



## COMMON FIXED POINT RESULTS FOR MAPPINGS UNDER NONLINEAR CONTRACTION OF CYCLIC FORM IN $b$ -METRIC SPACES

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**Abstract.** In this research, we interpret the notion of a  $b$ -cyclic  $(\Phi, C, D)$ -contraction for the pair  $(g, S)$  of self-mappings on the set  $Y$ . We employ our definition to introduce some common fixed point theorems for the two mappings  $g$  and  $S$  under a set of conditions. Also we introduce an example to support our results.

### 1. INTRODUCTION

Many years ago, different results were obtained in fixed point theory in  $b$ -metric spaces. A main topic in the fixed point theory is the cyclic contraction. Kirk et al. [15] established the first result in this interesting field.

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Now a days, others attained important outcomes in this dominant field see [20, 21, 29, 30]

We start with the definition of a cyclic map.

**Definition 1.1.** ([29]) Let  $C$  and  $D$  be non-empty subsets of a metric space  $(Y, d)$  and  $S: C \cup D \rightarrow C \cup D$ . Then  $S$  is called a cyclic map if  $S(C) \subseteq D$  and  $S(D) \subseteq C$ .

In 2003, Kirk et al. [15] gave the following interesting theorem in fixed point theory for a cyclic map.

**Theorem 1.2.** ([15]) Let  $C$  and  $D$  be nonempty closed subsets of a complete metric space  $(Y, d)$ . Suppose that  $S: C \cup D \rightarrow C \cup D$  is a cyclic map such that

$$d(Sx, Sy) \leq kd(x, y), \quad \forall x, y \in D.$$

If  $k \in [0, 1)$ , then  $S$  has a unique fixed point in  $C \cap D$ .

Some of contractive conditions are based on functions called control function which alter the distance between two points in a metric space. Such functions were inaugurated by Khan et al. [17]

**Definition 1.3.** ([17]) The function  $\Phi: [0, \infty) \rightarrow [0, \infty)$  is called an altering distance function if the following properties are satisfied:

- (1)  $\Phi$  is continuous and nondecreasing,
- (2)  $\Phi(\zeta) = 0$  if and only if  $\zeta = 0$ .

**Definition 1.4.** ([6, 11]) Let  $Y$  be a nonempty set and  $b \geq 1$  be a given real number. A function  $d: Y \times Y \rightarrow [0, \infty)$  is called  $b$ -metric. If it satisfies the following properties for each  $y_1, y_2, y_3 \in Y$ ,

- (1)  $d(y_1, y_2) = 0$  if and only if  $y_1 = y_2$ ,
- (2)  $d(y_1, y_2) = d(y_2, y_1)$ ,
- (3)  $d(y_1, y_3) \leq b[d(y_1, y_2) + d(y_2, y_3)]$ .

The pair  $(Y, d)$  is called a  $b$ -metric space.

**Example 1.5.** Let  $Y = l_p(R)$  with  $0 < p < 1$ , where  $l_p(R) = \{y_n \subset R : \sum_{n=1}^{\infty} |y_n|^p < \infty\}$ .

Define  $d: Y \times Y \rightarrow R^+$  by:

$$d(y, z) = (\sum_{n=1}^{\infty} |y_n - z_n|^p)^{\frac{1}{p}},$$

where  $y = \{y_n\}, z = \{z_n\}$ . Then  $d$  is a  $b$ -metric space (see [12]) with coefficient  $b = \frac{1}{p}$ .

**Example 1.6.** Let  $Y = L_p [0, 1]$  be the space of all real function  $x(t), t \in [0, 1]$  such that for  $0 < p < 1$ ,

$$\int_0^1 |y(t)|^p < \infty.$$

Define  $d : Y \times Y \rightarrow R^+$  by:

$$d(x, y) = \left( \int_0^1 |y(t) - z(t)|^p dt \right)^{\frac{1}{p}}.$$

Then  $d$  is a  $b$ -metric space (see [12]) with coefficient  $b = 2^{\frac{1}{p}}$ .

The above examples show that class of  $b$ -metric space is larger than the class of metric spaces. When  $b = 1$ , the concept of  $b$ -metric coincides with the concept of metric spaces. Many authors introduce many fixed point theorems in the notion of metric spaces, for more details see [1, 2, 3, 5, 7, 8, 9, 16, 22, 24, 25, 34, 35, 36, 37, 38, 39, 40, 41, 42]. Also, for some work on  $b$ -metric, we refer the reader to [4, 10, 13, 18, 19, 23, 26, 27, 28, 31, 32, 33].

**Definition 1.7.** ([13]) Let  $(Y, d)$  be a  $b$ - metric space.

- (1) A sequence  $\{y_n\}$  in  $Y$  is said to be Cauchy, if  $d(y_n, y_m) \rightarrow 0$  as  $n, m \rightarrow \infty$ .
- (2) A sequence  $\{y_n\}$  in  $Y$  is said to be convergent, if there exists  $y \in Y$  such that  $d(y_n, y) \rightarrow 0$  as  $n \rightarrow \infty$  and we write  $\lim_{n \rightarrow \infty} y_n = y$ .
- (3) The  $b$ -metric space  $(Y, d)$  is said to be complete if every Cauchy sequence in  $Y$  is convergent.

**Theorem 1.8.** ([14]) Let  $(Y, d)$  be a complete  $b$ -metric space with constant  $b \geq 1$ , such that  $b$ -metric is a continuous functional. Let  $S : Y \rightarrow Y$  be a contraction with constant  $k \in [0, 1)$  such that  $kb < 1$ . Then  $S$  has a unique fixed point.

The justification of this paper is to acquire common fixed point results for mapping satisfying nonlinear contractive conditions of a cyclic form based on the notion of an altering distance function.

## 2. THE MAIN RESULTS

We begin with the following definition.

**Definition 2.1.** Let  $(Y, d)$  be a  $b$ -metric space and  $C, D$  be nonempty closed subsets of  $Y$ . Let  $g, S : Y \rightarrow Y$  be two mappings. The pair  $(g, S)$  is called a  $b$ -cyclic  $(\Phi, C, D)$ -contraction, if the following conditions are satisfied:

- (1)  $\Phi$  is an altering distance function,
- (2)  $C \cup D$  has a cyclic representation *w.r.t.* the pair  $(g, S)$ ; that is  $g(C) \subseteq D$ ,  $S(D) \subseteq C$  and  $Y = C \cup D$ ,
- (3) there exists  $\delta > 0$  with  $b^2\delta < 1$  such that for all  $x, y \in Y$  with  $x \in C$  and  $y \in D$ , we have

$$\begin{aligned} & \Phi (bd (gx, Sy)) \\ & \leq \Phi \left( \delta \max \left\{ d(x, y), d(x, gx), d(y, Sy), \frac{1}{2b}d(x, Sy), \frac{1}{2b}d(gx, y) \right\} \right). \end{aligned} \quad (2.1)$$

From this point till the end of the paper, by  $\Phi$  we mean altering distance function unless otherwise stated and  $Y$  stands for a complete  $b$ -metric space. In the rest of this paper, we also mean by  $N$  set of non negative integer numbers.

**Theorem 2.2.** *Let  $(Y, d)$  be a  $b$ -complete metric space and  $C, D$  be nonempty closed subsets of  $Y$ . Let  $g, S : Y \rightarrow Y$  be two mapping. Assume the following:*

- (1) *the pair  $(g, S)$  is a  $b$ -cyclic  $(\Phi, C, D)$  contraction,*
- (2)  *$g$  or  $S$  is continuous.*

*Then  $g$  and  $S$  have a common fixed point.*

*Proof.* Choose  $y_0 \in C$ , let  $y_1 = gy_0$ . Since  $gC \subseteq D$ , we have  $y_1 \in D$ . Also, let  $y_2 = Sy_1$ . Since  $SD \subseteq C$ , we have  $y_2 \in C$ . Continuing this process, we can construct a sequence  $\{y_n\}$  in  $Y$  such that  $y_{2n+1} = gy_{2n}$ ,  $y_{2n+2} = Sy_{2n+1}$ ,  $y_{2n} \in C$  and  $y_{2n+1} \in D$ .

We divide our proof into the following steps:

**Step 1.** We will show that  $\{y_n\}$  is a Cauchy sequence in  $(Y, d)$ .

**Subcase 1:** Suppose that  $y_{2n} = y_{2n+1}$  for some  $n \in N$ . Since  $y_{2n}$  and  $y_{2n+1}$  are elements in  $Y$  with  $y_{2n} \in C$  and  $y_{2n+1} \in D$ , we have

$$\begin{aligned} & \Phi (bd (y_{2n+1}, y_{2n+2})) \\ & = \Phi (d (gy_{2n}, Sy_{2n+1})) \\ & \leq \Phi \left( \delta \max \left\{ d(y_{2n}, y_{2n+1}), d(y_{2n}, gy_{2n}), d(y_{2n+1}, Sy_{2n+1}), \right. \right. \\ & \quad \left. \left. \frac{1}{2b}d(y_{2n}, Sy_{2n+1}), \frac{1}{2b}d(gy_{2n}, y_{2n+1}) \right\} \right) \\ & = \Phi \left( \delta \max \left\{ d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1}), d(y_{2n+1}, y_{2n+2}), \right. \right. \\ & \quad \left. \left. \frac{1}{2b}d(y_{2n}, y_{2n+2}), \frac{1}{2b}d(y_{2n+1}, y_{2n+1}) \right\} \right) \end{aligned}$$

$$\begin{aligned} &\leq \Phi(\delta d(y_{2n+1}, y_{2n+2})) \\ &\leq \Phi(\delta bd(y_{2n+1}, y_{2n+2})). \end{aligned}$$

By properties of  $\phi$ , we have  $bd(y_{2n+1}, y_{2n+2}) \leq \delta bd(y_{2n+1}, y_{2n+2})$ . Since  $\delta b < 1$ , we have  $bd(y_{2n+1}, y_{2n+2}) = 0$  and hence  $y_{2n+2} = y_{2n+1}$ .

Similarly, we may show that  $y_{2n+3} = y_{2n+2}$ . Hence  $\{y_n\}$  is a constant sequence in  $Y$ , so it is a Cauchy sequence in  $(Y, d)$ .

**Subcase 2:**  $y_{2n} \neq y_{2n+1}$  for all  $n \in N$ . Given  $n \in N$ . If  $n$  is even, then  $n = 2q$  for some  $q \in N$ .

Since  $y_{2q} \in C$ ,  $y_{2q+1} \in D$  and  $y_{2q}, y_{2q+1}$  are elements in  $Y$ , we have

$$\begin{aligned} \Phi(bd(y_{n+1}, y_{n+2})) &= \Phi(bd(y_{2q+1}, y_{2q+2})) \\ &= \Phi(bd(gy_{2q}, Sy_{2q+1})) \\ &\leq \Phi\left(\delta \max\left\{d(y_{2q}, y_{2q+1}), d(y_{2q}, gy_{2q}), d(y_{2q+1}, Sy_{2q+1}), \right. \right. \\ &\quad \left. \left. \frac{1}{2b}d(y_{2q}, Sy_{2q+1}), \frac{1}{2b}d(gy_{2q}, y_{2q+1})\right\}\right) \\ &= \Phi\left(\delta \max\left\{d(y_{2q}, y_{2q+1}), d(y_{2q+1}, y_{2q+2}), \right. \right. \\ &\quad \left. \left. \frac{1}{2b}d(y_{2q}, y_{2q+2}), \frac{1}{2b}d(y_{2q+1}, y_{2q+2})\right\}\right) \\ &\leq \Phi\left(\delta \max\left\{d(y_{2q}, y_{2q+1}), d(y_{2q}, y_{2q+2})\right\}\right) \\ &\leq \Phi\left(\delta b \max\left\{d(y_{2q}, y_{2q+1}), d(y_{2q}, y_{2q+2})\right\}\right). \end{aligned}$$

If

$$\max\{d(y_{2q}, y_{2q+1}), d(y_{2q+1}, y_{2q+2})\} = d(y_{2q+1}, y_{2q+2}),$$

then

$$\begin{aligned} \Phi(bd(y_{2q+1}, y_{2q+2})) &\leq \Phi(\delta d(y_{2q+1}, y_{2q+2})) \\ &\leq \Phi(\delta bd(y_{2q+1}, y_{2q+2})) \\ &< \Phi(d(y_{2q+1}, y_{2q+2})) \\ &\leq \Phi(bd(y_{2q+1}, y_{2q+2})), \end{aligned}$$

which is a contradiction. Thus

$$\max\{d(y_{2q}, y_{2q+1}), d(y_{2q+1}, y_{2q+2})\} = d(y_{2q}, y_{2q+1}). \tag{2.2}$$

Therefore

$$\begin{aligned}\Phi (bd (y_{2q+1}, y_{2q+2})) &\leq \Phi (\delta d (y_{2q}, y_{2q+1})) \\ &\leq \Phi (\delta bd (y_{2q}, y_{2q+1})).\end{aligned}\quad (2.3)$$

If  $n$  is odd, then  $n = 2q + 1$  for some  $q \in \mathbb{N}$ . Since  $y_{2q+2}$  and  $y_{2q+1}$  are elements in  $Y$  with  $y_{2q+2} \in C$  and  $y_{2q+1} \in D$ , we have

$$\begin{aligned}\Phi (bd (y_{n+2}, y_{n+1})) &= \Phi (bd (y_{2q+3}, y_{2q+2})) \\ &= \Phi (bd (gy_{2q+2}, Sy_{2q+1})) \\ &\leq \Phi (\max \delta \{d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, gy_{2q+2}), d (y_{2q+2}, Sy_{2q+1}), \\ &\quad \frac{1}{2b} d (y_{2q+2}, Sy_{2q+1}), \frac{1}{2b} d (gy_{2q+2}, y_{2q+1})\}) \\ &\leq \Phi \left( \delta \max \left\{ d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, y_{2q+3}), \right. \right. \\ &\quad \left. \left. \frac{1}{2b} d (y_{2q+2}, y_{2q+2}), \frac{1}{2b} d (y_{2q+3}, y_{2q+1}) \right\} \right) \\ &\leq \Phi \left( \delta \max \left\{ d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, y_{2q+3}) \right\} \right) \\ &\leq \Phi \left( \delta b \max \left\{ d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, y_{2q+3}) \right\} \right).\end{aligned}$$

If

$$\max \{d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, y_{2q+3})\} = d (y_{2q+2}, y_{2q+3}),$$

then

$$\Phi (bd (y_{2q+2}, y_{2q+3})) \leq \Phi (\delta bd (y_{2q+2}, y_{2q+3})).$$

Properties of  $\phi$  implies that

$$bd (y_{2q+2}, y_{2q+3}) \leq \delta bd (y_{2q+2}, y_{2q+3}) < bd (y_{2q+2}, y_{2q+3}),$$

which is a contradiction. Therefore

$$\max \{d (y_{2q+2}, y_{2q+1}), d (y_{2q+2}, y_{2q+3})\} = d (y_{2q+2}, y_{2q+1}), \quad (2.4)$$

and hence

$$\Phi (bd (y_{2q+3}, y_{2q+2})) \leq \Phi (\delta bd (y_{2q+2}, y_{2q+1})). \quad (2.5)$$

From (2.3) and (2.5), we have

$$\Phi (bd (y_{n+1}, y_{n+2})) \leq \Phi (\delta bd (y_n, y_{n+1})) \leq \Phi (bd (y_n, y_{n+1})). \quad (2.6)$$

Since  $\Phi$  is an altering distance function, we have  $\{d (y_{n+1}, y_{n+2}) : n \in \mathbb{N} \cup \{0\}\}$  is a bounded nonincreasing sequence. Thus there exists  $\zeta \geq 0$  such that

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = \zeta.$$

On letting  $n \rightarrow \infty$  in (2.6), we have

$$\Phi(b\zeta) \leq \Phi(\delta b\zeta).$$

Claim:  $\zeta = 0$ . Suppose to the contrary, that is,  $\zeta \neq 0$ . By properties of  $\phi$ , we have

$$b\zeta \leq \delta b\zeta < \zeta,$$

which is a contradiction. Therefore  $\zeta = 0$ . Thus

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0. \quad (2.7)$$

Next, we show that  $\{y_n\}$  is a Cauchy sequence in  $b$ -metric space  $(Y, d)$ . It is sufficient to show that  $\{y_{2n}\}$  is a Cauchy sequence in  $(Y, d)$ . Suppose to the contrary, that is,  $\{y_{2n}\}$  is not a Cauchy sequence in  $(Y, d)$ . Then there exists  $\epsilon > 0$  for which we can find two subsequences  $\{y_{2m(i)}\}$  and  $\{y_{2n(i)}\}$  of  $\{y_{2n}\}$  such that  $n(i)$  is the smallest index for which

$$n(i) > m(i) > i, \quad d(y_{2m(i)}, y_{2n(i)}) \geq \epsilon. \quad (2.8)$$

This means that

$$d(y_{2m(i)}, y_{2n(i)-2}) < \epsilon. \quad (2.9)$$

From (2.8), (2.9) and the definition of the  $b$ -metric space, we get

$$\begin{aligned} \epsilon &\leq d(y_{2m(i)}, y_{2n(i)}) \\ &\leq bd(y_{2m(i)}, y_{2n(i)-2}) + bd(y_{2n(i)-2}, y_{2n(i)}) \\ &\leq bd(y_{2m(i)}, y_{2n(i)-2}) + b^2d(y_{2n(i)-2}, y_{2n(i)-1}) + b^2d(y_{2n(i)-1}, y_{2n(i)}) \\ &\leq \epsilon b + b^2d(y_{2n(i)-2}, y_{2n(i)-1}) + b^2d(y_{2n(i)-1}, y_{2n(i)}). \end{aligned}$$

By taking the sup limit of above inequalities using (2.7), we have

$$\epsilon \leq \limsup_{i \rightarrow +\infty} d(y_{2m(i)}, y_{2n(i)}) \leq \epsilon b. \quad (2.10)$$

Again, from (2.8) and the definition of the  $b$ -metric space, we get

$$\begin{aligned} \epsilon &\leq d(y_{2m(i)}, y_{2n(i)}) \\ &\leq b((d(y_{2m(i)}, y_{2m(i)+1}) + d(y_{2m(i)+1}, y_{2n(i)})). \end{aligned}$$

On taking the limsup in above inequalities and using (2.7), we get

$$\epsilon \leq \limsup_{i \rightarrow +\infty} bd(y_{2m(i)+1}, y_{2n(i)}). \quad (2.11)$$

Again, from the definition of the  $b$ -metric space, we get

$$d(y_{2m(i)}, y_{2n(i)-1}) \leq b((d(y_{2m(i)}, y_{2n(i)}) + d(y_{2n(i)+1}, y_{2n(i)-1})).$$

On taking the limsup in above inequalities and using (2.7) and (2.10), we get

$$\limsup_{i \rightarrow +\infty} bd(y_{2m(i)}, y_{2n(i)-1}) \leq \epsilon b^2. \quad (2.12)$$

Again, from the definition of the  $b$ -metric space, we get that

$$d(y_{2n(i)+1}, y_{2n(i)-1}) \leq \underline{d}(y_{2n(i)+1}, y_{2n(i)}) + d(y_{2n(i)}, y_{2n(i)-1}).$$

On taking the limsup in above inequalities and using the properties of  $\Phi$ , we get

$$\limsup_{i \rightarrow +\infty} bd(y_{2n(i)+1}, y_{2n(i)-1}) = 0. \quad (2.13)$$

Since  $y_{2m(i)} \in C$  and  $y_{2n(i)-1} \in D$ , we have

$$\begin{aligned} \Phi(bd(y_{2m(i)+1}, y_{2n(i)})) &= \Phi(bd(gy_{2m(i)}, Sy_{2n(i)-1})) \\ &\leq \Phi\left(\max \delta \left\{ d(y_{2m(i)}, y_{2n(i)-1}), d(y_{2m(i)}, y_{2m(i)}), \right. \right. \\ &\quad \left. \left. d(y_{2n(i)-1}, Sy_{2n(i)-1}), \right. \right. \\ &\quad \left. \left. \frac{1}{2b}d(y_{2m(i)}, gy_{2n(i)-1}), \frac{1}{2b}d(gy_{2m(i)}, y_{2n(i)-1}) \right\} \right) \\ &= \Phi\left(\delta \max \left\{ d(y_{2m(i)}, y_{2n(i)-1}), d(y_{2m(i)}, y_{2m(i)+1}), \right. \right. \\ &\quad \left. \left. d(y_{2n(i)-1}, y_{2n(i)}), \right. \right. \\ &\quad \left. \left. \frac{1}{2b}d(y_{2m(i)}, y_{2n(i)}), \frac{1}{2b}d(y_{2n(i)+1}, y_{2n(i)-1}) \right\} \right). \end{aligned}$$

Taking the limsup in above inequalities, and using the properties of  $\Phi$  and (2.7), (2.10), (2.11), (2.12) and (2.13), we get

$$\Phi(\epsilon) \leq \Phi(\epsilon \delta b^2).$$

Again, properties of  $\Phi$  implies that  $\epsilon \leq \epsilon \delta b^2$ . Since  $b^2 \delta < 1$ , we have  $\epsilon = 0$ , a contradiction. Thus  $\{y_n\}$  is a Cauchy sequence in  $(Y, d)$ .

**Step 2:** Existence of a common fixed point.

Since  $(Y, d)$  is a complete  $b$ -metric space and  $\{y_n\}$  is a Cauchy sequence in  $Y$  we have  $\{y_n\}$  converges to some  $v \in Y$ , that is,  $\lim_{n \rightarrow +\infty} d(y_n, v) = 0$ . Therefore,

$$\lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} y_{2n-1} = \lim_{n \rightarrow +\infty} y_{2n} = v. \quad (2.14)$$

Since  $\{y_{2n}\}$  is a sequence in  $C$ .  $C$  is closed and  $y_{2n} \rightarrow v$ , we have  $v \in C$ . Also, since  $\{y_{2n+1}\}$  is a sequence in  $D$ ,  $D$  is closed and  $y_{2n+1} \rightarrow v$ , we have  $v \in D$ .



Now, we show that  $v$  is a fixed point of  $g$  and  $S$ . Without loss of generality, we may assume that  $g$  is continuous, since  $y_{2n} \rightarrow v$ , we get  $y_{2n+1} = gy_{2n} \rightarrow gv$ . By the uniqueness of limit, we have  $v = gv$ .

Now, we show that  $v = Sv$ . Since  $v \in C$  and  $v \in D$ , we have

$$\begin{aligned} \Phi (bd (v, Sv)) &= \Phi (bd (gv, Sv)) \\ &\leq \Phi (\delta \max \{d (gv, Sv), d (v, gv), d (v, Sv), \\ &\quad \frac{1}{2b} d (v, Sv), \frac{1}{2b} d (gv, v)\}) \\ &= \Phi (\delta d (v, Sv)). \end{aligned}$$

Properties of  $\Phi$  implies that

$$bd(v, Sv) \leq \delta d(v, Sv),$$

the last inequality only if  $d(v, Sv) = 0$ , and hence  $v = Sv$ . □

If we take  $\Phi = I [0, +\infty]$  is the identity function in Theorem 2.2 we have the following result.

**Corollary 2.3.** *Let  $(Y, d)$  be a  $b$ -metric space and  $C, D$  be nonempty closed subsets of  $Y$ . Let  $g, S : Y \rightarrow Y$  be two mappings and  $C \cup D$  has a  $b$ -cyclic representation with respect to the pair  $(g, S)$ . Suppose there exists  $\delta > 0$  with  $b^2\delta < 1$  such that for all  $x, y \in Y$  with  $x \in C$  and  $y \in Y$ , we have*

$$bd (gx, Sy) \leq \delta \max \left\{ d (x, y), d (x, gx), d (y, Sy), \frac{1}{2b} d (x, Sy), \frac{1}{2b} d (gx, y) \right\}.$$

*If  $g$  or  $S$  is continuous, then  $g$  and  $S$  have a common fixed point.*

By taking  $g = S$  in Theorem 2.2, we have the following result.

**Corollary 2.4.** *Let  $(Y, d)$  be a  $b$ - metric space and  $C, D$  be nonempty closed subsets of  $Y$  with  $Y = C \cup D$ . Let  $g, S : Y \rightarrow Y$  be two mappings. Suppose there exists  $\delta > 0$  with  $b^2\delta < 1$  such that for all  $x, y \in Y$  with  $x \in C$  and  $y \in Y$ , we have*

$$\begin{aligned} &\Phi (bd (gx, gy)) \\ &\leq \Phi \left( \delta \max \left\{ d (x, y), d (x, gx), d (y, gy), \frac{1}{2b} d (x, gy), \frac{1}{2b} d (gx, y) \right\} \right). \end{aligned}$$

*Assume that  $g$  is a continuous and cyclic map, Then  $g$  has a fixed point.*

By taking  $C = D = Y$  in Theorem 2.2, we have the following result.

**Corollary 2.5.** *Let  $(Y, d)$  be a  $b$ -metric space. Let  $g, S : Y \rightarrow Y$  be two mappings. Suppose there exists  $\delta > 0$  with  $b^2\delta < 1$  such that for all  $x, y \in Y$ , we have*

$$\begin{aligned} & \Phi (bd (gx, Sy)) \\ & \leq \Phi \left( \delta \max \left\{ d(x, y), d(x, gx), d(y, Sy), \frac{1}{2b}d(x, Sy), \frac{1}{2b}d(gx, y) \right\} \right). \end{aligned}$$

*If  $g$  or  $S$  is continuous, then  $g$  and  $S$  have a common fixed point.*

**Example 2.6.** Let  $Y = \{1, 2, 3, 4, 5\}$ . Define  $d : Y \times Y \rightarrow [0, +\infty)$  by  
 $d(x, x) = 0$  if  $x \in \{1, 2, 3, 4, 5\}$ ;  
 $d(x, y) = 1$  if  $x, y \in \{1, 2, 3, 4\}$  and  $x \neq y$ ;  
 $d(x, y) = 20$  if  $x \in \{1, 2, 3\}$  and  $y = 5$ ;  
 $d(x, y) = 20$  if  $x = 5$  and  $y \in \{1, 2, 3\}$ ;  
 $d(x, y) = 12$  if  $x, y \in \{4, 5\}$  and  $x \neq y$ .

Define  $g : Y \rightarrow Y$  by  $g(x) = 1$  if  $x \in \{1, 2, 3, 4\}$  and  $g(5) = 4$ . Also, define  $S : Y \rightarrow Y$  by  $S(x) = 1$  if  $x \in \{1, 2, 3, 4\}$  and  $S(5) = 3$ . Also, define  $\Phi : [0, +\infty) \rightarrow [0, +\infty)$  via  $\Phi(t) = \frac{t}{4}$ . Let  $C = \{1, 3, 5\}$  and  $D = \{1, 2, 4\}$ . Then

- (1)  $(Y, d)$  is a complete  $b$ -metric space,
- (2)  $C \cup D$  has cyclic representation with respect to the pair  $(g, S)$ ,
- (3) for every two elements  $x, y \in Y$  with  $x \in C$  and  $y \in D$ , we have

$$\begin{aligned} & \Phi (2d (gx, Sy)) \\ & \leq \Phi \left( \frac{1}{8} \max \left\{ d(x, y), d(x, gx), d(y, Sy), \frac{1}{4}d(x, Sy), \frac{1}{4}d(gx, y) \right\} \right). \end{aligned}$$

The proof of (1) is obvious with  $b = 2$ . To prove part (2), since  $gC = \{1, 4\} \subseteq D$  and  $SD = \{1\} \subseteq C$ , we can say that  $C \cup D$  has  $b$ -cyclic representation with respect to the pair  $(g, S)$ . To prove part (3), we have the following two cases:

**Case I:** Let  $x = 1, 3$  and  $y \in D$ . Then  $g(x) = 1$  and  $S(y) = 1$  and hence  $\Phi(d(gx, Sy)) = 0$ . Thus we have

$$\begin{aligned} & \Phi (2d (gx, Sy)) \\ & \leq \Phi \left( \frac{1}{8} \max \left\{ d(x, y), d(x, gx), d(y, Sy), \frac{1}{4}d(x, Sy), \frac{1}{4}d(gx, y) \right\} \right). \end{aligned}$$

**Case II:** Let  $x = 5$  and  $y \in D \setminus \{1, 2\}$ . Then  $g(x) = 4$  and  $S(y) = 1$ . Hence  $\Phi(2d(gx, Sy)) = \Phi(2d(4, 1)) = \Phi(2) = \frac{1}{2}$  and  $d(x, y) = 10$ . Thus,

$$\begin{aligned}
\Phi(2d(gx, Sy)) &= \frac{1}{2} \leq \frac{5}{8} = \Phi\left(\frac{1}{8}d(x, y)\right) \\
&\leq \Phi\left(\frac{1}{8}\max\left\{d(x, y), d(x, gx), d(y, Sy), \frac{1}{4}d(x, Sy), \frac{1}{4}d(gx, y)\right\}\right) \\
&= \Phi\left(\frac{5}{2}\right).
\end{aligned}$$

Similarly, we can deal with the case  $x = 5$  and  $y = 4$ . Thus  $g$  and  $S$  satisfy all the hypothesis of Theorem 2.2. Hence  $g$  and  $S$  have a common fixed point. Here 1 is the common fixed point of  $g$  and  $S$ .

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