

ASYMPTOTIC PROPERTY FOR PERTURBED NONLINEAR FUNCTIONAL DIFFERENTIAL SYSTEMS

DONG MAN IM AND YOON HOE GOO*

ABSTRACT. This paper shows that the solutions to the perturbed nonlinear functional differential system

$$y' = f(t, y) + \int_{t_0}^t g(s, y(s), Ty(s))ds, f(t, 0) = 0, g(t, 0, 0) = 0$$

go to zero as t goes to infinity. To show asymptotic property, we impose conditions on the perturbed part $\int_{t_0}^t g(s, y(s), Ty(s))ds$ and the fundamental matrix of the unperturbed system $y' = f(t, y)$.

AMS Mathematics Subject Classification : 34D05.

Key words and phrases : asymptotically stable, exponentially asymptotic stability, exponentially asymptotic stability in variation., nonlinear nonautonomous system.

1. Introduction

Elaydi and Farran [8] introduced the notion of exponential asymptotic stability(EAS) which is a stronger notion than that of ULS. They investigated some analytic criteria for an autonomous differential system and its perturbed systems to be EAS. Pachpatte [13] investigated the stability and asymptotic behavior of solutions of the functional differential equation. Gonzalez and Pinto [9] proved theorems which relate the asymptotic behavior and boundedness of the solutions of nonlinear differential systems. Choi et al. [6,7] examined Lipschitz and exponential asymptotic stability for nonlinear functional systems. Also, Goo [11] and Choi and Goo [2,4] investigated Lipschitz and asymptotic stability for perturbed differential systems.

In this paper we will obtain some results on asymptotic property for nonlinear perturbed differential systems. We will employ the theory of integral inequalities to study asymptotic property for solutions of the nonlinear differential systems. The method incorporating integral inequalities takes an important place among

Received March 29, 2015. Accepted June 29, 2015. *Corresponding author .

© 2015 Korean SIGCAM and KSCAM.

the methods developed for the qualitative analysis of solutions to linear and nonlinear system of differential equations.

2. Preliminaries

We consider the nonlinear nonautonomous differential system

$$x'(t) = f(t, x(t)), \quad x(t_0) = x_0, \quad (1)$$

where $f \in C(\mathbb{R}^+ \times \mathbb{R}^n, \mathbb{R}^n)$, $\mathbb{R}^+ = [0, \infty)$ and \mathbb{R}^n is the Euclidean n -space. We assume that the Jacobian matrix $f_x = \partial f / \partial x$ exists and is continuous on $\mathbb{R}^+ \times \mathbb{R}^n$ and $f(t, 0) = 0$. Also, we consider the perturbed differential system of (1)

$$y' = f(t, y) + \int_{t_0}^t g(s, y(s), Ty(s)) ds, \quad y(t_0) = y_0, \quad (2)$$

where $g \in C(\mathbb{R}^+ \times \mathbb{R}^n \times \mathbb{R}^n, \mathbb{R}^n)$, $g(t, 0, 0) = 0$, and $T : C(\mathbb{R}^+, \mathbb{R}^n) \rightarrow C(\mathbb{R}^+, \mathbb{R}^n)$ is a continuous operator .

For $x \in \mathbb{R}^n$, let $|x| = (\sum_{j=1}^n x_j^2)^{1/2}$. For an $n \times n$ matrix A , define the norm $|A|$ of A by $|A| = \sup_{|x| \leq 1} |Ax|$.

Let $x(t, t_0, x_0)$ denote the unique solution of (1) with $x(t_0, t_0, x_0) = x_0$, existing on $[t_0, \infty)$. Then we can consider the associated variational systems around the zero solution of (1) and around $x(t)$, respectively,

$$v'(t) = f_x(t, 0)v(t), \quad v(t_0) = v_0 \quad (3)$$

and

$$z'(t) = f_x(t, x(t, t_0, x_0))z(t), \quad z(t_0) = z_0. \quad (4)$$

The fundamental matrix $\Phi(t, t_0, x_0)$ of (4) is given by

$$\Phi(t, t_0, x_0) = \frac{\partial}{\partial x_0} x(t, t_0, x_0),$$

and $\Phi(t, t_0, 0)$ is the fundamental matrix of (3).

Before giving further details, we give some of the main definitions that we need in the sequel [8].

Definition 2.1. The system (1) (the zero solution $x = 0$ of (1)) is called
 (S) *stable* if for any $\epsilon > 0$ and $t_0 \geq 0$, there exists $\delta = \delta(t_0, \epsilon) > 0$ such that if $|x_0| < \delta$, then $|x(t)| < \epsilon$ for all $t \geq t_0 \geq 0$,
 (AS) *asymptotically stable* if it is stable and if there exists $\delta = \delta(t_0) > 0$ such that if $|x_0| < \delta$, then $|x(t)| \rightarrow 0$ as $t \rightarrow \infty$,
 (ULS) *uniformly Lipschitz stable* if there exist $M > 0$ and $\delta > 0$ such that $|x(t)| \leq M|x_0|$ whenever $|x_0| \leq \delta$ and $t \geq t_0 \geq 0$,
 (EAS) *exponentially asymptotically stable* if there exist constants $K > 0$, $c > 0$, and $\delta > 0$ such that

$$|x(t)| \leq K|x_0|e^{-c(t-t_0)}, \quad 0 \leq t_0 \leq t$$

provided that $|x_0| < \delta$,

(EASV) *exponentially asymptotically stable in variation* if there exist constants $K > 0$ and $c > 0$ such that

$$|\Phi(t, t_0, x_0)| \leq K e^{-c(t-t_0)}, 0 \leq t_0 \leq t$$

provided that $|x_0| < \infty$.

Remark 2.1 ([9]). The last definition implies that for $|x_0| \leq \delta$

$$|x(t)| \leq K |x_0| e^{-c(t-t_0)}, 0 \leq t_0 \leq t.$$

We give some related properties that we need in the sequel. We need Alekseev formula to compare between the solutions of (1) and the solutions of perturbed nonlinear system

$$y' = f(t, y) + g(t, y), \quad y(t_0) = y_0, \quad (5)$$

where $g \in C(\mathbb{R}^+ \times \mathbb{R}^n, \mathbb{R}^n)$ and $g(t, 0) = 0$. Let $y(t) = y(t, t_0, y_0)$ denote the solution of (5) passing through the point (t_0, y_0) in $\mathbb{R}^+ \times \mathbb{R}^n$.

The following is a generalization to nonlinear system of the variation of constants formula due to Alekseev [1].

Lemma 2.1. *Let x and y be a solution of (1) and (5), respectively. If $y_0 \in \mathbb{R}^n$, then for all $t \geq t_0$ such that $x(t, t_0, y_0) \in \mathbb{R}^n$, $y(t, t_0, y_0) \in \mathbb{R}^n$,*

$$y(t, t_0, y_0) = x(t, t_0, y_0) + \int_{t_0}^t \Phi(t, s, y(s)) g(s, y(s)) ds.$$

Lemma 2.2 (Bihari-type inequality). *Let $u, \lambda \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$ and $w(u)$ be nondecreasing in u . Suppose that, for some $c > 0$,*

$$u(t) \leq c + \int_{t_0}^t \lambda(s) w(u(s)) ds, \quad t \geq t_0 \geq 0.$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t \lambda(s) ds \right],$$

where $t_0 \leq t < b_1$, $W(u) = \int_{u_0}^u \frac{ds}{w(s)}$, $W^{-1}(u)$ is the inverse of $W(u)$, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t \lambda(s) ds \in \text{dom} W^{-1} \right\}.$$

Lemma 2.3 ([10]). *Let $u, \lambda_1, \lambda_2, \lambda_3, \lambda_4 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$, and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$ and $0 \leq t_0 \leq t$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) \int_{t_0}^s (\lambda_2(\tau) w(u(\tau)) + \lambda_3(\tau) \int_{t_0}^{\tau} \lambda_4(r) u(r) dr) d\tau ds.$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t \lambda_1(s) \int_{t_0}^s (\lambda_2(\tau) + \lambda_3(\tau) \int_{t_0}^{\tau} \lambda_4(r) dr) d\tau ds \right],$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t \lambda_1(s) \int_{t_0}^s (\lambda_2(\tau) + \lambda_3(\tau) \int_{t_0}^\tau \lambda_4(r) dr) d\tau ds \in \text{dom} W^{-1} \right\}.$$

Lemma 2.4 ([3]). *Let $u, \lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5, \lambda_6, \lambda_7 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$, and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$ and $0 \leq t_0 \leq t$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) u(s) ds + \int_{t_0}^t \lambda_2(s) \int_{t_0}^s (\lambda_3(\tau) w(u(\tau)) + \lambda_4(\tau) \int_{t_0}^\tau \lambda_5(r) w(u(r)) dr) d\tau ds + \int_{t_0}^t \lambda_6(s) \int_{t_0}^s \lambda_7(\tau) u(\tau) d\tau ds. \tag{6}$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) \int_{t_0}^s (\lambda_3(\tau) + \lambda_4(\tau) \int_{t_0}^\tau \lambda_5(r) dr) d\tau + \lambda_6(s) \int_{t_0}^s \lambda_7(\tau) d\tau) ds \right], \tag{7}$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) \int_{t_0}^s (\lambda_3(\tau) + \lambda_4(\tau) \int_{t_0}^\tau \lambda_5(r) dr) d\tau + \lambda_6(s) \int_{t_0}^s \lambda_7(\tau) d\tau) ds \in \text{dom} W^{-1} \right\}.$$

Proof. Define a function $v(t)$ by the right member of (6). Then, we have $v(t_0) = c$ and

$$\begin{aligned} v'(t) &= \lambda_1(t) u(t) + \lambda_2(t) \left(\int_{t_0}^t (\lambda_3(s) w(u(s)) + \lambda_4(s) \int_{t_0}^s \lambda_5(\tau) w(u(\tau)) d\tau) ds \right. \\ &\quad \left. + \lambda_6(t) \int_{t_0}^t \lambda_7(s) u(s) ds \right) \\ &\leq \left[\lambda_1(t) + \lambda_2(t) \left(\int_{t_0}^t (\lambda_3(s) + \lambda_4(s) \int_{t_0}^s \lambda_5(\tau) d\tau) ds \right. \right. \\ &\quad \left. \left. + \lambda_6(t) \int_{t_0}^t \lambda_7(s) ds \right) \right] w(v(t)), \end{aligned}$$

$t \geq t_0$, since $v(t)$ is nondecreasing, $u \leq w(u)$, and $u(t) \leq v(t)$. Now, by integrating the above inequality on $[t_0, t]$ and $v(t_0) = c$, we have

$$v(t) \leq c + \int_{t_0}^t \left(\lambda_1(s) + \lambda_2(s) \int_{t_0}^s (\lambda_3(\tau) + \lambda_4(\tau) \int_{t_0}^\tau \lambda_5(r) dr) d\tau + \lambda_6(s) \int_{t_0}^s \lambda_7(\tau) d\tau \right) w(v(s)) ds. \tag{8}$$

It follows from Lemma 2.2 that (8) yields the estimate (7). □

For the proof we need the following corollary from Lemma 2.4.

Corollary 2.5. *Let $u, \lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5, \lambda_6 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$, and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$ and $0 \leq t_0 \leq t$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) \int_{t_0}^s \lambda_2(\tau) u(\tau) d\tau ds + \int_{t_0}^t \lambda_3(s) \int_{t_0}^s (\lambda_4(\tau) w(u(\tau)) + \lambda_5(\tau) \int_{t_0}^{\tau} \lambda_6(r) w(u(r)) dr) d\tau ds.$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t (\lambda_1(s) \int_{t_0}^s \lambda_2(\tau) d\tau + \lambda_3(s) \int_{t_0}^s (\lambda_4(\tau) + \lambda_5(\tau) \int_{t_0}^{\tau} \lambda_6(r) dr) d\tau) ds \right],$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t (\lambda_1(s) \int_{t_0}^s \lambda_2(\tau) d\tau + \lambda_3(s) \int_{t_0}^s (\lambda_4(\tau) + \lambda_5(\tau) \int_{t_0}^{\tau} \lambda_6(r) dr) d\tau) ds \in \text{dom} W^{-1} \right\}.$$

Lemma 2.6 ([5]). *Let $u, \lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5, \lambda_6 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$ and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) u(s) ds + \int_{t_0}^t \lambda_2(s) w(u(s)) ds + \int_{t_0}^t \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) u(\tau) d\tau ds + \int_{t_0}^t \lambda_5(s) \int_{t_0}^s \lambda_6(\tau) w(u(\tau)) d\tau ds, \quad 0 \leq t_0 \leq t. \quad (9)$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) + \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) d\tau + \lambda_5(s) \int_{t_0}^s \lambda_6(\tau) d\tau) ds \right], \quad (10)$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) + \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) d\tau + \lambda_5(s) \int_{t_0}^s \lambda_6(\tau) d\tau) ds \in \text{dom} W^{-1} \right\}.$$

Proof. Define a function $z(t)$ by the right member of (9). Then, we have $z(t_0) = c$ and

$$\begin{aligned} z'(t) &= \lambda_1(t) u(t) + \lambda_2(t) w(u(t)) + \lambda_3(t) \int_{t_0}^t \lambda_4(s) u(s) ds + \lambda_5(t) \int_{t_0}^t \lambda_6(s) w(u(s)) ds \\ &\leq (\lambda_1(t) + \lambda_2(t) + \lambda_3(t) \int_{t_0}^t \lambda_4(s) ds + \lambda_5(t) \int_{t_0}^t \lambda_6(s) ds) w(z(t)), \quad t \geq t_0, \end{aligned}$$

since $z(t)$ and $w(u)$ are nondecreasing, $u \leq w(u)$, and $u(t) \leq z(t)$. Therefore, by integrating on $[t_0, t]$, the function z satisfies

$$z(t) \leq c + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) + \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) d\tau) w(z(s)) + \lambda_5(s) \int_{t_0}^s \lambda_6(\tau) d\tau w(z(s)) ds. \tag{11}$$

It follows from Lemma 2.2 that (11) yields the estimate (10). □

We prepare two corollaries from Lemma 2.6 that are used in proving the theorems.

Corollary 2.7. *Let $u, \lambda_1, \lambda_2, \lambda_3 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$ and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) w(u(s)) ds + \int_{t_0}^t \lambda_2(s) \int_{t_0}^s \lambda_3(\tau) u(\tau) d\tau ds, \quad 0 \leq t_0 \leq t.$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) \int_{t_0}^s \lambda_3(\tau) d\tau) ds \right],$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) \int_{t_0}^s \lambda_3(\tau) d\tau) ds \in \text{dom} W^{-1} \right\}.$$

Corollary 2.8. *Let $u, \lambda_1, \lambda_2, \lambda_3, \lambda_4 \in C(\mathbb{R}^+)$, $w \in C((0, \infty))$ and $w(u)$ be nondecreasing in u , $u \leq w(u)$. Suppose that for some $c > 0$,*

$$u(t) \leq c + \int_{t_0}^t \lambda_1(s) u(s) ds + \int_{t_0}^t \lambda_2(s) w(u(s)) ds + \int_{t_0}^t \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) w(u(\tau)) d\tau ds, \quad 0 \leq t_0 \leq t.$$

Then

$$u(t) \leq W^{-1} \left[W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) + \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) d\tau) ds \right],$$

where $t_0 \leq t < b_1$, W, W^{-1} are the same functions as in Lemma 2.2, and

$$b_1 = \sup \left\{ t \geq t_0 : W(c) + \int_{t_0}^t (\lambda_1(s) + \lambda_2(s) + \lambda_3(s) \int_{t_0}^s \lambda_4(\tau) d\tau) ds \in \text{dom} W^{-1} \right\}.$$

3. Main results

In this section, we investigate asymptotic property for solutions of perturbed nonlinear functional differential systems.

Theorem 3.1. *Let the solution $x = 0$ of (1) be EASV. Suppose that the perturbing term $g(t, y, Ty)$ satisfies*

$$|g(t, y(t), Ty(t))| \leq e^{-\alpha t} \left(a(t) w(|y(t)|) + |Ty(t)| \right), \tag{12}$$

and

$$|Ty(t)| \leq b(t) \int_{t_0}^t k(s) |y(s)| ds, \tag{13}$$

where $\alpha > 0$, $a, b, k, w \in C(\mathbb{R}^+)$, $a, b, k, w \in L_1(\mathbb{R}^+)$, $w(u)$ is nondecreasing in u , and $u \leq w(u)$. If

$$M(t_0) = W^{-1} \left[W(c) + \int_{t_0}^{\infty} M e^{\alpha s} \int_{t_0}^s [a(\tau) + b(\tau) \int_{t_0}^{\tau} k(r) dr] d\tau ds \right] < \infty, \quad (14)$$

where $t \geq t_0$ and $c = |y_0| M e^{\alpha t_0}$, then all solutions of (2) approach zero as $t \rightarrow \infty$.

Proof. Let $x(t) = x(t, t_0, y_0)$ and $y(t) = y(t, t_0, y_0)$ be solutions of (1) and (2), respectively. Since the solution $x = 0$ of (1) is EASV, it is EAS by remark 2.1. Using Lemma 2.1, (12), and (13), we have

$$\begin{aligned} |y(t)| &\leq |x(t)| + \int_{t_0}^t |\Phi(t, s, y(s))| \int_{t_0}^s |g(\tau, y(\tau), Ty(\tau))| d\tau ds \\ &\leq M |y_0| e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha(t-s)} \int_{t_0}^s e^{-\alpha\tau} (a(\tau)w(|y(\tau)|) \\ &\quad + b(\tau) \int_{t_0}^{\tau} k(r) e^{-\alpha r} |y(r)| dr) d\tau ds. \end{aligned}$$

Then, we obtain

$$\begin{aligned} |y(t)| &\leq M |y_0| e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha(t-s)} \int_{t_0}^s (a(\tau)w(|y(\tau)|) e^{\alpha\tau} \\ &\quad + b(\tau) \int_{t_0}^{\tau} k(r) |y(r)| e^{\alpha r} dr) d\tau ds, \end{aligned}$$

since w is nondecreasing. Set $u(t) = |y(t)| e^{\alpha t}$. By Lemma 2.3 and (14) we have

$$\begin{aligned} |y(t)| &\leq e^{-\alpha t} W^{-1} \left[W(c) + \int_{t_0}^t M e^{\alpha s} \int_{t_0}^s [a(\tau) + b(\tau) \int_{t_0}^{\tau} k(r) dr] d\tau ds \right] \\ &\leq e^{-\alpha t} M(t_0), \quad t \geq t_0, \end{aligned}$$

where $c = M |y_0| e^{\alpha t_0}$. The above estimation yields the desired result. \square

Remark 3.1. Letting $b(t) = 0$ in Theorem 3.1, we obtain the similar result as that of Theorem 3.5 in [4].

Theorem 3.2. Let the solution $x = 0$ of (1) be EASV. Suppose that the perturbing term $g(t, y, Ty)$ satisfies

$$|g(t, y(t), Ty(t))| \leq e^{-\alpha t} (a(t)|y(t)| + |Ty(t)|), \quad (15)$$

and

$$|Ty(t)| \leq b(t)w(|y(t)|) + c(t) \int_{t_0}^t k(s)w(|y(s)|) ds, \quad (16)$$

where $\alpha > 0$, $a, b, c, k, w \in C(\mathbb{R}^+)$, $a, b, c, k, w \in L_1(\mathbb{R}^+)$, $w(u)$ is nondecreasing in u , $u \leq w(u)$. If

$$M(t_0) = W^{-1} \left[W(c) + \int_{t_0}^{\infty} M e^{\alpha s} \int_{t_0}^s [a(\tau) + b(\tau) + c(\tau) \int_{t_0}^{\tau} k(r) dr] d\tau ds \right] < \infty, \quad (17)$$

where $t \geq t_0$ and $c = |y_0| M e^{\alpha t_0}$, then all solutions of (2) approach zero as $t \rightarrow \infty$.

Proof. Let $x(t) = x(t, t_0, y_0)$ and $y(t) = y(t, t_0, y_0)$ be solutions of (1) and (2), respectively. Since the solution $x = 0$ of (1) is EASV, it is EAS by Remark 2.1. Applying Lemma 2.1, (15), and (16), we have

$$\begin{aligned} |y(t)| &\leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha(t-s)} \int_{t_0}^s e^{-\alpha\tau} (a(\tau)|y(\tau)| + b(\tau)w(|y(\tau)|)) \\ &\quad + c(\tau) \int_{t_0}^{\tau} k(r)e^{-\alpha r} w(|y(r)|) dr d\tau ds. \end{aligned}$$

Since w is nondecreasing, we obtain

$$\begin{aligned} |y(t)| &\leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha(t-s)} \int_{t_0}^s (a(\tau)|y(\tau)|e^{\alpha\tau} + b(\tau)w(|y(\tau)|e^{\alpha\tau}) \\ &\quad + c(\tau) \int_{t_0}^{\tau} k(r)w(|y(r)|e^{\alpha r}) dr) d\tau ds. \end{aligned}$$

Set $u(t) = |y(t)|e^{\alpha t}$. By Corollary 2.5 and (17), we have

$$\begin{aligned} |y(t)| &\leq e^{-\alpha t} W^{-1} \left[W(c) + \int_{t_0}^t M e^{\alpha s} \int_{t_0}^s [a(\tau) + b(\tau) + c(\tau) \int_{t_0}^{\tau} k(r) dr] d\tau ds \right] \\ &\leq e^{-\alpha t} M(t_0), \quad t \geq t_0, \end{aligned}$$

where $c = M|y_0|e^{\alpha t_0}$. From the above estimation, we obtain the desired result. \square

Remark 3.2. Letting $w(u) = u$, $b(t) = c(t) = 0$ in Theorem 3.2, we obtain the similar result as that of Corollary 3.6 in [4].

Theorem 3.3. Let the solution $x = 0$ of (1) be EASV. Suppose that the perturbed term $g(t, y, Ty)$ satisfies

$$\int_{t_0}^t |g(s, y(s), Ty(s))| ds \leq e^{-\alpha t} (a(t)w(|y(t)|) + |Ty(t)|), \quad (18)$$

and

$$|Ty(t)| \leq b(t) \int_{t_0}^t k(s)|y(s)| ds, \quad (19)$$

where $\alpha > 0$, $a, b, k, w \in C(\mathbb{R}^+)$, $a, b, k, w \in L_1(\mathbb{R}^+)$ and $w(u)$ is nondecreasing in u , $u \leq w(u)$. If

$$M(t_0) = W^{-1} \left[W(c) + M \int_{t_0}^{\infty} (a(s) + b(s) \int_{t_0}^s k(\tau) d\tau) ds \right] < \infty, \quad (20)$$

where $b_1 = \infty$ and $c = M|y_0|e^{\alpha t_0}$, then all solutions of (2) approach zero as $t \rightarrow \infty$.

Proof. Let $x(t) = x(t, t_0, y_0)$ and $y(t) = y(t, t_0, y_0)$ be solutions of (1) and (2), respectively. Since the solution $x = 0$ of (1) is EASV, it is EAS. By conditions, Lemma 2.1, (18), and (19), we have

$$|y(t)| \leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha(t-s)} [e^{-\alpha s} a(s) w(|y(s)|) + e^{-\alpha s} b(s) \int_{t_0}^s k(\tau) |y(\tau)| d\tau] ds.$$

Since w is nondecreasing, we have

$$|y(t)| \leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t M e^{-\alpha t} a(s) w(|y(s)| e^{\alpha s}) ds + \int_{t_0}^t M e^{-\alpha t} b(s) \int_{t_0}^s k(\tau) |y(\tau)| e^{\alpha \tau} d\tau ds.$$

Then, it follows from Corollary 2.7 with $u(t) = |y(t)|e^{\alpha t}$ and (20) that

$$|y(t)| \leq e^{-\alpha t} W^{-1} \left[W(c) + M \int_{t_0}^t (a(s) + b(s) \int_{t_0}^s k(\tau) d\tau) ds \right] \leq e^{-\alpha t} M(t_0), \quad t \geq t_0,$$

where $c = M|y_0|e^{\alpha t_0}$. Hence, all solutions of (2) approach zero as $t \rightarrow \infty$, and so the proof is complete. \square

Remark 3.3. Letting $b(t) = 0$ in Theorem 3.3, we obtain the similar result as that of Theorem 3.7 in [4].

Theorem 3.4. Let the solution $x = 0$ of (1) be EASV. Suppose that the perturbed term $g(t, y, Ty)$ satisfies

$$\int_{t_0}^t |g(s, y(s), Ty(s))| ds \leq e^{-\alpha t} (a(t)|y(t)| + |Ty(t)|), \quad (21)$$

and

$$|Ty(t)| \leq b(t)w(|y(t)|) + c(t) \int_{t_0}^t k(s)w(|y(s)|) ds, \quad (22)$$

where $\alpha > 0$, $a, b, c, k, w \in C(\mathbb{R}^+)$, $a, b, c, k, w \in L_1(\mathbb{R}^+)$ and $w(u)$ is nondecreasing in u , $u \leq w(u)$. If

$$M(t_0) = W^{-1} \left[W(c) + M \int_{t_0}^{\infty} (a(s) + b(s) + c(s) \int_{t_0}^s k(\tau) d\tau) ds \right] < \infty, \quad (23)$$

where $b_1 = \infty$ and $c = M|y_0|e^{\alpha t_0}$, then all solutions of (2) approach zero as $t \rightarrow \infty$.

Proof. Let $x(t) = x(t, t_0, y_0)$ and $y(t) = y(t, t_0, y_0)$ be solutions of (1) and (2), respectively. Since the solution $x = 0$ of (1) is EASV, it is EAS. By means of Lemma 2.1, (21), and (22), we have

$$|y(t)| \leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t Me^{-\alpha(t-s)} [e^{-\alpha s}(a(s)|y(s)| + b(s)w(|y(s)|) + c(s) \int_{t_0}^s k(\tau)w(|y(\tau)|)d\tau)] ds.$$

Since w is nondecreasing, we have

$$|y(t)| \leq M|y_0|e^{-\alpha(t-t_0)} + \int_{t_0}^t Me^{-\alpha t}(a(s)|y(s)|e^{\alpha s} + b(s)w(|y(s)|e^{\alpha s}) + c(s) \int_{t_0}^s k(\tau)w(|y(\tau)|e^{\alpha \tau})d\tau) ds.$$

Set $u(t) = |y(t)|e^{\alpha t}$. Then, it follows from Corollary 2.8 and (23) that

$$|y(t)| \leq e^{-\alpha t} W^{-1} \left[W(c) + M \int_{t_0}^t (a(s) + b(s) + c(s) \int_{t_0}^s k(\tau) d\tau) ds \right] \leq e^{-\alpha t} M(t_0), \quad t \geq t_0,$$

where $c = M|y_0|e^{\alpha t_0}$. From the above inequality, we obtain the desired result. \square

Remark 3.4. Letting $w(u) = u$, $b(t) = c(t) = 0$ in Theorem 3.4, we obtain the similar result as that of Corollary 3.8 in [4].

Acknowledgment

The authors are very grateful for the referee's valuable comments.

REFERENCES

1. V.M. Alekseev, *An estimate for the perturbations of the solutions of ordinary differential equations*, Vestn. Mosk. Univ. Ser. I. Math. Mekh. **2** (1961), 28-36(Russian).
2. S.I. Choi and Y.H. Goo, *Lipschitz and asymptotic stability for perturbed functional differential systems*, J. Appl. Math. & Informatics **33** (2015), 219-228.
3. S.I. Choi and Y.H. Goo, *h-stability and boundedness in perturbed functional differential systems*, Far East J. Math. Sci. **97** (2015), 69-93.
4. S.I. Choi and Y.H. Goo, *Lipschitz and asymptotic stability of nonlinear systems of perturbed differential equations*, Korean J. Math. **23** (2015), 181-197.
5. S.I. Choi and Y.H. Goo, *Boundedness in perturbed nonlinear functional differential systems*, J. Chungcheong Math. Soc. **28** (2015), 217-228.
6. S.K. Choi, Y.H. Goo and N.J. Koo, *Lipschitz and exponential asymptotic stability for nonlinear functional systems*, Dynamic Systems and Applications **6** (1997), 397-410.
7. S.K. Choi, N.J. Koo and S.M. Song, *Lipschitz stability for nonlinear functional differential systems*, Far East J. Math. Sci. **5** (1999), 689-708.

8. S. Elaydi and H.R. Farran, *Exponentially asymptotically stable dynamical systems*, Appl. Anal. **25** (1987), 243-252.
9. P. Gonzalez and M. Pinto, *Stability properties of the solutions of the nonlinear functional differential systems*, J. Math. Appl. **181** (1994), 562-573.
10. Y.H. Goo, *Boundedness in the perturbed differential systems*, J. Korean Soc. Math. Educ. Ser. B: Pure Appl. Math. **20** (2013), 223-232.
11. Y.H. Goo, *Lipschitz and asymptotic stability for perturbed nonlinear differential systems*, J. Korean Soc. Math. Educ. Ser. B: Pure Appl. Math. **21** (2014), 11-21.
12. V. Lakshmikantham and S. Leela, *Differential and Integral Inequalities: Theory and Applications Vol. I*, Academic Press, New York and London, 1969.
13. B.G. Pachpatte, *A note on Gronwall-Bellman inequality*, J. Math. Anal. Appl. **44** (1973), 758-762.

Dong Man Im received the BS and Ph.D at Inha University. Since 1982 he has been at Cheongju University as a professor. His research interests focus on Algebra and differential equations.

Department of Mathematics Education Cheongju University Cheongju Chungbuk 360-764, Korea.

e-mail: dmim@cheongju.ac.kr

Yoon Hoe Goo received the BS from Cheongju University and Ph.D at Chungnam National University under the direction of Chin-Ku Chu. Since 1993 he has been at Hanseo University as a professor. His research interests focus on topological dynamical systems and differential equations.

Department of Mathematics, Hanseo University, Seosan 356-706, Korea.

e-mail: yhgoo@hanseo.ac.kr