

ANOTHER METHOD FOR A KUMMER-TYPE TRANSFORMATION FOR A ${}_2F_2$ HYPERGEOMETRIC FUNCTION

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ABSTRACT. Very recently, by employing an addition theorem for the confluent hypergeometric function, Paris has obtained a Kummer-type transformation for a ${}_2F_2(x)$ hypergeometric function with general parameters in the form of a sum of ${}_2F_2(-x)$ functions. The aim of this note is to derive his result without using the addition theorem.

1. Introduction and results required

We start with a Kummer-type transformation for a ${}_2F_2(x)$ hypergeometric function with general parameters in the form of a sum of ${}_2F_2(-x)$ functions due to Paris [1, Eq.(3)]:

$$(1.1) \quad {}_2F_2 \left(\begin{matrix} a, & d \\ b, & c \end{matrix} \middle| x \right) = e^x \sum_{n=0}^{\infty} \frac{(c-d)_n}{(c)_n n!} (-x)^n {}_2F_2 \left(\begin{matrix} b-a, & d \\ b, & c+n \end{matrix} \middle| -x \right),$$

where $(a)_n = \Gamma(a+n)/\Gamma(a)$ ($n = 0, 1, 2, \dots$) is the Pochhammer symbol. Paris [1] also considered several interesting special cases of (1.1). This result (1.1) was established with the help of the integral representation for ${}_2F_2$ [3, Eq.(4.8.3.11)]:

$$(1.2) \quad \begin{aligned} & {}_2F_2 \left(\begin{matrix} a, & d \\ b, & c \end{matrix} \middle| x \right) \\ &= \frac{\Gamma(b)}{\Gamma(a)\Gamma(b-a)} \int_0^1 t^{a-1} (1-t)^{b-a-1} {}_1F_1(d; c; xt) dt \end{aligned}$$

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and

$$(1.3) \quad {}_2F_2 \left(\begin{matrix} a, & d \\ b, & c \end{matrix} \middle| x \right) \\ = \frac{\Gamma(b)}{\Gamma(a)\Gamma(b-a)} \int_0^1 t^{b-a-1} (1-t)^{a-1} {}_1F_1(d; c; x-xt) dt$$

provided $\Re(b) > 0$ and $\Re(a) > 0$, and the addition theorem for the confluent hypergeometric function in the form [2, Eq.(2.3.5)]:

$$(1.4) \quad {}_1F_1(d; c; x-xt) = e^x \sum_{n=0}^{\infty} \frac{(c-d)_n}{(c)_n n!} (-x)^n {}_1F_1(d; c+n; -xt).$$

Paris [1] remarked that the special case of (1.1) when $c = d$ reduces to the well-known Kummer's first theorem [3]:

$$(1.5) \quad {}_1F_1(a; b; x) = e^x {}_1F_1(b-a; b; -x).$$

Here we aim at showing that (1.1) can be derived by using (1.5) instead of (1.4).

2. Derivation of (1.1)

Start with the left-hand side of (1.1) and use (1.2), it becomes

$${}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) \\ = \frac{\Gamma(c)}{\Gamma(d)\Gamma(c-d)} \int_0^1 t^{d-1} (1-t)^{c-d-1} {}_1F_1(a; b; xt) dt,$$

which can be written as

$$(2.1) \quad {}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) \\ = \frac{\Gamma(c)}{\Gamma(d)\Gamma(c-d)} e^x \int_0^1 t^{d-1} (1-t)^{c-d-1} e^{-x} {}_1F_1(a; b; xt) dt.$$

Using (1.5) in the integrand of the integral in (2.1), we have

$$(2.2) \quad {}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) \\ = \frac{\Gamma(c)}{\Gamma(d)\Gamma(c-d)} e^x \int_0^1 t^{d-1} (1-t)^{c-d-1} e^{-x(1-t)} {}_1F_1(b-a; b; -xt) dt.$$

Now expand $e^{-x(1-t)}$ in (2.2) as the Maclaurin series, after a little simplification, we obtain

$$(2.3) \quad {}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) = \frac{\Gamma(c)}{\Gamma(d)\Gamma(c-d)} e^x \sum_{r=0}^{\infty} \frac{(-x)^r}{r!} \int_0^1 t^{d-1} (1-t)^{c-d+r-1} {}_1F_1(b-a; b; -xt) dt.$$

Substituting $1-t=u$ in (2.3) and simplifying, we get

$${}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) = \frac{\Gamma(c)}{\Gamma(d)\Gamma(c-d)} e^x \sum_{r=0}^{\infty} \frac{(-x)^r}{r!} \int_0^1 u^{c-d+r-1} (1-u)^{d-1} {}_1F_1(b-a; b; -x(1-u)) du.$$

Finally, applying (1.3) to the integral part in the last identity, we have

$${}_2F_2 \left(\begin{matrix} d, & a \\ c, & b \end{matrix} \middle| x \right) = e^x \sum_{r=0}^{\infty} \frac{(-x)^r}{r!} \frac{(c-d)_r}{(c)_r} {}_2F_2 \left(\begin{matrix} b-a, & d \\ b, & c+r \end{matrix} \middle| -x \right).$$

This completes the proof of (1.1).

References

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