

이변량 가우시안 Q -함수의 Craig 표현에 대한 기하학적인 유도

정희원 박 승 근*, 종신회원 이 일 규**

A Geometric Derivation of the Craig Representation for the Two-Dimensional Gaussian Q -Function

Seungkeun Park* *Regular Member*, Il-kyoo Lee**^o *Lifelong Member*

요 약

본 논문에서는 기하학적인 관점으로 이변량 가우시안 Q -함수의 Craig 표현에 대한 새롭게 간단한 유도를 제시하고 있다. 또한, 이러한 기하학적인 유도는 이변량 가우시안 Q -함수의 또 다른 Craig 표현 식을 제시하고 있다. 새롭게 유도된 이변량 가우시안 Q -함수의 Craig 식은 2개의 상관 가우시안 잡음에서 직교좌표의 변환으로 생성되는 2개 웨지 영역의 기하학으로부터 새롭게 구한 것이다. 제시된 Craig 형태는 이변량 가우시안 Q -함수로 표현되는 확률을 계산하는데, 중요한 역할을 할 수 있다.

Key Words: Geometric Derivation, Two-dimension, Craig, Gaussian Q -function, Cartesian

ABSTRACT

In this paper, we present a new and simple derivation of the Craig representation for the two-dimensional (2-D) Gaussian Q -function in the viewpoint of geometry. The geometric derivation also leads to an alternative Craig form for the 2-D Gaussian Q -function. The derived Craig form is newly obtained from the geometry of two wedge-shaped regions generated by the rotation of Cartesian coordinates over two correlated Gaussian noises. The presented Craig form can play a important role in computing the probability represented by the 2-D Gaussian Q -function.

I. Introduction

It is very important to evaluate error probability performance in designing wireless communication systems. The Craig representation has played a key role when evaluating the error probability performance of digital modulation systems over fading channels by using the moment-generating function(MGF) approach^[1-3]. Several derivations of

the Craig form for the one-dimensional(1-D) Gaussian Q -function were recently reported^[4-5]. The Craig form for the 2-D Gaussian Q -function applied to compute the error probability of M -ary phase shift keying system over various fading channels^[6-7]. The approximation for the 2-D Gaussian Q -function was presented in terms of the 1-D Gaussian Q -function^[8]. The algebraic derivation of the Craig form for the 2-D Gaussian Q -function was presented

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* 한국전자통신연구원 전자과환경연구팀 (seungpk@etri.re.kr), ** 공주대학교 전기전자제어공학부(leeik@kongju.ac.kr), (°: 교신저자) 논문번호 : KICS2010-11-541, 접수일자 : 2010년 11월 12일, 최종논문접수일자 : 2011년 2월 8일

in terms of the change of variables^[9]. However, it is said that there may exist a simple and new derivation of the Craig form.

It is well-known that the geometric derivation is easy to understand. Thus, in this paper, we will present a geometric derivation of the Craig representation by using the rotation of Cartesian coordinates. We hope that the presented derivation is easy and simple to understand the Craig form for the 2-D Gaussian Q-function.

II. Problem

Our starting point is the analytical expression of a double integral for the 2-D Gaussian Q-function in the following:

$$Q(x, y; \rho) = \int_x^\infty \int_y^\infty \frac{\exp\left[-\frac{u^2 - 2\rho uv + v^2}{2(1-\rho^2)}\right]}{2\pi\sqrt{1-\rho^2}} du dv \quad (1)$$

where ρ represents the correlation coefficient. Chronologically, Simon first derived the Craig form of the 2-D Gaussian Q-function by using the clever change of variables^[9]:

$$\theta = \tan^{-1}\left(\frac{\tan\Phi \pm \rho}{\sqrt{1-\rho^2}}\right). \quad (2)$$

It is also known that the Craig representation of the 2-D Gaussian Q-function developed by Simon is given by^[9, eq. (10)]

$$Q(x, y; \rho) = \frac{1}{2\pi} \int_0^{\tan^{-1}[(\sqrt{1-\rho^2}x/y)/(1-\rho y/x)]} \exp\left(-\frac{x^2}{2\sin^2\theta}\right) d\theta + \frac{1}{2\pi} \int_0^{\tan^{-1}[(\sqrt{1-\rho^2}y/x)/(1-\rho x/y)]} \exp\left(-\frac{y^2}{2\sin^2\theta}\right) d\theta; \quad (3) \\ x \geq 0, y \geq 0.$$

where

$$\tan^{-1}\left(\frac{x}{y}\right) = \frac{\pi}{2} [1 - \text{sgn}(y)] + \text{sgn}(y) \tan^{-1}\left(\frac{x}{|y|}\right)$$

in which $\text{sgn}(u) = 1$ if $u \geq 0$ and $\text{sgn}(u) = -1$ if $u < 0$. The generic Craig form for the 2-D Gaussian Q-function provided in^[10] was derived from the

upper limit of (3) and the properties of the 2-D Gaussian Q-function given in^[11, eq. (26.3.8) and (26.3.9)]. So far, however, geometric interpretations on the change of variables (1) have not been reported in detail.

It is said that the geometric solution of a problem is easy and simple. Thus, in this letter, motivated by unknown geometric derivation of the Craig form for the 2-D Gaussian Q-function, we present a new derivation for the Craig form on the basis of the geometry of two wedge-shaped regions. The regions are generated by the rotation of Cartesian coordinates.

III. Geometric Derivation of the Craig form for the 2-D Gaussian Q-Function

We consider X and Y to be two-dimensional Gaussian random variables (RV) with two zero means, $\mu_X = \mu_Y = 0$, two unit variances, $\sigma_X^2 = \sigma_Y^2 = 1$ and a correlation coefficient, ρ_{XY} . Figure 1 shows a graphical representation of the open region, $\Omega = \{(x, y) | X \geq x^*, Y \geq y^*\}$, determined by two constants $x^*, y^* \geq 0$.

Here, as illustrated in Figure 1, we rotate the Cartesian coordinates counterclockwise through the angle $\psi = \tan^{-1}(y^*/x^*)$ about the origin in a way that

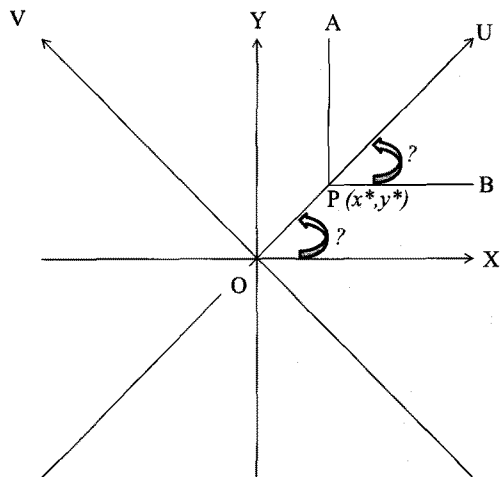


그림 1. 직교좌표 회전으로 인해 생성된 2개의 웨지영역에 대한 기하적인 해석
Fig. 1. The geometric interpretation on two wedge-shaped regions generated by the rotation of Cartesian coordinates.

$$\begin{bmatrix} U \\ V \end{bmatrix} = \begin{bmatrix} \cos\psi & \sin\psi \\ -\sin\psi & \cos\psi \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix}. \quad (4)$$

In terms of U - V Cartesian coordinates, the open region, $\Omega = \{(x, y) | X \geq x^*, Y \geq y^*\}$, can be divided into two wedge-shaped regions, $\sphericalangle APU$ and $\sphericalangle BPU$. The probability of the wedge-shaped region, $\Pr\{\sphericalangle APU\}$, is obtained by using (4) and the theory of linear combination of Gaussian RVs as

$$\begin{aligned} \Pr\{\sphericalangle APU\} &= \Pr\{X \geq x^*, V \geq 0\} \\ &= Q(x^*, 0; \rho_{XV}) \end{aligned} \quad (5)$$

where

$$\rho_{XV} = \frac{-\sin\psi + \rho_{XY}\cos\psi}{\sqrt{1 - \rho_{XY}\sin 2\psi}}. \quad (6)$$

Similarly, the probability $\Pr\{\sphericalangle BPU\}$ is obtained as

$$\begin{aligned} \Pr\{\sphericalangle BPU\} &= \Pr\{Y \geq y^*, V < 0\} \\ &= \int_{y^*}^{\infty} \int_{-\infty}^0 \frac{\exp\left[-\frac{y^2 - 2\rho_{YV}yv + v^2}{2(1 - \rho_{YV}^2)}\right]}{2\pi\sqrt{1 - \rho_{YV}^2}} dv dy \end{aligned} \quad (7)$$

where

$$\rho_{YV} = \frac{\cos\psi - \rho_{XY}\sin\psi}{\sqrt{1 - \rho_{XY}\sin 2\psi}}. \quad (8)$$

Employing ^[11, eq.(26.3.6)] to (7) gives

$$\Pr\{\sphericalangle BPU\} = Q(y^*, 0; -\rho_{YV}). \quad (9)$$

Next, applying ^[12, eq. (A.5)] to (5) and (9), respectively, and using the trigonometric identity for $\sin^{-1}\phi + \cos^{-1}\phi = \pi/2$ yield the result in the Craig form as

$$\begin{aligned} Q(x^*, y^*; \rho) &= \frac{1}{2\pi} \int_0^{\frac{\pi}{2} + \sin^{-1}\rho_{XV}} \exp\left(-\frac{x^{*2}}{2\sin^2\theta}\right) d\theta \\ &+ \frac{1}{2\pi} \int_0^{\cos^{-1}\rho_{YV}} \exp\left(-\frac{y^{*2}}{2\sin^2\theta}\right) d\theta; \end{aligned} \quad (10)$$

$$x^* \geq 0, y^* \geq 0.$$

Finally, letting $x^* = x$ and $y^* = y$ and substituting $\cos\psi = x/\sqrt{x^2 + y^2}$ and $\sin\psi = y/\sqrt{x^2 + y^2}$ into (10)

result in an alternative expression for the Craig form presented in (3) as

$$\begin{aligned} Q(x, y; \rho) &= \frac{1}{2\pi} \int_0^{\frac{\pi}{2} + \sin^{-1}\left(\frac{x-y}{\sqrt{x^2 - 2\rho xy + y^2}}\right)} \exp\left(-\frac{x^2}{2\sin^2\theta}\right) d\theta \\ &+ \frac{1}{2\pi} \int_0^{\cos^{-1}\left(\frac{x-y}{\sqrt{x^2 - 2\rho xy + y^2}}\right)} \exp\left(-\frac{y^2}{2\sin^2\theta}\right) d\theta; \end{aligned} \quad (11)$$

$$x \geq 0, y \geq 0.$$

Note that the alternative expression of (11) do not require the user-defined arc tan function such as the upper limit of (3).

IV. Conclusion

The main contribution of this paper is the geometric derivation of the Craig form for the 2-D Gaussian Q -function by using the rotation of Cartesian coordinates. The new derivation leads to the alternative Craig representation of the 2-D Gaussian Q -function with geometric interpretation. The derived expression can be applicable to the exact computation of the probability represented by the 2-D Gaussian Q -function.

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박 승 근 (Seungkeun Park)

정회원



1991년 2월 고려대학교 응용통계학과(이학 학사)
 1993년 8월 고려대학교 응용통계학과(이학석사)
 2004년 2월 충북대학교 정보통신공학과(공학박사)
 1993년 8월~현재 한국전자통신연구원 전파환경연구팀 책임연구원

<관심분야> 통신이론, 디지털 통신, 전자파간섭, 스펙트럼공학

이 일 규 (Il-kyoo Lee)

중신회원



1994년 2월 충남대학교 전자공학과(공학석사)
 2003년 2월 충남대학교 전자공학과(공학박사)
 1994년 2월~2004년 12월 한국전자통신연구원 선임연구원

2004년 3월~현재 공주대학교 전기전자제어공학부 부교수

<관심분야> RF 시스템, 초고주파회로 설계, 전자파간섭, 스펙트럼공학