

APPLICATION OF PRODUCT OF THE MULTIVARIABLE A -FUNCTION AND THE MULTIVARIABLE SRIVASTAVA'S POLYNOMIALS

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ABSTRACT. Gautam et al. [9] introduced the multivariable A -function, which is very general, reduces to yield a number of special functions, in particular, the multivariable H -function. Here, first, we aim to establish two very general integral formulas involving product of the general class of Srivastava multivariable polynomials and the multivariable A -function. Then, using those integrals, we find a solution of partial differential equations of heat conduction at zero temperature with radiation at the ends in medium without source of thermal energy. The results presented here, being very general, are also pointed out to yield a number of relatively simple results, one of which is demonstrated to be connected with a known solution of the above-mentioned equation.

1. Introduction and preliminaries

We consider a problem on outer heat conduction in a rod under certain boundary conditions. If the thermal coefficients are constants and there is no source of thermal energy, then the temperature $U(x, t)$ in one-dimensional rod $0 \leq x \leq L$ satisfies the following heat equation (see [14, p. 155, Eq. (6.7.1)]):

$$\frac{\partial U}{\partial t} = \mu \frac{\partial^2 U}{\partial x^2} \quad (t \in \mathbb{R}_0^+), \quad (1)$$

where $U(x, t)$ is the temperature distribution function of a thin bar, which has length L , and the positive constant $\mu = \frac{k}{c\rho}$ is called the thermal diffusivity of the material (k is thermal conductivity, c is heat capacity, ρ is density).

Here and in the following, let \mathbb{C} , \mathbb{R}^+ , and \mathbb{N} be the sets of complex numbers, positive real numbers, and positive integers, respectively, and let $\mathbb{R}_0^+ := \mathbb{R}^+ \cup \{0\}$

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and $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$. Let the following boundary conditions be satisfied

$$\frac{\partial U(0, t)}{\partial x} - hU(0, t) = 0, \quad \frac{\partial U(L, t)}{\partial x} + hU(L, t) = 0 \quad (h \in \mathbb{R}^+). \quad (2)$$

Here h is the heat transfer coefficient,

$$U(x, t) \text{ is finite as } t \rightarrow \infty, \quad (3)$$

and initial condition

$$U(x, 0) = f(x). \quad (4)$$

The function $U(x, t)$ can be represented as the product of a special function $X(x)$ and a time function $T(t)$ with

$$U(x, t) = X(x)T(t). \quad (5)$$

Substituting the differentiated forms of (5) in (1) and separating the variables on either side of the equation results in

$$\frac{1}{T} \frac{\partial T}{\partial t} = \frac{1}{X} \frac{\partial^2 X}{\partial x^2}. \quad (6)$$

Putting each side equal to a negative constant $-\mu E_q^2$, it is possible to obtain solution for $T(t)$ and $X(x)$.

$$T(t) = A e^{-\mu E_q^2 t}, \quad (7)$$

and

$$X(x) = B \cos E_q x + D \sin E_q x. \quad (8)$$

Using the equation (5), the general solution of (1) becomes

$$T(x, t) = e^{-\mu E_q^2 t} (m \cos (bx) + n \sin (E_q x)), \quad (9)$$

where m and n are real constants.

The (9) satisfies the (1), (2) and (3) on the conditions that

$$E_q n - hm = 0 \quad (10)$$

and

$$E_q (n \cos E_q L - m \sin E_q L) + h (m \cos E_q L + n \sin E_q L) = 0. \quad (11)$$

From (10) and (11), we find

$$m/n = E_q/h, \quad (12)$$

and

$$\tan E_q L = \frac{2E_q h}{E_q^2 - h^2}. \quad (13)$$

Then the solution of (1) takes the following form (see [2]):

$$U(x, t) = \sum_{q=0}^{\infty} R_q \left(\cos E_q x + \frac{h}{E_q} \sin E_q x \right) e^{-\mu E_q^2 t}, \quad (14)$$

here the quantities $U(x, t)$ and R_q are real numbers.

We will take a formal initial condition

$$\begin{aligned}
 \mathbf{U}(x, 0) = \mathbf{f}(x) &= \left(\sin \frac{\pi x}{L} \right)^{w-1} \\
 &\times S_{N_1, \dots, N_u}^{M_1, \dots, M_u} \begin{bmatrix} y_1 \left(\sin \frac{\pi x}{L} \right)^{2\rho_1} \\ \vdots \\ y_u \left(\sin \frac{\pi x}{L} \right)^{2\rho_u} \end{bmatrix} A \begin{pmatrix} Z_1 \left(\sin \frac{\pi x}{L} \right)^{2\eta_1} \\ \vdots \\ Z_s \left(\sin \frac{\pi x}{L} \right)^{2\eta_s} \end{pmatrix}, \quad (15)
 \end{aligned}$$

here $\mathbf{U}(x, 0)$ depends of several complex variables and parameters. Also, $S_{N_1, \dots, N_u}^{M_1, \dots, M_u} [y_1, \dots, y_u]$ are the generalized polynomials defined by (see [18])

$$\begin{aligned}
 S_{N_1, \dots, N_u}^{M_1, \dots, M_u} [y_1, \dots, y_u] &= \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} \frac{(-N_1)_{M_1 K_1}}{K_1!} \cdots \frac{(-N_u)_{M_u K_u}}{K_u!} \\
 &\times B [N_1, K_1; \dots; N_u, K_u] y_1^{K_1} \cdots y_u^{K_u}, \quad (16)
 \end{aligned}$$

where $M_1, \dots, M_u, N_1, \dots, N_u \in \mathbb{N}$ and the coefficients $B [N_1, K_1; \dots; N_u, K_u]$ are arbitrary real or complex constants. Gautam et al. [9] introduced the multivariable A-function defined by

$$\begin{aligned}
 &A(Z_1, \dots, Z_s) \\
 &:= A_{p, q; p_1, q_1; \dots; p_s, q_s}^{m, n; m_1, n_1; \dots; m_s, n_s} \left(\begin{matrix} Z_1 \\ \vdots \\ Z_s \end{matrix} \middle| \begin{matrix} (a_j; A_j^{(1)}, \dots, A_j^{(s)})_{1, p} \\ (b_j; B_j^{(1)}, \dots, B_j^{(s)})_{1, q} \\ \dots; (c_j^{(s)}, C_j^{(s)})_{1, p_s} \\ \dots; (d_j^{(s)}, D_j^{(s)})_{1, q_s} \end{matrix} \right) \\
 &:= \frac{1}{(2\pi\omega)^s} \int_{L_1} \cdots \int_{L_s} \phi'(t_1, \dots, t_s) \prod_{i=1}^s \theta'_i(t_i) Z_i^{t_i} dt_1 \cdots dt_s, \quad (17)
 \end{aligned}$$

where $\omega = \sqrt{-1}$; $\phi'(t_1, \dots, t_s)$ and $\theta'_j(t_j)$ ($j = 1, \dots, s$) are given as

$$\phi'(t_1, \dots, t_s) := \frac{\prod_{j=1}^m \Gamma(b_j - \sum_{i=1}^s B_j^{(i)} t_i) \prod_{j=1}^n \Gamma(1 - a_j + \sum_{i=1}^s A_j^{(i)} t_j)}{\prod_{j=n+1}^p \Gamma(a_j - \sum_{i=1}^s A_j^{(i)} t_j) \prod_{j=m+1}^q \Gamma(1 - b_j + \sum_{i=1}^s B_j^{(i)} t_j)} \quad (18)$$

and

$$\theta'_i(t_i) := \frac{\prod_{j=1}^{n_i} \Gamma(1 - c_j^{(i)} + C_j^{(i)} t_i) \prod_{j=1}^{m_i} \Gamma(d_j^{(i)} - D_j^{(i)} t_i)}{\prod_{j=n_i+1}^{p_i} \Gamma(c_j^{(i)} - C_j^{(i)} t_i) \prod_{j=m_i+1}^{q_i} \Gamma(1 - d_j^{(i)} + D_j^{(i)} t_i)} \quad (19)$$

$(m, n, p, q, m_i, n_i, p_i, q_i \in \mathbb{N}_0$ with $m \leq q, n \leq p, m_i \leq q_i, n_i \leq p_i$ and $z_i \neq 0$ ($i = 1, \dots, s$);
 $a_j, b_j, c_j^{(i)}, d_j^{(i)}, A_j^{(i)}, B_j^{(i)}, C_j^{(i)}, D_j^{(i)} \in \mathbb{C}$).

The multiple integral defining the A -function of r variables converges absolutely if

$$|\arg(\Omega'_i) Z_i| < \frac{1}{2} \eta'_i \pi, \quad \xi_i'^* = 0, \quad \eta'_i \in \mathbb{R}^+ \quad (i = 1, \dots, s), \tag{20}$$

where

$$\Omega'_i := \prod_{j=1}^p \{A_j^{(i)}\}^{A_j^{(i)}} \prod_{j=1}^q \{B_j^{(i)}\}^{-B_j^{(i)}} \prod_{j=1}^{q_i} \{D_j^{(i)}\}^{D_j^{(i)}} \prod_{j=1}^{p_i} \{C_j^{(i)}\}^{-C_j^{(i)}}, \tag{21}$$

$$\xi_i'^* := \Im \left(\sum_{j=1}^p A_j^{(i)} - \sum_{j=1}^q B_j^{(i)} + \sum_{j=1}^{q_i} D_j^{(i)} - \sum_{j=1}^{p_i} C_j^{(i)} \right), \tag{22}$$

$$\begin{aligned} \eta'_i := \Re \left(\sum_{j=1}^n A_j^{(i)} - \sum_{j=n+1}^p A_j^{(i)} + \sum_{j=1}^m B_j^{(i)} - \sum_{j=m+1}^q B_j^{(i)} + \sum_{j=1}^{m_i} D_j^{(i)} \right. \\ \left. - \sum_{j=m_i+1}^{q_i} D_j^{(i)} + \sum_{j=1}^{n_i} C_j^{(i)} - \sum_{j=n_i+1}^{p_i} C_j^{(i)} \right). \end{aligned} \tag{23}$$

For details about the nature of contours L_1, \dots, L_s and other special cases of the multivariable A -function, we refer to the papers [9, 16, 17].

In this paper, first, we aim to establish two very general integral formulas involving product of the general class of Srivastava multivariable polynomials and the multivariable A -function. Then, using those integrals, we find a solution of the partial differential equation (1). The results presented here, being very general, are also pointed out to yield a number of relatively simple results, one of which is demonstrated to be connected with a known solution of the above-mentioned equation. In this regard, for simplicity, in what follows, we use the following notations.

$$X := m_1, n_1; \dots; m_s, n_s; \quad Y := p_1, q_1; \dots; p_s, q_s; \tag{24}$$

$$\mathbb{A} := (a_j; A_j^{(1)}, \dots, A_j^{(s)})_{1,p} : (c_j^{(1)}, C_j^{(1)})_{1,p_1}; \dots; (c_j^{(s)}, C_j^{(s)})_{1,p_s}; \tag{25}$$

$$\mathbb{B} := (b_j; B_j^{(1)}, \dots, B_j^{(s)})_{1,q} : (d_j^{(1)}, D_j^{(1)})_{1,q_1}; \dots; (d_j^{(s)}, D_j^{(s)})_{1,q_s}; \tag{26}$$

$$B' := \frac{(-N_1)_{M_1 K_1}}{K_1!} \dots \frac{(-N_s)_{M_s K_s}}{K_s!} B[N_1, K_1; \dots; N_s, K_s]. \tag{27}$$

2. Integral formulas

We begin by recalling some known integral formulas in the following lemma (see, e.g., [10, p. 614, Eq. (1) and p. 615, Eq. (8)], and [4, 5, 6]).

Lemma 2.1. *Each of the following integral formulas holds.*

$$\int_0^L \left(\sin \frac{\pi x}{L}\right)^{w-1} \sin \frac{\pi x E_p}{L} dx = \frac{\pi \Gamma(w) L \sin\left(\frac{\pi E_p}{2}\right)}{2^{w-1} \Gamma\left(\frac{w \pm E_p + 1}{2}\right)} \quad (\Re(w) > 0); \quad (28)$$

$$\int_0^L \left(\sin \frac{\pi x}{L}\right)^{w-1} \cos \frac{\pi x E_p}{L} dx = \frac{\pi \Gamma(w) L \cos\left(\frac{\pi E_p}{2}\right)}{2^{w-1} \Gamma\left(\frac{w \pm E_p + 1}{2}\right)} \quad (\Re(w) > 0); \quad (29)$$

$$\begin{aligned} &\int_0^L \left(\cos E_q x + \frac{h}{E_q} \sin E_q x\right) \left(\cos E_p x + \frac{h}{E_p} \sin E_p x\right) dx \\ &= 2E_q^{-2} [(E_q^2 + h^2) L + 2l] \delta_{pq}, \end{aligned} \quad (30)$$

where $\delta_{pq} = 1$ ($p = q$) and $\delta_{pq} = 0$ otherwise and E_p (or E_q) is a positive root of the following transcendental equation (see (13))

$$\tan EL = \frac{2Eh}{E^2 - h^2}. \quad (31)$$

We establish two integral formulas, which are useful to find a solution of the partial differential equation (1), in the following theorems.

Theorem 2.2. *Let all involved notations and conditions be given as above. Then*

$$\begin{aligned} &\int_0^L \left(\sin \frac{\pi x}{L}\right)^{w-1} \sin \frac{E_p \pi x}{L} S_{N_1, \dots, N_u}^{M_1, \dots, M_u} \begin{pmatrix} y_1 \left(\sin \frac{\pi x}{L}\right)^{2\rho_1} \\ \vdots \\ y_u \left(\sin \frac{\pi x}{L}\right)^{2\rho_u} \end{pmatrix} A \begin{pmatrix} Z_1 \left(\sin \frac{\pi x}{L}\right)^{2\eta_1} \\ \vdots \\ Z_s \left(\sin \frac{\pi x}{L}\right)^{2\eta_s} \end{pmatrix} dx \\ &= \frac{L \sin\left(\frac{E_p \pi}{2}\right)}{2^{w-1}} \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} B' \frac{y_1^{K_1} \cdots y_u^{K_u}}{4^{\sum_{i=1}^u \rho_i K_i}} \\ &\times A_{p+1, q+2; Y}^{m, n+1; X} \left(\begin{matrix} Z_1 4^{-\eta_1} \\ \vdots \\ Z_s 4^{-\eta_s} \end{matrix} \middle| \begin{matrix} (1 - w - 2 \sum_{i=1}^u \rho_i K_i : 2\eta_1, \dots, 2\eta_s), \mathbb{A} \\ (\frac{1}{2} (1 - w - 2 \sum_{i=1}^u \rho_i K_i \pm E_p) : \eta_1, \dots, \eta_s), \mathbb{B} \end{matrix} \right), \end{aligned} \quad (32)$$

provided

$$\Re(w) > 0, \min\{\rho_i, \eta_l\} > 0 \quad (i = 1, \dots, u; l = 1, \dots, s),$$

$$\left| \arg(\Omega'_i) Z_i \sin\left(\frac{\pi x}{L}\right)^{2\eta_i} \right| < \frac{1}{2} \eta'_i \pi, \xi_i^{t*} = 0, \eta'_i \in \mathbb{R}^+ \quad (i = 1, \dots, s),$$

and

$$\Re \left(w + \sum_{i=1}^u K_i \rho_i \right) + \sum_{i=1}^s \eta_i \min_{1 \leq j \leq m_i} \Re \left(\frac{d_j^{(i)}}{D_j^{(i)}} \right) > 0.$$

Proof. Firstly, express the class of multivariable polynomials $S_{N_1, \dots, N_u}^{M_1, \dots, M_u}[\cdot]$ in the left sided integral of (32) as a series with the help of (16) and interchange the order of summations and x -integral (which is permissible under the conditions stated). Secondly, in the resulting expression, expressing the A -function of s -variables in the Mellin-contour integral and interchange the order of integrations which is justifiable due to absolute convergence of the integral involved. Thirdly, collect the power of $\sin\left(\frac{\pi x}{L}\right)$ and evaluate the inner x -integral with the help of (28). Finally, interpreting the Mellin-Barnes contour integral in the last resulting expression in the multivariable A -function, we obtain the desired result (32). \square

Theorem 2.3. *Let all involved notations and conditions be given as above. Then*

$$\begin{aligned}
 & \int_0^L \left(\sin \frac{\pi x}{L}\right)^{w-1} \cos \frac{E_p \pi x}{L} S_{N_1, \dots, N_u}^{M_1, \dots, M_u} \begin{pmatrix} y_1 \left(\sin \frac{\pi x}{L}\right)^{2\rho_1} \\ \vdots \\ y_u \left(\sin \frac{\pi x}{L}\right)^{2\rho_u} \end{pmatrix} A \begin{pmatrix} Z_1 \left(\sin \frac{\pi x}{L}\right)^{2\eta_1} \\ \vdots \\ Z_s \left(\sin \frac{\pi x}{L}\right)^{2\eta_s} \end{pmatrix} dx \\
 &= \frac{L \cos\left(\frac{E_p \pi}{2}\right)}{2^{w-1}} \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} B' \frac{y_1^{K_1} \cdots y_u^{K_u}}{4^{\sum_{i=1}^u \rho_i K_i}} \\
 (33) \quad & \times A_{p+1, q+2; Y}^{m, n+1; X} \left(\begin{matrix} Z_1 4^{-\eta_1} \\ \vdots \\ Z_s 4^{-\eta_s} \end{matrix} \middle| \begin{matrix} (1-w-2\sum_{i=1}^u \rho_i K_i : 2\eta_1, \dots, 2\eta_s), \mathbb{A} \\ (\frac{1}{2}(1-w-2\sum_{i=1}^u \rho_i K_i \pm E_p) : \eta_1, \dots, \eta_s), \mathbb{B} \end{matrix} \right),
 \end{aligned}$$

provided

$$\Re(w) > 0, \min\{\rho_i, \eta_l\} > 0 \quad (i = 1, \dots, u; \quad l = 1, \dots, s),$$

$$\left| \arg(\Omega'_i) Z_i \sin\left(\frac{\pi x}{L}\right)^{2\eta_i} \right| < \frac{1}{2} \eta'_i \pi, \quad \xi_i^* = 0, \quad \eta'_i \in \mathbb{R}^+ \quad (i = 1, \dots, s),$$

and

$$\Re\left(w + \sum_{i=1}^u K_i \rho_i\right) + \sum_{i=1}^s \eta_i \min_{1 \leq j \leq m_i} \Re\left(\frac{d_j^{(i)}}{D_j^{(i)}}\right) > 0.$$

Proof. A similar argument as in the proof of Theorem 2.2 will establish the result here. We omit the details. \square

3. A solution of (1)

Here we use the results in Section 2 to give a solution of (1) in the following theorem.

Theorem 3.1. *Let all involved notations and conditions be given as above. Then a solution of (1) is given as follows:*

$$\begin{aligned}
 U(x, t) &= \frac{L}{2^{w-1}} \sum_{p=0}^{\infty} \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} B' \frac{y_1^{K_1} \cdots y_u^{K_u}}{4^{\sum_{i=1}^u \rho_i K_i}} \\
 (34) \times & \frac{E_p^2}{[(E_p^2 + h^2)L + 2h]} \left(\cos E_p x + \frac{h}{E_p} \sin E_p x \right) \\
 & \times e^{-kE_p^2 t} A_{p+1, q+2; Y}^{m, n+1; X} \left(\begin{array}{c} Z_1 4^{-\eta_1} \\ \vdots \\ Z_s 4^{-\eta_s} \end{array} \middle| \begin{array}{l} (1 - w - 2 \sum_{i=1}^u \rho_i K_i : 2\eta_1, \dots, 2\eta_s), \mathbb{A} \\ (\frac{1}{2} (1 - w - 2 \sum_{i=1}^u \rho_i K_i \pm E_p) : \eta_1, \dots, \eta_s), \mathbb{B} \end{array} \right).
 \end{aligned}$$

Proof. Setting $t = 0$ in (14) and using (15), we have

$$\begin{aligned}
 & \left(\sin \frac{\pi x}{L} \right)^{w-1} S_{N_1, \dots, N_u}^{M_1, \dots, M_u} \left(\begin{array}{c} y_1 \left(\sin \frac{\pi x}{L} \right)^{2\rho_1} \\ \vdots \\ y_u \left(\sin \frac{\pi x}{L} \right)^{2\rho_u} \end{array} \right) A \left(\begin{array}{c} Z_1 \left(\sin \frac{\pi x}{L} \right)^{2\eta_1} \\ \vdots \\ Z_s \left(\sin \frac{\pi x}{L} \right)^{2\eta_s} \end{array} \right) \\
 (35) & = \sum_{q=0}^{\infty} \mathbf{R}_q \left(\cos E_q x + \frac{h}{E_q} \sin E_q x \right).
 \end{aligned}$$

Multiply both sides of (35) by $\cos E_p x + \frac{h}{E_p} \sin E_p x$ and integrating each side of the resulting identity with respect to x from 0 to L , with the aid of (30), (32) and (33), we obtain

$$\begin{aligned}
 \mathbf{R}_q &= \frac{1}{2^{w-1}} \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} B' \frac{y_1^{K_1} \cdots y_u^{K_u}}{4^{\sum_{i=1}^u \rho_i K_i}} \frac{2LE_q^2}{[(E_q^2 + h^2)L + 2h]} \\
 (36) & A_{p+1, q+2; Y}^{m, n+1; X} \left(\begin{array}{c} Z_1 4^{-\eta_1} \\ \vdots \\ Z_s 4^{-\eta_s} \end{array} \middle| \begin{array}{l} (1 - w - 2 \sum_{i=1}^u \rho_i K_i : 2\eta_1, \dots, 2\eta_s), \mathbb{A} \\ \left(\frac{1-w-2 \sum_{i=1}^u \rho_i K_i \pm E_p}{2} : \eta_1, \dots, \eta_s \right), \mathbb{B} \end{array} \right).
 \end{aligned}$$

Finally, substituting the \mathbf{R}_q in (36) for the \mathbf{R}_q in (14), we find the desired solution (34). □

4. Special cases and remarks

The results presented here, being very general, can be reduced to yield a number of relatively simple formulas and solutions. For example, when $A_j^{(i)}, B_j^{(i)}, C_j^{(i)}, D_j^{(i)} \in \mathbb{R}$ and $m = 0$ and $m_j = 0$, the multivariable A -function reduces to the multivariable H -function (see [19, 20]). Then we have a known solution of (1) (see, Chandel and Singh [3]) which is recorded in the following theorem.

Theorem 4.1. *Let all involved notations and conditions be given as above. Then a solution of (1) is given as follows:*

$$\begin{aligned}
 U(x, t) &= \frac{L}{2^{w-1}} \sum_{p=1}^{\infty} \sum_{K_1=0}^{[N_1/M_1]} \cdots \sum_{K_u=0}^{[N_u/M_u]} B' \frac{y_1^{K_1} \cdots y_u^{K_u}}{4^{\sum_{i=1}^u \rho_i K_i}} \frac{2L E_p^2}{[(E_p^2 + h^2)L + 2h]} \\
 (37) & \\
 &\times e^{-kE_p^2 t} H_{p+1, q+2; Y}^{0, n+1; X} \left(\begin{array}{c} Z_1 4^{-\eta_1} \\ \vdots \\ Z_s 4^{-\eta_s} \end{array} \middle| \begin{array}{c} (1 - w - 2 \sum_{i=1}^u \rho_i K_i : 2\eta_1, \dots, 2\eta_s), \mathbb{A} \\ \left(\frac{1-w-2 \sum_{i=1}^u \rho_i K_i \pm E_p}{2} : \eta_1, \dots, \eta_s \right), \mathbb{B} \end{array} \right),
 \end{aligned}$$

where $A_j^{(i)}$, $B_j^{(i)}$, $C_j^{(i)}$, $D_j^{(i)} \in \mathbb{R}$ and $m = 0$ and $m_j = 0$.

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