

## ON THE MINIMAL ENERGY SOLUTION IN A QUASILINEAR ELLIPTIC EQUATION

SANG DON PARK AND CHUL KANG

ABSTRACT. In this paper we seek a positive, radially symmetric and energy minimizing solution of an  $m$ -Laplacian equation,  $-div(|\nabla u|^{m-2}|\nabla u) = h(u)$ . In the variational sense, the solutions are the critical points of the associated functional called the energy,  $J(v) = \frac{1}{m} \int_{\mathbf{R}^N} |\nabla v|^m - \int_{\mathbf{R}^N} H(v)dx$ , where  $H(v) = \int_0^v h(t)dt$ . A positive, radially symmetric critical point of  $J$  can be obtained by solving the constrained minimization problem; minimize  $\{\int_{\mathbf{R}^N} |\nabla u|^m dx \mid \int_{\mathbf{R}^N} H(u)dx = 1\}$ . Moreover, the solution minimizes  $J(v)$ .

### 1. Introduction

In this paper we are concerned with the existence of positive, radially symmetric, nonincreasing solution of a quasilinear elliptic equation

$$(I) \quad -div(|\nabla u|^{m-2}|\nabla u) = h(u) \quad \text{in } \mathbf{R}^N,$$

where  $1 < m < N$  and the continuous function  $h$  satisfy the following conditions:

- ( $h_1$ )  $h(u) = 0$  for  $u \leq 0$
- ( $h_2$ )  $\lim_{u \rightarrow 0} h(u)/u^{m-1} = -\mu < 0$
- ( $h_3$ )  $\lim_{u \rightarrow \infty} h(u)/u^{m^*-1} = 0$ ,  $m^* = \frac{mN}{N-m}$
- ( $h_4$ ) There exists  $\xi > 0$  such that  $\int_0^\xi h(u) > 0$ .

This problem is  $m$ -Laplacian form related with the following elliptic partial differential equation

$$(1) \quad \begin{cases} -\Delta u = g(u) & \text{in } \mathbf{R}^N \\ u > 0. \end{cases}$$

---

Received July 29, 2002.

2000 Mathematics Subject Classification: 35C49.

Key words and phrases: quasilinear elliptic,  $m$ -Laplacian, constrained minimization, variational equation, radially symmetric, Lagrange multiplier.

The problem (1) was investigated by Berestycky and Lions [1] under the following growth conditions imposed on  $g$ ;

- (g<sub>1</sub>)  $-\infty < \underline{\lim}_{t \rightarrow 0^+} g(t)/t \leq \overline{\lim}_{t \rightarrow 0^+} g(t)/t = -m < 0$
- (g<sub>2</sub>)  $-\infty \leq \overline{\lim}_{t \rightarrow +\infty} g(t)/t^l = -m < 0$ , where  $l = \frac{N+2}{N-2}$ ,
- (g<sub>3</sub>) there exists  $\zeta > 0$  such that  $G(\zeta) = \int_0^\zeta g(t)dt > 0$ .

They showed that (1) has a positive, radial  $C^2$  solution decreasing with exponential decay rate. Equations of type (1) have been studied by a number of mathematicians, e.g., Dancer [3], Strauss [7] and Coleman, Glazer, Martin [2].

A function  $u \in W^{1,m}(\mathbf{R}^N)$  is called a generalized solution of (I) if it satisfies, for all  $v \in C_0^\infty(\mathbf{R}^N)$  :

$$\int_{\mathbf{R}^N} |\nabla u|^{m-2} \nabla u \nabla v - \int_{\mathbf{R}^N} h(u)v dx = 0.$$

Also, note that each generalized solution  $u$  is a critical point of the functional  $J$  on  $W^{1,m}(\mathbf{R}^N)$  defined by

$$J(v) = \frac{1}{m} \int_{\mathbf{R}^N} |\nabla v|^m - \int_{\mathbf{R}^N} H(v) dx,$$

where  $H(v) = \int_0^v h(t)dt$ . In relation to (I), our main result is as follows:

**THEOREM 1.1.** *Under the hypotheses (h<sub>1</sub>)-(h<sub>4</sub>), (I) possesses a solution  $u$  such that*

- (i)  $u > 0$  on  $\mathbf{R}^N$ ,
- (ii)  $u$  is spherically symmetric and  $u$  decreases with respect to  $r = |x|$ ,
- (iii)  $u$  minimizes the energy  $J$ , that is,  $J(v) \geq J(u)$  for any nontrivial  $v$  solving (I).

## 2. Proof of Theorem 1.1

Our main idea for Theorem 1.1 is the constrained minimization method. That is, the problem;

$$\text{minimize } \left\{ \int_{\mathbf{R}^N} |\nabla u|^m dx \mid \int_{\mathbf{R}^N} H(u) dx = 1 \right\}.$$

In exercising the constrained minimization method, the Pohožăev's identity is crucial. So we first prove the Pohožăev's identity for the equation (I).

THEOREM 2.1. (*Pohožăev's identity*). Let  $g : \mathbf{R} \rightarrow \mathbf{R}$  be continuous such that  $g(0) = 0$  and let  $G(u) = \int_0^u g(t)dt$  and  $u \in L_{loc}^\infty(\mathbf{R}^N) \cup W_{loc}^{1,m}(\mathbf{R}^N)$  satisfy

$$-div(|\nabla u|^{m-2}\nabla u) = g(u) \quad \text{in } \mathbf{R}^N.$$

Assume further that  $G(u) \in L^1(\mathbf{R}^N)$ . Then  $u$  satisfy

$$(2) \quad \frac{N-m}{m} \int_{\mathbf{R}^N} |\nabla u|^m dx - N \int_{\mathbf{R}^N} G(u) dx = 0$$

PROOF. If  $u$  is a solution of (I), on  $B_R$

$$(3) \quad \int_{B_R} [div(|\nabla u|^{m-2}\nabla u)(x, \nabla u) + g(u)(x, \nabla u)] dx = 0.$$

Since  $g(u)(x, \nabla u) = div(G(u)x) - NG(u)$ ,

$$(4) \quad \int_{B_R} g(u)(x, \nabla u) dx = -N \int_{B_R} G(u) dx + \int_{\partial B_R} G(u)(x, \nu) dS.$$

Now,

$$\begin{aligned} & \int_{B_R} div(|\nabla u|^{m-2}(x, \nabla u)\nabla u) dx \\ &= \int_{B_R} D_i(|\nabla u|^{m-2}(x, \nabla u)D_i u) dx \\ &= \int_{B_R} [D_i(|\nabla u|^{m-2})D_i u + |\nabla u|^{m-2}D_{ii}u](x, \nabla u) dx \\ & \quad + \int_{B_R} |\nabla u|^{m-2}D_i(x, \nabla u)D_i u dx \\ &= \int_{B_R} div(|\nabla u|^{m-2}\nabla u)(x, \nabla u) dx + \int_{B_R} |\nabla u|^{m-2}D_i(x, \nabla u)D_i u dx. \end{aligned}$$

Hence we obtain

$$(5) \quad \begin{aligned} & \int_{B_R} div(|\nabla u|^{m-2}\nabla u)(x, \nabla u) dx \\ &= \int_{B_R} div(|\nabla u|^{m-2}\nabla u(x, \nabla u)) dx - \int_{B_R} |\nabla u|^{m-2}D_i(x, \nabla u)D_i u dx, \end{aligned}$$

On the other hand,

$$(6) \quad \int_{B_R} |\nabla u|^{m-2} D_i(x, \nabla u) D_i u dx \\ = \int_{B_R} |\nabla u|^m dx + \int_{B_R} |\nabla u|^{m-2} D_i u D_{ij} u x_j dx$$

and observe that

$$(7) \quad \int_{B_R} |\nabla u|^{m-2} D_i u D_{ij} u x_j dx = \frac{1}{2} \int_{B_R} |\nabla u|^{m-2} D_j (|D_i u|^2) x_j dx \\ = \int_{B_R} |\nabla u|^{m-1} D_j (|\nabla u|) x_j dx \\ = \frac{1}{m} \int_{\partial B_R} |\nabla u|^m x_j \nu_j dS - \frac{N}{m} \int_{B_R} (|\nabla u|^m) dx.$$

Apply the Divergence theorem after substituting (6) and (7) for (5). Then we have

$$(8) \quad \int_{B_R} \operatorname{div}(|\nabla u|^{m-2} \nabla u)(x, \nabla u) dx \\ = \frac{N-m}{m} \int_{B_R} |\nabla u|^m dx + R \int_{\partial B_R} |\nabla u|^{m-2} \left| \frac{\partial u}{\partial \nu} \right|^2 dS - \frac{R}{m} \int_{\partial B_R} |\nabla u|^m dS.$$

By inserting (4) and (8) into (3), we obtain

$$(9) \quad \frac{N-m}{m} \int_{B_R} |\nabla u|^m dx - N \int_{B_R} G(u) dx \\ = R \left( \frac{1}{m} \int_{\partial B_R} |\nabla u|^m dS - \int_{\partial B_R} |\nabla u|^{m-2} |\partial u / \partial \nu|^2 dS - \int_{\partial B_R} G(u) dS \right).$$

So we have

$$(10) \quad \left| \frac{N-m}{m} \int_{B_R} |\nabla u|^m dx - N \int_{B_R} G(u) dx \right| \\ \leq R \left( C(m) \int_{\partial B_R} |\nabla u|^m + |G(u)| dS \right).$$

Since  $\int_{\mathbf{R}^N} |\nabla u|^m + |G(u)| dx = \int_0^\infty \left( \int_{\partial B_R} |\nabla u|^m + |G(u)| dS \right) dR < +\infty$ , there exists a sequence  $R_n \rightarrow \infty$  such that, as  $n \rightarrow \infty$ ,

$$R_n \int_{\partial B_{R_n}} |\nabla u|^m + |G(u)| dS \rightarrow 0.$$

Moreover, as  $n \rightarrow \infty$ ,

$$\int_{B_{R_n}} |\nabla u|^m dx \rightarrow \int_{\mathbf{R}^N} |\nabla u|^m dx, \quad \int_{B_{R_n}} G(u) dx \rightarrow \int_{\mathbf{R}^N} G(u) dx.$$

With this sequence  $R_n$ , limiting  $n$  to  $\infty$  in (10), we have

$$\frac{N-m}{m} \int_{\mathbf{R}^N} |\nabla u|^m dx - N \int_{\mathbf{R}^N} G(u) dx = 0.$$

□

PROOF OF THEOREM. Define  $T(u) = \int_{\mathbf{R}^N} |\nabla u|^m dx$  and  $V(u) = \int_{\mathbf{R}^N} H(u) dx$  where  $H(u) = \int_0^u h(t) dt$  and  $M = \{u \in W^{1,m}(\mathbf{R}^N) | V(u) = 1\}$ . We consider the following constrained minimization problem;

$$\text{minimize}\{T(u) | u \in M\}.$$

First, it is simple to show that  $V(u)$  is  $C^1$ -functional. Due to  $(h_4)$ , it is easily checked that  $M$  is not empty (see [1]). Choose a minimizing sequence  $(u_n)$ , that is,

$$\lim_{n \rightarrow \infty} T(u_n) = I \stackrel{\text{def}}{=} \inf_{u \in M} T(u).$$

Let  $u_n^*$  be the Schwarz spherical decreasing rearrangement of  $|u_n|$ . Then  $u_n^* \in W^{1,m}(\mathbf{R}^N)$ ,  $V(u_n^*) = 1$  and  $T(u_n^*) \leq T(u_n)$  (confer Theorem 1.25 in [4]). Hence  $(u_n^*)$  is again a minimizing sequence. Rewriting them by  $u_n$ , we may assume in the following that  $u_n$  is non-negative, spherically symmetric and non increasing in  $|x|$ . Now we assert that  $\|u_n\|_{W^{1,m}(\mathbf{R}^N)}$  is bounded. Define  $h_1(t) = (h(t) + \mu t^{m-1})^+$  and  $h_2(t) = (h(t) + \mu t^{m-1})^-$ , where  $a^+ = \max\{a, 0\}$  and  $a^- = -\min\{a, 0\}$ . Then  $h_i \geq 0$ , where  $i = 1, 2$  and  $h = h_1 - h_2$ . It follows from  $(h_1)$ ,  $(h_2)$  and  $(h_3)$  that

$$(11) \quad \lim_{t \rightarrow 0} \frac{h_1(t)}{t^{m-1}} = 0, \quad \lim_{t \rightarrow \infty} \frac{h_1(t)}{t^{m^*-1}} = 0$$

$$(12) \quad h_2(t) \geq \mu t^{m-1}.$$

Let  $H_i(u) = \int_0^u h_i(t) dt$ ,  $i = 1, 2$ . From (11) and (12), for any  $\varepsilon > 0$ , there exists  $C_\varepsilon > 0$ , such that

$$(13) \quad H_1(u) \leq C_\varepsilon |u|^{m^*} + \varepsilon H_2(u), \quad u \in \mathbf{R}.$$

Since  $\|\nabla u_n\|_{L^m}$  is bounded, we find that  $\|u_n\|_{L^{m^*}}$  is bounded by the Sobolev imbedding theorem  $(\mathcal{D}^{1,m}(\mathbf{R}^N) \hookrightarrow L^{m^*}(\mathbf{R}^N))$ ; see e.g., [8]. Since  $V(u_n) = 1$ , we have

$$(14) \quad \int_{\mathbf{R}^N} H_1(u_n) dx = \int_{\mathbf{R}^N} H_2(u_n) dx + 1.$$

We obtain from (13) and (14) with  $\varepsilon = \frac{1}{2}$ ,

$$C + \frac{1}{2} \int_{\mathbf{R}^N} H_2(u_n) dx \geq \int_{\mathbf{R}^N} H_2(u_n) dx + 1.$$

Hence  $\int_{\mathbf{R}^N} H_2(u_n) dx \leq C$ , and by (12)

$$\frac{\mu}{m} \int_{\mathbf{R}^N} |u_n|^m dx \leq \int_{\mathbf{R}^N} H_2(u_n) dx < C.$$

Thus  $\|u_n\|_{W^{1,m}(\mathbf{R}^N)}$  is bounded. Hence we may say, via subsequence argument, that there exists  $u \in W^{1,m}(\mathbf{R}^N)$  such that  $u_n \rightarrow u$  weakly in  $W^{1,m}(\mathbf{R}^N)$ . Observe that  $u_n \rightarrow u$  a.e., and  $u$  is nonnegative, non increasing and spherically symmetric.

From now on, we are to show that  $u$  is positive. Note also that  $\|u_n\|_{L^p(\mathbf{R}^N)} \leq C$  for any  $p$ , with  $m \leq p \leq m^*$ . Applying Strauss compactness lemma (see [7]), with  $Q(t) = t^m + t^{m^*}$ , we have

$$\int_{\mathbf{R}^N} H_1(u_n) dx \rightarrow \int_{\mathbf{R}^N} H_1(u) dx \quad \text{as } n \rightarrow \infty.$$

Applying Fatou's lemma to (14), we obtain

$$\int_{\mathbf{R}^N} H_1(u) dx \geq \int_{\mathbf{R}^N} H_2(u) dx + 1.$$

Hence  $V(u) \geq 1$ . Applying again Fatou's lemma, we have that  $T(u) \leq I$ . Now we assert that  $V(u) = 1$ , from which it follows that  $T(u) = I$ . Suppose to the contrary  $V(u) > 1$  and put  $u_\delta(x) = u(x/\delta)$ . Then there exists  $\delta$ ,  $0 < \delta < 1$ , such that  $V(u_\delta) = \delta^N V(u) = 1$ . However with this  $u_\delta$ , we have

$$0 < I \leq T(u_\delta) = \delta^{N-m} T(u) \leq \delta^{N-m} I < I,$$

which is absurd. Now since  $V$  and  $T$  are  $C^1$ -functionals on  $W^{1,m}(\mathbf{R}^N)$ , there exists a Lagrange multiplier  $\theta$  such that

$$\frac{1}{m} DT(u) = \theta DV(u).$$

We assert that  $\theta$  is positive. First note that  $\theta \neq 0$  and suppose to the contrary that  $\theta < 0$  and choose a function  $\psi \in C_0^\infty(\mathbf{R}^N)$  such that  $\langle DV(u), \psi \rangle = \int_{\mathbf{R}^N} h(u)\psi dx > 0$ . Since

$$V(u + \varepsilon\psi) - V(u) = \varepsilon \langle DV(u), \psi \rangle + o(\varepsilon)$$

and

$$T(u + \varepsilon\psi) - T(u) = m\varepsilon\theta \langle DV(u), \psi \rangle + o(\varepsilon),$$

we find that there exists  $\varepsilon > 0$  sufficiently small such that

$$V(w = u + \varepsilon\psi) > V(u) = 1$$

and

$$T(w = u + \varepsilon\psi) < T(u) = I.$$

Then again by changing the scale, there exists  $\theta, 0 < \theta < 1$  such that  $V(w_\theta) = 1$ , whence we obtain

$$T(w_\theta) = \theta^{N-m}T(w) < I,$$

which is absurd. Hence  $\theta > 0$  and  $u$  satisfies

$$-div(|\nabla u|^{m-2}\nabla u) = \theta h(u) \quad \text{in } \mathbf{R}^N,$$

and it is easy to see that  $u_{\theta^{1/m}}(x)$ , which is given by  $u(\frac{x}{\theta^{1/m}})$  is a solution of (I) in the sense that

$$\int_{\mathbf{R}^N} |\nabla u_{\theta^{1/m}}|^{m-2} \nabla u_{\theta^{1/m}} \nabla v dx = \int_{\mathbf{R}^N} h(u_{\theta^{1/m}}) v dx.$$

Finally we remark that  $u_{\theta^{1/m}} \in C^{1,\alpha}$  by the regularity theory ([6]) and  $u_{\theta^{1/m}} > 0$  by the Hopf boundary point lemma ([5]).

Now it remains to show (iii). Recall that if  $\underline{u}$  is a critical point of the problem  $\min\{T(u) \mid u \in M\}$ , then there exists  $\theta$  such that

$$-div(|\nabla \underline{u}|^{m-2}\nabla \underline{u}) = \theta h(\underline{u}) \quad \text{in } \mathbf{R}^N.$$

And if we set  $u = \underline{u}_{\theta^{1/m}}$ ,  $u$  satisfies

$$-div(|\nabla u|^{m-2}\nabla u) = h(u) \quad \text{in } \mathbf{R}^N.$$

Now by Theorem 2.1, we have

$$(15) \quad T(u) = \frac{mN}{N-m}V(u).$$

Changing the scale of  $u$  yields

$$(16) \quad T(u) = \theta^{(N-m)/m}T(\underline{u})$$

$$(17) \quad V(u) = \theta^{1/m}V(\underline{u}).$$

Noting that  $V(\underline{u}) = 1$ , we obtain  $\theta = \frac{N-m}{mN}T(\underline{u})$  from (15), (16) and (17). Again by Pohožăev's identity

$$\begin{aligned} J(u) &= \frac{1}{m}T(u) - V(u) \\ &= \left(\frac{1}{m} - \frac{N-m}{mN}\right)T(u) \\ (18) \quad &= \frac{1}{N} \left(\frac{N-m}{mN}\right)^{(N-m)/m} T(\underline{u})^{N/m}. \end{aligned}$$

Now let  $v$  be another solution of (I). By Pohožăev's identity, we obtain

$$T(v) = \frac{mN}{N-m}V(v).$$

Let  $\delta > 0$  be such that  $V(v_\delta) = 1$ . It is easy to see that  $\delta = \left(\frac{N-m}{Nm}T(v)\right)^{-1/N}$ . On the other hand,

$$\begin{aligned} T(v_\delta) &= \delta^{N-m}T(v) \\ &= \left(\frac{N-m}{Nm}\right)^{-(N-m)/N} T(v)^{m/N}. \end{aligned}$$

Hence

$$(19) \quad J(v) = \frac{T(v)}{N} = \frac{1}{N} \left(\frac{N-m}{mN}\right)^{(N-m)/m} T(v_\delta)^{N/m}.$$

Since  $\underline{u}$  is a minimum point of  $T(u)$  on  $M$ ,  $T(u_\delta) \geq T(\underline{u})$ . Hence from (18) and (19), we obtain the conclusion,  $J(v) \geq J(\underline{u})$ .  $\square$

## References

- [1] H. Berestycki, P. L. Lions, *Nonlinear scalar equations, I. Existence of ground state*, Arch. Mech. Anal. **82** (1983), 313–375.
- [2] S. Coleman, V. Glazer, A. Martin, *Action minima among solutions to a class of Euclidean scalar field equations*, Comm. Math. Phys. **58** (1978), no. 2, 211–221.
- [3] E. N. Dancer, *Boundary value problems for ordinary differential equations in infinite intervals*, Proc. London Math. Soc. **30** (1975), 76–94.
- [4] J. I. Diaz, *Nonlinear partial differential equations and free boundary, Vol I*, Pitman Advanced Publishing Program, 1985.
- [5] M. Guedda, L. Veron, *Quasilinear equations involving critical Sobolev exponents*, Nonlinear Analysis, Theory and Methods and Applications **13** (1989).
- [6] G. M. Liberman, *Boundary regularity for solutions degenerate elliptic equations*, Nonlinear Analysis, Theory, Methods and Applications **12** (1988), no. 11, 1203–1219.
- [7] W. A. Strauss, *Existence of solitary waves in higher dimensions*, Comm. Math. Phys. **55** (1977), 149–162.



- [8] M. Struwe, *Variational methods*, Springer Verlag, 1990.

Department of Mathematics and Informatics  
University of Hankyong  
Kyunggi 456-749, Korea  
*E-mail*: [sdpark@hnu.hankyong.ac.kr](mailto:sdpark@hnu.hankyong.ac.kr)  
[ckang@hnu.hankyong.ac.kr](mailto:ckang@hnu.hankyong.ac.kr)