

# Implementation of Single-Wire Communication Protocol for 3D IC Thermal Management Systems using a Thin Film Thermoelectric Cooler

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**Abstract**—We propose and implement a single-wire communication protocol for thermal management systems using thin film thermoelectric modules for 3D IC cooling. The proposed single-wire communication protocol connects the temperature sensors, located near hot spots, to measure the local temperature of the chip. A unique ID number identifying the location of each hot spot is assigned to each temperature sensor. The prototype chip was fabricated by a 0.13 μm CMOS MPW process, and the operation of the chip is verified.

**Index Terms**—3D IC cooling, thermoelectric cooler, single wire, communication, protocol, hot spot

## I. INTRODUCTION

3D integration technology has recently been proposed to solve the limitations of delay, bandwidth, and power consumption in interconnects of integrated circuits (ICs) [1-4]. The area of the chips can be reduced by stacking in the z-direction and shortening the total wire length as a mix of vertical and horizontal wires is used [1, 4]. In contrast, heat generation problems are exacerbated [5].

Heat generation in chips is an important issue for systems where such differences can easily cause mismatches between signal levels and bias currents, and

thus degrade the performance of the analog circuit and also reduce the noise margins [5].

The size/scale of semiconductor devices has increased rapidly over time, leading to a similar increase in the total consumed power. The total power dissipation was reduced without sacrifices of overall system performance by architecture innovation of multi-core system and supply voltage diet, during the period (a) in Fig. 1. However, power consumption has been growing again due to the increased number of cores on a chip while clock speed and power density have remained almost constant. The performance and power trend at period (b) shows that heat generation problem is more getting worse even though innovation of system architecture and supply voltage reduction. Total power and average power densities of chips are critical, but hot spots where the area is only about  $100 \times 100 \mu\text{m}^2$  and the local power

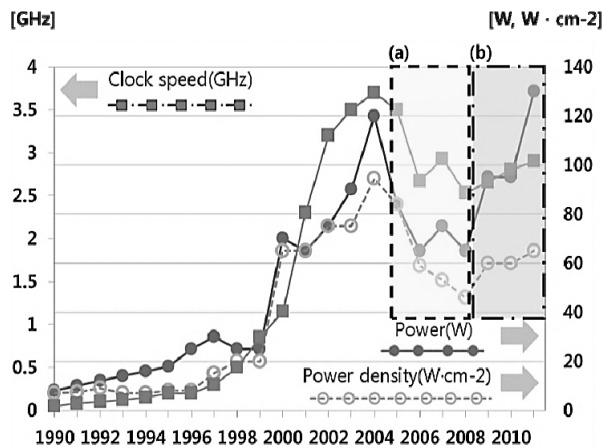


Fig. 1. Performance and power trends in the microelectronics [6, 7].

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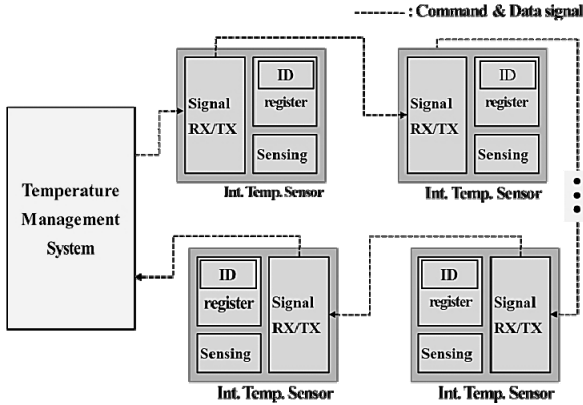


Fig. 4. The flow of single-wire communication.

Table 1. Single-wire communication command protocol

Header + Command	ID	Data	Example (ID = 001)
2bit + 1bit (1XX or 0XX)	N-bit	8-bit	Commands, ID, data (1XX 001 01000110)

block, the sensing command is terminated. In the case of a “Read” command (0XX 000 00000000), the first sensor block sends the stored data and command code (0XX 001 01000110) to the next sensor block. The new data (0XX 000 00000000) is then stored in the register. If the TMS receives the original read command (0XX 000 00000000), the command is terminated on N-th read cycle.

### III. EXPERIMENTAL RESULTS

Fig. 5 shows the setup for the measurement. The evaluation board was configured to an alternative environment because the 3D IC structure cooling system is actually difficult to implement. The evaluation board

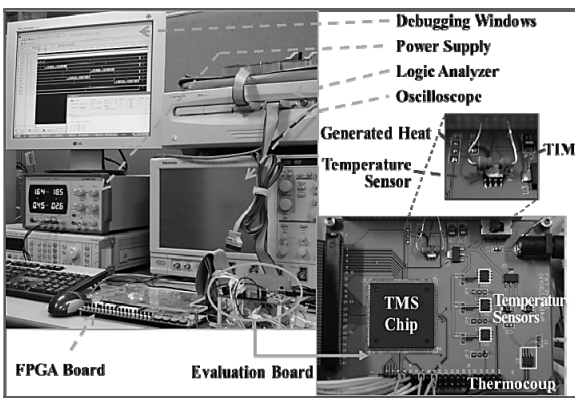


Fig. 5. Setup for the measurement.

consists of a TMS chip, 4 temperature sensors, and a thermocouple temperature sensor (external sensor). The unique ID of each internal temperature sensor is 000, 010, 011, and 111, respectively.

The TMS chip was designed and fabricated by using a Samsung’s 0.13 μm CMOS process. The chip consists of four internal sensor blocks, and each block is connected by a single wire. The connected temperature sensor on the chip is substituted “sensing” component. The chip area is 4.0 mm × 4.0 mm, but the core area of the chip is about 0.3 mm × 0.3 mm. The operating frequency is 1 MHz.

Fig. 6 shows the block diagram of internal temperature sensor used in the experiment. An accurate current reference using temperature and process compensation current mirror (TPC-CM) is used [14]. The temperature independent reference current is generated by summing PTAT (proportional to absolute temperature) current and CTAT (complementary to absolute temperature) current. The temperature coefficient and magnitude of the reference current are influenced by the process variation. To calibrate the process variation, the proposed TPC-CM uses two binary weighted current mirrors which control the temperature coefficient and magnitude of the reference current. After the PTAT and CTAT currents are measured, the switch codes of the TPC-CM are fixed in order that the magnitude of reference current is independent to temperature. The area of the internal temperature sensor is 0.72 mm × 0.08 mm [14].

The input/output chip signals were measured by a logic analyzer and temperature data from the fabricated TMS were displayed on the PC monitor. We placed a heating resistor below a temperature sensor having ID of 001) to make a hot spot.

The temperature sensor has a range of −55 to +125°C with a resolution of ±0.5°C. As a response of a starting

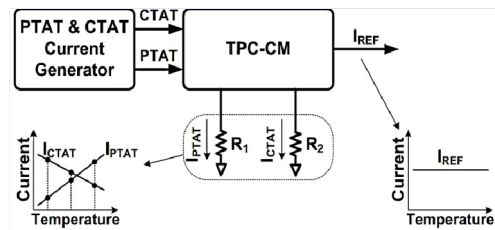


Fig. 6. The block diagram of internal temperature sensor of the chip [14].

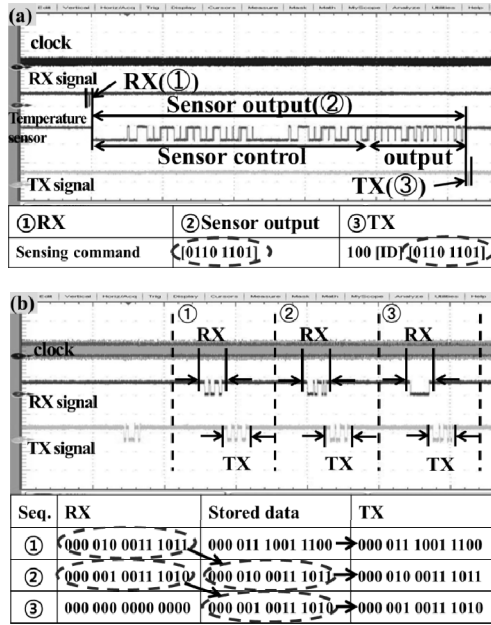


Fig. 7. Measured waveforms for (a) “Sensing,” and (b) “Read” commands.

signal from the TMS, the sensor in the fabricated evaluation board measures the hot spot temperature and store it to the internal register.

We checked the proper operation of “Read” and “Sensing” commands. Fig. 7 shows the measured waveforms when we apply “Sensing” and “Read” command to the chain of sensor block in the fabricated evaluation board. Fig. 7(a) shows waveform of internal temperature sensor having ID of (100), when the RX part of the sensor receives “Sensing” command. The sensor measures the temperature of the hot spot, then, the measured data(0110 1101) is stored in the internal register with sensor ID(100) and command code(100). The TX part of the sensor block sends stored data (100 100 0110 1101) to next sensor block.

Fig. 7(b) shows the waveform of internal temperature sensor(ID : 011), when the RX part of the sensor receives “Read” command. In the cycle ①, the stored data(000 011 1001 1100) is transmitted to next block, and the incoming data(000 010 0011 1011) is stored in the register. In the next cycle ②, RX receives “Read” command(000 001 0011 1010), the stored data (000 010 0011 1011) is immediately transmitted to next block, and incoming data(000 001 0011 1010) is stored in a register.

Fig. 8 shows measured temperature data displayed on

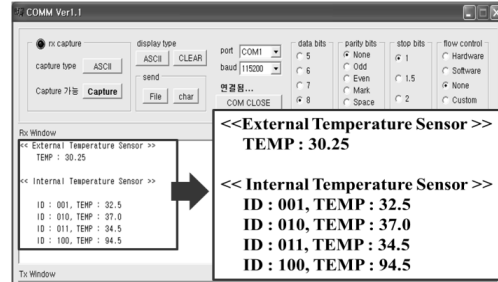


Fig. 8. Measured temperature data displayed on the PC monitor.

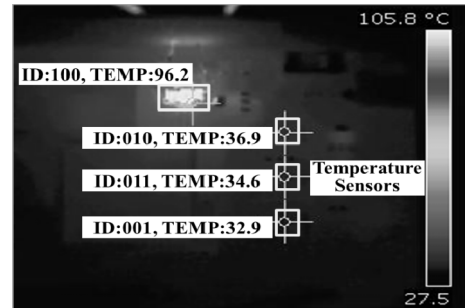


Fig. 9. Infrared image of the evaluation board when the resistor is powered.

the PC monitor, and Fig. 9 shows an infrared image of the evaluation board when hot spot of ID 100 is heated. As we can see, there is good agreement between the two data sets.

#### IV. CONCLUSIONS

We have proposed and implemented a single-wire communication protocol for TMS with a thin film thermoelectric module for 3D IC cooling. The chip was designed and fabricated by using a Samsung 0.13 μm CMOS process. The test board was fabricated using the chip, and the operation of the chip was verified.

The proposed single-wire communication protocol is designed to measure the temperature during operation of the circuit. The internal sensor interface, connected by a single wire, measures the temperature at all hot spots. The TEC is cooled by the measured temperature.

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