.com

²Department of Mathematics, Bhilai Institute of Technology,
Bhilai House, Durg (Chhattisgarh), India
e-mail: anilkumardby70@gmail.com

³Department of Mathematics, Vishwavidyalaya Engineering College,
(A Constituent College of CSVTU, Bhilai)
Ambikapur(Chhattisgarh), India
e-mail: mishra.urmila@gmail.com

⁴Department of Mathematics Education, Kyungnam University,
Changwon, Gyeongnam, 51767, Korea
e-mail: hyunhg8285@kyungnam.ac.kr

Abstract. In this paper, we present some fixed point theorems for rational type contractive conditions in the setting of a complete metric space via a cyclic (α, β) -admissible mapping imbedded in simulation function. Our results extend and generalize some previous works from the existing literature. We also give some examples to illustrate the obtained results.

⁰Received November 20, 2021. Revised May 17, 2022. Accepted June 21, 2022.

⁰2020 Mathematics Subject Classification: 47H10, 54H25.

⁰Keywords: Fixed point, metric space, simulation function, rational (α, β, Z) -contraction mapping, cyclic (α, β) -admissible mapping.

⁰Corresponding author: Urmila Mishra(mishra.urmila@gmail.com),
H. G. Hyun(hyunhg8285@kyungnam.ac.kr).

1. INTRODUCTION

Recently, Samet et al. [18] proved a generalization of Banach contraction principle by introducing the notion of $\alpha - \psi$ contractive type mappings and α -admissible mappings. This concept is further generalized by many authors ([3, 5, 6, 13]) by introducing generalized $\alpha - \psi$ contractive type mapping and α -admissible mapping in different metric spaces.

The concept of cyclic (α, β) -admissible mapping was introduced by Alizadeh et al. [1] by generalizing the concept of α -admissible mapping of Samet et al. [18]. They proved various fixed point theorems in the setting of metric spaces. Also, Khojasteh et al. [14] introduced the notion of z -contraction by defining the concept of simulation function. The concept of Khojasteh et al. [14] is further modified by Argoubi et al. [4]. They proved the existence of common fixed point results of a pair of nonlinear operators satisfying a certain contractive condition involving simulation functions, in the setting of ordered metric spaces. Afterward, several authors discussed the existence of fixed point by using the simulation function, for instance see ([2, 7, 9, 10, 11, 12, 15, 16, 17]).

In this paper, we consider rational (α, β, Z) contraction mappings under simulation functions involving a cyclic (α, β) -admissibility in a metric space. For this kind of contractions, we establish some fixed point results. Our results are generalization and extension of the results [9] and [16]. For more results of rational type contractions and Z -contraction we refer the paper in ([7, 8, 9, 11, 12, 16, 17]) and references cited therein.

Now we will give some basic definitions and results in metric spaces before presenting our main results.

2. PRELIMINARIES

Alizadeh et al. [1] introduced the notion of cyclic (α, β) -admissible mapping which is defined as follows:

Definition 2.1. ([1]) Let X be a nonempty set, f be a self-mapping on X and $\alpha, \beta : X \rightarrow [0, +\infty)$ be two mappings. We say that f is a cyclic (α, β) -admissible mapping if $x \in X$ with

$$\alpha(x) \geq 1 \Rightarrow \beta(f(x)) \geq 1$$

and

$$\beta(x) \geq 1 \Rightarrow \alpha(f(x)) \geq 1. \tag{2.1}$$

In 2015, Khojasteh et al. [14] introduced the class of simulation functions as given below and by using this definition they proved the following theorem:

Definition 2.2. Let $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ be a mapping. Then ζ is called a simulation function if it satisfies the following conditions:

- (ζ_1) $\zeta(0, 0) = 0$;
- (ζ_2) $\zeta(t, s) < s - t$ for all $t, s > 0$;
- (ζ_3) if $\{t_n\}$ and $\{s_n\}$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n = l > 0$, then $\limsup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$.

Theorem 2.3. ([14]) Let (X, d) be a complete metric space and $T : X \rightarrow X$ be a Z -contraction mapping with respect to a simulation function ζ , that is,

$$\zeta(d(Tx, Ty), d(x, y)) \geq 0,$$

for all $x, y \in X$. Then T has a unique fixed point.

It is worth mentioning that the Banach contraction is an example of Z -contraction by defining $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ via $\zeta(t, s) = \gamma s - t$ for all $s, t \in [0, \infty)$, where $\gamma \in [0, 1)$.

Argoubi et al.[4] modified the definition of [14] as follows:

Definition 2.4. A simulation function is a function $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ that satisfies the following conditions

- (1) $\zeta(t, s) < s - t$ for all $t, s > 0$;
- (2) if $\{t_n\}$ and $\{s_n\}$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n = l > 0$, then $\limsup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0$.

It is clear that any simulation function in the sense of Khojasteh et al. [14] (Definition 2.2) is also a simulation function in the sense of Argoubi et al. [4] (Definition 2.4). The following example is a simulation function in the sense of Argoubi et al. [4].

Example 2.5. Define a function $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ by

$$\zeta(t, s) = \begin{cases} 1, & \text{if } (s, t) = (0, 0); \\ \lambda s - t, & \text{if otherwise,} \end{cases}$$

where $\lambda \in (0, 1)$. Then ζ is a simulation function.

3. MAIN RESULTS

Now, we are ready to prove our result with the following definitions.

Definition 3.1. Let (X, d) be a complete metric space, $T : X \rightarrow X$ be a mapping and $\alpha, \beta : X \rightarrow [0, \infty)$ be two functions. Then T is said to be a rational (α, β, Z) -contraction mapping if it satisfies the following conditions:

- (1) T is cyclic (α, β) -admissible,

(2) there exists a simulation function $\zeta \in Z$ such that

$$\alpha(x)\beta(y) \geq 1 \Rightarrow \zeta(d(Tx, Ty), M(x, y)) \geq 0, \quad (3.1)$$

holds for all $x, y \in X$, where

$$M(x, y) = \max \left\{ d(x, y), \frac{d(x, Tx)d(y, Ty)}{1 + d(x, y)}, \frac{d(x, Tx)d(y, Ty)}{1 + d(Tx, Ty)} \right\}.$$

Theorem 3.2. *Let (X, d) be a complete metric space, $T : X \rightarrow X$ be a mapping and $\alpha, \beta : X \rightarrow [0, \infty)$ be two functions. Suppose that the following conditions hold:*

- (1) T is a rational (α, β, Z) -contraction mapping.
- (2) There exists an element $x_0 \in X$ such that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$.
- (3) T is continuous.

Then T has a fixed point $u \in X$.

Proof. Assume that there exists $x_0 \in X$ such that $\alpha(x_0) \geq 1$. We divide our proof into the following three steps:

Step 1. Define a sequence $\{x_n\}$ in X such that $x_{n+1} = Tx_n$ for all $n \in \mathbb{N} \cup \{0\}$. If $x_n = x_{n+1}$ for all $n \in \mathbb{N} \cup \{0\}$, then T has a fixed point and the proof is finished. Hence, we assume that $x_n \neq x_{n+1}$ for some $n \in \mathbb{N} \cup \{0\}$, that is $d(x_n, x_{n+1}) \neq 0$ for $n \in \mathbb{N} \cup \{0\}$. Since T is a cyclic (α, β) -admissible mapping, $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$,

$$\beta(x_1) = \beta(Tx_0) \geq 1.$$

It implies that

$$\alpha(x_2) = \alpha(Tx_1) \geq 1.$$

And also, we have

$$\alpha(x_1) = \alpha(Tx_0) \geq 1.$$

It implies that

$$\beta(x_2) = \beta(Tx_1) \geq 1.$$

By the continuing the above process, we have $\alpha(x_n) \geq 1$ and $\beta(x_n) \geq 1$, for all $n \in \mathbb{N} \cup \{0\}$. Thus $\alpha(x_n)\beta(x_{n+1}) \geq 1$, for all $n \in \mathbb{N} \cup \{0\}$. Therefore, we get

$$\zeta(d(Tx_n, Tx_{n+1}), M(x_n, x_{n+1})) \geq 0 \quad (3.2)$$

for all $n \in \mathbb{N}$, where

$$\begin{aligned}
 M(x_n, x_{n+1}) &= \max \left\{ d(x_n, x_{n+1}), \frac{d(x_n, Tx_n)d(x_{n+1}, Tx_{n+1})}{1 + d(x_n, x_{n+1})}, \right. \\
 &\quad \left. \frac{d(x_n, Tx_n)d(x_{n+1}, Tx_{n+1})}{1 + d(Tx_n, Tx_{n+1})} \right\} \\
 &= \max \left\{ d(x_n, x_{n+1}), \frac{d(x_n, x_{n+1})d(x_{n+1}, x_{n+2})}{1 + d(x_n, x_{n+1})}, \right. \\
 &\quad \left. \frac{d(x_n, x_{n+1})d(x_{n+1}, x_{n+2})}{1 + d(x_{n+1}, x_{n+2})} \right\} \\
 &= \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\}. \tag{3.3}
 \end{aligned}$$

It follows that

$$\zeta(d(x_{n+1}, x_{n+2}), \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\}) \geq 0. \tag{3.4}$$

(ζ_2) of Definition 2.2 implies that

$$\begin{aligned}
 0 &\leq \zeta(d(x_{n+1}, x_{n+2}), \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\}) \\
 &< \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\} - d(x_{n+1}, x_{n+2}).
 \end{aligned}$$

Thus, we conclude that

$$d(x_{n+1}, x_{n+2}) < \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\} \tag{3.5}$$

for all $n \geq 1$. From (3.5), we have

$$d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1}) \text{ for all } n \geq 1. \tag{3.6}$$

It follows that the sequence $\{d(x_n, x_{n+1})\}$ is nonincreasing. Therefore, there exists $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = r.$$

Note that if $r \neq 0$, that is $r > 0$, then by (ζ_2) of Definition 2.2, we have

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})) < 0,$$

which is a contradiction. This implies that $r = 0$, that is

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = 0. \tag{3.7}$$

Step 2. Now, we prove that $\{x_n\}$ is a Cauchy sequence. Suppose to the contrary, that is, $\{x_n\}$ is not a Cauchy sequence. Then there exists $\epsilon > 0$ and two subsequences $\{x_{m(k)}\}$ and $\{x_{n(k)}\}$ of $\{x_n\}$ with $m(k) > n(k) > k$ and $m(k)$ is the smallest index in \mathbb{N} such that

$$d(x_{n(k)}, x_{m(k)}) \geq \epsilon.$$

So, $d(x_{n(k)}, x_{m(k)-1}) < \epsilon$. Triangular inequality implies that

$$\begin{aligned} \epsilon &\leq d(x_{n(k)}, x_{m(k)}) \\ &\leq d(x_{n(k)}, x_{m(k)-1}) + d(x_{m(k)-1}, x_{m(k)}) \\ &< \epsilon + d(x_{m(k)-1}, x_{m(k)}). \end{aligned}$$

Taking $k \rightarrow \infty$ in the above inequality and using (3.7), we get

$$\lim_{k \rightarrow \infty} d(x_{n(k)}, x_{m(k)}) = \epsilon. \quad (3.8)$$

Again, by triangular inequality, we have

$$\begin{aligned} d(x_{n(k)-1}, x_{m(k)-1}) &\leq d(x_{n(k)-1}, x_{n(k)}) + d(x_{n(k)}, x_{m(k)}) \\ &\quad + d(x_{m(k)}, x_{m(k)-1}) \\ &\leq d(x_{n(k)-1}, x_{n(k)}) + d(x_{n(k)}, x_{n(k)-1}) \\ &\quad + d(x_{n(k)-1}, x_{m(k)}) + d(x_{m(k)}, x_{m(k)-1}) \\ &\leq 2d(x_{n(k)}, x_{n(k)-1}) + d(x_{n(k)-1}, x_{m(k)-1}) \\ &\quad + d(x_{m(k)-1}, x_{m(k)}) + d(x_{m(k)}, x_{m(k)-1}) \\ &\leq 2d(x_{n(k)}, x_{n(k)-1}) + d(x_{m(k)-1}, x_{n(k)-1}) \\ &\quad + 2d(x_{m(k)-1}, x_{m(k)}). \end{aligned}$$

Taking $k \rightarrow \infty$ in the above inequality and using (3.7) and (3.8), we get

$$\begin{aligned} \lim_{k \rightarrow \infty} d(x_{n(k)}, x_{m(k)}) &= \lim_{k \rightarrow \infty} d(x_{n(k)-1}, x_{m(k)-1}) \\ &= \epsilon. \end{aligned} \quad (3.9)$$

Since $\alpha(x_n) \geq 1$ and $\beta(x_n) \geq 1$ for all $n = 1, 2, 3, \dots$, we conclude that

$$\alpha(x_{n(k)-1})\beta(x_{m(k)-1}) \geq 1.$$

Since T is a rational (α, β, Z) -contraction, we have

$$\zeta(d(Tx_{n(k)-1}, Tx_{m(k)-1}), M(x_{n(k)-1}, x_{m(k)-1})) \geq 0 \quad (3.10)$$

for all $x, y \in X$, where

$$\begin{aligned}
 M(x_{n_{(k)-1}}, x_{m_{(k)-1}}) &= \max \left\{ d(x_{n_{(k)-1}}, x_{m_{(k)-1}}), \right. \\
 &\quad \frac{d(x_{n_{(k)-1}}, Tx_{n_{(k)-1}})d(x_{m_{(k)-1}}, Tx_{m_{(k)-1}})}{1 + d(x_{n_{(k)-1}}, x_{m_{(k)-1}})}, \\
 &\quad \left. \frac{d(x_{n_{(k)-1}}, Tx_{n_{(k)-1}})d(x_{m_{(k)-1}}, Tx_{m_{(k)-1}})}{1 + d(Tx_{n_{(k)-1}}, Tx_{m_{(k)-1}})} \right\} \\
 &= \max \left\{ d(x_{n_{(k)-1}}, x_{m_{(k)-1}}), \right. \\
 &\quad \frac{d(x_{n_{(k)-1}}, x_{n_{(k)}})d(x_{m_{(k)-1}}, x_{m_{(k)}})}{1 + d(x_{n_{(k)-1}}, x_{m_{(k)-1}})}, \\
 &\quad \left. \frac{d(x_{n_{(k)-1}}, x_{n_{(k)}})d(x_{m_{(k)-1}}, x_{m_{(k)}})}{1 + d(x_{n_{(k)}}, x_{m_{(k)}})} \right\} \\
 &= \max \{d(x_{n_{(k)-1}}, x_{m_{(k)-1}}), d(x_{n_{(k)-1}}, x_{n_{(k)}})\}.
 \end{aligned}$$

By (3.7) and (3.9), we conclude that

$$\lim_{n \rightarrow \infty} M(x_{n_{(k)-1}}, x_{m_{(k)-1}}) = \epsilon. \tag{3.11}$$

Note that by (ζ_2) and (ζ_3) of Definition 2.2, implies that

$$0 \leq \limsup \zeta(d(Tx_{n_{(k)-1}}, Tx_{m_{(k)-1}}), M(x_{n_{(k)-1}}, x_{m_{(k)-1}})) < 0,$$

which is a contradiction. Thus $\{x_n\}$ is a Cauchy sequence.

Step 3. Finally, we prove that T has a fixed point. Since $\{x_n\}$ is a Cauchy sequence in the complete metric space X , there exists a $x^* \in X$ such that $x_n \rightarrow x^*$. The continuity of T implies that $Tx_{2n} \rightarrow Tx^*$. Since $x_{2n+1} = Tx_{2n}$ and $x_{2n+1} \rightarrow x^*$, by uniqueness of limit, we get $Tx^* = x^*$. So x^* is a fixed point of T . This completes the proof. \square

We begin our next result with the following definitions and notations.

Definition 3.3. We denote by Ψ the family of all nondecreasing functions $\psi : [0, \infty) \rightarrow [0, \infty)$ such that

- (Ψ_1) ψ is a continuous;
- (Ψ_2) $\psi^{-1}(\{0\}) = 0$.

Definition 3.4. Let (X, d) be a complete metric space, $T : X \rightarrow X$ be a mapping and $\alpha, \beta : X \rightarrow [0, \infty)$ be two functions. Then T is said to be a generalized rational (α, β, Z) -contraction mapping if T satisfies the following conditions:

- (1) T is a cyclic (α, β) -admissible,
- (2) there exists a simulation function $\zeta \in Z$ such that

$$\alpha(x)\beta(y) \geq 1 \Rightarrow \zeta(\psi(d(Tx, Ty)), \psi(m(x, y))) \geq 0 \quad (3.12)$$

hold for all $x, y \in X$, where

$$m(x, y) = \max \left\{ d(y, Ty) \frac{1 + d(x, Tx)}{1 + d(x, y)}, \frac{d(x, Tx)d(x, Ty) + d(y, Ty)d(y, Tx)}{d(x, Ty) + d(y, Tx)} \right\}.$$

From now on, let (X, d) be a metric space and let $\alpha, \beta : X \rightarrow [0, \infty)$ be functions, $\psi \in \Psi$ and $\zeta \in Z$.

Theorem 3.5. *Let (X, d) be a complete metric space, and let $T : X \rightarrow X$ be a generalized rational (α, β, Z) - contraction mapping with respect to ζ . Suppose that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$, where $x_0 \in X$. Assume that either*

- (1) *T is continuous or*
- (2) *if $\{x_n\} \subset X$ is a sequence such that $\lim_{n \rightarrow \infty} d(x_n, x) = 0$ and for all $n = 1, 2, 3, \dots$,*

$$\beta(x_n) \geq 1. \quad (3.13)$$

If $T : X \rightarrow X$ is cyclic (α, β) -admissible, then T has a fixed point in X . Further if $\alpha(x)\beta(y) \geq 1$ for all fixed points x, y of T , then T has a unique fixed point.

Proof. Let $x_0 \in X$ be a point such that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$. Define a sequence $\{x_n\} \subset X$ by $x_{n+1} = Tx_n$ for all $n = 0, 1, 2, \dots$. If $x_n = x_{n_0+1}$ for some $n_0 \in \mathbb{N}$, then x_{n_0} is a fixed point of T , and proof is completed. Assume that $x_n \neq x_{n+1}$ for all $n = 0, 1, 2, \dots$. Since T is cyclic (α, β) -admissible and $\alpha(x_0) \geq 1$, $\beta(x_1) = \beta(Tx_0) \geq 1$, we have $\alpha(x_2) = \alpha(Tx_1) \geq 1$. By continuing this process, we have $\alpha(x_{2n}) \geq 1$ and $\beta(x_{2n+1}) \geq 1$ for all $n = 0, 1, 2, \dots$. Again, since T is cyclic (α, β) -admissible and $\beta(x_0) \geq 1$, $\alpha(x_1) = \alpha(Tx_0) \geq 1$ and $\beta(x_2) = \beta(Tx_1) \geq 1$.

Recursively, we obtain that

$$\beta(x_{2n}) \geq 1 \quad \text{and} \quad \alpha(x_{2n+1}) \geq 1$$

for all $n = 0, 1, 2, \dots$. Hence,

$$\alpha(x_n) \geq 1 \quad \text{and} \quad \beta(x_n) \geq 1$$

for all $n = 0, 1, 2, \dots$, and hence

$$\alpha(x_{n-1})\beta(x_n) \geq 1 \quad \text{for all } n = 0, 1, 2, \dots$$

Now for all $n = 1, 2, 3, \dots$,

$$\begin{aligned}
 m(x_{n-1}, x_n) &= \max \left\{ d(x_n, Tx_n) \frac{1 + d(x_{n-1}, Tx_{n-1})}{1 + d(x_{n-1}, x_n)}, \right. \\
 &\quad \left. \frac{d(x_{n-1}, Tx_{n-1})d(x_{n-1}, Tx_n) + d(x_n, Tx_n)d(x_n, Tx_{n-1})}{d(x_{n-1}, Tx_n) + d(x_n, Tx_{n-1})} \right\} \\
 &= \max \left\{ d(x_n, x_{n+1}) \frac{1 + d(x_{n-1}, x_n)}{1 + d(x_{n-1}, x_n)}, \right. \\
 &\quad \left. \frac{d(x_{n-1}, x_n)d(x_{n-1}, x_{n+1}) + d(x_n, x_{n+1})d(x_n, x_n)}{d(x_{n-1}, x_{n+1}) + d(x_n, x_n)} \right\} \\
 &= \max\{d(x_n, x_{n+1}), d(x_{n-1}, x_n)\}. \tag{3.14}
 \end{aligned}$$

It follows from (3.12) and (3.14), we have

$$\begin{aligned}
 0 &\leq \zeta(\psi(d(Tx_{n-1}, Tx_n)), \psi(m(x_{n-1}, x_n))) \\
 &= \zeta(\psi(d(x_n, x_{n+1})), \psi(\max\{d(x_n, x_{n+1}), d(x_{n-1}, x_n)\})) \\
 &< \psi(\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\}) - \psi(d(x_n, x_{n+1})). \tag{3.15}
 \end{aligned}$$

Consequently, we obtain that for all $n = 1, 2, 3, \dots$,

$$\psi(d(x_n, x_{n+1})) < \psi(\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\}).$$

If $\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} = d(x_n, x_{n+1})$ for some n , then

$$\psi(d(x_n, x_{n+1})) < \psi(d(x_n, x_{n+1})),$$

which is a contradiction. Hence $\max\{d(x_{n-1}, x_n), d(x_n, x_{n+1})\} = d(x_{n-1}, x_n)$ for all $n = 1, 2, 3, \dots$ and hence from (3.15)

$$\begin{aligned}
 0 &\leq \zeta(\psi(d(x_n, x_{n+1})), \psi(d(x_{n-1}, x_n))) \\
 &< \psi(d(x_{n-1}, x_n)) - \psi(d(x_n, x_{n+1})), \tag{3.16}
 \end{aligned}$$

which implies

$$\psi(d(x_n, x_{n+1})) < \psi(d(x_{n-1}, x_n))$$

for all $n = 1, 2, 3, \dots$. Since $\{\psi(d(x_{n-1}, x_n))\}$ is decreasing and bounded from below by 0, there exists $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} \psi(d(x_n, x_{n-1})) = r.$$

Now, we show that $\lim_{n \rightarrow \infty} \psi(d(x_n, x_{n-1})) = 0$. On the contrary, assume that $r > 0$. Let $t_n = \psi(d(x_n, x_{n+1}))$ and $s_n = \psi(d(x_{n-1}, x_n))$, for all $n = 1, 2, 3, \dots$. Then, $\lim_{n \rightarrow \infty} s_n = \lim_{n \rightarrow \infty} t_n = r$. From condition (ζ_3) we have

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(\psi(d(x_n, x_{n+1})), \psi(d(x_{n-1}, x_n))) < 0,$$

which is a contradiction. Hence, we have $r = 0$. Since $\psi \in \Psi$,

$$\lim_{n \rightarrow \infty} d(x_n, x_{n-1}) = 0. \quad (3.17)$$

We now show that $\{x_n\}$ is a Cauchy sequence. On contrary, let $\{x_n\}$ be not a Cauchy sequence. Then there exists $\epsilon > 0$ such that, for all $k > 0$ there exists $m(k) > n(k) > k$ with

$$d(x_{m(k)}, x_{n(k)}) \geq \epsilon \quad \text{and} \quad d(x_{m(k)-1}, x_{n(k)}) < \epsilon.$$

Then, we have

$$\begin{aligned} \epsilon &\leq d(x_{m(k)}, x_{n(k)}) \\ &\leq d(x_{m(k)}, x_{m(k)-1}) + d(x_{m(k)-1}, x_{n(k)}) \\ &< d(x_{m(k)}, x_{m(k)-1}) + \epsilon. \end{aligned}$$

Letting $k \rightarrow \infty$ in above inequality, we have

$$\lim_{k \rightarrow \infty} d(x_{m(k)}, x_{n(k)}) = \epsilon. \quad (3.18)$$

By using (3.17) and (3.18), we obtain

$$\lim_{k \rightarrow \infty} d(x_{m(k)+1}, x_{n(k)+1}) = \epsilon. \quad (3.19)$$

Since

$$\begin{aligned} \alpha(x_n) &\geq 1 \quad \text{and} \quad \beta(x_n) \geq 1 \quad \text{for all } n = 1, 2, 3, \dots, \\ \alpha(x_{m(k)})\beta(x_{n(k)}) &\geq 1, \quad \text{for all } k = 1, 2, 3, \dots \end{aligned}$$

We deduce that

$$\begin{aligned} &m(x_{m(k)}, x_{n(k)}) \\ &= \max \left\{ d(x_{n(k)}, Tx_{n(k)}) \frac{1 + d(x_{m(k)}, Tx_{m(k)})}{1 + d(x_{m(k)}, x_{n(k)})}, \right. \\ &\quad \left. \frac{d(x_{m(k)}, Tx_{m(k)})d(x_{m(k)}, Tx_{n(k)}) + d(x_{n(k)}, Tx_{n(k)})d(x_{n(k)}, Tx_{m(k)})}{d(x_{m(k)}, Tx_{n(k)}) + d(x_{n(k)}, Tx_{m(k)})} \right\} \\ &= \max \left\{ d(x_{n(k)}, x_{n(k)+1}) \frac{1 + d(x_{m(k)}, x_{m(k)+1})}{1 + d(x_{m(k)}, x_{n(k)})}, \right. \\ &\quad \left. \frac{d(x_{m(k)}, x_{m(k)+1})d(x_{m(k)}, x_{n(k)+1}) + d(x_{n(k)}, x_{n(k)+1})d(x_{n(k)}, x_{m(k)+1})}{d(x_{m(k)}, x_{n(k)+1}) + d(x_{n(k)}, x_{m(k)+1})} \right\}. \end{aligned}$$

Let $s_k = \psi(m(x_{m(k)}, x_{n(k)}))$ and $t_k = \psi(d(x_{m(k)+1}, x_{n(k)+1}))$. Then it follows from (3.17), (3.18) and (3.19), we have

$$\lim_{k \rightarrow \infty} s_k = \lim_{k \rightarrow \infty} t_k = \psi(\epsilon). \quad (3.20)$$

Since $\psi(\epsilon) > 0$, it follows from condition (ζ_3) that

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(\psi(d(x_{m(k)+1}, x_{n(k)+1})), \psi(m(x_{m(k)}, x_{n(k)}))) < 0,$$

which is a contradiction. Then $\{x_n\}$ is a Cauchy sequence. It follows from the completeness of X that there exists

$$x^* = \lim_{n \rightarrow \infty} x_n \in X. \tag{3.21}$$

If T is continuous, then $\lim_{n \rightarrow \infty} x_n = Tx^*$ and so $x^* = Tx^*$. Assume that (3.13) holds. Then $\alpha(x_n)\beta(x^*) \geq 1$ for all $n = 0, 1, 2, \dots$. We have

$$\begin{aligned} m(x_n, x^*) &= \max \left\{ d(x^*, Tx^*) \frac{1 + d(x_n, Tx_n)}{1 + d(x_n, x^*)}, \right. \\ &\quad \left. \frac{d(x_n, Tx_n)d(x_n, Tx^*) + d(x^*, Tx^*)d(x^*, Tx_n)}{d(x_n, Tx^*) + d(x^*, Tx_n)} \right\} \\ &= \max \left\{ d(x^*, x_n) \frac{1 + d(x_n, x_{n+1})}{1 + d(x_n, x^*)}, d(x^*, Tx^*) \right\}. \end{aligned}$$

Let $s_n := \psi(m(x_n, x^*))$ and $t_n := \psi(d(x_{n+1}, Tx^*))$. Then, $\lim_{n \rightarrow \infty} s_n = \lim_{n \rightarrow \infty} t_n = \psi(d(x^*, Tx^*))$. Assume that $\psi(d(x^*, Tx^*)) > 0$. Then

$$\lim_{n \rightarrow \infty} s_n = \lim_{n \rightarrow \infty} t_n > 0,$$

it follows from (ζ_3) that

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(\psi(d(x_{n+1}, Tx^*)), \psi(m(x_n, x^*))) < 0,$$

which is a contradiction.

Thus $\psi(d(x^*, Tx^*)) = 0$. From (ψ_2) we have $d(x^*, Tx^*) = 0$. Hence x^* is a fixed point of T .

We now show that the fixed point of T is unique under assumption that $\alpha(x)\beta(y) \geq 1$ for all fixed points x, y of T .

Let y^* be another fixed point of T . Then $\alpha(x^*)\beta(y^*) \geq 1$. Hence from (3.12), we have

$$\begin{aligned} 0 &\leq \zeta(\psi(d(Tx^*, Ty^*)), \psi(m(x^*, y^*))) \\ &= \zeta(\psi(d(x^*, y^*)), \psi(d(x^*, y^*))). \end{aligned} \tag{3.22}$$

If $d(x^*, y^*) > 0$, then $\psi(d(x^*, y^*)) > 0$. Hence it follows from (3.22) and (ζ_2) that

$$\begin{aligned} 0 &\leq \zeta(\psi(d(x^*, y^*)), \psi(d(x^*, y^*))) \\ &< \psi(d(x^*, y^*)) - \psi(d(x^*, y^*)) = 0, \end{aligned}$$

which is a contradiction. Hence $d(x^*, y^*) = 0$, and hence T has a unique fixed point. \square

Corollary 3.6. *Let (X, d) be a complete metric space and let $T : X \rightarrow X$ be a generalized rational (α, β, Z) -contraction mapping with respect to ζ such that*

$$\zeta(d(Tx, Ty), m(x, y)) \geq 0$$

for all $x, y \in X$ with $\alpha(x)\beta(y) \geq 1$. Suppose that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$, where $x_0 \in X$. Assume that either

- (1) *T is continuous or*
- (2) *if $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} d(x_n, x) = 0$ and $\beta(x_n) \geq 1$ for all n , then $\beta(x) \geq 1$.*

If $T : X \rightarrow X$ is cyclic (α, β) -admissible, then T has a fixed point in X . Further if $\alpha(x)\beta(y) \geq 1$ for all fixed points x, y of T , then T has a unique fixed point.

Note that the continuity of the mapping T in Theorem 3.2 can be dropped if we replace condition (3) by a suitable one as in the following result.

Corollary 3.7. *Let (X, d) be a complete metric space, $T : X \rightarrow X$ be a mapping and $\alpha, \beta : X \rightarrow [0, +\infty)$ be two functions. Suppose that the following conditions hold:*

- (1) *T is a rational (α, β, Z) -contraction mapping.*
- (2) *There exists an element $x_0 \in X$ such that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$.*
- (3) *If $\{x_n\}$ is a sequence in X converges to $x \in X$ with $\alpha(x_n) \geq 1$ (or $\beta(x_n) \geq 1$) for all $n \in \mathbb{N}$, then $\beta(x) \geq 1$ (or $\alpha(x) \geq 1$) for all $n \in \mathbb{N}$.*

Then T has a fixed point.

By taking the function $\beta : X \rightarrow [0, +\infty)$ to be α in Theorem 3.2, we get the following Corollary:

Corollary 3.8. *Let (X, d) be a complete metric space, $T : X \rightarrow X$ be a mapping and $\alpha : X \rightarrow [0, +\infty)$ be a function. Suppose that the following conditions hold:*

- (1) *There exists $\zeta \in Z$ such that if $x, y \in X$ with $\alpha(x)\alpha(y) \geq 1$, then $\zeta(d(Tx, Ty), M(x, y)) \geq 0$, where*

$$M(x, y) = \max \left\{ d(x, y), \frac{d(x, Tx)d(y, Ty)}{1 + d(x, y)}, \frac{d(x, Tx)d(y, Ty)}{1 + d(Tx, Ty)} \right\}.$$

- (2) *If $x \in X$ with $\alpha(x) \geq 1$, then $\alpha(Tx) \geq 1$.*
- (3) *There exists $x_0 \in X$ such that $\alpha(x_0) \geq 1$.*
- (4) *If $\{x_n\}$ is a sequence in X converges to $x \in X$ with $\alpha(x_n) \geq 1$ for all $n \in \mathbb{N}$, then $\alpha(x) \geq 1$ for all $n \in \mathbb{N}$.*

Then T has a fixed point.

Example 3.9. Let $X = [-1, 1]$. Define $d : X \times X \rightarrow \mathbb{R}$ by $d(x, y) = |x - y|$. Also, define the mapping $T : X \rightarrow X$ the two functions $\alpha, \beta : X \rightarrow [0, \infty)$ and the function $\zeta : [0, +\infty) \times [0, \infty) \rightarrow \mathbb{R}$ as follows:

$$T(x) = \begin{cases} \frac{x}{4}, & \text{if } x \in [0, 1], \\ 1/4, & \text{otherwise,} \end{cases}$$

$$\alpha(x) = \begin{cases} \frac{x+3}{2}, & \text{if } x \in [0, 1], \\ 0, & \text{otherwise,} \end{cases}$$

$$\beta(x) = \begin{cases} \frac{x+5}{4}, & \text{if } x \in [0, 1], \\ 0, & \text{otherwise,} \end{cases}$$

$$\zeta(t, s) = \frac{s}{s + 1} - t.$$

Then, we have the following:

- (1) (X, d) is a complete metric space.
- (2) ζ is a simulation function.
- (3) There exists $x_0 \in X$ such that $\alpha(x_0) \geq 1$ and $\beta(x_0) \geq 1$.
- (4) T is continuous.
- (5) T is cyclic (α, β) -admissible mapping.
- (6) For $x, y \in X$ with $\alpha(x)\beta(y) \geq 1$, we have

$$\zeta(d(Tx, Ty), M(x, y)) \geq 0,$$

where

$$M(x, y) = \max \left\{ d(x, y), \frac{d(x, Tx)d(y, Ty)}{1 + d(x, y)}, \frac{d(x, Tx)d(y, Ty)}{1 + d(Tx, Ty)} \right\}.$$

Indeed, the proof of (1), (2), (3) and (4) are clear. To prove (5), let $x \in X$. If $\alpha(x) \geq 1$ then $x \in [0, 1]$. So,

$$\beta(Tx) = \beta(x/4) = \frac{(x/4) + 5}{4} = \frac{x + 20}{16} \geq 1.$$

If $\beta(x) \geq 1$, then $x \in [0, 1]$. So,

$$\alpha(Tx) = \alpha(x/4) = \frac{(x/4) + 3}{2} = \frac{x + 12}{8} \geq 1.$$

So, T is cyclic (α, β) -admissible. To prove (6), let $x, y \in X$ with $\alpha(x)\beta(x) \geq 1$. Then $x, y \in [0, 1]$, therefore, we have

$$\begin{aligned} \zeta(d(Tx, Ty), M(x, y)) &= \frac{M(x, y)}{1 + M(x, y)} - d(Tx, Ty) \\ &\geq \frac{d(x, y)}{1 + d(x, y)} - |T(x) - T(y)| \\ &= \frac{d(x, y)}{1 + d(x, y)} - |x/4 - y/4| \\ &= \frac{|x - y|}{1 + |x - y|} - |x/4 - y/4| \\ &= \frac{3|x - y| - |x - y|^2}{4[1 + |x - y|]} \geq 0. \end{aligned}$$

So, T is a rational (α, β, Z) -contraction mapping. Hence this satisfies all the conditions of Theorem 3.2. So T has fixed point. Here 0 is the fixed point of T .

4. CONCLUSION

In this paper, we establish some unique fixed point results for rational (α, β, Z) -contraction mapping and generalized rational (α, β, Z) -contraction mapping in the setting of complete metric space via a cyclic (α, β) -admissible mapping imbedded in simulation function. Our results extend and generalize several results from the existing literature.

Acknowledgements: The authors are thankful to the learned referee for his/her deep observations and their suggestions, which greatly helped us to improve the paper significantly.

REFERENCES

- [1] S. Alizadeh, F. Moradlou and P. Salimi, *Some fixed point results for (α, β) - (ψ, ϕ) -contractive mappings*, Filomat, **28**(3) (2014), 635–647.
- [2] H.H. Alsulami, E. Karapinar, F. Khojasteh and A.F. Roldán-López-de-Hierro, *A proposal to the study of contractions in quasi-metric spaces*, Discrete Dyna. Nature and Soc., (2014) Article ID 269286, 1–10.
- [3] A.H. Ansari, J. Nantadilok and M.S. Khan, *Best proximity points of generalized cyclic weak (F, ψ, φ) -contractions in ordered metric spaces*, Nonlinear Funct. Anal. Appl., **25**(1) (2020), 55–67.
- [4] H. Argoubi, B. Samet and C. Vetro, *Nonlinear contractions involving simulation functions in a metric space with a partial order*, J. Nonlinear Sci. Appl., **8** (2015), 1082–1094.
- [5] H. Aydi and A. Felhi, *Fixed points in modular spaces via α -admissible mappings and simulation functions*, J. Nonlinear Sci. Appl., **9** (2016), 3686–3701.

- [6] H. Aydi, A. Felhi and S. Sahmim, *On common fixed points for (α, ψ) -contractions and generalized cyclic contractions in b -metric like spaces and consequences*, J. Nonlinear Sci. Appl., **9** (2016), 2492–2510.
- [7] H. Aydi, E. Karapinar and V. Rakoćević, *Non unique fixed point theorem on b -metric spaces via simulation functions*, Jordan J. Math. Stat., **12** (2019), 265–288.
- [8] M. Bousselsal and Z. Mostefaoui, *Some common fixed point results in partial metric spaces for generalized rational type contraction mappings*, Nonlinear Funct. Anal. Appl., **20**(1) (2015), 43–54.
- [9] Seong-Hoon Cho, *Fixed point theorem for (α, β) - z contractions in metric spaces*, Int. J. Math. Anal., **13**(4) (2019), 161–174.
- [10] A. Das, B. Hazarika, H.K. Nashine and J.K. Kim, *ψ -coupled fixed point theorem via simulation functions in complete partially ordered metric space and its applications*, Nonlinear Funct. Anal. Appl., **26**(2) (2021), 273–288.
- [11] E. Karapinar *Fixed points results via simulation functions*, Filomat, **30** (2016), 2343–2350.
- [12] E. Karapinar and F. Khojasteh, *An approach to best proximity point results via simulation functions*, J. Fixed Point Theory Appl., **19** (2017), 1983–1995.
- [13] E. Karapinar and B. Samet, *Generalized $\alpha - \psi$ contractive type mappings and related fixed point theorems with applications*, Abst. Appl. Anal., **2012** (2012), 17 pages.
- [14] F. Khojasteh, S. Shukla and S. Radenovic, *A new approach to the study of fixed point theory for simulation function*, Filomat, **29**(6) (2015), 1189–1194.
- [15] H.K. Nashine, R.W. Ibrahim, Y.J. Cho and J.K. Kim, *Fixed point theorems for the modified simulation function and applications to fractional economics systems*, Nonlinear Funct. Anal. Appl., **26** (1) (2021), 137–155.
- [16] H. Qawagneh, M.S. Noorani, W. Shatanawi, K. Abodayeh and H. Alsamir, *Fixed point for mappings under contractive condition based on simulation functions and cyclic (α, β) -admissibility*, J. Math. Anal., **9**(1) (2018), 38–51.
- [17] A.F. Roldán-López-de-Hierro, E. Karapinar, C. Roldán-López-de-Hierro and J. Martínez-Moreno, *Coincidence point theorems on metric spaces via simulation functions*, J. Comput. Appl. Math., **275** (2015), 345–355.
- [18] B. Samet, C. Vetro and P. Vetro, *Fixed point theorems for $(\alpha - \psi)$ -contractive type mappings*, Nonlinear Anal., **75** (2012), 2154–2165.