Vibration Reduction of Forklift Truck Using Optimization of Engine Mount Layout

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), Excel(**Key Words**: Forklift Truck(), Vibration(), Engine Mount(), Layout(Program(), Optimization()

ABSTRACT

The engine excitation forces are considered as major vibration source for the forklift truck, especially in small class. Even though the current engine mounting system designs are acceptable for vibration isolation, the performance of the engine mounting system is still required for the tendency of light weight, higher power and driver's higher vibration requirement. In this paper vibration reduction technique of forklift engine which is supported on rubber mounts is presented. Based on the dynamic model of resilient engine mounting system, design evaluation program is established. The design optimization technique and evaluation method of system properties are discussed. Effects of optimal design are validated through comparison with test results.

		- Nomenclature ————		1.	
E					
	•			,	
Ι	:				
K	:				
M	:				
k	:				
m	:		,		
$\boldsymbol{\varpi}$:				
φ	:				
				가	

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(1) 2.2 (TRA, torque roll axis) (1) (2~5) 가 가

가 가 $(1)\sim(4)$, (1) (11)

(2) 가 가 가 가 가

가 가

(5) (12) 가

가

 $\left| K - \omega^2 M \right| = 0$ (1) K M

ω

2. 가 $\left| K - \omega_i^2 M \right| \varphi_i = 0$ (2) 2.1

 ω_{i} Fig. 1

2

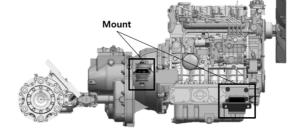


Fig. 1 A view of engine mounting layout

$$\varphi_{i}$$

$$[M] = \begin{bmatrix}
m & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & m & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & m & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & I_{x} & -I_{xy} & -I_{xz} \\
0 & 0 & 0 & -I_{xy} & I_{y} & -I_{yz} \\
0 & 0 & 0 & -I_{xz} & -I_{yz} & I_{z}
\end{bmatrix}$$

$$m$$
(3)

$$\begin{bmatrix} 0 & 0 & 0 & -I_{xz} & -I_{yz} & I_z \end{bmatrix}$$
 m

$$[K] = \begin{bmatrix} k_{11} & 0 & 0 & 0 & k_{51} & k_{61} \\ 0 & k_{22} & 0 & k_{42} & 0 & k_{62} \\ 0 & 0 & k_{33} & k_{43} & k_{53} & 0 \\ 0 & k_{42} & k_{43} & k_{44} & k_{54} & k_{64} \\ k_{51} & 0 & k_{53} & k_{54} & k_{55} & k_{65} \\ k_{61} & k_{62} & 0 & k_{64} & k_{65} & k_{66} \end{bmatrix}$$

$$E_{kj} = \frac{\sum_{l=0}^{6} (\varphi_j)_k m_{kl} (\varphi_j)_l}{\sum_{k=1}^{6} \sum_{l=1}^{6} (\varphi_j)_k m_{kl} (\varphi_j)_l}$$

$$E_{ki} \quad kj$$
(5)

가 2.3 (1)

가

가 Fig. 2 가

Fig. 3

(Excel)

(2) 가 (evolutionary)

가

가 가

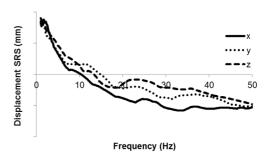


Fig. 2 Shock response spectrum

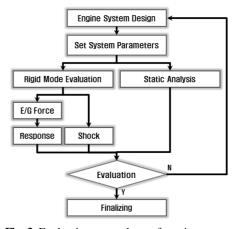


Fig. 3 Evaluation procedure of engine mount

가 0.000001, 0.075, 2000, 18.8 Hz 가 0 21 Hz (2) 가 가 가 가 . Figs. 5, 6 가 가 3 (3) 3. . Fig. 7 가 3.1 68 % (1) 3 가 2 가 가 Moment of Inertia 가 ■ Initial ■ Final 가 200 rpm 가 Fig. 4 lxy lxx lyy lzz lyz lzx 가 가 600 rpm 가 Fig. 5 Evaluation of system properties 0.9 0.8 0.7 0.6 Vibration (mm/s) 6.0 (Hz) 0.3 0.2 0.1 0 600 800 1000 1200 1400 Before Engine Speed (rpm)

Fig. 4 Engine vibration

Fig. 6 Calculation error

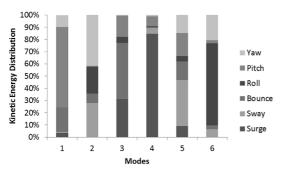


Fig. 7 Modal energy distribution of initial condition

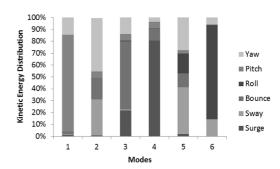


Fig. 9 Modal energy distribution of final condition

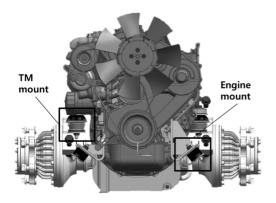


Fig. 8 Mount layout

Nitial Final

Fig. 10 Optimization result

3.2
(1)
Fig. 8
アナ
TM
アナ
・

, 가 . 가

가 . TM .

· · 가 Fig. 9
7 79 %

(2) Fig. 10 30 %

4.

가

가 가 가 가 가 . 3 30 %

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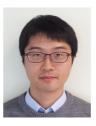
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