

**η -RICCI SOLITONS ON $\epsilon - LP$ -SASAKIAN MANIFOLDS
WITH A QUARTER-SYMMETRIC METRIC
CONNECTION**

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Abstract. In this paper, we study η -Ricci solitons on ϵ - LP -Sasakian manifolds with a quarter-symmetric metric connection satisfying certain curvature conditions. In particular, we have discussed that the Ricci soliton on $\epsilon - LP$ -Sasakian manifolds with a quarter-symmetric metric connection satisfying certain curvature conditions is expanding or steady according to the vector field ξ being timelike or spacelike. Moreover, we construct 3-dimensional examples of an $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection to verify some results of the paper.

1. Introduction

The study of manifolds with indefinite metrics is of high interest in physics and relativity theory. In [1], A. Bejancu and K. L. Duggal introduced the concept of ϵ -Sasakian manifolds. Later, it was shown by X. Xufeng and C. Xiaoli [29] that these manifolds are real hypersurfaces of indefinite Kahlerian manifolds. In 2010, M. M. Tripathi et al. [16] have studied ϵ -almost paracontact manifolds and in particular, ϵ -para-Sasakian manifolds. On the other hand, the concept of ϵ -Kenmotsu manifolds was introduced by U. C. De and A. Sarkar [27], they have studied some curvature properties on this manifold. ϵ -Kenmotsu manifolds have also been studied A. Haseeb [2], A. Haseeb et. al [4], R. N. Singh et. al [21] and many others. In 2012, R. Prasad and V. Srivastava have studied ϵ -Lorentzian para-Sasakian manifolds and shown its existence by an example [18]. Recently, A. Haseeb, A. Prakash and

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M. D. Siddiqi have studied ϵ -Lorentzian para-Sasakian manifolds with a quarter-symmetric metric connection and obtained some interesting results [3].

In 1982, R. S. Hamilton [22] introduced the notion of Ricci flow to find a canonical metric on a smooth manifold. Then Ricci flow has become a powerful tool for the study of Riemannian manifolds, especially for those manifolds with positive curvature. G. Perelman ([9], [10]) used Ricci flow and its surgery to prove Poincare conjecture. The Ricci flow is an evolution equation for metrics on a Riemannian manifold defined as follows:

$$\frac{\partial}{\partial t} g_{ij}(t) = -2R_{ij}.$$

A Ricci soliton emerges as the limit of the solutions of the Ricci flow. A solution to the Ricci flow is called Ricci soliton if it moves only by a one parameter group of diffeomorphism and scaling. A Ricci soliton (g, V, λ) on a Riemannian manifold (M, g) is a generalization of an Einstein metric such that [19, 23, 24, 26]

$$(1) \quad (\mathcal{L}_V g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) = 0,$$

where S is the Ricci tensor, \mathcal{L}_V is the Lie derivative operator along the vector field V on M and λ is a real number. The Ricci soliton is said to be shrinking, steady or expanding according to λ being negative, zero or positive, respectively. Ricci solitons, in the context of general relativity, have been studied by M. Ali and Z. Ahsan [15].

As a generalization of Ricci soliton, the notion of η -Ricci soliton was introduced by J. T. Cho and M. Kimura [11]. They have studied Ricci soliton of real hypersurfaces in a non-flat complex space form and defined η -Ricci soliton, which satisfies the equation

$$(2) \quad (\mathcal{L}_V g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta(X)\eta(Y) = 0,$$

where λ and μ are real numbers. In particular, if $\mu = 0$, then the notion of η -Ricci soliton (g, V, λ, μ) reduces to the notion of Ricci soliton (g, V, λ) . Recently, η -Ricci solitons have been studied by various authors such as A. Singh and S. Kishor [5], A. M. Blaga [6], D. G. Prakasha and B. S. Hadimani [8] and many others.

2. Preliminaries

A differentiable manifold M of dimension n is called an ϵ -Lorentzian para-Sasakian (briefly, ϵ -LP-Sasakian), if it admits a $(1, 1)$ -tensor

field ϕ , a contravariant vector field ξ , a 1-form η and a Lorentzian like metric g which satisfy

$$(3) \quad \phi^2 X = X + \eta(X)\xi, \quad \eta(\xi) = -1,$$

$$(4) \quad g(\xi, \xi) = -\epsilon, \quad \eta(X) = \epsilon g(X, \xi), \quad \phi\xi = 0, \quad \eta(\phi X) = 0,$$

$$(5) \quad g(\phi X, \phi Y) = g(X, Y) + \epsilon \eta(X)\eta(Y),$$

$$(6) \quad (\nabla_X \phi)(Y) = g(X, Y)\xi + \epsilon \eta(Y)X + 2\epsilon \eta(X)\eta(Y)\xi,$$

$$(7) \quad \nabla_X \xi = \epsilon \phi X$$

for all vector fields $X, Y \in \chi(M)$, where ϵ is -1 or 1 according to the vector field ξ being spacelike or timelike and ∇ denotes the Levi-Civita connection with respect to g . If we put

$$(8) \quad \Phi(X, Y) = g(\phi X, Y)$$

for all vector fields X and Y on M , then $\Phi(X, Y)$ is a symmetric $(0, 2)$ tensor field. Also since the 1-form η is closed in an $\epsilon - LP$ -Sasakian manifold, so we have [18]

$$(9) \quad (\nabla_X \eta)(Y) = \Phi(X, Y), \quad \Phi(X, \xi) = 0$$

for all vector fields $X, Y \in \chi(M)$.

Moreover, the curvature tensor R , the Ricci tensor S and the Ricci operator Q in an $\epsilon - LP$ -Sasakian manifold with the Levi-Civita connection satisfy the following equations [18]:

$$(10) \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y,$$

$$(11) \quad R(\xi, X)Y = \epsilon g(X, Y)\xi - \eta(Y)X,$$

$$(12) \quad R(\xi, X)\xi = -R(X, \xi)\xi = X + \eta(X)\xi,$$

$$(13) \quad \eta(R(X, Y)Z) = \epsilon[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)],$$

$$(14) \quad S(X, \xi) = (n - 1)\eta(X), \quad Q\xi = \epsilon(n - 1)\xi,$$

where $X, Y, Z \in \chi(M)$ and $g(QX, Y) = S(X, Y)$.

We note that if $\epsilon = 1$ and the structure vector field ξ is timelike, then an $\epsilon - LP$ -Sasakian manifold is usual LP -Sasakian manifold.

Definition 2.1. An $\epsilon - LP$ -Sasakian manifold is said to be a generalized η -Einstein manifold if its Ricci tensor S of type $(0, 2)$ satisfies [13]

$$S(Y, Z) = l_1g(Y, Z) + l_2\eta(Y)\eta(Z) + l_3g(\phi Y, Z),$$

where l_1, l_2 and l_3 are the scalar functions on M . If $l_3 = 0$, then the manifold reduces to an η -Einstein manifold.

3. Curvature tensor on an $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection

A linear connection $\bar{\nabla}$ in a Riemannian manifold M is said to be a quarter-symmetric connection [25] if the torsion tensor T of the connection $\bar{\nabla}$ is of the form

$$(15) \quad T(X, Y) = \bar{\nabla}_X Y - \bar{\nabla}_Y X - [X, Y] = \eta(Y)\phi X - \eta(X)\phi Y,$$

where η is a 1-form and ϕ is a $(1, 1)$ tensor field. If moreover, a quarter-symmetric connection $\bar{\nabla}$ satisfies the condition

$$(16) \quad (\bar{\nabla}_X g)(Y, Z) = 0$$

for all $X, Y, Z \in \chi(M)$, where $\chi(M)$ is the Lie algebra of vector fields on M , then $\bar{\nabla}$ is said to be a quarter-symmetric metric connection, otherwise it is said to be a quarter-symmetric non-metric connection.

Let M be an n -dimensional $\epsilon - LP$ -Sasakian manifold and ∇ be the Levi-Civita connection on M . A quarter-symmetric metric connection $\bar{\nabla}$ in an $\epsilon - LP$ -Sasakian manifold is defined by [25]

$$(17) \quad \bar{\nabla}_X Y = \nabla_X Y + H(X, Y),$$

where $H(X, Y)$ is a tensor of type $(1, 1)$ such that

$$(18) \quad H(X, Y) = \frac{1}{2}[T(X, Y) + T'(X, Y) + T'(Y, X)],$$

where T' and T are related by

$$(19) \quad g(T'(X, Y), Z) = g(T(Z, X), Y).$$

From (15) and (19), we get

$$(20) \quad T'(X, Y) = \eta(X)\phi(Y) - \epsilon g(\phi X, Y)\xi.$$

Now combining (15), (18) and (20), we obtain

$$(21) \quad H(X, Y) = \eta(Y)\phi(X) - \epsilon g(\phi X, Y)\xi.$$

Thus a quarter-symmetric metric connection $\bar{\nabla}$ in an $\epsilon - LP$ -Sasakian manifold is given by

$$(22) \quad \bar{\nabla}_X Y = \nabla_X Y + \eta(Y)\phi X - \epsilon g(\phi X, Y)\xi.$$

A quarter symmetric metric connection have been studied by many authors in several ways to a different extent such as K. Mandal and U. C. De [12], M. Ahmad et al. [14], R. Prasad and A. Haseeb [17], R. N. Singh and S. K. Pandey [20], U. C. De and A. K. Mondal [28] and many others.

The curvature tensor \bar{R} of quarter-symmetric metric connection $\bar{\nabla}$ in M is defined by

$$(23) \quad \bar{R}(X, Y)Z = \bar{\nabla}_X \bar{\nabla}_Y Z - \bar{\nabla}_Y \bar{\nabla}_X Z - \bar{\nabla}_{[X, Y]}Z.$$

From (3)-(7), (9), (22) and (23), we obtain

$$(24) \quad \begin{aligned} \bar{R}(X, Y)Z = R(X, Y)Z + (2 - \epsilon)[g(\phi X, Z)\phi Y - g(\phi Y, Z)\phi X] \\ + \epsilon \eta(Z)[\eta(Y)X - \eta(X)Y] \\ + [\eta(X)g(Y, Z) - \eta(Y)g(X, Z)]\xi, \end{aligned}$$

where $X, Y, Z \in \chi(M)$ and $R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]}Z$ is the Riemannian curvature tensor of the Levi-Civita connection ∇ .

Let $\{e_1, e_2, e_3, \dots, e_{n-1}, \xi\}$ be a frame of orthonormal basis of the tangent space at any point of the manifold. The Ricci tensor \bar{S} and the scalar curvature \bar{r} of the manifold with a quarter-symmetric metric connection are defined by [7]

$$\begin{aligned} \bar{S}(X, Y) &= \sum_{i=1}^n \epsilon_i g(\bar{R}(e_i, X)Y, e_i), \\ \bar{r} &= \sum_{i=1}^n \epsilon_i \bar{S}(e_i, e_i), \end{aligned}$$

respectively. Also we have

$$g(X, Y) = \sum_{i=1}^n \epsilon_i g(X, e_i)g(Y, e_i),$$

where $X, Y \in \chi(M)$ and $\epsilon_i = g(e_i, e_i) = +1$ or -1 . Contracting X in (24), we get

$$(25) \quad \begin{aligned} \bar{S}(Y, Z) = S(Y, Z) + (1 - \epsilon)g(Y, Z) + (n\epsilon - 1)\eta(Y)\eta(Z) \\ - (2 - \epsilon)g(\phi Y, Z)\psi, \end{aligned}$$

where $\psi = \text{trace}\phi$ and is defined by $\psi = \sum_{i=1}^n \epsilon_i g(\phi e_i, e_i)$. Contracting again Y and Z in (25), it follows that

$$(26) \quad \bar{r} = r - (n-1)\epsilon - (2-\epsilon)\psi^2,$$

where r is the scalar curvature of the connection ∇ .

From the equations (22), (24) and (25), we can easily prove the following Lemma:

Lemma 3.1. *Let M be an n -dimensional ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection. Then we have*

$$(27) \quad \bar{R}(X, Y)\xi = (1-\epsilon)[\eta(Y)X - \eta(X)Y],$$

$$(28) \quad \bar{R}(\xi, X)Y = -(1-\epsilon)[g(X, Y)\xi + \eta(Y)X],$$

$$\bar{R}(\xi, X)\xi = (1-\epsilon)[X + \eta(X)\xi],$$

$$(29) \quad \bar{S}(X, \xi) = (1-\epsilon)(n-1)\eta(X), \quad \bar{S}(\xi, \xi) = -(1-\epsilon)(n-1),$$

$$(30) \quad \bar{\nabla}_X \xi = -(1-\epsilon)\phi X$$

for any vector fields $X, Y \in \chi(M)$.

Now, we express the Lie derivative along ξ on M with a quarter-symmetric metric connection as follows:

$$(31) \quad (\bar{\mathcal{L}}_\xi g)(Y, Z) = \bar{\mathcal{L}}_\xi g(Y, Z) - g(\bar{\mathcal{L}}_\xi Y, Z) - g(Y, \bar{\mathcal{L}}_\xi Z).$$

By virtue of (15), (31) takes the form

$$(32) \quad (\bar{\mathcal{L}}_\xi g)(Y, Z) = \bar{\nabla}_\xi g(Y, Z) - g(\bar{\nabla}_\xi Y - \bar{\nabla}_Y \xi - \phi Y, Z) \\ + g(Y, \bar{\nabla}_\xi Z - \bar{\nabla}_Z \xi - \phi Z)$$

which after computation gives

$$(33) \quad (\bar{\mathcal{L}}_\xi g)(Y, Z) = 2\epsilon g(\phi Y, Z)$$

for all $Y, Z \in \chi(M)$.

4. η -Ricci solitons on ϵ -LP-Sasakian manifolds with a quarter-symmetric metric connection

Suppose that an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection admits an η -Ricci soliton (g, ξ, λ, μ) . Then (2) holds and we have

$$(34) \quad (\bar{\mathcal{L}}_{\xi}g)(Y, Z) + 2\bar{S}(Y, Z) + 2\lambda g(Y, Z) + 2\mu\eta(Y)\eta(Z) = 0.$$

By virtue of (33), (34) takes the form

$$(35) \quad \bar{S}(Y, Z) = -\epsilon g(\phi Y, Z) - \lambda g(Y, Z) - \mu\eta(Y)\eta(Z).$$

Putting $Y = Z = \xi$ in (35) and using (3), (4) and (29), we obtain

$$(36) \quad \lambda - \epsilon\mu = (1 - \epsilon)(n - 1).$$

Thus we have the following:

Theorem 4.1. *If (g, ξ, λ, μ) is an η -Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection, then the scalars λ and μ are related by $\lambda - \epsilon\mu = (1 - \epsilon)(n - 1)$.*

Example 4.2. *We consider the 3-dimensional manifold*

$$M = \{(x, y, z) \in R^3\},$$

where (x, y, z) are the standard coordinates in R^3 . Let e_1, e_2 and e_3 be the vector fields on M given by

$$e_1 = e^z \frac{\partial}{\partial y}, \quad e_2 = e^z \left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right), \quad e_3 = \frac{\partial}{\partial z} = \xi,$$

which are linearly independent at each point of M and hence form a basis of T_pM . Let g be the Lorentzian like (semi-Riemannian) metric on M defined by

$$g(e_1, e_1) = g(e_2, e_2) = 1, \quad g(e_3, e_3) = -\epsilon, \quad g(e_1, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0.$$

Let η be the 1-form on M defined by $\eta(X) = \epsilon g(X, e_3) = \epsilon g(X, \xi)$ for all $X \in \chi(M)$. Let ϕ be the $(1, 1)$ tensor field on M defined by

$$\phi e_1 = -\epsilon e_1, \quad \phi e_2 = -\epsilon e_2, \quad \phi e_3 = 0.$$

The linearity property of ϕ and g yields

$$\eta(e_3) = -1, \quad \phi^2 X = X + \eta(X)\xi, \quad g(\phi X, \phi Y) = g(X, Y) + \epsilon\eta(X)\eta(Y)$$

for all $X, Y \in \chi(M)$.

Now, by direct computations, we obtain

$$[e_1, e_2] = 0, \quad [e_2, e_3] = -e_2, \quad [e_3, e_1] = e_1.$$

The Riemannian connection ∇ of the metric tensor g is given by

$$2g(\nabla_X Y, Z) = Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) \\ + g(Y, [Z, X]) + g(Z, [X, Y]),$$

which is known as Koszul's formula. Using Koszul's formula, we can easily calculate

$$(37) \quad \nabla_{e_1} e_1 = -\epsilon e_3, \quad \nabla_{e_2} e_1 = 0, \quad \nabla_{e_3} e_1 = 0, \quad \nabla_{e_1} e_2 = 0, \quad \nabla_{e_2} e_2 = -\epsilon e_3, \\ \nabla_{e_3} e_2 = 0, \quad \nabla_{e_1} e_3 = -e_1, \quad \nabla_{e_2} e_3 = -e_2, \quad \nabla_{e_3} e_3 = 0.$$

$$\text{Let} \quad X = \sum_{i=1}^3 X^i e_i = X^1 e_1 + X^2 e_2 + X^3 e_3 \in \chi(M).$$

Also, one can easily verify that

$$\nabla_X \xi = \epsilon \phi X \quad \text{and} \quad (\nabla_X \phi)Y = g(X, Y)\xi + \epsilon \eta(Y)X + 2\epsilon \eta(X)\eta(Y)\xi.$$

Thus the manifold M is an ϵ -LP-Sasakian manifold. From (22) and (37), we find

$$(38) \quad \bar{\nabla}_{e_1} e_1 = (1 - \epsilon)e_3, \quad \bar{\nabla}_{e_2} e_1 = 0, \quad \bar{\nabla}_{e_3} e_1 = 0, \quad \bar{\nabla}_{e_1} e_2 = 0, \quad \bar{\nabla}_{e_2} e_2 = (1 - \epsilon)e_3, \\ \bar{\nabla}_{e_3} e_2 = 0, \quad \bar{\nabla}_{e_1} e_3 = -(1 - \epsilon)e_1, \quad \bar{\nabla}_{e_2} e_3 = -(1 - \epsilon)e_2, \quad \bar{\nabla}_{e_3} e_3 = 0.$$

It is known that

$$(39) \quad R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z.$$

By using the above results, we can easily calculate the components of the curvature tensors as follows:

$$(40) \quad R(e_1, e_2)e_1 = -\epsilon e_2, \quad R(e_1, e_2)e_2 = \epsilon e_1, \quad R(e_1, e_2)e_3 = 0, \\ R(e_2, e_3)e_1 = 0, \quad R(e_2, e_3)e_2 = -\epsilon e_3, \quad R(e_2, e_3)e_3 = -e_2, \\ R(e_1, e_3)e_1 = -\epsilon e_3, \quad R(e_1, e_3)e_2 = 0, \quad R(e_1, e_3)e_3 = -e_1,$$

and

$$(41) \quad \bar{R}(e_1, e_2)e_1 = 2(1 - \epsilon)e_2, \quad \bar{R}(e_1, e_2)e_2 = -2(1 - \epsilon)e_1, \quad \bar{R}(e_1, e_2)e_3 = 0, \\ \bar{R}(e_2, e_3)e_1 = 0, \quad \bar{R}(e_2, e_3)e_2 = (1 - \epsilon)e_3, \quad \bar{R}(e_2, e_3)e_3 = -(1 - \epsilon)e_2, \\ \bar{R}(e_1, e_3)e_1 = (1 - \epsilon)e_3, \quad \bar{R}(e_1, e_3)e_2 = 0, \quad \bar{R}(e_1, e_3)e_3 = -(1 - \epsilon)e_1.$$

From these curvature tensors, we obtain

$$(42) \quad S(e_1, e_1) = S(e_2, e_2) = 2\epsilon, \quad S(e_3, e_3) = -2.$$

$$(43) \quad \bar{S}(e_1, e_1) = \bar{S}(e_2, e_2) = -3(1 - \epsilon), \quad \bar{S}(e_3, e_3) = -2(1 - \epsilon).$$

Therefore, from (42) and (43) we get $r = 6\epsilon$ and $\bar{r} = -8(1 - \epsilon)$, respectively. Thus it can be seen that the equation (26) is satisfied, where

$\psi = \sum_{i=1}^3 \epsilon_i g(\phi e_i, e_i) = -2\epsilon$. Now from the equations (8), (15) and (16) we find

$$(44) \quad \Phi(e_1, e_1) = \Phi(e_2, e_2) = -\epsilon, \Phi(e_3, e_3) = 0,$$

$$(45) \quad T(e_1, e_1) = T(e_2, e_2) = T(e_3, e_3) = T(e_1, e_2) = 0,$$

$$T(e_1, e_3) = e_1, T(e_2, e_3) = e_2,$$

$$(46) \quad (\bar{\nabla}_X g)(Y, Z) = 0$$

for any vector fields $X, Y, Z \in \chi(M)$, respectively. Thus the connection $\bar{\nabla}$ defined on M is a quarter-symmetric metric connection.

Now from (35), we find $\bar{S}(e_1, e_1) = 1 - \lambda$ and $\bar{S}(e_3, e_3) = \epsilon\lambda - \mu$, therefore from (43) it follows that $\lambda = 4 - 3\epsilon$ and $\mu = 2\epsilon - 1$. Thus (g, ξ, λ, μ) for $\lambda = 4 - 3\epsilon$ and $\mu = 2\epsilon - 1$ defines an η -Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection. By using these values of the scalars λ and μ in (35), we obtain

$$(47) \quad \bar{S}(Y, Z) = -\epsilon g(\phi Y, Z) - (4 - 3\epsilon)g(Y, Z) - (2\epsilon - 1)\eta(Y)\eta(Z).$$

Thus the manifold M (defined in Example 4.2) admitting an η -Ricci soliton (g, ξ, λ, μ) with a quarter-symmetric metric connection is a generalized η -Einstein manifold of the form (47).

Definition 4.3. An ϵ -LP-Sasakian manifold is said to be

(i) conformally flat with a quarter-symmetric metric connection if

$$(48) \quad \bar{C}(X, Y)Z = 0,$$

(ii) quasi conformally flat with a quarter-symmetric metric connection if

$$(49) \quad g(\bar{C}(X, Y)Z, \phi W) = 0,$$

(iii) ξ -conformally flat with a quarter-symmetric metric connection if

$$(50) \quad \bar{C}(X, Y)\xi = 0,$$

where \bar{C} is the conformal curvature tensor with a quarter-symmetric metric connection and is given by

$$(51) \quad \bar{C}(X, Y)Z = \bar{R}(X, Y)Z - \frac{1}{(n-2)}[\bar{S}(Y, Z)X - \bar{S}(X, Z)Y \\ + g(Y, Z)\bar{Q}X - g(X, Z)\bar{Q}Y] + \frac{\bar{r}}{(n-1)(n-2)}[g(Y, Z)X - g(X, Z)Y]$$

for all $X, Y, Z, W \in \chi(M)$, \bar{Q} is the Ricci operator with a quarter-symmetric metric connection such that $g(\bar{Q}X, Y) = \bar{S}(X, Y)$.

In [3], A. Haseeb, A. Prakash and M. D. Siddiqi proved that conformally flat, quasi-conformally flat and ξ -conformally flat ϵ -LP-Sasakian manifolds with a quarter-symmetric metric connection are an η -Einstein manifold. In the same way, we can easily prove:

Proposition 4.4. *An n -dimensional conformally flat, quasi-conformally flat and ξ -conformally flat ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection $\bar{\nabla}$ defined by (22) are an η -Einstein manifold of the form*

$$(52) \quad \bar{S}(X, W) = \left[\frac{\bar{r}}{n-1} + (1-\epsilon) \right] g(X, W) + \epsilon \left[\frac{\bar{r}}{n-1} + n(1-\epsilon) \right] \eta(X)\eta(W),$$

$$(53) \quad \begin{aligned} \bar{S}(X, W) &= \left[\frac{\bar{r}}{(n-1)} + (1-\epsilon)(2n-3) \right] g(X, W) \\ &+ \left[\frac{\epsilon\bar{r}}{(n-1)} - (1-\epsilon)(3n-4) \right] \eta(X)\eta(W), \end{aligned}$$

$$(54) \quad \bar{S}(X, W) = \left[\frac{\bar{r}}{n-1} + (1-\epsilon) \right] g(X, W) + \left[\frac{\epsilon\bar{r}}{n-1} - n(1-\epsilon) \right] \eta(X)\eta(W),$$

respectively.

Now we prove the following:

Theorem 4.5. *If (g, ξ, λ, μ) is an η -Ricci soliton on conformally flat, quasi-conformally flat and ξ -conformally flat ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection, then the scalars λ and μ are related by $\lambda - \epsilon\mu = (1-\epsilon)(n-1)$.*

Proof. Firstly, we assume that the manifold M with a quarter-symmetric metric connection is conformally flat. Then from (34), (35) and (52) we have

$$\begin{aligned} \epsilon g(\phi Y, Z) + \left[\lambda + \frac{\bar{r}}{(n-1)} + (1-\epsilon) \right] g(Y, Z) \\ + \epsilon \left[\frac{\bar{r}}{n-1} + n(1-\epsilon) + \epsilon\mu \right] \eta(Y)\eta(Z) = 0. \end{aligned}$$

Putting $Y = Z = \xi$ in the last equation then using (3) and (4), we find

$$(55) \quad \lambda - \epsilon\mu = (1-\epsilon)(n-1).$$

Secondly, we assume that the manifold M with a quarter-symmetric metric connection is quasi-conformally flat. Then from (34), (35) and (53), we have

$$\epsilon g(\phi Y, Z) + \left[\lambda + \frac{\bar{r}}{(n-1)} + (1-\epsilon)(2n-3) \right] g(Y, Z)$$

$$+[\frac{\epsilon\bar{r}}{(n-1)} - (1-\epsilon)(3n-4) + \mu]\eta(Y)\eta(Z) = 0.$$

Putting $Y = Z = \xi$ in the last equation then using (3) and (4), we find

$$(56) \quad \lambda - \epsilon\mu = (1-\epsilon)(n-1).$$

Next, we assume that the manifold M with a quarter-symmetric metric connection is ξ -conformally flat. Then from (34), (35) and (54) we have

$$\begin{aligned} \epsilon g(\phi Y, Z) + [\lambda + \frac{\bar{r}}{(n-1)} + (1-\epsilon)]g(Y, Z) \\ + [\frac{\epsilon\bar{r}}{(n-1)} - n(1-\epsilon) + \mu]\eta(Y)\eta(Z) = 0. \end{aligned}$$

Putting $Y = Z = \xi$ in the last equation then using (3) and (4), we find

$$(57) \quad \lambda - \epsilon\mu = (1-\epsilon)(n-1).$$

Thus from (55), (56) and (57), Theorem 4.4 is proved. □

In particular, if $\mu = 0$, then from (55)-(57) it follows that $\lambda = (1-\epsilon)(n-1)$. Thus we have

Corollary 4.6. *If (g, ξ, λ) is a Ricci soliton on conformally flat, quasi-conformally flat and ξ -conformally flat $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection, then the Ricci soliton on M is steady or expanding according to the vector field ξ being timelike or spacelike.*

Let (g, V, λ, μ) be an η -Ricci soliton on an $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection. Then we have

$$(58) \quad (\bar{\mathcal{L}}_V g)(Y, Z) + 2\bar{S}(Y, Z) + 2\lambda g(Y, Z) + 2\mu\eta(Y)\eta(Z) = 0,$$

where $\bar{\mathcal{L}}_V$ is the Lie derivative along the vector field V on M with a quarter-symmetric metric connection.

Now, let (g, V, λ, μ) be an η -Ricci soliton on an $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection such that V is pointwise collinear with ξ , i.e., $V = b\xi$, where b is a function. Then (58) holds and we have

$$(59) \quad \begin{aligned} bg(\bar{\nabla}_Y \xi, Z) + (Yb)\eta(Z) + bg(Y, \bar{\nabla}_Z \xi) + (Zb)\eta(Y) + 2bg(\phi Y, Z) \\ + 2\bar{S}(Y, Z) + 2\lambda g(Y, Z) + 2\mu\eta(Y)\eta(Z) = 0 \end{aligned}$$

which in view of (30) takes the form

$$(60) \quad \begin{aligned} 2b\epsilon g(\phi Y, Z) + (Yb)\eta(Z) + (Zb)\eta(Y) \\ + 2\bar{S}(Y, Z) + 2\lambda g(Y, Z) + 2\mu\eta(Y)\eta(Z) = 0. \end{aligned}$$

Putting $Z = \xi$ in (60) and using (3), (4) and (29) it follows that

$$(61) \quad -(Yb) + (\xi b)\eta(Y) + 2(1 - \epsilon)(n - 1)\eta(Y) + 2\epsilon\lambda\eta(Y) - 2\mu\eta(Y) = 0.$$

Again putting $Y = \xi$ in (61) and using (3), we get

$$(62) \quad (\xi b) + (1 - \epsilon)(n - 1) + \epsilon\lambda - \mu = 0.$$

Combining the equations (61) and (62), we have

$$(63) \quad db = [(1 - \epsilon)(n - 1) + \epsilon\lambda - \mu]\eta.$$

Now applying d on (63), we find

$$(64) \quad [(1 - \epsilon)(n - 1) + \epsilon\lambda - \mu]d\eta = 0.$$

Since $d\eta \neq 0$, so it follows from (64) that

$$(65) \quad \lambda - \epsilon\mu = (1 - \epsilon)(n - 1).$$

By using (64) in (63), we find $db = 0$, i.e., b is a constant. Therefore (60) reduces to

$$\bar{S}(Y, Z) = -\lambda g(Y, Z) - b\epsilon g(\phi Y, Z) - \mu\eta(Y)\eta(Z)$$

which in view of (25), takes the form

$$(66) \quad S(Y, Z) = -(\lambda + 1 - \epsilon)g(Y, Z) - (n\epsilon - 1 + \mu)\eta(Y)\eta(Z) \\ + [(2 - \epsilon)\psi - b\epsilon]g(\phi Y, Z).$$

Thus we have the following theorem:

Theorem 4.7. *If (g, V, λ, μ) is an η -Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection such that V is pointwise collinear with ξ , then V is a constant multiple of ξ and the manifold is a generalized η -Einstein manifold with the Levi-Civita connection of the form (66) and the scalars λ and μ are related by $\lambda - \epsilon\mu = (1 - \epsilon)(n - 1)$.*

In particular, if $\mu = 0$, then from (65) it follows that $\lambda = (1 - \epsilon)(n - 1)$. Thus we have

Corollary 4.8. *If (g, V, λ) is a Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection such that V is pointwise collinear with ξ , then the Ricci soliton on M is steady or expanding according to the vector field ξ being timelike or spacelike.*

5. η -Ricci solitons on ϵ -LP-Sasakian manifolds with a quarter-symmetric metric connection satisfying $\bar{R}(X, Y) \cdot \bar{S} = 0$

Let M be an n -dimensional ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection admits an η -Ricci soliton (g, ξ, λ, μ) satisfying $\bar{R}(X, Y) \cdot \bar{S} = 0$. Then we have

$$(67) \quad \bar{S}(\bar{R}(X, Y)U, V) + \bar{S}(U, \bar{R}(X, Y)V) = 0$$

for any $X, Y, U, V \in \chi(M)$. Putting $X = \xi$ in (67), we have

$$(68) \quad \bar{S}(\bar{R}(\xi, Y)U, V) + \bar{S}(U, \bar{R}(\xi, Y)V) = 0.$$

In view of (28), (68) becomes

$$g(Y, U)\bar{S}(\xi, V) + \eta(U)\bar{S}(Y, V) + g(Y, V)\bar{S}(U, \xi) + \eta(V)\bar{S}(U, Y) = 0, \\ (1 - \epsilon) \neq 0$$

which by putting $U = \xi$ and then using (3), (29) reduces to

$$(69) \quad \bar{S}(Y, V) = -(1 - \epsilon)(n - 1)g(Y, V).$$

In view of (25), (69) takes the form

$$(70) \quad S(Y, V) = -n(1 - \epsilon)g(Y, V) - (n\epsilon - 1)\eta(Y)\eta(V) + (2 - \epsilon)g(\phi Y, V)\psi.$$

From (33), (34) and (69), we find

$$(71) \quad \epsilon g(\phi Y, V) - (1 - \epsilon)(n - 1)g(Y, V) + \lambda g(Y, V) + \mu \eta(Y)\eta(V) = 0.$$

Taking $V = Y = \xi$ in (71) then using (3) and (4), it follows that

$$(72) \quad \lambda - \epsilon\mu = (1 - \epsilon)(n - 1).$$

Thus we have the following theorem:

Theorem 5.1. *If (g, ξ, λ, μ) is an η -Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection satisfying $\bar{R}(X, Y) \cdot \bar{S} = 0$, then the manifold is a generalized η -Einstein manifold with the Levi-Civita connection of the form (70) and the scalars λ and μ are related by $\lambda - \epsilon\mu = (1 - \epsilon)(n - 1)$.*

In particular, if $\mu = 0$, then from (72) it follows that $\lambda = (1 - \epsilon)(n - 1)$. Thus we have

Corollary 5.2. *If (g, ξ, λ) is a Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection satisfying $\bar{R} \cdot \bar{S} = 0$, then the Ricci soliton on M is always expanding according to the vector field ξ being spacelike.*

6. η -Ricci solitons on ϵ -LP-Sasakian manifolds with a quarter-symmetric metric connection satisfying $\bar{S} \cdot \bar{R} = 0$

Let M be an n -dimensional ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection admits an η -Ricci soliton (g, ξ, λ, μ) satisfying $\bar{S} \cdot \bar{R} = 0$. Then we have

$$(73) \quad (X \wedge_{\bar{S}} Y) \bar{R}(U, V)Z + \bar{R}((X \wedge_{\bar{S}} Y)U, V)Z + \bar{R}(U, (X \wedge_{\bar{S}} Y)V)Z \\ + \bar{R}(U, V)(X \wedge_{\bar{S}} Y)Z = 0$$

for any $X, Y, Z, U, V \in \chi(M)$, where the endomorphism $X \wedge_{\bar{S}} Y$ is defined by

$$(74) \quad (X \wedge_{\bar{S}} Y)Z = \bar{S}(Y, Z)X - \bar{S}(X, Z)Y.$$

Taking $Y = \xi$ in (73), we have

$$(75) \quad (X \wedge_{\bar{S}} \xi) \bar{R}(U, V)Z + \bar{R}((X \wedge_{\bar{S}} \xi)U, V)Z + \bar{R}(U, (X \wedge_{\bar{S}} \xi)V)Z \\ + \bar{R}(U, V)(X \wedge_{\bar{S}} \xi)Z = 0$$

which in view of (74) becomes

$$(76) \quad \bar{S}[\xi, \bar{R}(U, V)Z]X - \bar{S}[X, \bar{R}(U, V)Z]\xi + \bar{S}(\xi, U)\bar{R}(X, V)Z \\ - \bar{S}(X, U)\bar{R}(\xi, V)Z + \bar{S}(\xi, V)\bar{R}(U, X)Z - \bar{S}(X, V)\bar{R}(U, \xi)Z \\ + \bar{S}(\xi, Z)\bar{R}(U, V)X - \bar{S}(X, Z)\bar{R}(U, V)\xi = 0.$$

By using (29) in (76), we find

$$(77) \quad (1 - \epsilon)(n - 1)[\eta(\bar{R}(U, V)Z)X + \eta(U)\bar{R}(X, V)Z \\ + \eta(V)\bar{R}(U, X)Z + \eta(Z)\bar{R}(U, V)X] - \bar{S}[X, \bar{R}(U, V)Z]\xi \\ - \bar{S}(X, U)\bar{R}(\xi, V)Z - \bar{S}(X, V)\bar{R}(U, \xi)Z - \bar{S}(X, Z)\bar{R}(U, V)\xi = 0.$$

Taking inner product of (77) with ξ , we get

$$-(1 - \epsilon)(n - 1)[\eta(\bar{R}(U, V)Z)\eta(X) + \eta(U)\eta(\bar{R}(X, V)Z) \\ + \eta(V)\eta(\bar{R}(U, X)Z) + \eta(Z)\eta(\bar{R}(U, V)X)] + \epsilon\bar{S}[X, \bar{R}(U, V)Z] \\ - \epsilon\bar{S}(X, U)\eta(\bar{R}(\xi, V)Z) - \epsilon\bar{S}(X, V)\eta(\bar{R}(U, \xi)Z) - \epsilon\bar{S}(X, Z)\eta(\bar{R}(U, V)\xi) = 0$$

which by putting $U = Z = \xi$ then using (27) and (28) reduces to

$$(78) \quad -(1 - \epsilon)^2(n - 1)[g(X, V) - \eta(X)\eta(V)] + \epsilon\bar{S}[X, (1 - \epsilon)(V + \eta(V)\xi)] = 0$$

from which we obtain

$$(79) \quad \bar{S}(X, V) = -(1 - \epsilon)(n - 1)g(X, V), \quad (1 - \epsilon) \neq 0.$$

In view of (25), (79) takes the form

$$(80) \quad S(X, V) = -n(1 - \epsilon)g(X, V) - (n\epsilon - 1)\eta(X)\eta(V) + (2 - \epsilon)g(\phi X, V)\psi.$$

From (33), (34) and (79), we find

$$(81) \quad \epsilon g(\phi Y, V) - (1 - \epsilon)(n - 1)g(Y, V) + \lambda g(Y, V) + \mu \eta(Y)\eta(V) = 0.$$

Taking $V = Y = \xi$ in (81) then using (3) and (4), it follows that

$$(82) \quad \lambda - \epsilon \mu = (1 - \epsilon)(n - 1).$$

Thus we have the following theorem:

Theorem 6.1. *If (g, ξ, λ, μ) is an η -Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection satisfying $\bar{S} \cdot \bar{R} = 0$, then the manifold is a generalized η -Einstein manifold with the Levi-Civita connection of the form (80) and the scalars λ and μ are related by $\lambda - \epsilon \mu = (1 - \epsilon)(n - 1)$.*

In particular, if $\mu = 0$, then from (82) it follows that $\lambda = (1 - \epsilon)(n - 1)$. Thus we have

Corollary 6.2. *If (g, ξ, λ) is a Ricci soliton on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection satisfying $\bar{S} \cdot \bar{R} = 0$, then the Ricci soliton on M is always expanding according to the vector field ξ being spacelike.*

7. ϵ -LP-Sasakian manifolds with a quarter-symmetric metric connection with second order parallel tensor

Let us suppose that α be a symmetric parallel tensor of type $(0, 2)$ with respect to the connection $\bar{\nabla}$, that is, $\bar{\nabla} \alpha = 0$. Then we have

$$(83) \quad \alpha[\bar{R}(X, Y)Z, W] + \alpha[Z, \bar{R}(X, Y)W] = 0$$

for any $X, Y, Z, W \in \chi(M)$.

Replacing $X = Z = W = \xi$ in (83), we have

$$(84) \quad \alpha[\bar{R}(\xi, Y)\xi, \xi] + \alpha[\xi, \bar{R}(\xi, Y)\xi] = 0$$

which in view of (28) yields

$$(85) \quad \alpha(Y, \xi) = -\eta(Y)\alpha(\xi, \xi) = -\epsilon g(Y, \xi)\alpha(\xi, \xi), \quad (1 - \epsilon) \neq 0.$$

Differentiating (85) with respect to $\bar{\nabla}$ along any arbitrary vector field X , we find

$$(86) \quad \begin{aligned} \alpha(\bar{\nabla}_X Y, \xi) + \alpha(Y, \bar{\nabla}_X \xi) &= -\epsilon[(\bar{\nabla}_X g)(Y, \xi) + g(\bar{\nabla}_X Y, \xi) \\ &\quad + g(Y, \bar{\nabla}_X \xi)]\alpha(\xi, \xi) - 2\epsilon g(Y, \xi)\alpha(\bar{\nabla}_X \xi, \xi). \end{aligned}$$

By virtue of (16) and (85), (86) reduces to

$$\alpha(Y, \bar{\nabla}_X \xi) = -\epsilon g(Y, \bar{\nabla}_X \xi) \alpha(\xi, \xi) - 2\epsilon g(Y, \xi) \alpha(\bar{\nabla}_X \xi, \xi)$$

which in view of (30) takes the form

$$(87) \quad -\alpha(Y, \phi X) = \epsilon g(Y, \phi X) \alpha(\xi, \xi) + 2\epsilon g(Y, \xi) \alpha(\phi X, \xi).$$

Replacing Y by ϕX in (85), we get

$$(88) \quad \alpha(\phi X, \xi) = 0.$$

Combining (87) and (88), we obtain

$$(89) \quad -\alpha(Y, \phi X) = \epsilon g(Y, \phi X) \alpha(\xi, \xi).$$

By replacing X by ϕX in (89) and using (3), it follows that

$$\alpha(Y, X) = -\epsilon g(Y, X) \alpha(\xi, \xi).$$

The fact that $\alpha(\xi, \xi)$ is a constant can be checked by differentiating it along any vector field on M . Thus we have the following theorem:

Theorem 7.1. *On an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection any symmetric parallel second order covariant tensor is a constant multiple of the metric tensor.*

Example 7.2. *We consider the $(2n+1)$ -dimensional manifold $M = \{(x_1, x_2, x_3, \dots, x_{2n}, x_{2n+1}) \in R^{2n+1}\}$, where $(x_1, x_2, x_3, \dots, x_{2n}, x_{2n+1})$ are the standard coordinates in R^{2n+1} . Let $e_1, e_2, e_3, \dots, e_{2n}$ and e_{2n+1} be the vector fields on M^{2n+1} given by*

$$e_k = \cosh x_{2n+1} \frac{\partial}{\partial x_k} + \sinh x_{2n+1} \frac{\partial}{\partial x_{k+1}}, \text{ if } k = 1, 3, \dots, (2n-1),$$

$$e_k = \sinh x_{2n+1} \frac{\partial}{\partial x_{k-1}} + \cosh x_{2n+1} \frac{\partial}{\partial x_k}, \text{ if } k = 2, 4, \dots, 2n, \text{ and } e_{2n+1} = \xi$$

which are linearly independent at each point of M . Let g be the Lorentzian like (semi-Riemannian) metric on M defined for $1 \leq i, j \leq (2n+1)$ by

$$g(e_i, e_j) = 0, \text{ if } i \neq j; \quad g(e_i, e_j) = 1, \text{ if } i = j < (2n+1);$$

$$g(e_i, e_j) = -\epsilon, \text{ if } i = j = (2n+1).$$

Let η be the 1-form on M defined by $\eta(X) = \epsilon g(X, e_{2n+1}) = \epsilon g(X, \xi)$ for all $X \in \chi(M)$. Let ϕ be the $(1, 1)$ tensor field on M defined by

$$\phi e_k = -\epsilon e_{k+1}, \text{ if } k = 1, 3, \dots, (2n-1); \quad \phi e_k = -\epsilon e_{k-1}, \text{ if } k = 2, 4, \dots, 2n,$$

$$\text{and } \phi e_{2n+1} = 0.$$

The linearity property of ϕ and g yields

$$\eta(e_{2n+1}) = -1, \quad \phi^2 X = X + \eta(X)\xi, \quad g(\phi X, \phi Y) = g(X, Y) + \epsilon\eta(X)\eta(Y)$$

for all $X, Y \in \chi(M)$.

Now, by direct computations, we obtain

$$[e_k, \xi] = -e_{k+1}, \text{ if } k = 1, 3, \dots, (2n - 1); [e_k, \xi] = -e_{k-1}, \text{ if } k = 2, 4, \dots, 2n;$$

$$[e_i, e_j] = 0, \text{ if } 1 \leq i, j \leq 2n.$$

Using Koszul's formula for the metric g , we can easily calculate

$$(90) \quad \nabla_{e_i} e_{2n+1} = -e_{i+1}, \text{ if } i = 1, 3, \dots, (2n - 1);$$

$$\nabla_{e_i} e_{2n+1} = -e_{i-1}, \text{ if } i = 2, 4, \dots, 2n;$$

$$\nabla_{e_i} e_{i+1} = \nabla_{e_{i+1}} e_i = -\epsilon e_{2n+1}, \text{ if } i = 1, 3, 5, \dots, (2n - 1);$$

$$\nabla_{e_i} e_{i-1} = \nabla_{e_{i-1}} e_i = -\epsilon e_{2n+1}, \text{ if } i = 2, 4, 6, \dots, 2n;$$

$\nabla_{e_i} e_{i+j} = \nabla_{e_{i+j}} e_i = 0$, if $1 \leq i \leq (2n - 1), 2 \leq j \leq (2n - 1)$ but $i + j < (2n + 1)$, where n is a natural number. Also, one can easily verify that

$$\nabla_X \xi = \epsilon \phi X \quad \text{and} \quad (\nabla_X \phi)(Y) = g(X, Y)\xi + \epsilon\eta(Y)X + 2\epsilon\eta(X)\eta(Y)\xi.$$

Thus the manifold M is an $\epsilon - LP$ -Sasakian manifold.

In particular, for the 3-dimensional $\epsilon - LP$ -Sasakian manifold we consider $M = \{(x_1, x_2, x_3) \in R^3\}$, where (x_1, x_2, x_3) are the standard coordinates in R^3 . Let e_1, e_2 and e_3 be the vector fields on M given by

$$e_1 = \cosh x_3 \frac{\partial}{\partial x_1} + \sinh x_3 \frac{\partial}{\partial x_2}, \quad e_2 = \sinh x_3 \frac{\partial}{\partial x_1} + \cosh x_3 \frac{\partial}{\partial x_2}, \quad e_3 = \frac{\partial}{\partial x_3} = \xi,$$

which are linearly independent at each point of M^3 and hence form a basis of $T_p M$. Let g be the Lorentzian like (semi-Riemannian) metric on M defined by

$$g(e_1, e_1) = g(e_2, e_2) = 1, \quad g(e_3, e_3) = -\epsilon, \quad g(e_1, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0.$$

Let η be the 1-form on M defined by $\eta(X) = \epsilon g(X, e_3) = \epsilon g(X, \xi)$ for all $X \in \chi(M)$. Let ϕ be the $(1, 1)$ tensor field on M defined by

$$\phi e_1 = -\epsilon e_2, \quad \phi e_2 = -\epsilon e_1, \quad \phi e_3 = 0.$$

The linearity property of ϕ and g yields

$$\eta(e_3) = -1, \quad \phi^2 X = X + \eta(X)\xi, \quad g(\phi X, \phi Y) = g(X, Y) + \epsilon\eta(X)\eta(Y)$$

for all $X, Y \in \chi(M)$.

Now, by direct computations, we obtain

$$[e_1, e_2] = 0, \quad [e_2, e_3] = -e_1, \quad [e_3, e_1] = e_2.$$

Using Koszul's formula, we can easily calculate

$$(91) \quad \nabla_{e_1}e_1 = 0, \quad \nabla_{e_2}e_1 = -\epsilon e_3, \quad \nabla_{e_3}e_1 = 0, \quad \nabla_{e_1}e_2 = -\epsilon e_3, \quad \nabla_{e_2}e_2 = 0, \\ \nabla_{e_3}e_2 = 0, \quad \nabla_{e_1}e_3 = -e_2, \quad \nabla_{e_2}e_3 = -e_1, \quad \nabla_{e_3}e_3 = 0.$$

Also, one can easily verify that

$$\nabla_X\xi = \epsilon\phi X \quad \text{and} \quad (\nabla_X\phi)Y = g(X, Y)\xi + \epsilon\eta(Y)X + 2\epsilon\eta(X)\eta(Y)\xi.$$

Thus the manifold M is an ϵ -LP-Sasakian manifold. From (22) and (91), we find

$$(92) \quad \bar{\nabla}_{e_1}e_1 = 0, \quad \bar{\nabla}_{e_2}e_1 = (1 - \epsilon)e_3, \quad \bar{\nabla}_{e_3}e_1 = 0, \quad \bar{\nabla}_{e_1}e_2 = (1 - \epsilon)e_3, \\ \bar{\nabla}_{e_2}e_2 = 0, \quad \bar{\nabla}_{e_3}e_2 = 0, \quad \bar{\nabla}_{e_1}e_3 = 0, \quad \bar{\nabla}_{e_2}e_3 = 0, \quad \bar{\nabla}_{e_3}e_3 = 0.$$

It is known that

$$(93) \quad R(X, Y)Z = \nabla_X\nabla_YZ - \nabla_Y\nabla_XZ - \nabla_{[X, Y]}Z.$$

By using the above results, we can easily obtain the components of the curvature tensors as follows:

$$(94) \quad R(e_1, e_2)e_1 = \epsilon e_2, \quad R(e_1, e_2)e_2 = -\epsilon e_1, \quad R(e_1, e_2)e_3 = 0, \\ R(e_2, e_3)e_1 = 0, \quad R(e_2, e_3)e_2 = -\epsilon e_3, \quad R(e_2, e_3)e_3 = -e_2, \\ R(e_1, e_3)e_1 = -\epsilon e_3, \quad R(e_1, e_3)e_2 = 0, \quad R(e_1, e_3)e_3 = -e_1,$$

and

$$(95) \quad \bar{R}(e_1, e_2)e_1 = \epsilon e_2, \quad \bar{R}(e_1, e_2)e_2 = 2(1 - \epsilon)e_1, \quad \bar{R}(e_1, e_2)e_3 = 0, \\ \bar{R}(e_2, e_3)e_1 = 0, \quad \bar{R}(e_2, e_3)e_2 = (1 - \epsilon)e_3, \quad \bar{R}(e_2, e_3)e_3 = -(1 - \epsilon)e_2, \\ \bar{R}(e_1, e_3)e_1 = (1 - \epsilon)e_3, \quad \bar{R}(e_1, e_3)e_2 = 0, \quad \bar{R}(e_1, e_3)e_3 = -(1 - \epsilon)e_1.$$

From these curvature tensors, we calculate

$$(96) \quad S(e_1, e_1) = S(e_2, e_2) = 0, \quad S(e_3, e_3) = -2.$$

$$(97) \quad \bar{S}(e_1, e_1) = \bar{S}(e_2, e_2) = (1 - \epsilon), \quad \bar{S}(e_3, e_3) = -2(1 - \epsilon).$$

Therefore, from (96) and (97) we obtain $r = 2\epsilon$ and $\bar{r} = 0$, respectively. Thus it can be seen that the equation (26) is satisfied, where $\psi = \sum_{i=1}^3 \epsilon_i g(\phi e_i, e_i) = 0$.

If we take $\mu = 0$ in (35), then putting $Y = Z = e_i$ and sum up with respect to $i(1 \leq i \leq 3)$, we have

$$\sum_{i=1}^3 \epsilon_i \bar{S}(e_i, e_i) = -\epsilon \sum_{i=1}^3 \epsilon_i g(\phi e_i, e_i) - \lambda \sum_{i=1}^3 \epsilon_i g(e_i, e_i)$$

which after computation gives $\lambda = 0$. Thus a Ricci soliton (g, ξ, λ) on an ϵ -LP-Sasakian manifold with a quarter-symmetric metric connection

is steady for the timelike $\epsilon - LP$ -Sasakian manifold with a quarter-symmetric metric connection, which verifies corollaries 4.6 and 4.8.

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