

ON THE SPECIAL FINSLER METRIC

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ABSTRACT. Given a Riemannian manifold (M, α) with an almost Hermitian structure f and a non-vanishing covariant vector field b , consider the generalized Randers metric $L = \alpha + \beta$, where β is a special singular Riemannian metric defined by b and f . This metric L is called an (a, b, f) -metric. We compute the inverse and the determinant of the fundamental tensor (g_{ij}) of an (a, b, f) -metric. Then we determine the maximal domain \mathcal{D} of $TM \setminus O$ for an (a, b, f) -manifold where a y -local Finsler structure L is defined. And then we show that any (a, b, f) -manifold is quasi-C-reducible and find a condition under which an (a, b, f) -manifold is C-reducible.

1. Introduction

Let M be a smooth $2m$ -dimensional manifold. We will consider a Finsler metric $L = \alpha + \beta$, where α is a Riemannian metric on M and β is a singular Riemannian metric on M . We call such a Finsler metric a generalized Randers metric. In case where β is a 1-form on M , L is a usual Randers metric.

We denote a point of M by $x = (x^i)$ and a tangent vector at that point x by $y = (y^i)$. Let $\alpha(x, y) = (a_{ij}(x)y^i y^j)^{1/2}$ be a Riemannian metric on M . Given an almost Hermitian structure $f_j^i(x)$ of (M, α) and a non-vanishing covariant vector field $b_i(x)$ on M , we have a singular Riemannian metric $\beta(x, y) = (b_{ij}(x)y^i y^j)^{1/2}$, where $b_{ij} = b_i b_j + f_i f_j$ and $f_i = b_r f_r^i$. Such $L = \alpha + \beta$ is an interesting example of a generalized Randers metric, which we call an (a, b, f) -metric. For the further study about (a, b, f) -metrics, we refer to [3] and [4].

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Note that a manifold with an (a, b, f) -metric becomes a Rizza manifold. A Rizza manifold (M, L, f) is by definition a Finsler manifold (M, L) with an almost complex structure $f_j^i(x)$ satisfying the condition

$$L(x, \phi_\theta(y)) = L(x, y),$$

where $\phi_\theta^i_j = \cos \theta \cdot \delta_j^i + \sin \theta \cdot f_j^i$. But an (a, b, f) -metric is not a y -global Finsler metric. And so we have to restrict a domain in the tangent bundle $T(M)$ over M , say, $\{y : \beta(y) \neq 0\}$. In section 4, we show that the $n \times n$ Hessian matrix $(g_{ij}) := ((\frac{1}{2}L^2)_{y_i y_j})$ is positive definite on $\{y : \beta(y) \neq 0\}$ by checking the sign of determinant of (g_{ij}) . For this purpose, we compute the determinant of (g_{ij}) .

It is interesting and valuable to study Finsler space with some important tensors of special form. For example, M. Matsumoto[6] initiated the study of a Finsler metric whose Cartan tensor $A_{ijk} := \frac{L}{4}(L^2)_{y^i y^j y^k}$ satisfies

$$A_{ijk} = \mathfrak{S}_{(ijk)}\{Q_{ij}R_k\},$$

where Q_{ij} is a symmetric Finsler tensor field satisfying $Q_{ij}y^j = 0$ and R_k is assumed to satisfy $R_k y^k = 0$. Here we use the notation $\mathfrak{S}_{(ijk)}$ to denote the summation of the cyclic permutation of indices i, j, k , i.e.,

$$\mathfrak{S}_{(ijk)}\{S_{ijk}\} = S_{ijk} + S_{jki} + S_{kij}.$$

In case $R_k = A_k$ with $A_k := g^{ij}A_{ijk}$, the Finsler manifold is called quasi-C-reducible. Furthermore, if $Q_{ij} = \frac{1}{n+1}h_{ij}$ where h_{ij} is the angular metric $h_{ij} := g_{ij} - L_i L_j$, we call the Finsler manifold to be C-reducible. In section 4, we show that any (a, b, f) -manifold is quasi-C-reducible and find a sufficient condition that an (a, b, f) -manifold is C-reducible. To get A_k , we compute the inverse (g^{ij}) of (g_{ij}) .

2. Preliminaries

Let (M, α) be a $2m$ -dimensional Riemannian manifold and let $f_j^i(x)$ be an almost Hermitian structure of (M, α) . For a non-vanishing covariant vector field $b_i(x)$ on M , we have a singular Riemannian metric

$$\beta(x, y) = (b_{ij}(x)y^i y^j)^{1/2},$$

where $b_{ij} = b_i b_j + f_i f_j$, $f_i = b_r f_r^i$ and we consider a generalized Randers metric $L = \alpha + \beta$. Such a generalized Randers metric $L = \alpha + \beta$ is called an (a, b, f) -metric and (M, L) an (a, b, f) -manifold.

Recall the definition of a y -global Finsler metric F on M .

DEFINITION 2.1. A y -global Finsler metric on M is a function $F : TM \rightarrow \mathbb{R}$ such that

- (F1) Nonnegativity: $F \geq 0$ on TM .
- (F2) Regularity: F is smooth on $TM \setminus O$.
- (F3) Absolute homogeneity: $F(x, \lambda y) = |\lambda|F(x, y)$ for all $\lambda \in \mathbb{R}$.
- (F4) Strong convexity: The $n \times n$ Hessian matrix $(g_{ij}) := ((\frac{1}{2}F^2)_{y_i y_j})$ is positive definite at every point of $TM \setminus O$.

Note that for the most important physical applications, the assumptions are too restrictive. And so we have to consider a y -local Finsler structure F defined only on a domain \mathcal{D} of $TM \setminus O$ with $\mathcal{D} \cap T_x M \neq \emptyset$ for every $x \in M$.

Now we find the maximal domain \mathcal{D} of $TM \setminus O$ for (a, b, f) -metric. Because $L(y) = \alpha(y) + \beta(y)$ is positive for any $y \in TM \setminus O$ and both α and β are regular away from $\{y : \beta(y) = 0\} = \ker B$ with $B = (b_{ij})$, our possible domain \mathcal{D} is the complement $\mathbb{C}(\ker B)$ of $\ker B$. In section 4, we show that (g_{ij}) is positive definite on $\mathbb{C}(\ker B)$, i.e., all the eigenvalues of (g_{ij}) are positive on $\mathbb{C}(\ker B)$.

We use the following lemma extensively in the next section. For its proof, see [1].

LEMMA 2.1. Let (P_{ij}) be a real symmetric non-singular matrix with the inverse (P^{ij}) . And let $(Q_{ij}) = (P_{ij} \pm c_i c_j)$ with $1 \pm c^2 \neq 0$ and $c^2 := c_i P^{ij} c_j$. Then the matrix (Q_{ij}) is non-singular and its inverse is $(Q^{ij}) = (P^{ij} \mp \frac{1}{1 \pm c^2} c^i c^j)$ where $c^i = P^{ij} c_j$ and $\det(Q_{ij}) = (1 \pm c^2) \det(P_{ij})$.

3. The computation of the determinant and the inverse of (g_{ij})

In this section, we compute the inverse and the determinant of the fundamental tensor (g_{ij}) of (a, b, f) -metric. Here we assume that $y \in \mathbb{C} \ker B$.

For $L = \alpha + \beta$, we have

$$g_{ij} = \frac{L}{\alpha} a_{ij} + \frac{L}{\beta} b_i b_j + \frac{L}{\beta} f_i f_j + L_i L_j - \frac{L}{\alpha} \alpha_i \alpha_j - \frac{L}{\beta} \beta_i \beta_j,$$

where $\alpha_i = \frac{\partial \alpha}{\partial y^i}$, $\beta_i = \frac{\partial \beta}{\partial y^i}$, $L_i = \alpha_i + \beta_i$. We put $\alpha^i = a^{ir} \alpha_r$, $\beta^i = a^{ir} \beta_r$, $b^i = a^{ij} b_j$ and $f^i = a^{ij} f_j$. Then we can apply Lemma 2.1 to (g_{ij}) five times.

PROPOSITION 3.1. For the fundamental tensor (g_{ij}) of an (a, b, f) -metric $L = \alpha + \beta$, the determinant of (g_{ij}) is

$$\det(g_{ij}) = \frac{L\gamma}{\alpha\beta} \det A$$

and the inverse (g^{ij}) of (g_{ij}) is given by

$$(3.1) \quad g^{ij} = \frac{\alpha}{L} a^{ij} - \frac{\alpha^2}{\gamma L} b^{ij} + \frac{\alpha^2 \gamma}{L^3} \alpha^i \alpha^j - \frac{\alpha}{L^2 \beta} (\alpha^i \beta^j + \alpha^j \beta^i) + \frac{\alpha^2}{L\gamma} \beta^i \beta^j,$$

where $A = (\frac{L}{\alpha} a_{ij})$, $\gamma = \beta + b^2 \alpha$, $b^{ij} = b^i b^j + f^i f^j$.

Proof. First, we set

$$P_{ij} = \frac{L}{\alpha} a_{ij}, \quad c_{1i} = \sqrt{\frac{L}{\beta}} b_i \quad \text{and} \quad (Q_1)_{ij} = \frac{L}{\alpha} a_{ij} + \frac{L}{\beta} b_i b_j.$$

Note that $c_1^2 = c_{1i} P^{ij} c_{1j} = \frac{\alpha}{\beta} b^2$, where $b^2 = a^{ij} b_i b_j$ and (a^{ij}) is the inverse of (a_{ij}) . And note also that $b^2 = a^{ij} b_i b_j$ is positive, because (a_{ij}) is positive definite. In particular, the quantity $1 + c_1^2 = \frac{\gamma}{\beta} > 0$, where $\gamma = \beta + b^2 \alpha > 0$. By Lemma 2.1, we have

$$\det Q_1 = \frac{\gamma}{\beta} \det \left(\frac{L}{\alpha} a_{ij} \right) = \frac{\gamma}{\beta} \det A,$$

$$(Q_1)^{ij} = \frac{\alpha}{L} a^{ij} - \frac{\alpha^2}{\gamma L} b^i b^j.$$

Secondly, let

$$(Q_2)_{ij} = (Q_1)_{ij} + \frac{L}{\beta} f_i f_j, \quad c_{2i} = \sqrt{\frac{L}{\beta}} f_i$$

and apply Lemma 2.1 in the same way. Then we have $c_2^2 = c_{2i} (Q_1)^{ij} c_{2j} = \frac{\alpha}{\beta} b^2$, $1 + c_2^2 = \frac{\gamma}{\beta} > 0$. And Lemma 2.1 says that

$$\det Q_2 = \frac{\gamma}{\beta} \det Q_1 = \frac{\gamma^2}{\beta^2} \det A,$$

$$(Q_2)^{ij} = \frac{\alpha}{L} a^{ij} - \frac{\alpha^2}{\gamma L} b^{ij}.$$

Thirdly, let

$$(Q_3)_{ij} = (Q_2)_{ij} + L_i L_j, \quad c_{3i} = L_i.$$

Then we have $c_3^2 = c_{3i}(Q_2)^{ij}c_{3j} = 1$, $1 + c_3^2 = 2$. And by Lemma 2.1,

$$\det Q_3 = \frac{2\gamma^2}{\beta^2} \det A,$$

$$(Q_3)^{ij} = \frac{\alpha}{L}a^{ij} - \frac{\alpha^2}{\gamma L}b^{ij} - \frac{1}{2L^2}y^i y^j.$$

Fourthly, let

$$(Q_4)_{ij} = (Q_3)_{ij} - \frac{L}{\beta}\beta_i\beta_j, \quad c_{4i} = \sqrt{\frac{L}{\beta}}\beta_i.$$

Then we have $c_4^2 = c_{4i}(Q_3)^{ij}c_{4j} = \frac{1}{\beta}\left(b^2\alpha - \frac{b^4\alpha^2}{\gamma} - \frac{\beta^2}{2L}\right)$, $1 - c_4^2 = \frac{\beta(2L+\gamma)}{2L\gamma} > 0$. And by Lemma 2.1,

$$\det Q_4 = \frac{(2L + \gamma)\gamma}{L\beta} \det A,$$

$$(Q_4)^{ij} = \frac{\alpha}{L}a^{ij} - \frac{\alpha^2}{\gamma L}b^{ij} - \frac{1}{L(2L + \gamma)}y^i y^j$$

$$- \frac{\alpha}{L(2L + \gamma)\beta}(a^{ik}b_{kl}y^l y^j + y^i y^k b_{kl}a^{lj})$$

$$+ \frac{2\alpha^2}{(2L + \gamma)\beta^2\gamma}a^{ik}b_{kl}y^l y^m b_{mn}a^{nj}.$$

Finally, let

$$g_{ij} = (Q_4)_{ij} - \frac{L}{\alpha}\alpha_i\alpha_j, \quad c_{5i} = \sqrt{\frac{L}{\alpha}}\alpha_i.$$

Then we get $c_5^2 = c_{5i}(Q_4)^{ij}c_{5j} = \frac{L+\gamma}{2L+\gamma} - \frac{L\beta}{\alpha(2L+\gamma)}$, $1 - c_5^2 = \frac{L^2}{\alpha(2L+\gamma)} > 0$. And by Lemma 2.1,

$$\det(g_{ij}) = \frac{L^2}{\alpha(2L + \gamma)} \cdot \frac{(2L + \gamma)\gamma}{L\beta} \det A = \frac{L\gamma}{\alpha\beta} \det A,$$

$$g^{ij} = \frac{\alpha}{L}a^{ij} - \frac{\alpha^2}{\gamma L}b^{ij} + \frac{\gamma}{L^3}y^i y^j$$

$$- \frac{\alpha}{L^2\beta}(a^{ik}b_{kl}y^l y^j + y^i y^k b_{kl}a^{lj}) + \frac{\alpha^2}{L\beta^2\gamma}a^{ik}b_{kl}y^l y^m b_{mn}a^{nj}.$$

If we set $\alpha^i = \frac{y^i}{\alpha}$ and $\beta^i = \frac{a^{ir}b_{rs}y^s}{\beta}$, then the last equation yields equation (3.1). □

4. Theorems

In this section, with the aid of Proposition 3.1, we show the positivity of g_{ij} and the quasi-C-reducibility of an (a, b, f) -metric and find a sufficient condition of being C-reducible.

Now we are ready to prove that (g_{ij}) is positive definite on $\mathbb{C}(\ker B)$. This implies that $\mathbb{C}(\ker B)$ is the maximal domain \mathcal{D} of $TM \setminus O$ for an (a, b, f) -manifold where a y -local Finsler structure L is defined.

THEOREM 4.1. (g_{ij}) is positive definite on $\mathbb{C}(\ker B)$.

Proof. Consider a one-parameter family of the (a, b, f) -metric $L^\epsilon = \alpha + \epsilon\beta$ with $0 \leq \epsilon \leq 1$. Let g^ϵ be the fundamental tensor of L^ϵ . For $\epsilon > 0$, by Proposition 3.1, we have

$$\det(g_{ij}^\epsilon) = \frac{L^\epsilon \gamma^\epsilon}{\epsilon \alpha \beta} \det A^\epsilon,$$

where $A^\epsilon = (\frac{L^\epsilon}{\alpha} a_{ij})$, $\gamma^\epsilon = \epsilon\beta + \epsilon^2 b^2 \alpha > 0$, and so $\det(g_{ij}^\epsilon)$ is positive. In particular, none of the eigenvalues of (g_{ij}^ϵ) can vanish. For $\epsilon = 0$, $L^\epsilon = \alpha$ and all the eigenvalues of $(g_{ij}^\epsilon) = (g_{ij})$ are positive. Since $\det(g_{ij}^\epsilon)$ is continuous for ϵ , all the eigenvalues of (g_{ij}^ϵ) are positive by the intermediate value theorem. And so all the eigenvalues of (g_{ij}) are positive. This means that (g_{ij}) is positive definite. \square

Next, we show that (a, b, f) -manifolds are quasi-C-reducible and we determine a sufficient condition under which (a, b, f) -manifolds are C-reducible. We start with the definitions of quasi-C-reducibility and of C-reducibility.

DEFINITION 4.1. A Finsler manifold of dimension n , $n \geq 3$, is quasi-C-reducible if there exists a symmetric Finsler tensor field Q_{ij} satisfying $Q_{ij}y^j = 0$ and $A_{ijk} = \mathfrak{S}_{(ijk)}\{Q_{ij}A_k\}$, where $A_k := g^{ij}A_{ijk}$.

DEFINITION 4.2. A Finsler manifold of dimension n , $n \geq 3$, is C-reducible if A_{ijk} is in the form $A_{ijk} = \frac{1}{n+1} \mathfrak{S}_{(ijk)}\{h_{ij}A_k\}$, where $h_{ij} := g_{ij} - L_i L_j$ is the angular metric of L .

Note that for (a, b, f) -metric, the Cartan tensor is

$$\begin{aligned} A_{ijk} &:= \frac{L}{4} (L^2)_{y^i y^j y^k} = \frac{L}{2} (g_{ij})_{y^k} \\ &= \frac{L}{2} \mathfrak{S}_{(ijk)} \left\{ \left(\frac{\alpha_{ij}}{\alpha} - \frac{\beta_{ij}}{\beta} \right) (\alpha\beta_k - \beta\alpha_k) \right\}. \end{aligned}$$

By Proposition 3.1, we get

$$A_k = \frac{\lambda}{2}(\alpha\beta_k - \beta\alpha_k),$$

where $\lambda = (\frac{n+1}{\alpha} - \frac{b^2L}{\beta\gamma})$. Since $rank(b_{ij}) = 2$, $\lambda \neq 0$. And if we let

$$Q_{ij} = \frac{L}{\lambda} \left(\frac{\alpha_{ij}}{\alpha} - \frac{\beta_{ij}}{\beta} \right),$$

we have $A_{ijk} = \mathfrak{S}_{(ijk)}\{Q_{ij}A_k\}$. Because Q_{ij} is symmetric and $Q_{ij}y^j = 0$ by Euler's theorem, we have

THEOREM 4.2. *(a, b, f)-manifolds are quasi-C-reducible.*

Since the angular metric h_{ij} for (a, b, f) -manifold is $L \cdot (\alpha_{ij} + \beta_{ij})$, we can conclude

THEOREM 4.3. *If an (a, b, f)-metric $L = \alpha + \beta$ satisfies*

$$\frac{\alpha_{ij}}{\alpha} - \frac{\beta_{ij}}{\beta} = \frac{\lambda}{n+1}(\alpha_{ij} + \beta_{ij}),$$

or equivalently $b^2\alpha\alpha_{ij} = (n\gamma + \beta)\beta_{ij}$, then the (a, b, f)-manifold is C-reducible.

REMARK. If $A_i = 0$ for a C-reducible manifold, then $A_{ijk} = 0$ immediately. And so the manifold is Riemannian. For a C-reducible (a, b, f) -manifold with $A_i = 0$, we can show that

$$g_{ij}(x) = g_{pq}(x)f_i^p f_j^q.$$

In other words, such an (a, b, f) -manifold is an almost Hermitian manifold. For its proof, we refer the readers to [2].

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