The Visualization of the Flow Field through Ship's Propulsion Mechanism of Weis-Fogh Type using the PIV

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Abstract: The Flow fields of a ship's propulsion mechanism of Weis-Fogh type were investigated by the PIV. Velocity vectors and velocity profiles around the operating and stationary wings were observed at opening angles of $\alpha=15^{\circ}$ and 30° , velocity ratios of Re= $0.52 \times 10^{4} - 1.0 \times 10^{4}$. V/U=0.5~1.5 and Reynolds number of As the results the fluid between wing and wall was inhaled in the opening stage and was jet in the closing stage. The wing in the translating stage accelerated the fluid in the channel. And the flow fields of this propulsion mechanism were unsteady and complex, but those were clarified by flow visualization using the PIV.

Key words : Fluid machinery, Propulsion mechanism, Flow visualization, PIV, Unsteady flow

1. Introduction

The Weis-Fogh mechanism, discovered through the analysis of wing motion in the hovering flight of a small bee called Encarsia Formosa, is а novel and very efficient mechanism for lift generation^{[1],[2]}.

Figure 1 shows the principles of the motions. Here, the bee is able to remain hovering flight by moving its wings in a horizontal plane while holding the body upright. First. the wings clap from the side of the dorsal body revolving around their leading edge. Then, they open their

wings from the state where the trailing edges are touching each other(fling), move in the horizontal plane while maintaining angle(we fixed open define the fixed а open angle as 1/2 of the angle formed by intersection of two wings in the second one of Fig. 1). The wings change their moving direction and the opening angle on the ventral side(flap) and then move back to the horizontal plane and clap touching their leading edges again. These motions are repeated. The lower picture of Fig. 1 2-dimensional model of this shows а movement. Generally, wings in а still state need some distance in order to gain

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Fig. 1 Hovering flight of Encarsia formosa

wing sufficient circulation around the for (Wargner effect). generating lift This is the case in airplane wings. However, in of this mechanism, pair opposite а circulations around wings is generated at the moment when the two wings opening touching their trailing edge. This enables the wings to gain sufficient lift in spite of Tsutahara^{[3],[4]} short stroke. presented the model, propulsion which used а two-dimensional model of the Weis-Fogh mechanism in the water channel, and showed propulsive device that this effectively conducting operates very by experiments the dynamic on characteristics, and а working test on a model ship propulsion the new ship as Ro^{[5],[6]} system. simulated the unsteady flow fields by applying the vortex method on the circumference of the wing while the propulsive mechanism was being operated, and also verified the pressure around the wing and the time variation of the thrust and the drag on the wing.

But in calculation the limitation ;opening angle α=30°, velocity ratio V/U=1.0 kept from the investigation of various flow field, And for the practical propulsion use of this mechanism, it is necessary to clarify the flow field. Hence this experiment would contribute to the the propulsion mechanism practical use of

as clear visualization of flow field with parameters.

2. Experiment device and method

2.1 Model of the propulsion mechanism

Figure 2 shows the model of a Weis-Fogh type ship propulsion mechanism.

Perpendicularly, the figure shows the upper part of the model, and, as a wing in channel oscillates the water in а reciprocal operation, the propulsive power left (the direction rises to the towards which the ship is progressing). This model Tsutahara is identical to the et al. model^[3], and so a brief synopsis of it will be sufficient.

A wing is installed in a square channel. When the point p corresponding to the center axis of the wing is oscillated back



Fig. 2 A model of propulsion mechanism

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and forth along the y-axis, the wing first opens at point p from the lower surface (opening stage). Then, maintaining an open angle a, the wing moves translationally in a parallel movement (translating stage), and finally rotates and closes on the upper surface (closing stage) through the reciprocal motion of point p. It then executes an opening stage at the upper surface once more, moves translationally once again, and repeats the closing stage at the lower surface.

Originally, in the Weis-Fogh mechanism 1, circulation shown in Fig. in the as direction formed opposite is at each position of wing, as a pair of flat-plate wings open while their trailing edges touch. However, through the principle of a mirror image, when channel walls are placed and the same motions as above are executed by a single wing, shown as in the propulsion model of Fig. 2, the identical effects can be achieved with а pair of wings.

2.2 Driving system of the wing

Figure 3 shows the schematic diagram of the driving system of the wing.





explained propulsion mechanism model, and it was made as following for easy visualization experiment.

The wings were taken the shape of NACA0010 with transparent acrylic panel. a chord length of 80mm, which has span 100mm and thickness of 10mm. The of wing has a hole located at a point 0.75 away from trailing edge to link the axis.

Water channel is 200mm in width, 700mm in length, and 250mm in height the entrance of water channel has a guide vane for smooth flow.

The side board of water channel was made of transparent acrylic panel for good board. permeation of light. The bottom which didn't have to be permeated with light was painted black. Some parts of the driving system were installed under the bottom board.

Meanwhile, in the method of driving of a wing, as shown in picture, power of motor spins the chain through belt, pulley, worm gear and sprocket.

The reciprocating motion of the slider where the axis of wing is attached was done with a pin that is fixed on the upper part of the chain.

Also, the wing is being linked to the axis of wing. therefore when the slider the reciprocating motion, does the moment would generate around the axis of to open the wing. For wing keeping а fixed opening angle, adjustable plate was attached to the upper side of the slider.

The movement velocity of the wing was controlled by voltage of direct current, and the motor's rpm was calculated by proximity sensor and pulse meter.

2.3 Visualization experiment by PIV

Figure 4 shows the schematic structure of experimental device by the PIV.



Fig. 4 Schematic structure of experimental device

this experiment, driving system of a In shown as Fig. 3 was wing installed in water channel of circulating water tank flowing uniform flow. enabled clear visualization.

In detail, after installing the driving system of a wing in the water channel, sheet light made of CW laser was thrown on vertical and horizontal direction with uniform flow outside circulating water field was taken tank, and a picture by high-speed camera in a vertical direction with the upper side of wing.

PVC А spherical shape with 100 μm average diameter and 1.02 specific gravity was used as chasing particle. High speed camera's model is PHOTRON's FASTCAM 1280 PCI, **JENOPTIK's** laser is Ienlas D2.8. table shows and 1 the main specification of PIV system. The experiment conditions fixed were that the opening angle of a wing a=15° and 30° with the Reynolds number Re= $0.52 \times 10^4 \sim$ 1.0×10^4 , and the ratio of wing speed(V) to uniform flow(U) of V/U=0.5~1.5.

Table 1 Main specification of PIV system

Item	Specification
Image board	Fast Cam-X panel link board drive
Light source	8W continuos wave laser
Sheet light	Cylindrical lens: Ø3.8×11.4mm
Resolution	1280×1024pixel
Software	CACTUS 3.2
Error vector(%)	Average: about 0.1%

3. Results and discussions

Figure 5 shows the continuous flow (NACA0010) pattern the wing around during for Re=7.000. one stroke the Reynolds number defined Re as by the wing chord and uniform flow.

In Fig. 5, (a) refers to the velocity vectors and (b) represents the velocity profiles under the same conditions as in Fig. 5 (a). In Fig. 5. 1 represents the 2opening stage; to 4. the translating stage; and 5, the closing stage.

First, as seeing the velocity vector, the velocity vector around the wing turn towards the direction of movement of the wing in all process, showing that experiment matches the results of simulation.

Seeing the velocity profile, flow pattern of the upper stream side and downstream has similar side of wing shape in all process, but velocity profile length the of downstream side of wing is longer than that of the upper stream side of wing.

These show that as the wing moves, it accelerates the fluid the movement in water channel. which indicates that the propulsion mechanism functions effectively as a pump.



Fig. 5 Flow pattern for one stroke of the wing (H=2.5C, rp=0.75C, V/U=1.0, α =30°)

Also. during the process of opening between the wing and the wall, fluid was inhaled. and when closing, fluid was jet. This will be considered specifically in Fig. 7 and Fig. 10 where it was photographed in a close-up.

Figure 6 shows the flow pattern around the stopped wing in same condition of Fig. 5.

In comparing with the pictures 1,3,5 in Fig. 5 and the pictures 1,3,5 in Fig. 6, when the wing moves, it accelerates fluid in the channel while the wing stops, it simply moves as a resistance. It is clearly especially 6(b) showing in the Fig. velocity profile of the wing's wake.

Figure 7 shows a velocity profile of changing the opening angle a and a ratio of velocity V/U photographed up close in



Fig. 7 Velocity profile around wing with α and V/U at the opening stage

a process of opening. Fig. 7(a) is the velocity profile with fixed ratio of velocity V/U=1.0 and the opening angle of α =7°, 15°, 23°.

As indicated from the figure, fluid between wing and wall is inhaled in a

velocity of opening, and flow of process fluid accelerates as the opening angle increases. Fig. 7(b)is the velocity profile opening angle of a=23° with the of the of V/U=0.5, ratio of velocity 1.0, 1.5. As indicated from figure, the larger the the ratio velocity. the larger flow velocity of between wing and wall the opening at stage.

Figure 8 shows flow pattern of the α=15° a=30° opening angle of and photographed in a close-up when the wing came at the center of water channel during a translating stage.



Fig. 8 Velocity vector and velocity profile around wing with α at the translating stage (V/U=1.0)

Comparing the velocity vector, in case α=15° of the opening angle of velocity vector around the wing turns towards to the direction of wing movement more than in case of the opening angle of $\alpha=30^{\circ}$ The scale is also larger. Seeing velocity profile, in case of the opening angle of a =15° velocity profile accelerated more of of the pressured side to the uniform fluid flow than in case of the opening angle of a =30°.

Examining the boundary laver around wing to uniform flow the pressured side of α=15°, velocity in profile, in case of

differently in case of α =30°, it shows that the flow separated in the vicinity of the leading edge reattached in the vicinity of middle of the wing.

Figure 9 shows flow pattern with the ratio of velocity V/U in the case of opening angle of $\alpha=30^{\circ}$ in condition same as Fig. 8.



Fig. 9 Velocity vector and velocity profile around wing with V/U at the translating stage $(\alpha=30^{\circ})$

Seeing velocity vector, it indicates the fluid around the wing has the same direction with the movement of the wing, larger the ratio of velocity. and the the faster the movement velocity of fluid is.

Seeing velocity profile, when the wing moves in а translating it shows stage, accelerating fluid of the pressured side to uniform flow, the larger the ratio of velocity, the more accelerating fluid is.

10 shows Figure the velocity profile with closing angle a and ratio of velocity V/U photographed up close in the closing stage. Fig. 10(a) is velocity profile of the 15°, 7° with closing angle of α=23°, the fixed ratio of velocity of V/U=1.0. As



Fig. 10 Velocity profile around wing with a and V/U at the closing stage

indicated from the figure, fluid which wall locates between wing and is spouted in closing stage, and effusion velocity of fluid increases when the closing angle Fig. 10(b) is velocity profile at decreases. closing angle of a=15° with the ratio the V/U=0.5, of velocity of 1.0, 1.5. As from the figure, indicated the larger the velocity, the larger jet ratio of between the wing and the wall is in the closing This happens because the stage. larger the ratio of velocity, the faster the closing of а wing. Especially in the case of V/U=1.5. the flow is separated in the vicinity of leading edge of the pressured side because of high wing speed.

4. Conclusion

The Flow fields of a ship's propulsion mechanism of Weis-Fogh type were investigated bv the PIV. Velocity vectors around and velocity profiles the operating

stationary wings were observed at and angles of a=15° and 30°, velocity opening V/U=0.5~1.5 ratios of and Reynolds Re= $0.52 \times 10^{4} \times 1.0 \times 10^{4}$. number of The Flow fields considered about were each experiment parameter with opening. translating and closing And the stages. results are summarized as following:

(1) When the wing operates. it accelerates the fluid in water channel. But when the wing stops, it acts as а resistance.

(2) Fluid between wing and wall is inhaled in the opening the stage, and suction velocity of fluid increases the as opening angle and the velocity ratio increase.

(3) Fluid around the wing moves in the same direction as the movement wing of the translating stage, the movement in velocity of fluid increases as the opening angle is small and the velocity ratio is large.

(4) Fluid of pressured side to uniform flow is accelerating in the translating the scale increases as the opening stage, the velocity ratio is angle is small and large.

(5) Fluid between wing and wall is jet in the closing stage, and the jet velocity of fluid increases as the closing angle is small and the velocity ratio is large.

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