

## New Methods of Construction for Biharmonic Maps

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**ABSTRACT.** In this paper we study some properties of Riemannian manifolds, we construct a new example of non-harmonic biharmonic maps, and we characterize the biharmonicity of some curves on Riemannian manifolds.

### 1. Preliminaries and Notations

Let  $(M, g)$  be a Riemannian manifold. By  $R$ , Ric and Ricci we denote respectively the Riemannian curvature tensor, the Ricci curvature and the Ricci tensor of  $(M, g)$ . Thus  $R$ , Ric and Ricci are defined by:

$$(1.1) \quad R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]}Z,$$

$$(1.2) \quad \text{Ric}(X, Y) = g(R(X, e_i)e_i, Y), \quad \text{Ricci } X = R(X, e_i)e_i,$$

where  $\nabla$  is the Levi-Civita connection with respect to  $g$ ,  $\{e_i\}$  is an orthonormal frame, and  $X, Y, Z \in \Gamma(TM)$ . Given a smooth function  $f$  on  $M$ , the gradient of  $f$  is defined by

$$(1.3) \quad g(\text{grad } f, X) = X(f), \quad \text{grad } f = e_i(f)e_i,$$

the Hessian of  $f$  is defined by

$$(1.4) \quad \text{Hess}_f(X, Y) = g(\nabla_X \text{grad } f, Y),$$

where  $X, Y \in \Gamma(TM)$ , the Laplacian of  $f$  is defined by

$$(1.5) \quad \Delta f = \text{trace Hess}_f = g(\nabla_{e_i} \text{grad } f, e_i).$$

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(For more details, see for example [6]).

Let  $\varphi : (M, g) \rightarrow (N, h)$  be a smooth map between two Riemannian manifolds, the tension field of  $\varphi$  is given by

$$(1.6) \quad \tau(\varphi) = \text{trace } \nabla d\varphi = \nabla_{e_i}^\varphi d\varphi(e_i) - d\varphi(\nabla_{e_i} e_i),$$

where  $\{e_i\}$  is an orthonormal frame on  $(M, g)$ , and  $\nabla^\varphi$  denote the pull-back connection on  $\varphi^{-1}TN$ . Then,  $\varphi$  is called harmonic map if the tension field vanishes, i.e.  $\tau(\varphi) = 0$  (for more details on the concept of harmonic maps see [2, 3, 4]). We define the index form for harmonic maps by (see [8]):

$$(1.7) \quad I(v, w) = \int_M h(J_\varphi(v), w)v^g, \quad v, w \in \Gamma(\varphi^{-1}TN)$$

(or over any compact subset  $D \subset M$ ), where:

$$(1.8) \quad \begin{aligned} J_\varphi(v) &= -\text{trace } R^N(v, d\varphi)d\varphi - \text{trace}(\nabla^\varphi)^2 v \\ &= -R^N(v, d\varphi(e_i))d\varphi(e_i) - \nabla_{e_i}^\varphi \nabla_{e_i}^\varphi v + \nabla_{\nabla_{e_i} e_i}^\varphi v, \end{aligned}$$

$R^N$  is the curvature tensor of  $(N, h)$ ,  $\nabla^N$  is the Levi-Civita connection of  $(N, h)$ , and  $v^g$  is the volume form of  $(M, g)$ . If  $\tau_2(\varphi) \equiv J_\varphi(\tau(\varphi))$  is null on  $M$ , then  $\varphi$  is called a biharmonic map (see [3], [5]).

## 2. The Riemannian Manifold $(M, \tilde{g})$

**Definition 2.1.** Let  $M$  be a Riemannian manifold equipped with Riemannian metric  $g$ , and let  $f \in C^\infty(M)$ . We define on  $M$  a Riemannian metric, denoted  $\tilde{g}$ , by  $\tilde{g} = g + df \otimes df$ . For  $X, Y \in \Gamma(TM)$ , we have the following

$$(2.1) \quad \tilde{g}(X, Y)_x = g(X, Y)_x + X(f)_x Y(f)_x, \quad \forall x \in M.$$

The Levi-Civita connection of  $(M, \tilde{g})$  can now be related to those of  $(M, g)$  as follows.

**Theorem 2.2.** Let  $(M, g)$  be a Riemannian manifold, if  $\tilde{\nabla}$  denote the Levi-Civita connection of  $(M, \tilde{g})$ , then

$$(2.2) \quad \tilde{\nabla}_X Y = \nabla_X Y + \frac{\text{Hess}_f(X, Y)}{1 + \|\text{grad } f\|^2} \text{grad } f,$$

where  $\nabla$  is the Levi-Civita connection of  $(M, g)$ ,  $\text{Hess}_f$  (resp.  $\text{grad } f$ ) is the Hessian (resp. the gradient vector) of  $f$  with respect to  $g$ , and  $\|\text{grad } f\|^2 = g(\text{grad } f, \text{grad } f)$ .

*Proof.* Let  $X, Y, Z \in \Gamma(TM)$ , from the Koszul formula (see [6]), we have

$$(2.3) \quad \begin{aligned} 2\tilde{g}(\tilde{\nabla}_X Y, Z) &= 2g(\nabla_X Y, Z) + X(Y(f)Z(f)) + Y(Z(f)X(f)) \\ &\quad - Z(X(f)Y(f)) + Z(f)[X, Y](f) + Y(f)[Z, X](f) \\ &\quad - X(f)[Y, Z](f), \end{aligned}$$

let  $\{E_i\}$  be a geodesic frame on  $(M, g)$  at  $x \in M$ , by (2.3) we obtain

$$(2.4) \quad \begin{aligned} 2\tilde{g}(\tilde{\nabla}_X Y, E_i) &= 2g(\nabla_X Y, E_i) + X(Y(f)g(E_i, \text{grad } f)) \\ &\quad + Y(X(f)g(E_i, \text{grad } f)) - E_i(g(X, \text{grad } f)g(Y, \text{grad } f)) \\ &\quad + E_i(f)[X, Y](f) + Y(f)(\nabla_{E_i} X)(f) + X(f)(\nabla_{E_i} Y)(f), \end{aligned}$$

from equation (2.4), and the definition of Hessian (1.4), we get

$$(2.5) \quad \begin{aligned} \tilde{g}(\tilde{\nabla}_X Y, E_i) &= g(\nabla_X Y, E_i) + g(\nabla_X Y, \text{grad } f)g(E_i, \text{grad } f) \\ &\quad + \text{Hess}_f(X, Y)g(E_i, \text{grad } f), \end{aligned}$$

from equation (2.5), we obtain

$$(2.6) \quad \begin{aligned} \tilde{g}(\tilde{\nabla}_X Y, Z) &= g(\nabla_X Y, Z) + g(\nabla_X Y, \text{grad } f)g(Z, \text{grad } f) \\ &\quad + \text{Hess}_f(X, Y)g(Z, \text{grad } f), \end{aligned}$$

so that

$$(2.7) \quad \tilde{g}(\tilde{\nabla}_X Y, Z) = \tilde{g}(\nabla_X Y, Z) + \text{Hess}_f(X, Y)Z(f).$$

Hence Theorem 2.2 follows from (2.7), with

$$(2.8) \quad Z(f) = \frac{1}{1 + \|\text{grad } f\|^2} \tilde{g}(Z, \text{grad } f). \quad \square$$

Now consider the curvature tensor  $\tilde{R}$  of  $(M, \tilde{g})$ , writing  $R$  for the curvature tensor of  $(M, g)$ . We have the following result:

**Theorem 2.3.** *Let  $(M, g)$  be a Riemannian manifold, and let  $f \in C^\infty(M)$ . Then, for all  $X, Y, Z \in \Gamma(TM)$ , we have*

$$(2.9) \quad \begin{aligned} \tilde{R}(X, Y)Z &= R(X, Y)Z + \frac{g(R(X, Y) \text{grad } f, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f \\ &\quad - \frac{\text{Hess}_f(X, \text{grad } f) \text{Hess}_f(Y, Z)}{(1 + \|\text{grad } f\|^2)^2} \text{grad } f \\ &\quad + \frac{\text{Hess}_f(Y, \text{grad } f) \text{Hess}_f(X, Z)}{(1 + \|\text{grad } f\|^2)^2} \text{grad } f \\ &\quad + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \nabla_X \text{grad } f - \frac{\text{Hess}_f(X, Z)}{1 + \|\text{grad } f\|^2} \nabla_Y \text{grad } f. \end{aligned}$$

*Proof.* By the definition of the curvature tensor  $\tilde{R}$ ,

$$(2.10) \quad \tilde{R}(X, Y)Z = \tilde{\nabla}_X \tilde{\nabla}_Y Z - \tilde{\nabla}_Y \tilde{\nabla}_X Z - \tilde{\nabla}_{[X, Y]} Z,$$

and Theorem 2.2, we obtain

$$\begin{aligned}
\tilde{R}(X, Y)Z &= \tilde{\nabla}_X(\nabla_Y Z + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
&\quad - \tilde{\nabla}_Y(\nabla_X Z + \frac{\text{Hess}_f(X, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
(2.11) \quad &\quad - (\nabla_{[X, Y]} Z + \frac{\text{Hess}_f([X, Y], Z)}{1 + \|\text{grad } f\|^2} \text{grad } f),
\end{aligned}$$

the first term of (2.11) is given by

$$\begin{aligned}
&\tilde{\nabla}_X(\nabla_Y Z + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
&= \nabla_X(\nabla_Y Z + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
(2.12) \quad &\quad + \frac{\text{Hess}_f(X, \nabla_Y Z + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f)}{1 + \|\text{grad } f\|^2} \text{grad } f,
\end{aligned}$$

by equation (2.12), and the definition of Hessian (1.4), we obtain

$$\begin{aligned}
&\tilde{\nabla}_X(\nabla_Y Z + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
&= \nabla_X \nabla_Y Z + \frac{g(\nabla_X \nabla_Y \text{grad } f, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f \\
&\quad + \frac{\text{Hess}_f(Y, \nabla_X Z)}{1 + \|\text{grad } f\|^2} \text{grad } f - \frac{\text{Hess}_f(X, \text{grad } f) \text{Hess}_f(Y, Z)}{(1 + \|\text{grad } f\|^2)^2} \text{grad } f \\
(2.13) \quad &\quad + \frac{\text{Hess}_f(Y, Z)}{1 + \|\text{grad } f\|^2} \nabla_X \text{grad } f + \frac{\text{Hess}_f(X, \nabla_Y Z)}{1 + \|\text{grad } f\|^2} \text{grad } f,
\end{aligned}$$

using the similar method, the second term of (2.11) is given by

$$\begin{aligned}
&-\tilde{\nabla}_Y(\nabla_X Z + \frac{\text{Hess}_f(X, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f) \\
&= -\nabla_Y \nabla_X Z - \frac{g(\nabla_Y \nabla_X \text{grad } f, Z)}{1 + \|\text{grad } f\|^2} \text{grad } f \\
&\quad - \frac{\text{Hess}_f(X, \nabla_Y Z)}{1 + \|\text{grad } f\|^2} \text{grad } f + \frac{\text{Hess}_f(Y, \text{grad } f) \text{Hess}_f(X, Z)}{(1 + \|\text{grad } f\|^2)^2} \text{grad } f \\
(2.14) \quad &\quad - \frac{\text{Hess}_f(X, Z)}{1 + \|\text{grad } f\|^2} \nabla_Y \text{grad } f - \frac{\text{Hess}_f(Y, \nabla_X Z)}{1 + \|\text{grad } f\|^2} \text{grad } f.
\end{aligned}$$

Theorem 2.3 follows from equations (2.11), (2.13) and (2.14).  $\square$

### 3. The Biharmonic of the Identity Map

Let  $(M, g)$  be a Riemannian manifold,  $f \in C^\infty(M)$ , and denote by

$$\begin{aligned} \tilde{I}: (M, g) &\longrightarrow (M, \tilde{g}), \\ x &\longmapsto x \end{aligned}$$

the identity map.

**Theorem 3.1.** *If  $\|\text{grad } f\| = 1$ , then the identity map  $\tilde{I}$  is a proper biharmonic if and only if the function  $f$  is non-harmonic on  $M$ , and satisfying the following*

$$\begin{aligned} (\Delta f) \text{Ricci}(\text{grad } f) &= -(\Delta^2 f) \text{grad } f - \nabla_{\text{grad}(\Delta f)} \text{grad } f \\ &\quad - \frac{\Delta f}{2} \text{grad}(\Delta f), \end{aligned}$$

where  $\Delta f$  is the Laplacian of  $f$  with respect to  $g$ , and  $\Delta^2 f = \Delta(\Delta f)$ .

*Proof.* Let  $\{E_i\}$  be a normal orthonormal frame on  $(M, g)$  at  $x$ , we have

$$\begin{aligned} \tau(\tilde{I}) &= \nabla_{E_i}^{\tilde{I}} d\tilde{I}(E_i) - d\tilde{I}(\nabla_{E_i} E_i) \\ &= \tilde{\nabla}_{E_i} E_i \\ &= \frac{\text{Hess}_f(E_i, E_i)}{1 + \|\text{grad } f\|^2} \text{grad } f \\ (3.1) \quad &= \frac{\Delta f}{2} \text{grad } f, \end{aligned}$$

note that  $\tilde{I}$  is harmonic if and only if  $\Delta f = 0$ , i.e. the function  $f$  is harmonic on  $(M, g)$ . We compute the bitension field of the identity  $\tilde{I}$ , we have

$$\begin{aligned} \tilde{R}(\tau(\tilde{I}), d\tilde{I}(E_i))d\tilde{I}(E_i) &= \frac{\Delta f}{2} \tilde{R}(\text{grad } f, E_i)E_i \\ &= \frac{\Delta f}{2} \left( R(\text{grad } f, E_i)E_i \right. \\ &\quad + \frac{1}{2}g(R(\text{grad } f, E_i) \text{grad } f, E_i) \text{grad } f \\ &\quad - \frac{1}{4} \text{Hess}_f(\text{grad } f, \text{grad } f) \text{Hess}_f(E_i, E_i) \text{grad } f \\ &\quad + \frac{1}{4} \text{Hess}_f(E_i, \text{grad } f) \text{Hess}_f(\text{grad } f, E_i) \text{grad } f \\ &\quad + \frac{1}{2} \text{Hess}_f(E_i, E_i) \nabla_{\text{grad } f} \text{grad } f \\ (3.2) \quad &\quad \left. - \frac{1}{2} \text{Hess}_f(\text{grad } f, E_i) \nabla_{E_i} \text{grad } f \right), \end{aligned}$$

since  $\|\text{grad } f\|$  is constant on  $M$ , we obtain

$$\text{Hess}_f(\text{grad } f, X) = 0, \quad \nabla_{\text{grad } f} \text{grad } f = 0,$$

for all  $X \in \Gamma(TM)$ , from (3.2) and the definition of Ricci curvature, we get

$$(3.3) \quad \begin{aligned} \tilde{R}(\tau(\tilde{I}), d\tilde{I}(E_i))d\tilde{I}(E_i) &= \frac{\Delta f}{2} \left( \text{Ricci}(\text{grad } f) \right. \\ &\quad \left. - \frac{1}{2} \text{Ric}(\text{grad } f, \text{grad } f) \text{grad } f \right). \end{aligned}$$

We compute

$$(3.4) \quad \begin{aligned} \nabla_{E_i}^{\tilde{I}} \nabla_{E_i}^{\tilde{I}} \tau(\tilde{I}) - \nabla_{\nabla_{E_i}^{\tilde{I}} E_i}^{\tilde{I}} \tau(\tilde{I}) &= \frac{1}{2} \tilde{\nabla}_{E_i} \tilde{\nabla}_{E_i} \Delta f \text{grad } f \\ &= \frac{1}{2} \tilde{\nabla}_{E_i} \nabla_{E_i} \Delta f \text{grad } f \\ &= \frac{1}{2} \left( \nabla_{E_i} \nabla_{E_i} \Delta f \text{grad } f \right. \\ &\quad \left. + \frac{1}{2} \text{Hess}_f(E_i, \nabla_{E_i} \Delta f \text{grad } f) \text{grad } f \right), \end{aligned}$$

by definitions (1.5), (1.3), (1.4), we get

$$(3.5) \quad \begin{aligned} \nabla_{E_i} \nabla_{E_i} \Delta f \text{grad } f &= (\Delta^2 f) \text{grad } f + 2 \nabla_{\text{grad}(\Delta f)} \text{grad } f \\ &\quad + (\Delta f) \text{trace}(\nabla)^2 \text{grad } f, \\ \frac{1}{2} \text{Hess}_f(E_i, \nabla_{E_i} \Delta f \text{grad } f) &= \frac{\Delta f}{2} g(\nabla_{E_i} \text{grad } f, \nabla_{E_i} \text{grad } f) \\ (3.6) \quad &= -\frac{\Delta f}{2} g(\text{grad } f, \text{trace}(\nabla)^2 \text{grad } f), \end{aligned}$$

from equations (3.3), (3.4), (3.5), (3.6), and the following

$$\text{trace}(\nabla)^2 \text{grad } f = \text{Ricci}(\text{grad } f) + \text{grad}(\Delta f),$$

the identity map  $\tilde{I}$  is a proper biharmonic map if and only if

$$(3.7) \quad \begin{aligned} 2(\Delta f) \text{Ricci}(\text{grad } f) - (\Delta f) \text{Ric}(\text{grad } f, \text{grad } f) \text{grad } f \\ + (\Delta^2 f) \text{grad } f + 2 \nabla_{\text{grad}(\Delta f)} \text{grad } f + (\Delta f) \text{grad}(\Delta f) \\ - \frac{\Delta f}{2} g(\text{grad } f, \text{grad}(\Delta f)) \text{grad } f = 0, \end{aligned}$$

with  $\Delta f \neq 0$ . From (3.7), we have

$$(3.8) \quad (\Delta f) \text{Ric}(\text{grad } f, \text{grad } f) + \Delta^2 f + \frac{\Delta f}{2} g(\text{grad } f, \text{grad}(\Delta f)) = 0.$$

Theorem 3.1 follows from (3.7) and (3.8).  $\square$

**Example 3.2.** Let  $\alpha$  be a non-constant smooth function on  $(0, \infty)$ , such that the derivative function  $\alpha^{(1)} > 0$ , and let  $\mathbb{H}^4 = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 | x_4 > 0\}$

be a 4-dimensional hyperbolic space, we set  $M = (0, \infty) \times \mathbb{H}^4$  equipped with the Riemannian metric

$$g = 2[\alpha^{(1)}(t + x_4)]^2(dt^2 + dx_1^2 + dx_2^2 + dx_3^2 + dx_4^2),$$

and let  $f(t, x_1, x_2, x_3, x_4) = \alpha(t + x_4)$  for all  $(t, x_1, x_2, x_3, x_4) \in M$ . By direct computations we obtain

$$\begin{aligned} \text{grad } f &= \frac{1}{2\alpha^{(1)}(t + x_4)} \left( \frac{\partial}{\partial t} + \frac{\partial}{\partial x_4} \right), \\ \|\text{grad } f\| &= 1, \\ \Delta f &= \frac{4\alpha^{(2)}(t + x_4)}{\alpha^{(1)}(t + x_4)^2}, \\ \Delta^2 f &= \frac{-12\alpha^{(2)}(t + x_4)\alpha^{(3)}(t + x_4) + 4\alpha^{(4)}(t + x_4)\alpha^{(1)}(t + x_4)}{[\alpha^{(1)}(t + x_4)]^5}, \\ \text{grad}(\Delta f) &= \frac{-4[\alpha^{(2)}(t + x_4)]^2 + 2\alpha^{(3)}(t + x_4)\alpha^{(1)}(t + x_4)}{[\alpha^{(1)}(t + x_4)]^5} \left( \frac{\partial}{\partial t} + \frac{\partial}{\partial x_4} \right), \\ \text{Ricci}(\text{grad } f) &= \frac{-2\alpha^{(3)}(t + x_4)\alpha^{(1)}(t + x_4) + 2[\alpha^{(2)}(t + x_4)]^2}{[\alpha^{(1)}(t + x_4)]^5} \left( \frac{\partial}{\partial t} + \frac{\partial}{\partial x_4} \right), \\ \nabla_{\text{grad}(\Delta f)} \text{grad } f &= 0. \end{aligned}$$

According to Theorem 3.1 the identity map  $\tilde{I}: (M, g) \rightarrow (M, \tilde{g})$ , where

$$\tilde{g} = 3[\alpha^{(1)}(t + x_4)]^2(dt^2 + dx_4^2) + 2[\alpha^{(1)}(t + x_4)]^2(dx_1^2 + dx_2^2 + dx_3^2) + 2[\alpha^{(1)}(t + x_4)]^2 dt dx_4,$$

is a proper biharmonic map if and only if

$$(3.9) \quad 5\alpha^{(2)}(t + x_4)\alpha^{(3)}(t + x_4) - \alpha^{(4)}(t + x_4)\alpha^{(1)}(t + x_4) = 0,$$

and  $\alpha^{(2)}(t + x_4) \neq 0$ . Note that, the differential equation (3.9) has solutions, for example, we set  $\alpha(s) = s^2$ , or  $\alpha(s) = \sqrt{s}$ ,  $\forall s \in (0, \infty)$ .

Using the similar technique of Example 3.2 we have:

**Example 3.3.** Let  $M = \mathbb{R}^3$  equipped with the Riemannian metric

$$g = e^{x+y}(dx^2 + dy^2) + e^{\frac{x+y}{2}} dz^2,$$

and let  $f(x, y, z) = \sqrt{2}e^{\frac{x+y}{2}}$ ,  $\forall (x, y, z) \in \mathbb{R}^3$ . Then, the function  $f$  satisfies the conditions of Theorem 3.2 so, the identity map  $\tilde{I}: (\mathbb{R}^3, g) \rightarrow (\mathbb{R}^3, \tilde{g})$  is a proper biharmonic. Here,  $\Delta f = \frac{3\sqrt{2}}{4}e^{-\frac{x+y}{2}}$ , and the Riemannian metric  $\tilde{g}$  is given by

$$\tilde{g} = \frac{3}{2}e^{x+y}(dx^2 + dy^2) + e^{\frac{x+y}{2}} dz^2 + e^{x+y} dx dy.$$

**Remark 3.4.** Let  $(M, g)$  be a Riemannian manifold, and let  $f$  be a smooth function on  $M$  such that  $\|\text{grad } f\| = 1$  and  $\Delta f = k$ , where  $k \in \mathbb{R}$ . Then, the identity map  $\tilde{T} : (M, g) \rightarrow (M, \tilde{g})$  is biharmonic if and only if it is harmonic. Indeed; from Theorem 3.1 the identity map  $\tilde{T}$  is a biharmonic map if and only if  $\text{Ricci}(\text{grad } f) = 0$ , and by Bochner-Weitzenböck formula for smooth functions (see [7])

$$\frac{1}{2}\Delta(\|\text{grad } f\|^2) = \|\text{Hess}_f\|^2 + g(\text{grad } f, \text{grad}(\Delta f)) + \text{Ric}(\text{grad } f, \text{grad } f),$$

we obtain  $\|\text{Hess}_f\| = 0$ , so that  $\Delta f = 0$ , that is  $\tilde{T}$  is harmonic map.

#### 4. Biharmonic Maps into a Product Manifolds

**Definition 4.1.** Let  $M$  and  $N$  be two Riemannian manifolds equipped with Riemannian metrics  $g$  and  $h$ , respectively, and let  $f \in C^\infty(M)$ . Consider the product manifold  $M \times N$  and denote by  $\pi : M \times N \rightarrow M$  and  $\eta : M \times N \rightarrow N$  its projections. We define on  $M \times N$  a Riemannian metric, denoted  $G_f$ , by

$$(4.1) \quad G_f = \pi^*g + \eta^*h + \pi^*(df \otimes df).$$

**Remark 4.2.**

- (1) The Definition 4.1 is a natural generalization of diagonal Riemannian metrics on product Riemannian manifolds (see for example [6]).
- (2)  $(M \times N, G_f)$  is the product Riemannian manifold of the Riemannian manifolds  $(M, \tilde{g})$  and  $(N, h)$ , where  $\tilde{g} = g + df \otimes df$ . Then, the Levi-Civita connection of  $(M \times N, G_f)$  can now be related to those of  $(M, \tilde{g})$  and  $(N, h)$  as follows

$$(4.2) \quad \nabla_X^{G_f} Y = (\tilde{\nabla}_{X_1} Y_1, \nabla_{X_2}^N Y_2),$$

where  $\tilde{\nabla}$  (resp.  $\nabla^N$ ) is the Levi-Civita connection of  $(M, \tilde{g})$  (resp.  $(N, h)$ ), the same for the Riemannian curvature tensor  $R^{G_f}$  of  $(M \times N, G_f)$ , we have

$$(4.3) \quad R^{G_f}(X, Y)Z = (\tilde{R}(X_1, Y_1)Z_1, R^N(X_2, Y_2)Z_2),$$

where  $\tilde{R}$  (resp.  $R^N$ ) is the Riemannian curvature tensor of  $(M, \tilde{g})$  (resp.  $(N, h)$ ).

Here,  $X = (X_1, X_2), Y = (Y_1, Y_2), Z = (Z_1, Z_2) \in \Gamma(TM) \times \Gamma(TN)$ .

Next, let  $y_0$  be an arbitrary point of a Riemannian manifold  $(N, h)$ , and denote by  $i_{y_0} : (M, g) \rightarrow (M \times N, G_f)$ ,  $x \mapsto (x, y_0)$  the inclusion map of  $M$  at the  $y_0$  level in  $M \times N$ , where  $(M, g)$  is a Riemannian manifold, and  $f \in C^\infty(M)$ . We note that the inclusion  $i_{x_0} : (N, h) \rightarrow (M \times N, G_f)$ , defined by  $i_{x_0}(y) = (x_0, y)$  is always a totally geodesic map, that is  $\nabla di_{x_0} = 0$ , thus harmonic for any function  $f \in C^\infty(M)$ . From Theorem 3.1, we get the following



**Theorem 4.3.** *If  $\|\text{grad } f\| = 1$ , the inclusion map  $i_{y_0}$  is a proper biharmonic map if and only if the identity map  $\tilde{I} : (M, g) \rightarrow (M, \tilde{g})$  is a proper biharmonic.*

**Theorem 4.4.** *Let  $\psi : (M, g) \rightarrow (N, h)$  be a smooth map and  $f$  a harmonic function on  $(M, g)$ . Then, the graph map  $\varphi : (M, g) \rightarrow (M \times N, G_f)$  with  $\varphi(x) = (x, \psi(x))$  is a biharmonic if and only if the map  $\psi : (M, g) \rightarrow (N, h)$  is a biharmonic. Furthermore, if  $\psi$  is proper biharmonic, then so is the graph.*

*Proof.* Let  $\{E_i\}$  be a normal orthonormal frame on  $(M, g)$  at  $x$ , from the definition of tension field, Theorem 2.2, and (4.2), we have

$$\begin{aligned}
 \tau(\varphi) &= \nabla_{E_i}^\varphi d\varphi(E_i) - d\varphi(\nabla_{E_i}^M E_i) \\
 &= \nabla_{(E_i, d\psi(E_i))}^{G_f}(E_i, d\psi(E_i)) \\
 &= \left( \frac{\text{Hess}_f(E_i, E_i)}{1 + \|\text{grad } f\|^2} \text{grad } f, \nabla_{d\psi(E_i)}^N d\psi(E_i) \right) \\
 (4.4) \quad &= \left( \frac{\Delta f}{1 + \|\text{grad } f\|^2} \text{grad } f, \tau(\psi) \right),
 \end{aligned}$$

so that  $\varphi$  is harmonic if and only if  $\Delta f = 0$  and  $\tau(\psi) = 0$ , i.e. the function  $f$  is harmonic on  $(M, g)$ , and  $\psi$  is a harmonic map. Next, we compute the bitension field of the graph map, with  $\Delta f = 0$ . Let  $\{E_i\}$  be an orthonormal frame on  $(M, g)$ , according to (4.4) the tension field of  $\varphi$  is given by  $\tau(\varphi) = (0, \tau(\psi))$ , we compute

$$\begin{aligned}
 R^{G_f}(\tau(\varphi), d\varphi(E_i))d\varphi(E_i) &= R^{G_f}((0, \tau(\psi)), (E_i, d\psi(E_i)))(E_i, d\psi(E_i)) \\
 (4.5) \quad &= (0, R^N(\tau(\psi), d\psi(E_i))d\psi(E_i)),
 \end{aligned}$$

by (4.5) and the following

$$(4.6) \quad \nabla_{E_i}^\varphi \nabla_{E_i}^\varphi \tau(\varphi) = \tilde{\nabla}_{(E_i, d\psi(E_i))}^N (0, \nabla_{d\psi(E_i)}^N \tau(\psi)) = (0, \nabla_{E_i}^\psi \nabla_{E_i}^\psi \tau(\psi)),$$

we have  $\tau_2(\varphi) = (0, \tau_2(\psi))$ , so that the graph map  $\varphi$  is a biharmonic if and only if  $\tau_2(\psi) = 0$ .  $\square$

**Remark 4.5.** Using Theorem 4.4, we can construct many examples for proper biharmonic maps.

**Example 4.6.** The map  $\varphi : \mathbb{R}^4 \setminus \{0\} \rightarrow (\mathbb{R}^4 \times \mathbb{R}^4, G_f)$  given by  $\varphi(x) = (x, x/\|x\|^2)$  is a proper biharmonic map, where  $f$  is a smooth harmonic function on  $\mathbb{R}^4 \setminus \{0\}$ . This follows from Theorem 4.2 and the fact that  $\varphi$  is the graph of the inversion  $\psi : \mathbb{R}^4 \setminus \{0\} \rightarrow \mathbb{R}^4$  defined by  $\psi(x) = x/\|x\|^2$  which is known ([1]) to be a proper biharmonic map

### 5. Biharmonic Curve in $(M, \tilde{g})$

Let  $\gamma : I \subset \mathbb{R} \rightarrow (M, \tilde{g})$ ,  $t \mapsto \gamma(t)$  be a differentiable curve in a Riemannian manifold  $(M, g)$ , where  $f$  be a smooth function on  $M$ . Suppose that

$$\|\text{grad } f\| = 1, \quad \nabla_{\dot{\gamma}} \dot{\gamma} = \lambda(\text{grad } f) \circ \gamma,$$

for some smooth function  $\lambda : I \rightarrow \mathbb{R}$ . We have the following result:

**Theorem 5.1.** *The curve  $\gamma$  is biharmonic if and only if the function  $f$  satisfies the following*

$$\rho R((\text{grad } f) \circ \gamma, \dot{\gamma})\dot{\gamma} + 2\rho''(\text{grad } f) \circ \gamma + 2\rho'\nabla_{\dot{\gamma}} \text{grad } f + \rho\nabla_{\dot{\gamma}}\nabla_{\dot{\gamma}} \text{grad } f = 0,$$

where  $\rho(t) = \lambda(t) + \frac{1}{2} \text{Hess}_f(\dot{\gamma}, \dot{\gamma})$ ,  $\forall t \in I$ . Furthermore, if the function  $\rho$  is a non-null constant on  $I$ , then the curve  $\gamma$  is a proper biharmonic if and only if the gradient vector of  $f$  is Jacobi field along  $\gamma$  on  $(M, g)$ , i.e.

$$R((\text{grad } f) \circ \gamma, \dot{\gamma})\dot{\gamma} + \nabla_{\dot{\gamma}}\nabla_{\dot{\gamma}} \text{grad } f - \nabla_{\nabla_{\dot{\gamma}} \dot{\gamma}} \text{grad } f = 0.$$

*Proof.* The tension field of the curve  $\gamma$  is given by

$$(5.1) \quad \tau(\gamma) = \nabla_{\frac{d}{dt}}^{\gamma} d\gamma\left(\frac{d}{dt}\right) = \tilde{\nabla}_{\dot{\gamma}} \dot{\gamma},$$

by (5.1), and Theorem 2.2, we have

$$(5.2) \quad \tau(\gamma) = \nabla_{\dot{\gamma}} \dot{\gamma} + \frac{1}{2} \text{Hess}_f(\dot{\gamma}, \dot{\gamma})(\text{grad } f) \circ \gamma,$$

we set  $\rho(t) = \lambda(t) + \frac{1}{2} \text{Hess}_f(\dot{\gamma}(t), \dot{\gamma}(t))$ , with  $\nabla_{\dot{\gamma}} \dot{\gamma} = \lambda(\text{grad } f) \circ \gamma$ , we get

$$(5.3) \quad \tau(\gamma) = \rho(\text{grad } f) \circ \gamma,$$

now, the curve  $\gamma$  is biharmonic if and only if

$$(5.4) \quad \tilde{R}(\tau(\gamma), d\gamma\left(\frac{d}{dt}\right))d\gamma\left(\frac{d}{dt}\right) + \nabla_{\frac{d}{dt}}^{\gamma} \nabla_{\frac{d}{dt}}^{\gamma} \tau(\gamma) = 0,$$

from (5.3), and Theorem 2.3, with

$$\text{Hess}_f(\text{grad } f, X) = 0, \quad \nabla_{\text{grad } f} \text{grad } f = 0,$$

for all  $X \in \Gamma(TM)$ , the first term on the left-hand side of (5.4) is

$$(5.5) \quad \begin{aligned} \tilde{R}(\tau(\gamma), d\gamma\left(\frac{d}{dt}\right))d\gamma\left(\frac{d}{dt}\right) &= \rho R((\text{grad } f) \circ \gamma, \dot{\gamma})\dot{\gamma} \\ &+ \frac{\rho}{2} g(R((\text{grad } f) \circ \gamma, \dot{\gamma})(\text{grad } f) \circ \gamma, \dot{\gamma})(\text{grad } f) \circ \gamma, \end{aligned}$$

for the second term on the left-hand side of (5.4), we compute

$$(5.6) \quad \begin{aligned} \nabla_{\frac{d}{dt}}^{\gamma} \tau(\gamma) &= \nabla_{\frac{d}{dt}}^{\gamma} \rho(\text{grad } f) \circ \gamma \\ &= \rho'(\text{grad } f) \circ \gamma + \rho \tilde{\nabla}_{\dot{\gamma}} \text{grad } f, \end{aligned}$$

by (5.6), and Theorem 2.2, we get

$$(5.7) \quad \begin{aligned} \nabla_{\frac{d}{dt}}^{\gamma} \nabla_{\frac{d}{dt}}^{\gamma} \tau(\gamma) &= \nabla_{\frac{d}{dt}}^{\gamma} [\rho'(\text{grad } f) \circ \gamma + \rho \tilde{\nabla}_{\dot{\gamma}} \text{grad } f] \\ &= \rho''(\text{grad } f) \circ \gamma + \rho' \nabla_{\frac{d}{dt}}^{\gamma} (\text{grad } f) \circ \gamma \\ &\quad + \rho' \tilde{\nabla}_{\dot{\gamma}} \text{grad } f + \rho \nabla_{\frac{d}{dt}}^{\gamma} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f \\ &= \rho''(\text{grad } f) \circ \gamma + 2\rho' \tilde{\nabla}_{\dot{\gamma}} \text{grad } f \\ &\quad + \rho \tilde{\nabla}_{\dot{\gamma}} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f + \frac{\rho}{2} \text{Hess}_f(\dot{\gamma}, \tilde{\nabla}_{\dot{\gamma}} \text{grad } f)(\text{grad } f) \circ \gamma, \end{aligned}$$

by definition (1.4), with  $\|\text{grad } f\| = 1$ , we have

$$(5.8) \quad \text{Hess}_f(\dot{\gamma}, \tilde{\nabla}_{\dot{\gamma}} \text{grad } f) = -g((\text{grad } f) \circ \gamma, \tilde{\nabla}_{\dot{\gamma}} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f),$$

from (5.5), (5.7) and (5.8), the the curve  $\gamma$  is biharmonic if and only if

$$(5.9) \quad \begin{aligned} &\rho R((\text{grad } f) \circ \gamma, \dot{\gamma})\dot{\gamma} + \frac{\rho}{2} g(R((\text{grad } f) \circ \gamma, \dot{\gamma})(\text{grad } f) \circ \gamma, \dot{\gamma})(\text{grad } f) \circ \gamma \\ &+ \rho''(\text{grad } f) \circ \gamma + 2\rho' \tilde{\nabla}_{\dot{\gamma}} \text{grad } f + \rho \tilde{\nabla}_{\dot{\gamma}} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f \\ &- \frac{\rho}{2} g((\text{grad } f) \circ \gamma, \tilde{\nabla}_{\dot{\gamma}} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f)(\text{grad } f) \circ \gamma = 0, \end{aligned}$$

by equation (5.9) we find that

$$(5.10) \quad \begin{aligned} &-\frac{\rho}{2} g(R((\text{grad } f) \circ \gamma, \dot{\gamma})(\text{grad } f) \circ \gamma, \dot{\gamma}) + \rho'' \\ &+ \frac{\rho}{2} g((\text{grad } f) \circ \gamma, \tilde{\nabla}_{\dot{\gamma}} \tilde{\nabla}_{\dot{\gamma}} \text{grad } f) = 0. \end{aligned}$$

The Theorem 5.1, follows from (5.9) and (5.10).  $\square$

**Remark 5.2.** From equation (5.3), the curve  $\gamma$  is harmonic if and only if  $\rho = 0$ .

**Example 5.3.** Let  $\mathbb{D} = \{(x, y) \in \mathbb{R}^2 | x^2 + y^2 < 1\}$ , and let  $M = \mathbb{D} \times \mathbb{R}$  equipped with the Riemannian metric

$$g = dx^2 + dy^2 + \frac{1}{1 - x^2 - y^2} dz^2.$$

We consider the curve on  $(M, g)$ ,

$$\gamma(t) = (t, t, -t^2 + 2t - \ln(t+1)), \quad \frac{1}{\sqrt{2}} > t > -\frac{1}{\sqrt{2}}.$$

The tension field of the curve  $\gamma$  (with respect to  $g$ ) is given by

$$\left( -\frac{t}{(t+1)^2}, -\frac{t}{(t+1)^2}, \frac{-1+2t^2}{(t+1)^2} \right)$$

Let  $f(x, y, z) = xy + z$ ,  $\forall (x, y, z) \in M$ , we have

$$\|\text{grad } f\| = 1, \quad (\text{grad } f) \circ \gamma = (t, t, 1 - 2t^2),$$

so that,  $\lambda(t) = -\frac{1}{(t+1)^2}$ , and note that

$$\frac{1}{2} \text{Hess}_f(\dot{\gamma}, \dot{\gamma}) = \frac{1}{(t+1)^2},$$

then the curve  $\gamma$  is harmonic on  $(M, \tilde{g})$ , because  $\rho(t) = 0$ , with

$$\tilde{g} = (1 + y^2)dx^2 + (1 + x^2)dy^2 + \frac{x^2 + y^2 - 2}{x^2 + y^2 - 1}dz^2 + 2xydx dy + 2ydx dz + 2xdy dz.$$

**Example 5.4.** Let  $M = \mathbb{R}^n \setminus \{0\}$  equipped with the Riemannian metric  $g = 4\|x\|^2 dx_i^2$ ,  $f(x) = \|x\|^2$ ,  $\forall x \in M$ , and consider the proper biharmonic curve on  $(M, g)$ ,

$$\gamma(t) = \left( \sqrt{\frac{t^2 + 1}{2}}, 0, \dots, 0 \right), \quad \forall t \in \mathbb{R}.$$

Then,  $\|\text{grad } f\| = 1$ , the gradient vector of  $f$  is Jacobi field along  $\gamma$ ,

$$\nabla_{\dot{\gamma}} \dot{\gamma} = (\text{grad } f) \circ \gamma = \frac{1}{\sqrt{2t^2 + 2}} \frac{\partial}{\partial x_1},$$

and note that  $\text{Hess}_f(\dot{\gamma}, \dot{\gamma}) = 0$ , so that  $\rho(t) = 1$ ,  $\forall t \in \mathbb{R}$ . According to Theorem 5.1 the curve  $\gamma : \mathbb{R} \rightarrow (M, \tilde{g})$  is also proper biharmonic, with

$$\tilde{g} = 4\|x\|^2 dx_i^2 + 4x_i x_j dx_i \otimes dx_j.$$

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