

Selective Encryption Algorithm Using Hybrid Transform for GIS Vector Map

Bang Nguyen Van*, Suk-Hwan Lee**, and Ki-Ryong Kwon**

Abstract

Nowadays, geographic information system (GIS) is developed and implemented in many areas. A huge volume of vector map data has been accessed unlawfully by hackers, pirates, or unauthorized users. For this reason, we need the methods that help to protect GIS data for storage, multimedia applications, and transmission. In our paper, a selective encryption method is presented based on vertex randomization and hybrid transform in the GIS vector map. In the proposed algorithm, polylines and polygons are focused as the targets for encryption. Objects are classified in each layer, and all coordinates of the significant objects are encrypted by the key sets generated by using chaotic map before changing them in DWT, DFT domain. Experimental results verify the high efficiency visualization by low complexity, high security performance by random processes.

Keywords

Chaotic Map, GIS Vector Map, Selective Encryption, Vector Map Security

1. Introduction

A geographical information system (GIS) [1-3] is a large system invented to manipulate, analyze, store, capture, and control the geographic. In a GIS, vectors often express geographical features and illustrate features as geometrical shapes. Many varying phenomena can be represented by vector data. Vector map manages all kinds of the geographic information data as geometric factor, topology and metadata by vector data. Vector data reflect features of the real object in the GIS environment, we only use a small size for storing data; graphic represent the spatial data that quite similar handed map; projection is made easily and coordinates transformation [4-6]. For these reasons, vector map is applied in many areas and we also use it in GIS application that help users easily access to services through high technology devices or internet.

However, the detailed vector maps require huge amounts of data, processing, storing, transmitting them poses a challenge and we need human resources, servers, etc., to save a digital map. But, any company can use it, create illegal copies of the map and sell or distribute them easily many times without taking any permission from the original GIS data provider. Besides, GIS data is used in military

※ This is an Open Access article distributed under the terms of the Creative Commons Attribution Non-Commercial License (<http://creativecommons.org/licenses/by-nc/3.0/>) which permits unrestricted non-commercial use, distribution, and reproduction in any medium, provided the original work is properly cited.
Manuscript received May 19, 2015; first revision November 16, 2015; accepted January 19, 2016.

Corresponding Author: Ki-Ryong Kwon (krkwon@pknu.ac.kr)

* Dept. of IT Convergence and Applications Engineering, Pukyong National University, Busan, Korea (nguyenbang1619@gmail.com, krkwon@pknu.ac.kr)

**Dept. of Information Security, Tongmyong University, Busan, Korea (skylee@tu.ac.kr)

fields that require the high level security and must be protect away from attackers, also unauthorized users. So vector map is necessary to be protected and prevent illegal duplication and distribution of it.

In vector map security, conventional approaches encrypt whole data, so the cryptography of data files and profiles increase complexity, and these methods take a long time. Furthermore, the decryption data often occurs loss data and it takes a long time to processing time, because authors use the complicated mathematical models on big digital data. It is not also flexible for various data types.

For meeting above requirements, a selective encryption scheme is proposed for GIS map security for multimedia applications, storage and transmission. In proposed algorithm, vector map is separated to select polyline/polygon layer. We select and encrypt the significant objects in each layer by key sets generated by using Chaotic map before changing them in DWT, DFT domain. In DWT domain, we select some coefficients and encrypt them by changing first coefficient in DFT domain. Summary, our proposed method focus on polylines/polygon objects as target for selective encryption, and change values of vertices of polylines/polygons by key sets before transforming them by using hybrid transform. Main advantages of the proposed algorithm are simple computing and transforming processes but it still meets requirements of security by random processes, and it can be applied to many types of vector map data. Experimental results show the high efficiency visualization by low complexity, high security performance by random processes and cryptography. In addition, experiments also show unique performance, decrypting error approximate zero and computation time be very short.

The remaining parts of paper are organized as follows: Section 2 gives a brief description about vector map security watermarking, full encryption and selective encryption. Section 3 explains the proposed algorithm in the detail. And we show experimental results and analytics. Finally, Section 5 gives a conclusion of the paper.

2. Related Works

Until now, we can separate GIS data into two categories: vector and raster forms. Vector data is a collection of layers in which the layer includes many geographical objects. These objects reflect geographical features and topography of real objects or location. A layer includes vector data which represent the world using points, polygons, and lines (polylines) [7,8], as shown Fig. 1.

According to the recent growth of network digital media, data are needed to protect from distribution and illegal copying. Many approaches are researched for this issues; these include authentication, encryption, and time stamping.

Digital watermarking has been researched to solve the issues in vector map since 2000s. The traditional method embed secret information in some locations of vector map: [9-11] proposes certain rules, they help to select a set of coordinates of vertices, and editing them by using a certain range of precision; [12,13] modify coefficients in the frequency domain to complete watermarking hiding that is one of the important solution of watermarking algorithm, but the disturb to the vector map content is also existing, the resistance performance to data fitting, interpolation, scaling is poor. In summary, the existing methods of geospatial watermarking can be distributed as follows: algorithm uses DCT, DWT, and DFT domain, the algorithms in spatial domain, and algorithms inherited in 3D watermarking. Not similar with general multimedia data types, watermarking in vector map has its distinct features due to the application environments and special data structures of vector data. However, watermarking isn't a

foolproof way to protect them, it only identifies the rightful owner of the work, so it is the final step in security policy.

The full encryption algorithms usually encrypt all components of original data to change whole data. Wu et al. [14] considered characteristics of the storage, parameters and initial values of chaotic map. After that, he proposed a new compound encryption method, this process is not available to any type formats of data and object indexing. Li [15] selected the vector dataset in external Oracle DBMS for encryption, and he used standard cryptography DES combining with an R-tree spatial index. This algorithm encrypts the spatial index when the GIS dataset is transmitted to the client and designs the key management of public and private keys on a PKI system. In this process, the key length is short so it cannot keep data on the DBMS with high security. Dakroury et al. [16] described better the encrypting algorithm, AES and RSA cryptography are combined along with watermarking method that used in internet online service. This algorithm encrypts all parts of a shape-file using 256 bit for private key of a block cipher AES. Jang et al. [17] encrypted perceptually all polylines and polygons by lossless minimum coding object (MCO) units. But, these algorithms use whole shape-files for encryption and they do not consider important features, it is taking a long time to handle.

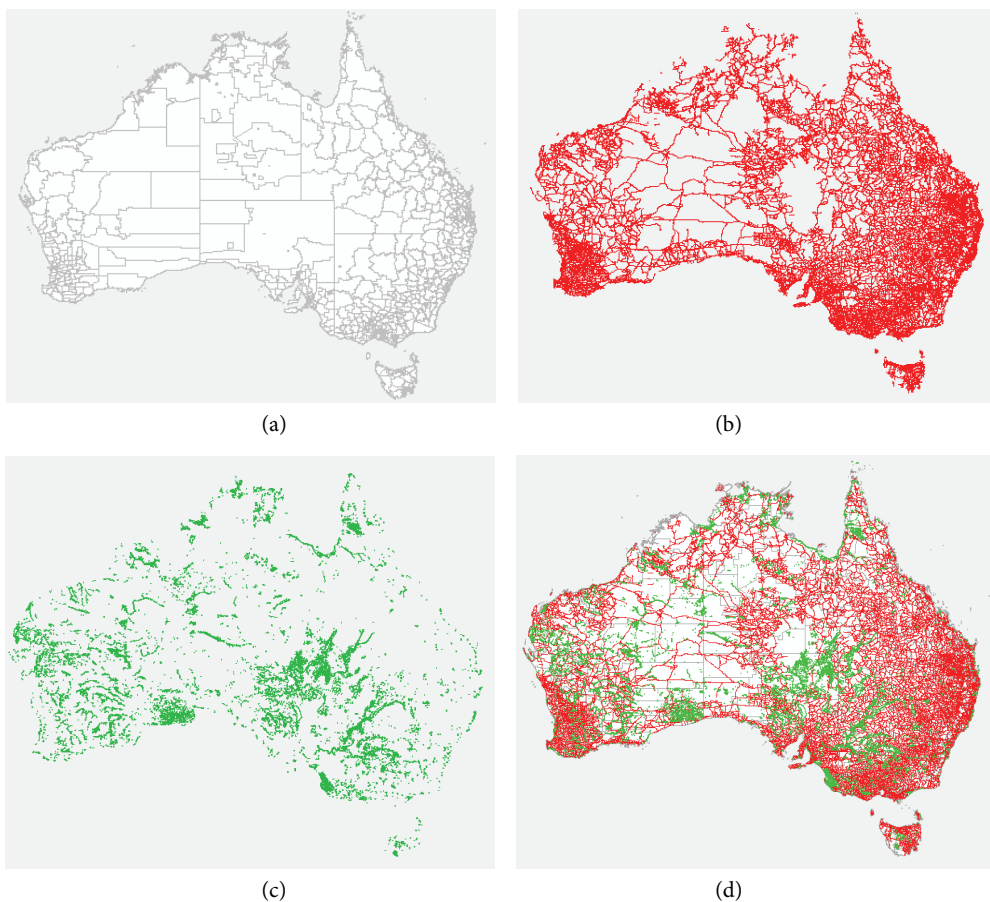


Fig. 1. An example GIS vector map. (a) Area layer, (b) road layer, (c) water layer, and (d) area + road + water layers.

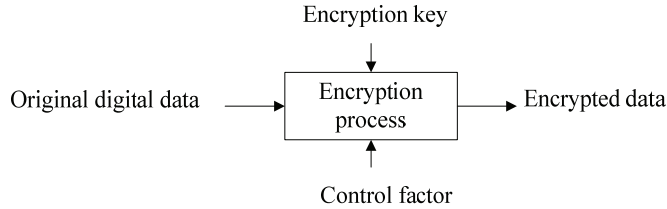


Fig. 2. The concept of selective encryption.

In digital data protection topic, selective encryption methods have been researched since 2000s. The simple concept of selective encryption is showed in Fig. 2. Nowadays, many selective encryption algorithms are proposed to video and image. However, all algorithms used DES, AES or other symmetric-key algorithms become quite simple algebraic structure and not high security. Therefore, our proposed method only select polyline and polygon objects in GIS map for encryption. They are considered as protected part and user need authority to access this part. Firstly, we randomize these objects by randomization values generated from SHA-512 and chaotic map. After that, we continued to encrypt them in DWT, DFT domain. The step by step of our method is explained in detail in Section 3.

3. Proposed Algorithm

3.1 Encryption Process

Fig. 3 shows the illustration diagram of our proposed algorithm, and we also explain the step-by-step in detail, as follows:

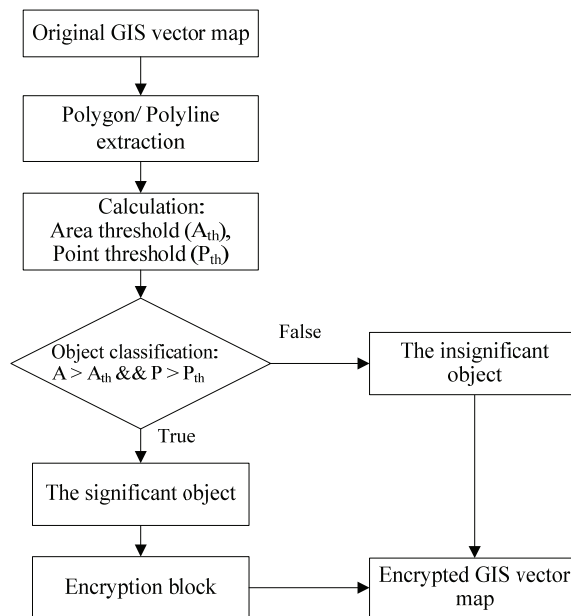


Fig. 3. Illustration diagram for proposed encryption technique.

- A vector map M is a set of layers: $M = \{L_i | i \in [1, |M|]\}$ with $|M|$: the cardinality in map M (the cardinality of a set is a measure of the "number of elements of the set").
- A layer L_i include many polyline/polygon object: $L_i = \{O_{ij} | j \in [1, |L_i|]\}$ with $|L_i|$ is the total number of objects in layer L_i .
- An object O_{ij} is a set of vertices $O_{ij} = \{v_{ijk} | k \in [1, |O_{ij}|]\}$ and O_{ij} has two attributes: the total number of points and the area of the bounding box. We find the area threshold ($B_{i,th}$) and the point threshold ($A_{i,th}$) in layer L_i .
- All objects are classified into two groups by comparing their attributes with threshold values.
- The proposed method leave the insignificant objects without encryption.
- With the significant objects, all vertices of these objects are encrypted by key sets generating from hybrid transform and chaotic map.

The detail of each step is illustrated in continuous sections.

3.1.1 Object definition

In the proposed method, polyline and polygon objects are selected for encryption. Nevertheless, we have many objects in a layer, so if all of them are encrypted, it also take a long processing time. An object has two characteristics such as the area of the bounding box (A) and the number of points (P), as shown in Fig. 4(a). These characteristics are different when comparing each other. Some objects are created by a few vertices and the value of area is very small. These objects are very simple and they are marked as the insignificant objects, as shown in Fig. 4(b). In the same way, we have some objects created from many vertices and the area of the bounding box is larger than, it also complex than and mark it as a significant object, as shown in Fig. 4(c).

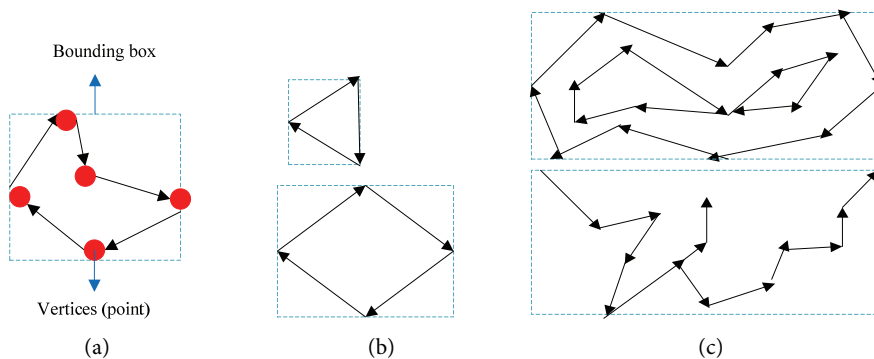


Fig. 4. Example about objects in a layer.

For this reason, the probability distribution is used to define thresholds in one layer. By this way, we classify an insignificant object or a significant object by comparing object's attributes with thresholds. In a layer L_i , two threshold values: $A_{i,th}$ and $B_{i,th}$ are calculated as following:

- A layer $L_i : L_i = \{O_{ij} | j \in [1, |L_i|]\}$ with $|L_i|$ is the cardinality of a layer L_i .
- An object O_{ij} has two attributes: The total number of points (B_{ij}) and the area of bounding box (A_{ij}).

- So, in layer L_i we have: $A_i = \{A_{ij} | j \in [1, |A_i|]\}$, $B_i = \{B_{ij} | j \in [1, |B_i|]\}$ and: $|A_i| = |B_i| = |L_i|$.
- The discrete probability distribution is used to find threshold in set A_i, B_i with thresholds are the smallest values as possible by condition (1), (2):

$$A_{i_th} \in A_i \text{ and } F(A) = \sum P(X = A_{ij} \ \& \ A_{ij} \geq A_{i_th}) \geq 0.5 \tag{1}$$

$$B_{i_th} \in B_i \text{ and } F(B) = \sum P(X = B_{ij} \ \& \ B_{ij} \geq B_{i_th}) \geq 0.5 \tag{2}$$

With X is called a discrete random variable and $\sum_{j=1}^{|A_i|} P(X = A_{ij}) = \sum_{j=1}^{|B_i|} P(X = B_{ij}) = 1$. And if an object have $A_{ij} \geq A_{i_th}$ and $B_{ij} \geq B_{i_th}$, mark it as a significant object, else mark it as an insignificant object.

3.1.2 Chaotic map

The logistic map is the classic example of a non-linear recursion relation whose iterative values (trajectory) can exhibit deterministic chaos. The classical chaos system in one-dimension is a logistic map, which can be defined by following:

$$x_{k+1} = \mu x_k (1 - x_k) \tag{3}$$

μ is a positive constant sometimes known as the “biotic potential” gives the so-called logistic map $0 \leq \mu \leq 4$, $k=0,1,2,\dots$, and all the values of $\{x_i\}$ appear in the range $[0,1]$ for the initial value $x_0 \in [0,1]$. It is noted that Eq. (3) has the chaotic behavior [27, 28] when μ appears in the range $[3.57, 4]$, and especially the chaotic behavior called Pomeau–Manneville scenario [18] when μ appears in the range $[3.57, 3.82]$.

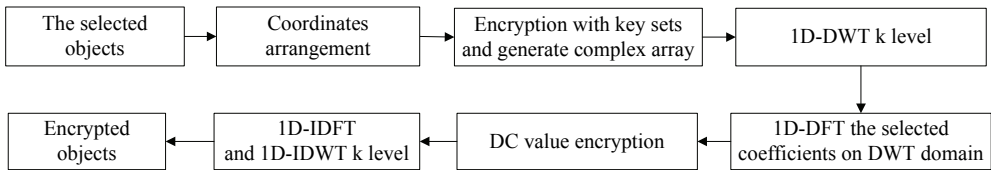


Fig. 5. Proposed encryption for vector map.

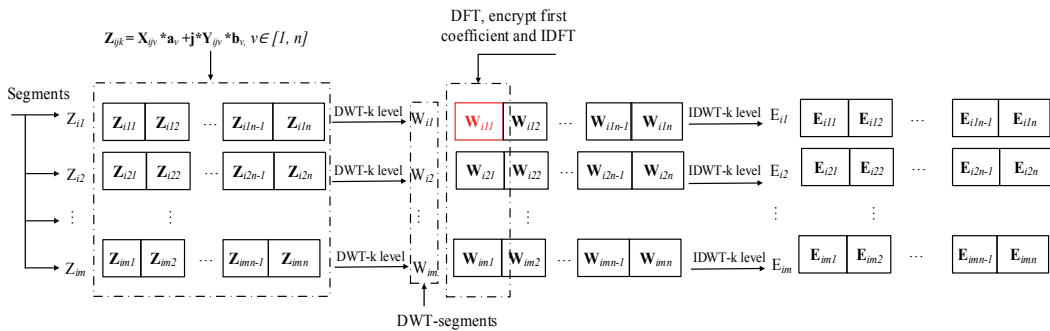


Fig. 6. Selective encryption process in polyline/polygon layer.

3.1.3 Encryption block

After all objects are classified, the significant objects are encrypted, as illustrated in Fig. 5 and shown in Fig. 6.

- Step 1: X, Y coordinates of the significant objects are selected and arrange into two 1D-arrays and the length of one array is N_s . Define length of the segment is n , with $n = 2^k$ and k is determined by using **the floor function** ($\lfloor x \rfloor$ is the largest integer less than or equal to x) and N_s , as follows:

$$k = \lfloor \log_2 \sqrt{N_s} \rfloor \tag{4}$$

The number of segments is determined, by equation:

$$m = \lfloor N_s/n \rfloor \tag{5}$$

- Step 2: The user key K_i is used to create two key sets for layer L_i . It is generated randomly the first key in each key set by SHA-512 algorithm from user key [19] with key length is 512 bits for each key. And other keys are generated by using chaotic map as Eq. (3). Fig. 7 shows a key process for the key sets generation and DFT encryption value. And, we have two key set: $a = \{a_i | i \in [1, n]\}$, $b = \{b_i | i \in [1, n]\}$ and DFT encryption value: $E_{DFT} = n * a_1 * b_1$.

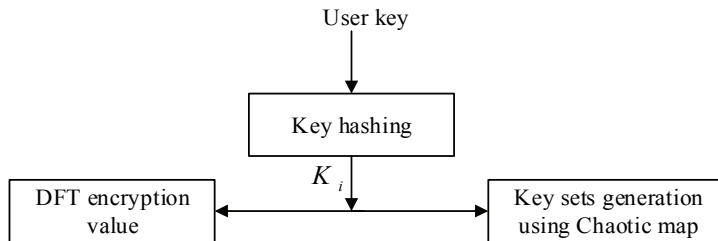


Fig. 7. Shows a key process for key sets generation and DFT coefficient encryption.

- Step 3: All coordinates in one segment are multiplied with values of two key sets a, b and we make the complex numbers as equation: $Z_i = X_i * a_i + j Y_i * b_i, i \in [1, n]$.
- Step 4: This segment is applied DWT-k level to get a set of DWT coefficients. Select all first coefficients of DWT coefficients and continue to apply DFT to get a set of DFT coefficients.
- Step 5: In DFT domain, the first coefficient is multiplied with DFT encryption value by Eq. (6).

$$DFT^* = DFT * E_{DFT} \tag{6}$$

Then, we perform IDFT to get a set of encrypted values of second transformed values.

- Step 6: All first coefficients in DWT-segments are replaced by encrypted values in step 5 and IDWT-k level to get a set of encrypted values of first transformed values. And, the real and image parts of the encrypted complex values also are the encrypted coordinates of objects.

3.2 Decryption Process

To perform decryption, after threshold values are defined, the decryption block is used to decrypt the selected vertices of the significant objects. If the user has the correct key when he decrypts the encrypted map, and the decoded data should be like a transcript of the input map. The output map is very various if the user provides an incorrect key. Results will verify the high efficiency visualization by low complexity, high security performance in the next section. In addition, experiments also show a unique performance, decryption error approximate zero and computation time faster than the existing algorithms.

4. Experimental Results

4.1 Object Definition

In our algorithm, the significant objects and the insignificant objects are defined based on threshold values in layers. After that, we only select the significant objects for encryption. When we change two values (that are user-defined) in Eqs. (1)–(2), threshold values are also changed and percentage of the encrypted vertices change according to this values, as shown in Fig. 8.

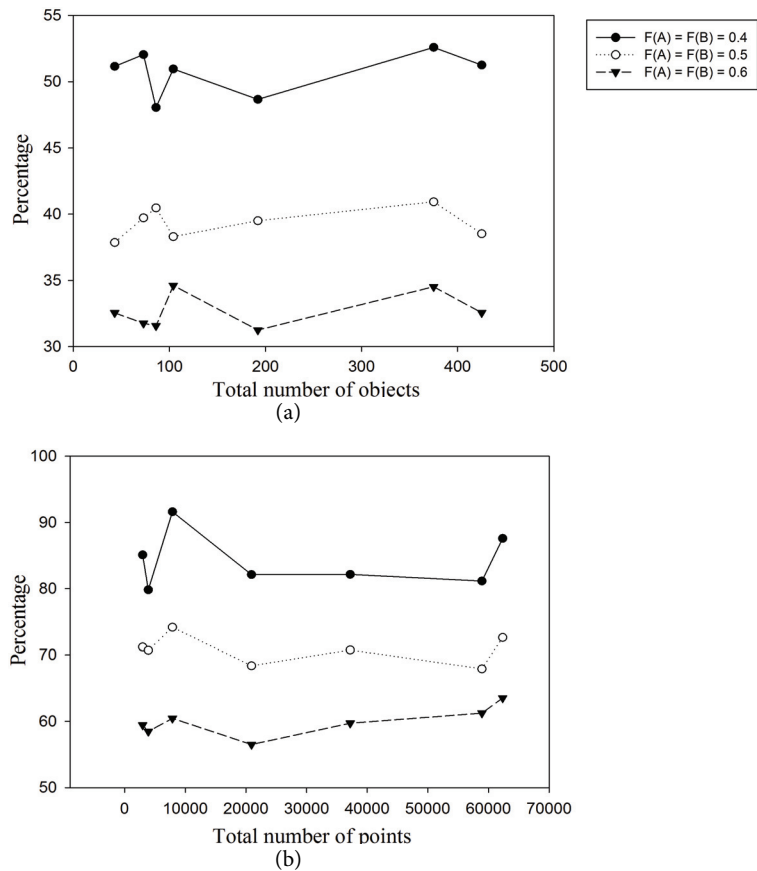


Fig. 8. Percentages of the significant objects (a) and the encrypted points (b).

4.2 Visualization

For performance evaluation of the proposed algorithm, many different scaled maps are used that contain layers, including rivers, roads, lakes, and countries in the world. Simulation results prove that the encrypted map change absolutely perception of whole maps, as shown in Figs. 9–11. The proposed method changes the whole visual image of map because randomly some vertices are encrypted lead to scrambling shape of all objects. In addition, the proposed method changes only vertices position of objects in the layer. The size of input and output map are the same, so it is not a lose data.

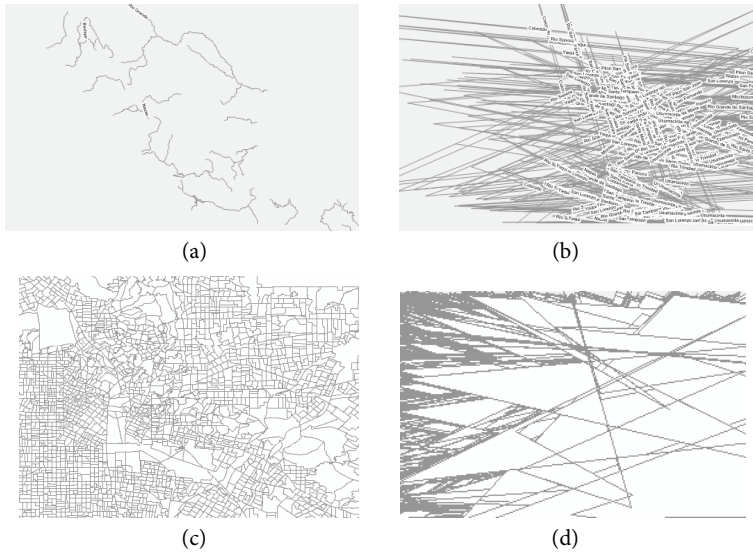


Fig. 9. Experimental results with scaling layers 1:5,000. (a) Original polyline layer, (b) encrypted polyline layer, (c) original polygon layer, and (d) encrypted polygon layer.

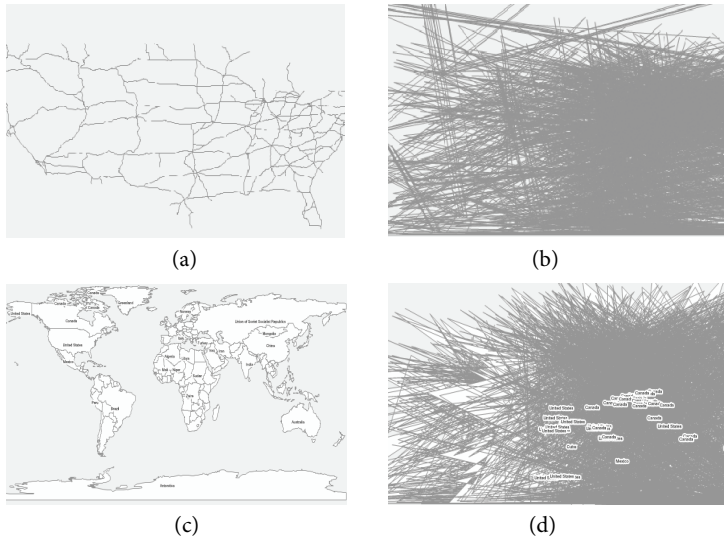


Fig. 10. Experimental results with scaling layers 1:10,000, 1:100,000. (a) Original polyline layer, (b) encrypted polyline layer, (c) original polygon layer, and (d) encrypted polygon layer.

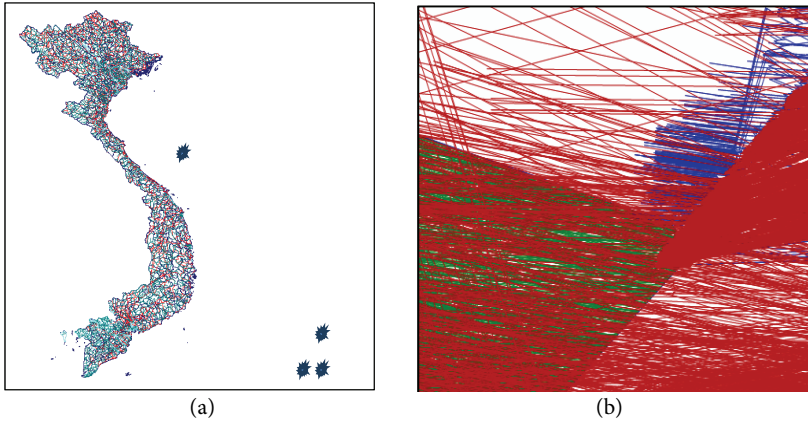


Fig. 11. Experimental result with full scaling layers 1:5,000. (a) Original map and (b) encrypted map.

4.3 Decryption Error

We used 1:5,000, 1:10,000 and 1:100,000 scaling maps in our experiments. Firstly, we experimented with each polyline layer and polygon layer. Then, we tested the full map of 1:5,000 scale. Experimental results show that all maps are changed as given by Figs. 9–11. Unauthorized users cannot see anything on the map because we changed polyline/polygon through many processes: multiplication, DWT, IDWT, DFT and IDFT.

Table 1. The error between original coordinates and decrypted coordinates

Original coordinates	Decryption coordinates	Error
144.13246	144.132460000128	1.27982957565109E-10
-37.32808	-37.3280800000347	3.47029072145233E-11
...
-118.749289	-118.749289001048	2.83009171653248E-10
34.817734	34.8177340000613	6.12985218140238E-11

Table 2. The max, min error between original map and decryption map

Size (kB)	Total object	Total point	Max error	Min error	Average error
332	76	20920	4.58763E-07	0	1.75211E-08
449	147	28162	3.70411E-07	0	1.72524E-08
751	20	47947	2.88627E-07	0	4.00043E-08
965	7011	37209	1.13562E-07	0	2.92078E-10
1246	375	79499	6.41549E-07	0	6.00142E-08
1730	13960	61798	7.83001E-08	0	1.76301E-09

In this algorithm, only coordinates of points (vertices) in objects are changed. The encrypted map still have the same size as the original map. However, Chaotic map is used to generate random number and key values from user's key hashing SHA-512 bits, it make these values not absolutely similar in encryption and decryption step. Meaning of this issues come from the problem of system calculation

when it stored real numbers in memory. With storing vertices in double type, it seems be no problem when the decryption errors values are approximately zero, as given by Table 1. Then, many maps are tested to find the maximum error and calculate the average error, as shown in Table 2.

4.4 Distance Measure

We use Eq. (7) to calculate the difference between encrypted map and original map:

$$D(E', L) = \sum_{i=1}^N d(P_{ij}) \tag{7}$$

where L is an original map and $E'(L)$ is corresponding encrypted map and N is total object in original map. $d(P_{ij})$ is distance between corresponding objects in $E'(L)$ and L , which is computed by

$$d(P_{ij}) = \sum_{j=1}^{N_{ij}} \sqrt{(|x'_j - x_j|^2 + |y'_j - y_j|^2)} \tag{8}$$

where N_{ij} is the total number of points in object P_{ij} .

We used polyline map, polygon map to experiment with different passwords K_1 and K_2 . Then we calculate $D(E', L)$ distance of each experimental time, as show in Table 3.

Table 3. Experimental distance measure

Total number of points	Distance	
	User key K_1	User key K_2
798	35,682	39,065
1249	53,018	50,682
2457	200,133	178,431
2967	233,311	200,644
3900	318,270	404,741

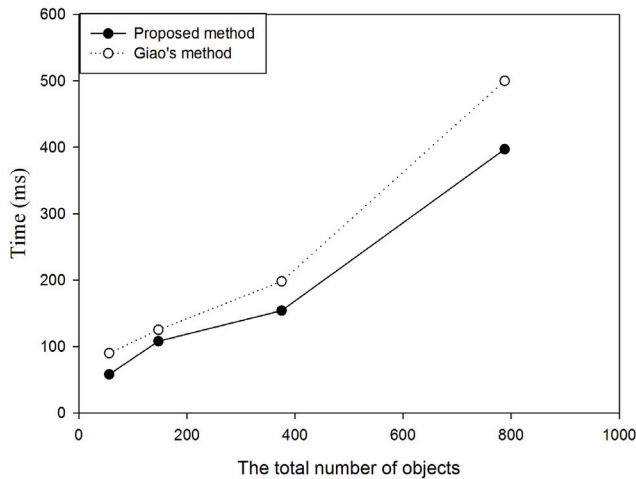


Fig. 12. Computation time according to the total number of objects.

4.5 Computation Time

The computation time of proposed methods depends on many factors. Moreover, it also depends on random processes, size of the map. Therefore, to measure the computation time we need to use specific mathematical model. In this section we just show the dependence of computation time and we compared result with Giao's algorithm [20,21] under same the total number of objects, as shown in Fig. 12. Analyzing the detail results, we verify that the computation time of our method have lower than those of Giao's method.

4.6 Security

Cryptographic security: Our proposed method use threshold values to select the significant objects, this method encrypted 60%-70% of data with the key values and random coefficients created by using Chaotic map and secret key.

Key sensitivity analysis: A highly key sensitive encryption algorithm protects the encrypted data against various cryptanalytic attacks. While developing a cryptosystem, it is assumed that an intruder knows the encryption structure and a-priori probability of used key $k \in K$. As per the Kerckhoff's principle [22], only secrecy of the used key is required. Even a strong or well-designed cryptosystem can be broken easily if the key is poorly chosen or key space is too small. Thus, a good cryptosystem should satisfy the following two conditions to verify the key sensitivity and key space:

- The key space should be discretized in such a way that two ciphertexts encrypted by two slightly different keys $k_1, k_2 \in K$ should be completely different.
- With the generated keys, the ciphertext should be responding to slight changes, signals, or influences.

The original layer is encrypted by using the slightly different keys, and we analysis the difference between the obtained encrypted layers. The different layers are evaluated to verify the condition that, "layer is encrypted with slightly different keys should be completely different".

For security evaluation, the slightly different keys are generated by modifying the first key in each key set a, b and modifying coefficient μ in Eq. (3). And then, the method change one of them when keeping other values in the modified key. So, when test the key sensitivity, algorithm use the original key with three components. For the original key $K_1: (3.52, 0.34, 0.62)$ (three parameters (μ, a_1, b_1) represent for key K), the modified keys are expressed as $K_2: (3.42, 0.34, 0.62)$, $K_3: (3.52, 0.44, 0.62)$ and $K_4: (3.52, 0.34, 0.52)$. We use K_1 to generate an encrypted layer of the original layer (Fig. 9(c)) and Fig. 13(a) show image of this layer. After that, we continue to generate other encrypted layers with the slightly modified keys K_2, K_3 , and K_4 . Fig. 13(b)–(d) indicates the corresponding encrypted layers. It is observed that layers encrypted with slightly different keys are completely incomprehensible. This verifies that, "ciphertexts generated using slightly different keys are completely different from each other".

With another provision of key sensitivity, the encrypted layer is decoded with key K_2, K_3 instead of the correct key K_1 , as shown in Fig. 14. The layer is decoded with incorrect keys that completely incomprehensible, and do not leak any information about the original layer.

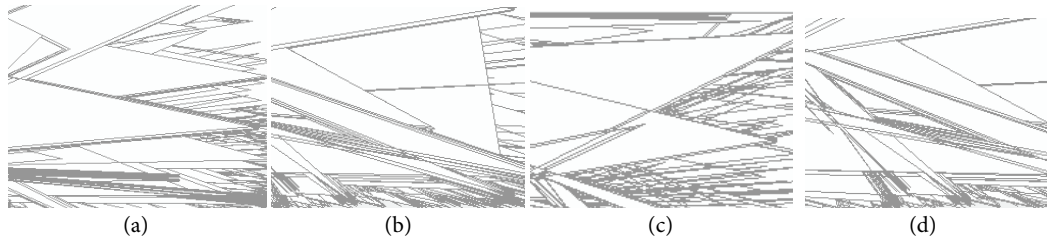


Fig. 13. Key sensitivity with original layer (Fig. 9(c)) using different keys. (a) Key K_1 , (b) key K_2 , (c) key K_3 , and (d) key K_4 .

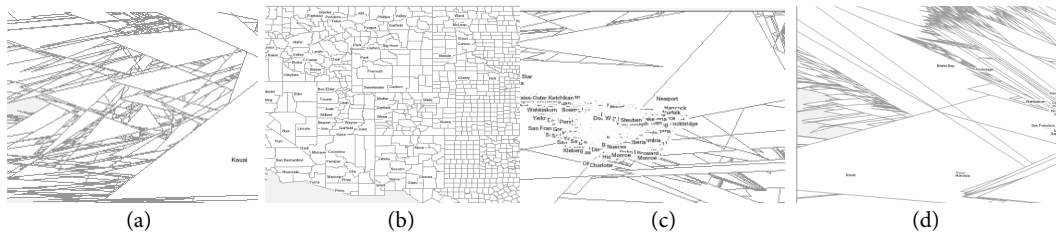


Fig. 14. Key sensitivity analysis for decryption process. (a) Proposed encrypted map, (b) decrypted map with K_1 , (c) decrypted map with K_2 , and (d) decrypted map with K_3 .

4.7 Algorithm Comparison

We compare the properties of the proposed method with the existing encryption method [20,21]—authors use DCT transform for GIS vector map encryption. In these papers, authors select all vertices in a layer and encrypt them by random algorithm in DCT domain, they did not consider important part in each layer. So, this is full encryption methods and still need very long computation time (we proved it in Sections 4.1 and 4.5). Our method only select the significant objects (that is defined by owner based on threshold values) for encryption, it would be very difficult to break the encryption algorithm or try to predict the encrypted part. Furthermore, authors only used a set of random value to encrypt coefficients in DCT domain and they didn't clearly explain in security evaluation part. We think that it should be broken easily because the key is poorly chosen and key space is too small.

5. Conclusion

In this paper, a new method is proposed which aim to reduce the ratio of encrypted data in GIS vector map but still assure the performance and the high security. This considers how to select significant objects in a layer by using threshold values. After that, the selected vertices are encrypted with random numbers, key values generating from chaotic map and hybrid transforms. We confirm that human perception do not see any information in encrypted map, poor error in decryption step, computation time is less than it in the existing methods, high security and a large amount of GIS vector map data can be protected by this algorithm. The algorithm can be used in many kind of application or standard vector map because it is proposed to encrypt randomly vertices of important/complex objects (polygons and polylines), so it can be applied for any vector map data and GIS database on on/off-lines server.

Acknowledgement

This research was supported by Basic Science Research Program through the National Research Foundation of Korea (NRF) funded by the Ministry of Education, Science and Technology (NRF-2014R1A1A4A01006663 and NRF-2016R1D1A3B03931003) and the ICT R&D program of MSIP/IITP (R0126-15-1112, Development of Media Application Framework based on Multi-modality which enables Personal Media Reconstruction).

References

- [1] K. E. Foote and M. Lynch, "Geographic information systems as an integrating technology: context, concepts, and definitions," 2014 [Online]. Available: http://www.colorado.edu/geography/gcraft/notes/intro/intro_f.html.
- [2] M. F. Goodchild, "Twenty years of progress: GIScience in 2010," *Journal of Spatial Information Science*, vol. 2010, no. 1, pp. 3-20, 2010.
- [3] The GIS spatial data model, 2015 [Online]. Available: https://courses.washington.edu/gis250/lessons/introduction_gis/spatial_data_model.html.
- [4] GIS digital vector maps, 2015 [Online]. Available: <http://www.mapmart.com/Products/DigitalVectorMapping.aspx>.
- [5] Vector data, 2015 [Online]. Available: https://docs.qgis.org/2.8/en/docs/gentle_gis_introduction/vector_data.html.
- [6] Advantage of vector map, 2015 [Online]. Available: <https://maxdisruption.wordpress.com/2011/01/14/advantage-and-disadvantages-of-vectorraster-data/>.
- [7] E. Bertino and M. L. Damiani, "A controlled access to spatial data on web," in *Proceedings of 7th AGILE Conference on Geographic Information Science*, Crete, Greece, pp. 82-91, 2004.
- [8] S. C. Chen, X. Wang, N. Rishe, and M. A. Weiss, "A web-based spatial data access system using semantic R-trees," *Journal of Information Sciences*, vol. 167, no. 1-4, pp. 41-61, 2004.
- [9] R. Ohbuchi, H. Ueda, and S. Endoh, "Robust watermarking of vector digital maps," in *Proceedings of IEEE International Conference on Multimedia and Expo*, Lausanne, Switzerland, 2002, pp. 577-580.
- [10] M. Voigt and C. Busch, "Feature-based watermarking of 2D vector data," in *Proceedings of the SPIE 5020: Security and Watermarking of Multimedia Content*. Bellingham, WA: International Society for Optics and Photonics, 2003, pp. 359-366.
- [11] G. Schulz and M. Voigt, "A high capacity watermarking system for digital maps," in *Proceedings of the 2004 Workshop on Multimedia and Security*, Magdeburg, Germany, 2004, pp. 180-186.
- [12] C. Wang, Z. Peng, Y. Peng, L. Yu, J. Wang, and Q. Zhao, "Watermarking geographical data on spatial topological relations," *Multimedia Tools and Applications*, vol. 57, no. 1, pp. 67-89, 2012.
- [13] S. H. Lee and K. R. Kwon, "Vector watermarking scheme for GIS vector map management," *Multimedia Tools and Applications*, vol. 63, no. 3, pp. 757-790, 2013.
- [14] F. Wu, W. Cui, and H. Chen, "A compound chaos-based encryption algorithm for vector geographic data under network circumstance," in *Proceedings of 1st International Congress on Image and Signal Processing*, Sanya, China, 2008, pp. 254-258.
- [15] G. Li, "Research of key technologies on encrypting vector spatial data in oracle spatial," in *Proceedings of 2nd International Conference on Information Engineering and Computer Science*, Wuhan, China, 2010, pp. 1-4.
- [16] Y. Dakroury, I. A. El-ghafar, and A. Tammam, "Protecting GIS data using cryptography and digital watermarking," *International Journal of Computer Science and Network Security*, vol. 10, no. 1, pp. 75-84, 2010.

- [17] B. J. Jang, S. H. Lee, and K. R. Kwon, "Perceptual encryption with compression for secure vector map data processing," *Digital Signal Processing*, vol. 25, pp. 224-243, 2014.
- [18] Y. Pomeau and P. Manneville, "Intermittent Transition to Turbulence in Dissipative Dynamical Systems," *Communications in Mathematical Physics*, vol. 74, no. 2, pp. 189-197, 1980.
- [19] RSA Laboratories, PKCS #5: Password-Based Cryptography Standard (version 2.1) [Online]. Available: <https://germany.emc.com/emc-plus/rsa-labs/standards-initiatives/pkcs-5-password-based-cryptography-standard.htm>.
- [20] P. N. Giao, S. H. Lee, and K. R. Kwon, "Selective encryption algorithm for GIS vector map using geometric objects," *International Journal of Security and Its Applications*, vol. 9, no. 2, pp. 61-72, 2015.
- [21] P. N. Giao, G. C. Kwon, S. H. Lee, and K. R. Kwon, "Selective encryption algorithm based on DCT for GIS vector map," *Journal of Korea Multimedia Society*, vol. 17, no. 7, pp. 769-777, 2014.
- [22] Wikipedia, Kerckhoffs's principle [Online]. Available: http://en.wikipedia.org/wiki/Kerckhoffs's_principle.



Bang Van Nguyen

He received a B.S. degree in School of Electronic & Telecommunication from Hanoi University of Science & Technology (HUST) in 2014. Currently, he is a Master student in Multimedia Communication & Signal Processing Lab in Pukyong National University. His research interests include video processing & application, GIS applications, data security, and smart system.



Suk-Hwan Lee <http://orcid.org/0000-0003-4779-2888>

He received the B.S., M.S., and Ph.D. degrees in Electrical Engineering from Kyungpook National University, Korea in 1999, 2001, and 2004, respectively. He is currently an associate professor in Department of Information Security at Tongmyong University. His research interests include multimedia security, digital image processing, and computer graphics.



Ki-Ryong Kwon

He received the B.S., M.S., and Ph.D. degrees in electronics engineering from Kyungpook National University in 1986, 1990, and 1994, respectively. He worked at Hyundai Motor Company from 1986-1988 and at Pusan University of Foreign Language from 1996-2006. He is currently a professor in Department of IT Convergence and Application Engineering at the Pukyong National University. He has researched University of Minnesota in USA on 2000-2002 with Post-Doc. and Colorado State University on 2011-2012 with visiting professor. He is currently the President of Korea Multimedia Society. His research interests are in the area of digital image processing, multimedia security and watermarking, bioinformatics, weather radar information processing.