

## Forced Oscillation Criteria for Nonlinear Hyperbolic Equations via Riccati Method

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ABSTRACT. In this paper, we consider the nonlinear hyperbolic equations with forcing term. Some sufficient conditions for the oscillation are derived by using integral averaging method and a generalized Riccati technique.

### 1. Introduction

We shall provide oscillation results of solution of the hyperbolic equation

$$(E) \quad \frac{\partial}{\partial t} \left( r(t) \frac{\partial}{\partial t} u(x, t) \right) + p(t) \frac{\partial}{\partial t} u(x, t) \\ - a(t) \Delta u(x, t) - \sum_{i=1}^k b_i(t) \Delta u(x, \tau_i(t)) \\ + \sum_{i=1}^m q_i(x, t) \varphi_i(u(x, \sigma_i(t))) = f(x, t), \quad (x, t) \in \Omega \equiv G \times (0, \infty),$$

where  $\Delta$  is the Laplacian in  $\mathbb{R}^n$  and  $G$  is a bounded domain of  $\mathbb{R}^n$  with piecewise smooth boundary  $\partial G$ . Recently, the oscillation of solution of hyperbolic equation via Riccati method has been investigated by many authors, see for example [2], [6], [7]. In particular, Shoukaku [6] established the oscillation results of solution of the equation (E). In the work of [6], restriction is imposed on forcing term  $f(x, t)$  to be oscillatory function.

Gaef and Spikes [3], Wong and Agarwal [8], Li [4] and Agawal, et al [1] obtained several oscillation results for second order nonlinear differential equations. Their results used the different assumption of forcing term from the work of [6].

Motivated by the work of [1], in this paper we will obtain the oscillation results

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of the hyperbolic equation (E), and remove the assumption of the forcing term such as the work [6].

We assume throughout this paper that:

- (H1)  $r(t) \in C^1([0, \infty); (0, \infty))$ ,  $p(t) \in C([0, \infty); \mathbb{R})$ ,  
 $a(t), b_i(t) \in C([0, \infty); [0, \infty))$  ( $i = 1, 2, \dots, k$ ),  
 $q_i(x, t) \in C(\bar{\Omega}; [0, \infty))$  ( $i = 1, 2, \dots, m$ ),  $f(x, t) \in C(\bar{\Omega}; \mathbb{R})$ ;
- (H2)  $\tau_i(t) \in C([0, \infty); \mathbb{R})$ ,  $\lim_{t \rightarrow \infty} \tau_i(t) = \infty$  ( $i = 1, 2, \dots, k$ ),  
 $\sigma_i(t) \in C^1([0, \infty); \mathbb{R})$ ,  $\lim_{t \rightarrow \infty} \sigma_i(t) = \infty$  ( $i = 1, 2, \dots, m$ );
- (H3)  $\varphi_i(s) \in C^1(\mathbb{R}; \mathbb{R})$  ( $i = 1, 2, \dots, m$ ) are convex on  $[0, \infty)$ , and  $\varphi_i(s) \geq 0$  and  $\varphi_i(-s) = -\varphi_i(s)$  for  $s \geq 0$ .

We consider the following Dirichlet and Robin boundary boundary conditions

- (B1)  $u = \psi$  on  $\partial G \times [0, \infty)$ ,
- (B2)  $\frac{\partial u}{\partial \nu} + \mu u = \tilde{\psi}$  on  $\partial G \times [0, \infty)$ ,

where  $\nu$  denotes the unit exterior normal vector to  $\partial G$  and  $\psi, \tilde{\psi} \in C(\partial G \times (0, \infty); \mathbb{R})$ ,  $\mu \in C(\partial G \times (0, \infty); [0, \infty))$ .

**Definition 1.** By a *solution* of Eq. (E) we mean a function  $u \in C^2(\bar{G} \times [t_{-1}, \infty)) \cap C(\bar{G} \times [t_{-1}, \infty))$  which satisfies (E), where

$$t_{-1} = \min \left\{ 0, \min_{1 \leq i \leq k} \left\{ \inf_{t \geq 0} \tau_i(t) \right\} \right\}, \quad \tilde{t}_{-1} = \min \left\{ 0, \min_{1 \leq i \leq m} \left\{ \inf_{t \geq 0} \sigma_i(t) \right\} \right\}.$$

**Definition 2.** A solution  $u$  of Eq. (E) is said to be *oscillatory* in  $\Omega$  if  $u$  has a zero in  $G \times (t, \infty)$  for any  $t > 0$ . That is, there exists a point  $t_1 > t$  such that  $u(x, t_1) = 0$ .

**Definition 3.** We say that functions  $H_1, H_2$  belong to a function class  $\mathbb{H}$ , denoted by  $H_1, H_2 \in \mathbb{H}$ , if  $H_1, H_2 \in C(D; [0, \infty))$  satisfy

$$H_i(t, t) = 0, \quad H_i(t, s) > 0 \quad (i = 1, 2) \quad \text{for } t > s,$$

where  $D = \{(t, s) : 0 < s \leq t < \infty\}$ . Moreover, the partial derivatives  $\partial H_1 / \partial t$  and  $\partial H_2 / \partial s$  exist on  $D$  such that

$$\frac{\partial H_1}{\partial t}(s, t) = h_1(s, t)H_1(s, t) \quad \text{and} \quad \frac{\partial H_2}{\partial s}(t, s) = -h_2(t, s)H_2(t, s),$$

where  $h_1, h_2 \in C_{loc}(D; \mathbb{R})$ .

## 2. Reduction to One-Dimensional Problems

In this section we reduce the multi-dimensional oscillation problems for (E) to

one-dimensional oscillation problems. It is known that the first eigenvalue  $\lambda_1$  of the eigenvalue problem

$$\begin{aligned} -\Delta w &= \lambda w & \text{in } G, \\ w &= 0 & \text{on } \partial G \end{aligned}$$

is positive, and the corresponding eigenfunction  $\Phi(x)$  can be chosen so that  $\Phi(x) > 0$  in  $G$ . Now we define

$$q_i(t) = \min_{x \in \bar{G}} q_i(x, t).$$

The following notation will be used:

$$\begin{aligned} U(t) &= K_\Phi \int_G u(x, t) \Phi(x) dx, & \tilde{U}(t) &= \frac{1}{|G|} \int_{\partial G} u(x, t) dx, \\ F(t) &= K_\Phi \int_G f(x, t) \Phi(x) dx, & \tilde{F}(t) &= \frac{1}{|G|} \int_{\partial G} f(x, t) dx, \\ \Psi(t) &= K_\Phi \int_{\partial G} \psi \frac{\partial \Phi}{\partial \nu}(x) dS, & \tilde{\Psi}(t) &= \frac{1}{|G|} \int_{\partial G} \tilde{\psi} dS, \end{aligned}$$

where  $K_\Phi = (\int_G \Phi(x) dx)^{-1}$  and  $|G| = \int_G dx$ .

**Theorem 1.** *If every eventually positive solution  $y(t)$  of the functional differential inequalities*

$$(1) \quad (r(t)y'(t))' + p(t)y'(t) + \sum_{i=1}^m q_i(t)\varphi_i(y(\sigma_i(t))) \leq \pm G(t)$$

*satisfies  $\liminf_{t \rightarrow \infty} y(t) = 0$ , then every solution  $u(x, t)$  of the problem (E), (B1) is oscillatory in  $\Omega$  or satisfies*

$$(2) \quad \liminf_{t \rightarrow \infty} |U(t)| = 0,$$

where

$$G(t) = F(t) - a(t)\Psi(t) - \sum_{i=1}^k b_i(\tau_i(t))\Psi(\tau_i(t)).$$

*Proof.* Suppose to the contrary that there is a nonoscillatory solution  $u$  of the problem (E), (B1) which does not satisfy (2). Without loss of generality we may assume that  $u(x, t) > 0$  in  $G \times [t_0, \infty)$  for some  $t_0 > 0$  because the case where  $u(x, t) < 0$  can be treated similarly. Since (H2) holds, we see that  $u(x, \tau_i(t)) > 0$  ( $i = 1, 2, \dots, k$ ) and  $u(x, \sigma_i(t)) > 0$  ( $i = 1, 2, \dots, m$ ) in  $G \times [t_1, \infty)$  for some

$t_1 \geq t_0$ . Multiplying (E) by  $K_\Phi \Phi(x)$  and integrating over  $G$ , we obtain

$$(3) \quad \begin{aligned} & (r(t)U'(t))' + p(t)U'(t) \\ & - a(t)K_\Phi \int_G \Delta u(x, t)\Phi(x)dx - \sum_{i=1}^k b_i(t)K_\Phi \int_G \Delta u(x, \tau_i(t))\Phi(x)dx \\ & + \sum_{i=1}^m K_\Phi \int_G q_i(x, t)\varphi_i(u(x, \sigma_i(t)))\Phi(x)dx = F(t), \quad t \geq t_1. \end{aligned}$$

From Green's formula it follows that

$$(4) \quad K_\Phi \int_G \Delta u(x, t)\Phi(x)dx \leq -\Psi(t), \quad t \geq t_1,$$

$$(5) \quad K_\Phi \int_G \Delta u(x, \tau_i(t))\Phi(x)dx \leq -\Psi(\tau_i(t)), \quad t \geq t_1.$$

An application of Jensen's inequality shows that

$$(6) \quad \sum_{i=1}^m K_\Phi \int_G q_i(x, t)\varphi_i(u(x, \sigma_i(t)))\Phi(x)dx \geq \sum_{i=1}^m q_i(t)\varphi_i(U(\sigma_i(t))), \quad t \geq t_1.$$

Combining (3)–(6) yields

$$(r(t)U'(t))' + p(t)U'(t) + \sum_{i=1}^m q_i(t)\varphi_i(U(\sigma_i(t))) \leq G(t), \quad t \geq t_1.$$

Therefore  $U(t)$  is a positive solution of (1) which does not satisfy (2). This contradicts the hypothesis and completes the proof.  $\square$

**Theorem 2.** *If every eventually positive solution  $y(t)$  of the functional differential inequalities*

$$(7) \quad (r(t)y'(t))' + p(t)y'(t) + \sum_{i=1}^m q_i(t)\varphi_i(y(\sigma_i(t))) \leq \pm \tilde{G}(t)$$

*satisfies  $\liminf_{t \rightarrow \infty} y(t) = 0$ , then every solution  $u(x, t)$  of the problem (E), (B2) is oscillatory in  $\Omega$  or satisfies*

$$(8) \quad \liminf_{t \rightarrow \infty} |\tilde{U}(t)| = 0,$$

where

$$\tilde{G}(t) = \tilde{F}(t) + a(t)\tilde{\Psi}(t) + \sum_{i=1}^k b_i(\tau_i(t))\tilde{\Psi}(\tau_i(t)).$$

*Proof.* Suppose to the contrary that there is a nonoscillatory solution  $u$  of problem (E), (B2) which does not satisfy (8). Without loss of generality we may assume that  $u(x, t) > 0$  in  $G \times [t_0, \infty)$  for some  $t_0 > 0$ . Since (H2) holds, we see that  $u(x, \tau_i(t)) > 0$  ( $i = 1, 2, \dots, k$ ) and  $u(x, \sigma_i(t)) > 0$  ( $i = 1, 2, \dots, m$ ) in  $G \times [t_1, \infty)$  for some  $t_1 \geq t_0$ . Dividing (E) by  $|G|$  and integrating over  $G$ , we obtain

$$(9) \quad \begin{aligned} & (r(t)\tilde{U}'(t))' + p(t)\tilde{U}'(t) \\ & - \frac{a(t)}{|G|} \int_G \Delta u(x, t) dx - \sum_{i=1}^k \frac{b_i(t)}{|G|} \int_G \Delta u(x, \tau_i(t)) dx \\ & + \frac{1}{|G|} \sum_{i=1}^m \int_G q_i(x, t) \varphi_i(u(x, \sigma_i(t))) dx = \tilde{F}(t), \quad t \geq t_1. \end{aligned}$$

It follows from Green's formula that

$$(10) \quad \frac{1}{|G|} \int_G \Delta u(x, t) dx \leq \tilde{\Psi}(t), \quad t \geq t_1,$$

$$(11) \quad \frac{1}{|G|} \int_G \Delta u(x, \tau_i(t)) dx \leq \tilde{\Psi}(\tau_i(t)), \quad t \geq t_1.$$

Applying Jensen's inequality, we observe that

$$(12) \quad \frac{1}{|G|} \sum_{i=1}^m \int_G q_i(x, t) \varphi_i(u(x, \sigma_i(t))) dx \geq \sum_{i=1}^m q_i(t) \varphi_i(\tilde{U}(\sigma_i(t))), \quad t \geq t_1.$$

Combining (9)–(12) yields

$$(r(t)\tilde{U}'(t))' + p(t)\tilde{U}'(t) + \sum_{i=1}^m q_i(t) \varphi_i(\tilde{U}(\sigma_i(t))) \leq \tilde{G}(t), \quad t \geq t_1.$$

Hence,  $\tilde{U}(t)$  is a positive solution of (7) which does not satisfy (8). This contradicts the hypothesis and completes the proof.  $\square$

### 3. Second Order Functional Differential Inequality

We obtain the sufficient conditions for every positive solution  $y(t)$  of the functional differential inequality

$$(13) \quad (r(t)y'(t))' + p(t)y'(t) + \sum_{i=1}^m q_i(t) \varphi_i(y(\sigma_i(t))) \leq f(t)$$

to satisfy  $\liminf_{t \rightarrow \infty} y(t) = 0$ , where  $f(t) \in C([0, \infty); \mathbb{R})$ . We assume the following hypotheses:

$$(H4) \quad \varphi'_j(t) > 0, \varphi'_j(t) \text{ is nondecreasing for } t > 0 \text{ and some } j \in \{1, 2, \dots, m\};$$

(H5) there exists a positive constant  $\sigma$  such that

$$\sigma'_j(t) \geq \sigma \quad \text{and} \quad \sigma_j(t) \leq t;$$

(H6) there exists a positive constant  $K$  such that

$$q_j(t) \geq K|f(t)|.$$

**Theorem 3.** *If the Riccati inequalities for  $i = 1, 2$*

$$(14) \quad x'(t) + \frac{1}{2} \frac{1}{p_i(t)} x^2(t) \leq -q(t)$$

have no solution on  $[T, \infty)$  for all large  $T$ , then eventually positive solution of (13) satisfies  $\liminf_{t \rightarrow \infty} y(t) = 0$ , where

$$p_1(t) = \tilde{K}e^{R(t)}, \quad p_2(t) = p_1(\sigma_j(t)), \quad R(t) = \log r(t) + \int_{t_0}^t \frac{p(s)}{r(s)} ds,$$

$$q(t) = \frac{e^{R(t)}}{r(t)} \{q_j(t) - K|f(t)|\}$$

for every positive constant  $\tilde{K}$ .

*Proof.* Suppose that  $y(t)$  is an eventually positive solution of (13) on  $[t_0, \infty)$  for some  $t_0 > 0$ , and  $\liminf_{t \rightarrow \infty} y(t) > 0$ . Hence, there exists  $k_1 > 0$  such that  $y(t) \geq k_1$ ,  $t \geq t_1$  for some  $t_1 \geq t_0$ . It follows from (13) that

$$(15) \quad \left( e^{R(t)} y'(t) \right)' + q_j(t) \frac{e^{R(t)}}{r(t)} \varphi_j(y(\sigma_j(t))) \leq \frac{e^{R(t)}}{r(t)} f(t), \quad t \geq t_1.$$

Since  $\varphi_j(y(\sigma_j(t))) > \varphi_j(k_1) \equiv K_1$ ,  $t \geq t_2$  for some  $t_2 \geq t_1$ , we can see from (H6) that

$$(16) \quad \left( e^{R(t)} y'(t) \right)' \leq -\frac{e^{R(t)}}{r(t)} \{K_1 q_j(t) - |f(t)|\} \leq 0, \quad t \geq t_2.$$

Then we consider  $y'(t) < 0$  or  $y'(t) \geq 0$  for  $t \geq t_2$ .

Case 1.  $y'(t) < 0$  for  $t \geq t_2$ . Setting

$$z(t) = \frac{e^{R(t)} y'(t)}{\varphi_j(y(t))},$$

then

$$\begin{aligned}
 (17) \quad z'(t) &= \frac{(e^{R(t)}y'(t))'}{\varphi_j(y(t))} - e^{R(t)}y'(t)\frac{y'(t)\varphi_j'(y(t))}{\varphi_j^2(y(t))} \\
 &\leq -q_j(t)\frac{e^{R(t)}\varphi_j(y(\sigma_j(t)))}{r(t)\varphi_j(y(t))} + \frac{e^{R(t)}|f(t)|}{r(t)\varphi_j(y(t))} - e^{-R(t)}\varphi_j'(y(t))z^2(t) \\
 &\leq -q_j(t)\frac{e^{R(t)}}{r(t)} + \frac{e^{R(t)}|f(t)|}{r(t)\varphi_j(k_1)} - e^{-R(t)}\varphi_j'(k_1)z^2(t) \\
 &\leq -\frac{e^{R(t)}}{r(t)}\left\{q_j(t) - \frac{|f(t)|}{K_1}\right\} - e^{-R(t)}\varphi_j'(k_1)z^2(t)
 \end{aligned}$$

which contradicts the fact that  $z(t)$  is negative solution of (14).

Case 2.  $y'(t) \geq 0$  for  $t \geq t_2$ . Since  $y(t) > 0$ ,  $y'(t) \geq 0$  eventually, we see that  $y(\sigma_j(t)) \geq k_1$  for some  $k_1 > 0$ . Let

$$w(t) = \frac{e^{R(t)}y'(t)}{\varphi_j(y(\sigma_j(t)))}.$$

By using  $e^{R(t)}y'(t)$  is nonincreasing, we have

$$\begin{aligned}
 (18) \quad w'(t) &= \frac{(e^{R(t)}y'(t))'}{\varphi_j(y(\sigma_j(t)))} - e^{R(t)}y'(t)\frac{\sigma_j'(t)y'(\sigma_j(t))\varphi_j'(y(\sigma_j(t)))}{\varphi_j^2(y(\sigma_j(t)))} \\
 &\leq -q_j(t)\frac{e^{R(t)}}{r(t)} + \frac{e^{R(t)}|f(t)|}{r(t)\varphi_j(y(\sigma_j(t)))} \\
 &\quad - e^{-R(\sigma_j(t))}\varphi_j'(y(\sigma_j(t)))\sigma_j'(t)w^2(t) \\
 &\leq -\frac{e^{R(t)}}{r(t)}\left\{q_j(t) - \frac{|f(t)|}{\varphi_j(k_1)}\right\} \\
 &\quad - e^{-R(\sigma_j(t))}\varphi_j'(k_1)\sigma w^2(t), \quad t \geq t_2.
 \end{aligned}$$

Therefore  $w(t)$  is a positive solution of (14). This contradicts the hypothesis and completes the proof.  $\square$

**Theorem 4.** *If for some  $T \geq 0$  and for  $i = 1, 2$ , there exist  $H_1, H_2 \in \mathbb{H}$  and some  $c \in (a, b)$  such that  $T \leq a < b$  and*

$$\begin{aligned}
 (19) \quad &\frac{1}{H_1(c, a)} \int_a^c H_1(s, a) \left\{ q(s) - \frac{1}{2} \lambda_1^2(s, a) p_i(s) \right\} \phi(s) ds \\
 &+ \frac{1}{H_2(b, c)} \int_c^b H_2(b, s) \left\{ q(s) - \frac{1}{2} \lambda_2^2(b, s) p_i(s) \right\} \phi(s) ds > 0,
 \end{aligned}$$

then eventually positive solution of (13) satisfies  $\liminf_{t \rightarrow \infty} y(t) = 0$ , where  $\phi(t) \in C^1((T, \infty); (0, \infty))$  and

$$\lambda_1(s, t) = \frac{\phi'(s)}{\phi(s)} + h_1(s, t), \quad \lambda_2(t, s) = \frac{\phi'(s)}{\phi(s)} - h_2(t, s).$$

*Proof.* Suppose that  $y(t)$  is a positive solution of (13) on  $[t_0, \infty)$  for some  $t_0 > 0$ , and  $\liminf_{t \rightarrow \infty} y(t) > 0$ . At first, we assume that  $y(t) > 0$  on  $(a, b)$  for  $a, b \geq t_0$ . Proceeding as the same proof of Theorem 3, we have the inequality (14). Multiplying (14) by  $H_2(t, s)$  and  $\phi(s)$ , integrating over  $[c, t]$  for  $t \in [c, b)$  and letting  $t \rightarrow b^-$ , we see easily that

$$(20) \quad \frac{1}{H_2(b, c)} \int_c^b H_2(b, s) \left\{ q(s) - \frac{1}{2} \lambda_2^2(b, s) p_i(s) \right\} \phi(s) ds \leq x(c) \phi(c).$$

Similarly, multiplying (14) by  $H_1(s, t)$  and  $\phi(s)$ , integrating over  $[t, c]$  for  $t \in (a, b]$  and letting  $t \rightarrow a^+$ , we have

$$(21) \quad \frac{1}{H_1(c, a)} \int_a^c H_1(s, a) \left\{ q(s) - \frac{1}{2} \lambda_1^2(s, a) p_i(s) \right\} \phi(s) ds \leq -x(c) \phi(c).$$

Adding (20) and (21), we can lead to the contradiction. Pick up a sequence  $\{T_i\} \subset [t_0, \infty)$  such that  $T_i \rightarrow \infty$  as  $i \rightarrow \infty$ . By assumptions, for each  $i \in \mathbb{N}$ , there exists  $a_i, b_i, c_i \in [0, \infty)$  such that  $T_i \leq a_i < c_i < b_i$ , and (19) holds with  $a, b, c$  replaced by  $a_i, b_i, c_i$ , respectively. From that, every nontrivial solution  $y(t)$  of (13) has no zero  $t_i \in (a_i, b_i)$ . Noting that  $t_i > a_i \geq T_i$ ,  $i \in \mathbb{N}$ , we see that  $y(t)$  is a eventually positive solution of (13). This contradiction proves that Theorem 4 holds.  $\square$

**Theorem 5.** For some functions  $H_1, H_2 \in \mathbb{H}$ , each  $T \geq 0$  and for  $i = 1, 2$ , if

$$(22) \quad \limsup_{t \rightarrow \infty} \int_T^t H_1(s, T) \left\{ q(s) - \frac{1}{2} \lambda_1^2(s, T) p_i(s) \right\} \phi(s) ds > 0$$

and

$$(23) \quad \limsup_{t \rightarrow \infty} \int_T^t H_2(t, s) \left\{ q(s) - \frac{1}{2} \lambda_2^2(t, s) p_i(s) \right\} \phi(s) ds > 0,$$

then eventually positive solution of (13) satisfies  $\liminf_{t \rightarrow \infty} y(t) = 0$ , where  $\phi(t) \in C^1((T_0, \infty); (0, \infty))$  for some  $T_0 > 0$ .

*Proof.* For any  $T \geq t_0$ , let  $a = T$ . In (22) we choose  $T = a$ . Then there exists  $c > a$  such that for  $t \in (a, c]$

$$(24) \quad \int_a^c H_1(s, a) \left\{ q(s) - \frac{1}{2} \lambda_1^2(s, a) p_i(s) \right\} \phi(s) ds > 0$$

(cf. [9, Theorem 8.8.5]). In (23) we choose  $T = c$ . Then there exists  $b > c$  such that for  $t \in [c, b)$

$$(25) \quad \int_c^b H_2(b, s) \left\{ q(s) - \frac{1}{2} \lambda_2^2(b, s) p_i(s) \right\} \phi(s) ds > 0.$$

Combining (22) and (23) we obtain (19). The conclusion come from Theorem 4, and the proof is completed.  $\square$

#### 4. Oscillation Criteria for Eq. (E)

##### 4.1. Oscillation results by Riccati inequality

We are going to use the following lemma which is due to Usami [5].

**Lemma.** *If there exists a function  $\phi(t) \in C^1([T_0, \infty); (0, \infty))$  such that*

$$\int_{T_1}^{\infty} \left( \frac{\bar{p}(t)|\phi'(t)|^\beta}{\phi(t)} \right)^{\frac{1}{\beta-1}} dt < \infty, \quad \int_{T_1}^{\infty} \frac{1}{\bar{p}(t)(\phi(t))^{\beta-1}} dt = \infty,$$

$$\int_{T_1}^{\infty} \phi(t)\bar{q}(t)dt = \infty$$

for some  $T_1 \geq T_0$ , then the Riccati inequality

$$x'(t) + \frac{1}{\beta} \frac{1}{\bar{p}(t)} |x(t)|^\beta \leq -\bar{q}(t),$$

where  $\beta > 1$ ,  $\bar{p}(t) \in C([T_0, \infty); (0, \infty))$  and  $\bar{q}(t) \in C([T_0, \infty); \mathbb{R})$ , has no solution on  $[T, \infty)$  for all large  $T$ .

Combining Theorems 1-3, we obtain following theorems.

**Theorem 6.** *Assume that (H1)–(H5) hold, and that*

(H7) *there exists a positive constant  $K$  such that*

$$q_j(t) \geq K|G(t)|.$$

If for  $i = 1, 2$ ,

$$\int_{T_1}^{\infty} \left( \frac{p_i(t)\phi'(t)^2}{\phi(t)} \right) dt < \infty, \quad \int_{T_1}^{\infty} \frac{1}{p_i(t)\phi(t)} dt = \infty,$$

$$\int_{T_1}^{\infty} \phi(t)Q(t)dt = \infty,$$

then every solution  $u(x, t)$  of (E), (B1) is oscillatory in  $\Omega$  or satisfies (2), where

$$Q(t) = \frac{e^{R(t)}}{r(t)} \left\{ q_j(t) - K|G(t)| \right\}.$$

**Theorem 7.** *Assume that (H1)–(H5) hold, and that*

(H8) *there exists a positive constant  $K$  such that*

$$q_j(t) \geq K|\tilde{G}(t)|.$$

If for  $i = 1, 2$ ,

$$\int_{T_1}^{\infty} \left( \frac{p_i(t)\phi'(t)^2}{\phi(t)} \right) dt < \infty, \quad \int_{T_1}^{\infty} \frac{1}{p_i(t)\phi(t)} dt = \infty,$$

$$\int_{T_1}^{\infty} \phi(t)\tilde{Q}(t)dt = \infty,$$

then every solution  $u(x, t)$  of (E), (B2) is oscillatory in  $\Omega$  or satisfies (8), where

$$\tilde{Q}(t) = \frac{e^{R(t)}}{r(t)} \left\{ q_j(t) - K|\tilde{G}(t)| \right\}.$$

**Example 1.** We consider the problem

$$(26) \quad \frac{\partial}{\partial t} \left( e^t \frac{\partial}{\partial t} u(x, t) \right) + e^t \frac{\partial}{\partial t} u(x, t) - \left( e^t + e^{\frac{t}{2}} \right) \Delta u(x, t)$$

$$+ 2e^t u \left( x, t - \frac{\pi}{2} \right) = e^{\frac{t}{2}} \sin x \sin t, \quad (x, t) \in (0, \pi) \times (0, \infty),$$

$$(27) \quad u(0, t) = u(\pi, t) = 0, \quad t > 0.$$

Here  $n = k = m = 1$ ,  $r(t) = e^t$ ,  $p_1(t) = e^{2t}$ ,  $p_2(t) = e^{2t-\pi/2}$ ,  $q_1(x, t) = 2e^t$ ,  $\sigma_1(t) = t - \pi/2$  and  $f(x, t) = e^t \sin x \sin t$ . It is easily verified that  $\Phi(x) = \sin x$  and

$$q_1(t) \equiv 2e^t \geq \frac{\pi}{4} |e^{\frac{t}{2}} \sin t| \equiv |G(t)|.$$

By choosing  $\phi(t) = e^{-3t}$ , the conditions of Theorem 6 are satisfied. Therefore, we conclude that every solution  $u$  of the problem (26), (27) is oscillatory in  $(0, \pi) \times (0, \infty)$  or satisfies (2). For example,  $u = \sin x \sin t$  is such a solution.

**Example 2.** Consider the problem

$$(28) \quad \frac{\partial}{\partial t} \left( e^{-t} \frac{\partial}{\partial t} u(x, t) \right) + 2e^{-t} \frac{\partial}{\partial t} u(x, t) - \Delta u(x, t)$$

$$+ e^{\frac{t}{2}} u \left( x, \frac{t}{2} \right) = (e^{-t} + 1) \cos x, \quad (x, t) \in \left( 0, \frac{\pi}{2} \right) \times (0, \infty),$$

$$(29) \quad -u_x(0, t) = 0, \quad u_x \left( \frac{\pi}{2}, t \right) = -e^{-t}, \quad t > 0.$$

Here  $n = k = m = 1$ ,  $r(t) = e^{-t}$ ,  $p_1(t) = e^t$ ,  $p_2(t) = e^{t/2}$ ,  $q_1(x, t) = 2e^{-t}$ ,  $a(t) = 1$ ,  $\sigma_1(t) = t/2$  and  $f(x, t) = (e^{-t} + 1) \cos x$ . A simple calculation yields  $\tilde{G}(t) = 2/\pi$  and

$$q_1(t) \equiv e^{\frac{t}{2}} \geq \frac{2}{\pi} \equiv |\tilde{G}|.$$

By choosing  $\phi(t) = e^{-\frac{3}{2}t}$  we note that the conditions of Theorem 7 holds. Therefore, every solution  $u$  of the problem (28), (29) is oscillatory in  $(0, \pi) \times (0, \infty)$  or satisfies

(8). For example,  $u = e^{-t} \cos x$  is such a solution.

#### 4.2. Interval oscillation results

Combining Theorems 1–2 and 4, we have following theorems.

**Theorem 8.** *Assume that (H1)–(H5) and that (H7) hold. If for some  $T \geq 0$  and for  $i = 1, 2$ , there exist  $H_1, H_2 \in \mathbb{H}$  and some  $c \in (a, b)$  such that  $T \leq a < b$ , (19) with  $q(s)$  replaced by  $Q(s)$ , then every solution  $u(x, t)$  of (E), (B1) is oscillatory in  $\Omega$  or satisfies (2).*

**Theorem 9.** *Assume that (H1)–(H5) and (H8) hold. If for some  $T \geq 0$  and for  $i = 1, 2$ , there exist  $H_1, H_2 \in \mathbb{H}$  and some  $c \in (a, b)$  such that  $T \leq a < b$ , (19) with  $q(s)$  replaced by  $\tilde{Q}(s)$ , then every solution  $u(x, t)$  of (E), (B2) is oscillatory in  $\Omega$  or satisfies (8).*

Combining Theorems 1–2 and 5, we obtain two theorems.

**Theorem 10.** *Assume that (H1)–(H5) and (H7) hold. For some functions  $H_1, H_2 \in \mathbb{H}$ , some  $T \geq 0$  and for  $i = 1, 2$ , if (22) and (23) with  $q(s)$  replaced by  $Q(s)$  hold, then every solution  $u(x, t)$  of (E), (B1) is oscillatory in  $\Omega$  or satisfies (2).*

**Theorem 11.** *Assume that (H1)–(H5) and (H8) hold. For some functions  $H_1, H_2 \in \mathbb{H}$ , some  $T \geq 0$  and for  $i = 1, 2$ , if (22) and (23) with  $q(s)$  replaced by  $\tilde{Q}(s)$  hold, then every solution  $u(x, t)$  of (E), (B2) is oscillatory in  $\Omega$  or satisfies (8).*

**Remark.** Our results in this paper hold without the hypotheses (H5) and (H6), if condition  $\sigma_j(t) = t$  satisfied.

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