

Design and Implementation of Vehicle Internal Alarm System using Raspberry-pie Multi-sensor

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Abstract

This paper describes the design and implementation of a vehicle internal alarm system using raspberry-pie and gas sensor. It provides a notification system for sleepiness during driving, a driving time notification system and a smoking detection system. We coded using 'Python'. And we use 'MySQL' and 'PHP' to build the necessary servers and web pages for gathering sensing data and monitoring. The developed system was tested by several methods. All experiments showed satisfactory response signals and detected with immediate responses.

Keywords: Vehicle Internal Alarm System, Raspberry-pie, Multi-sensor, Smoking Detection System

1. Introduction

Today, car accidents are a hot topic brought up when watching the news. These accidents commonly arise due to as many calls it, 'sleep-driving'. Many drivers will close their windows to either use the heater or air-conditioner, however at the same time, the carbon dioxide (CO₂) that is created as we breathe out will build up inside our cars. This will eventually cause the people in the car to become drowsy which may lead to an accident. To prevent this from happening we have built a microcomputer called Raspberry-pie[1] which warns the driver to ventilate the car when the possibility of sleep-driving seems too high. On the other hand, many people today use car sharing services and although smoking while using such benefits are banned, it's extremely hard for owners of these car sharing services to completely exterminate the use of cigarettes. Furthermore, for future customers the stench of cigarettes may be very uncomfortable. Hence to fix this issue, the 'Raspberry-pie' can be used to inform the car sharing service owners/companies if smoking is detected within the cars. Finally, long-distance drives can increase the chances of a car accident; therefore, a system will be created to inform the driver to take breaks during certain intervals. There were many researches using sensor in the traffic field [2]. But this paper is a research for easy application to the real world. Section 2 of the paper briefly describes the major hardware components used in the system. Section 3 describes the design and implementation of the system in detail, section 4 explains the experimental results and section 5 will be the conclusion.

2. Major hardware and software environment

There are three main functions used to create the system in raspberry-pie. These include an alarm that notifies the need of ventilation by the measure of air quality, a smoke detection system and a Timer-based 'break-reminder' system. Inside the car, the raspberry-pie's air quality sensor [3, 4] will measure the carbon dioxide levels in real time. If the levels are too high the system will output a message to ventilate the car. Inside the car, the raspberry-pie's air quality sensor will measure the carbon dioxide levels in real time. If the levels are too high the system will output a message to ventilate the car. Furthermore, the timer function in raspberry-pie will immediately activate as the car starts up and will output a message to take a break during the chosen time intervals to avoid sleep-driving for long-distance drivers. For the car sharing services, raspberry-pie's smoke detection sensor [3, 4] is placed within the car and will directly send the customer's information through the owner/company's server's real time if smoking is detected.



Figure 1. Air quality



Figure 2. Smoke detection sensor



Figure 3. Raspberry-Pie

The most important component in the proposed system's software environment is the construction and reconfiguration of the server as the correct configuration as it will allow the server to manage the information from the raspberry-pie. To successfully achieve this system, an Apache web server [5] will be made and My-SQL DB [6, 7] will be installed and used as a database. Also we used three different types of languages including, PHP [7, 8], Python [9] and JavaScript to implement the system.

3. System Design and Implementation

3.1 System Design and Algorithm

Figure 4 shows the overall structure of the site's design and implementation. When the air quality sensor detects a certain amount of carbon dioxide in the vehicle, the system will inform the driver through either a display or sound system in the vehicle. Meanwhile a transmission system will be constructed for the car renting company. As soon as the smoke sensor inside the car encounters smoke, it'll quickly record the time of when the smoke was recognized and the car number which will be sent directly to the car company. Also, for the timer inside the car, a system was implemented that will notify the driver to take a break after a certain predefined period has elapsed since the vehicle was started.

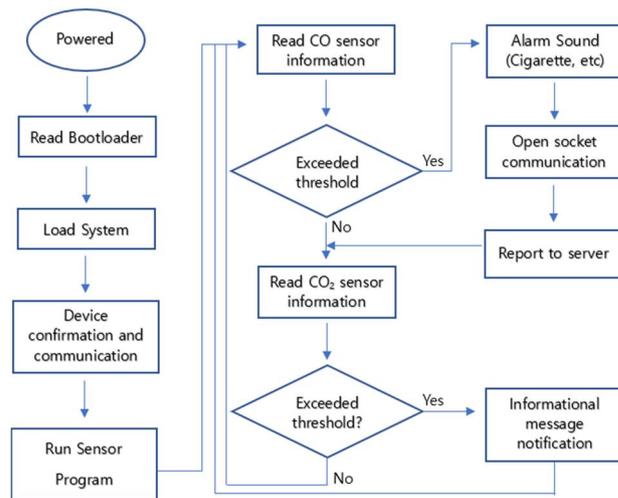


Figure 4. Configuration Diagram

3.2 System details and implementation

3.2.1 Air quality measurement

Air quality measurements will be made using a sensor that identifies carbon dioxide and air quality called ZP01-MP503. First, when looking at the data sheet in Figure 5, pin 1 is ground, pin 2 is VCC, pin 3 is signal A and pin 4 is signal B. When both signal A and B from the sensor show 0V, the air quality is very good. When signal A shows 0V while B shows 5V the air quality is good. Vice versa, when Signal A shows 5V and B shows 0V the air quality is normal and finally, when both Signal A and B show 5V the air quality is bad. By using this as a basis of air quality measurement we have decided that ventilation is required when the air quality reaches bad (both Signal A and B show 5V).

Pin definition

Pin	Name	Function
1	GND	Input power -
2	5V	Input power +
3	A	Output A
4	B	Output B

Output Signal

Grade	Output A	Output B	Pollution Grade
0	0V	0V	Clean
1	0V	+5V	Light pollution
2	+5V	0V	Moderate pollution
3	+5V	+5V	Severe pollution

Figure 5. CO₂ Sensor Data

The ADC (MCP3008) utilizes 7 pins. As channels 1~7 are left, these are connected to channels 1 and 2. It is important to note that if signal A and B is connected to the MCP3008 directly when emitting 5V it'll most likely damage the ADC; hence it should be adjusted within the range of 3~4V with the appropriate resistance. Now the components are connected as the following. Air quality sensor to channel 0, ZP01-MP503's signal A to channel 1 and ZP01-MP503's signal B to channel 2. This connection structure makes the development much easier. Figure 6 shows a code that reads can read multiple channels, furthermore this code detects and outputs once per second. Ultimately, while channel 0 gets its value from the smoke sensor, channels 1 and 2 gets its value from the air quality sensor. This value is then calculated and the code will output a voltage

value.

The coding in figure 6 is saved as spisensor.py to run. “sudo python spisensor.py” can then be inputted into the command line to run this code, furthermore the results are as shown in figure 7. In figure 7, channel 0 is reading the value from the carbon dioxide sensor while channel 1 and 2 are the values of ZP01-MP503’s A and B. It is also seen that channels 1 and 2 are below 0.2V, so this voltage is treated as 0V. Overall, as A and B are both assumed to be emitting no signals the air quality is good.

```

spisensor.py - /home/pi/gpiotest/spisensor.py (3.4.2)
File Edit Format Bun Options Windows Help
import time
import spidev
import sys, os

spi = spidev.SpiDev()
spi.open(0,0)

def analog_read(channel):
    rspi.xfer2([1,(8-channel) << 4,0])
    adc_out = ((r[1]&3)<<8) + r[2]
    return adc_out

while True:
    reading0 = analog_read(0)
    voltage0 = reading0 * 3.3 / 1024
    print("Chnne10 Reading=%d \t Voltage=%f" % (reading0,voltage0))

    reading1 = analog_read(1)
    voltage1 = reading1 * 3.3 / 1024
    print("Chnne11 Reading=%d \t Voltage=%f" % (reading1,voltage1))

    reading2 = analog_read(2)
    voltage2 = reading2 * 3.3 / 1024
    print("Chnne12 Reading=%d \t Voltage=%f" % (reading2,voltage2))
    print("\n")
    time.sleep(1)
    
```

Figure 6. CO₂ Sensor additional coding

```

pi@raspberrypi: ~/gpiotest
pi@raspberrypi:~$ cd gpiotest
pi@raspberrypi:~/gpiotest$ ls
a.out  python-spi  sensor1.py  sensors.py  spisensor.py
pi@raspberrypi:~/gpiotest$ sudo python spisensor.py
py-spidev screen sensor.py spidev_test.c
Chnne10 Reading=108      Voltage=0.348047
Chnne11 Reading=42      Voltage=0.135352
Chnne12 Reading=76      Voltage=0.244922

Chnne10 Reading=107      Voltage=0.344824
Chnne11 Reading=42      Voltage=0.135352
Chnne12 Reading=21      Voltage=0.067676

Chnne10 Reading=107      Voltage=0.344824
Chnne11 Reading=43      Voltage=0.138574
Chnne12 Reading=0        Voltage=0.000000

Chnne10 Reading=108      Voltage=0.348047
Chnne11 Reading=43      Voltage=0.138574
Chnne12 Reading=5        Voltage=0.016113

Chnne10 Reading=108      Voltage=0.348047
Chnne11 Reading=43      Voltage=0.138574
Chnne12 Reading=42      Voltage=0.135352
    
```

Figure 7. CO₂ Sensor

Figure 8 shows an experiment in which a sensor is placed inside a sealed container which is filled with carbon dioxide. This is the type of environment with a lack of oxygen with leads to drowsiness.

When looking at the results of the above experiment in figure 9, it can be seen that both Channel 1 and 2 show the value of 1023. This outputs the fact that the air at this point is bad according to figure 5. When actually measuring the voltage value it comes to about 3.5V, meanwhile the value in figure 7 says 3.296777 which is about 3.3V. When looking at the datasheet of MCP3008, there is a voltage limit of 5.5V, hence to the appropriate resistance was used to attain a stable result. Overall, when signal A and B shows the value of 1023, there will be a message for the driver to ventilate the vehicle.



Figure 8. CO₂ Sensor measurement

```

pi@raspberrypi:~/gpiotest
Chnne11 Reading=1023      Voltage=3.296777
Chnne12 Reading=1023      Voltage=3.296777

Chnne10 Reading=200      Voltage=0.644531
Chnne11 Reading=1023      Voltage=3.296777
Chnne12 Reading=1023      Voltage=3.296777

Chnne10 Reading=193      Voltage=0.621973
Chnne11 Reading=1023      Voltage=3.296777
Chnne12 Reading=1023      Voltage=3.296777

Chnne10 Reading=188      Voltage=0.605859
Chnne11 Reading=1023      Voltage=3.296777
Chnne12 Reading=1023      Voltage=3.296777

Chnne10 Reading=188      Voltage=0.605859
Chnne11 Reading=1023      Voltage=3.296777
Chnne12 Reading=1023      Voltage=3.296777
    
```

Figure 9. CO₂ Sensor measurement results

3.2.2 Smoke sensor

Figure 10 shows the process of reading the analog sensor values. The MCP3008 has a total of 8 channels ranging from 0~7. One sensor was installed at channel 0 and a code was made as shown in figure 10 which reads the output value of channel 0 once per second. Moreover, the principle of analog sensors was used to create the coding in figure 10. The ADC MCP3008 receives the voltage of 3.3V and reads the voltage value of channels 0~7 and returns the value of the digital signals. To immediately run the python code that was created above, the command 'sudo' can be used as shown in figure 11. To use raspberry pie's hardware functions, the use of "sudo" command is necessary as you need super user privileges.



```

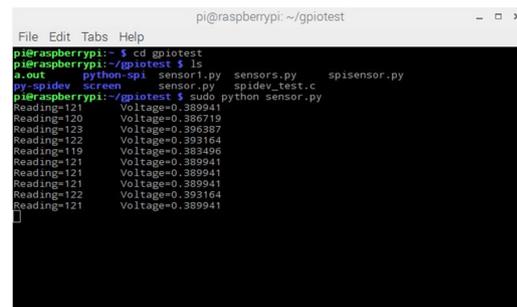
sensor.py - /home/pi/gpiotest/sensor.py (3.4.2)
File Edit Format Run Options Windows Help
import time
import spidev
import sys, os

spi = spidev.SpiDev()
spi.open(0,0)

def analog_read(channel):
    r=spi.xfer2([1,(8+channel) << 4,0])
    adc_out = ((r[1]&3)<<8) + r[2]
    return adc_out

while True:
    reading = analog_read(0)
    voltage = reading * 3.3 / 1024
    print("Reading=%d \t Voltage=%f" % (reading,voltage))
    time.sleep(1)
  
```

Figure 10. Analog sensor value load



```

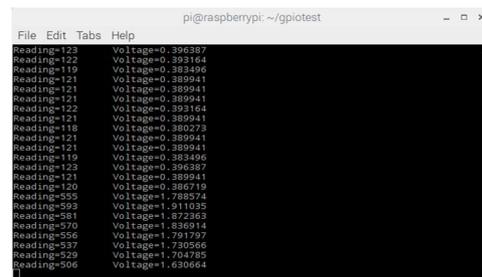
pi@raspberrypi: ~ - ssh
pi@raspberrypi:~$ cd gpiotest
pi@raspberrypi:~/gpiotest$ ls
ls -l
-rw-r--r-- 1 pi pi 1024 2018-07-11 10:24 sensor.py
-rw-r--r-- 1 pi pi 1024 2018-07-11 10:24 spidev_test.c
pi@raspberrypi:~/gpiotest$ sudo python sensor.py
Reading=121 Voltage=0.389941
Reading=120 Voltage=0.386719
Reading=123 Voltage=0.396387
Reading=122 Voltage=0.393164
Reading=119 Voltage=0.383496
Reading=121 Voltage=0.389941
Reading=121 Voltage=0.389941
Reading=121 Voltage=0.389941
Reading=122 Voltage=0.393164
Reading=121 Voltage=0.389941
  
```

Figure 11. The command 'sudo'

In figure 12, hazardous materials were created to check if the sensors are functioning properly. In this figure the CO sensor (MQ-7) is designed to adjust the sensitivity as it is in analog format. Figure 13 shows that the gas leaks readings ranged from 120 to 555. From here the voltage value from 0V~3.3V was calculated which the results show that it outputs from the range of 0~1023. So, when 3.3/1024 is done, there will be an output of voltage per 1 value. Therefore, if the reading value is 120 is equivalent voltage value is about 0.386719V and this will output a digital value of 120. The CO sensor used in this case detects a certain type of chemical reaction when it is preheated and when it is exposed to gas, the resistance value decreased while the voltage value will increase. Furthermore, the CO sensor usually has a voltage value of less than 0.5 when it's undetectable, meanwhile it can be detected when raised to more than 1.5V.



Figure 12. Hazardous material detection check



```

pi@raspberrypi: ~ - ssh
pi@raspberrypi:~/gpiotest$ sudo python sensor.py
Reading=123 Voltage=0.396387
Reading=122 Voltage=0.393164
Reading=119 Voltage=0.383496
Reading=121 Voltage=0.389941
Reading=121 Voltage=0.389941
Reading=122 Voltage=0.393164
Reading=121 Voltage=0.389941
Reading=118 Voltage=0.380273
Reading=121 Voltage=0.389941
Reading=121 Voltage=0.389941
Reading=119 Voltage=0.383496
Reading=122 Voltage=0.396387
Reading=121 Voltage=0.389941
Reading=120 Voltage=0.386719
Reading=555 Voltage=1.748274
Reading=593 Voltage=1.911035
Reading=561 Voltage=1.872263
Reading=570 Voltage=1.836914
Reading=556 Voltage=1.791797
Reading=537 Voltage=1.720566
Reading=529 Voltage=1.704785
Reading=596 Voltage=1.630664
  
```

Figure 13. CO₂ Sensor detection screen

ventilation when carbon dioxide levels are too high for the prevention drowsiness while driving and the detection of smoke is performed by using a smoke sensor. Additionally, a there is a timer function operating to remind the driver to take a break. This system was tested by several methods. First, the system was installed on the interior of the vehicle and smoke levels were measured by intentionally smoking cigarettes inside the car. Second, the system was placed on a laboratory desk to detect hazardous substances. Third, the timer function inside the car was tested to observe if the vehicle was notified during certain intervals of driving time. All experiments showed satisfactory response signals and detected with immediate responses.

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