

Modeling of CPC/COLSS for YGN#3,4 Simulator

영광#3,4호기 시뮬레이터의 노심보호 및 감시계통 모델링

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요 약 : 본 논문에서는 한국형 원자력발전소의 기준모델인 영광 3,4호기 운전원 훈련용 시뮬레이터의 모델링 절차와 ABB-CE 원전의 독특한 계통인 CPC/COLSS(Core Protection Calculator/Core Operating Limit Supervisory System) 계통에 대한 모델링을 전개하고 있다. CPC/COLSS는 원자로를 포함하는 냉각재계통(NSSS)과 핵연료의 건전성을 보장하기 위한 계통으로서 감시 및 보호 과정에서의 계산을 디지털화시킴으로서 정확성과 함께 원자로의 안전성을 향상시킨 특색있는 계통이다. 따라서 영광 3,4호기 시뮬레이터에서는 CPC/COLSS 계통에 대한 정확한 모델링을 하여 시험을 통해 성능 및 기능에 대한 검증은 마침으로서 CPC/COLSS 시뮬레이션 모델 개발이 성공적으로 되었고 영광 3,4호기 운전 특성에 맞는 시뮬레이터를 개발하였다.

Keywords : CPC, COLSS, DNBR, LPD, simulation model

I. Introduction

The safety and reliability of nuclear power plant operations relies heavily on the plant operators ability to respond to various emergency situations. The importance of operator ability to respond to emergency situation was revealed in the accident investigation of the TMI disaster in 1979. The accident report concluded that the operator's mistake during the accident contributed greatly to the disaster. The TMI disaster demonstrated the importance of operator training and the use of simulators for this very purpose. It has become standard industry practice to utilize simulators to improve the safety and reliability of nuclear power plants operations. KEPCO has decided to localize this technology which has been relied solely on foreign vendors until now. The simulators built for Younggwang#3,4("YGN#3,4"), which is the basic model of the Korean nuclear power plant design, has been developed precisely for this purpose. The basic model of the Korean standard nuclear power plant has several features which are conceptually different from those of other nuclear power plants in Korea. One of these features is the CPC/COLSS(Core Protection Calculator/Core Operational Limit Supervisory System).

The CPC, which is a digital computer based protection system, is designed to provide on-line calculations of Departure from Nucleate Boiling Ratio(DNBR) and Local Power Density(LPD) and to initiate reactor trip if the core conditions exceed the DNBR and LPD setpoint. The COLSS is designed to

assist the operator in implementing the Limiting Conditions for Operations(LCOs) in Technical Specifications for DNBR/Linear Heat Rate(LHR) margin, azimuthal tilt, and Axial Shape Index(ASI) and to provide alarm when the LCOs are reached. A particular attention was placed on the development of CPC/COLSS safety system which is unique to the YGN#3,4. The analysis of performance and operations showed that the simulation model developed was indeed accurate simulation of the YGN#3,4 power plant[1]-[5].

II. Overview of CPC/COLSS

The CPC(Core Protection Calculator)is composed of 4 computers which continuously calculate DNBR and Local Power Density(LPD) to initiate a reactor trip when needed during certain transients to prevent violation of the DNB and fuel centerline melt fuel design limits[1][4][5]. The minimum DNBR is calculated as follows :

$$DNBR_K = \frac{q_{DNB}^{(K)}}{F_K \cdot q_{LOCAL}^{(K)}} \quad K=2,3,\dots,21 \quad (1)$$

where subscript K stands for the node number of core. The minimum is selected and adjustment terms applied.

$$DNBR_{MIN} = \text{MIN}[DNBR_2, DNBR_3, \dots, DNBR_{21}] \quad (2)$$

$$DNBR_{ST} = E_{DNB1} \cdot [DNBR_{MIN} + E_{DNB2}] \quad (3)$$

where

$DNBR_K$: Array of DNB ratios in hot-channel

$DNBR_{ST}$: Minimum static DNBR.

E_{DNB1}, E_{DNB2} : DNBR adjustment terms, constant

q_{DNB} hot channel critical heat flux(BTU/sec-ft²)

The Local power density is calculated as follows :

$$L_{PD} = B_{LPD} \cdot TR \cdot PKMX \cdot PF_{LPE} \quad (4)$$

where

B_{LPE} : Corrected core average power, % of rated power

$PKMX$: Maximum 3-D peaking factor computed in power distribution program

TR : Azimuthal tilt allowance

PF_{LPE} : CEA deviation penalty factor for LPD

The CEAC(Control Element Assembly Calculator) is composed of 2 computers which continuously measure positions of all CEA's(Control Element Assemblies) to detect deviations and provide power penalties, if needed, for input to the CPC's which provides the 4 independent channels for the DNBR and LPD trip functions[2]. The low DNBR and high LPD trips assure that the Specified Acceptable fuel Design Limits (SAFDL's) on DNBR and centerline melt are not exceeded during Anticipated Operational Occurrences (AOO's), and assist the Engineered Safety Features Actuation System(ESFAS) by limiting the consequences of certain postulated accidents, The CPCS software has approximately 6,000 constants[6][7]. The constants used by YGN CPCS have been tuned specifically for the YGN#3,4 power plant. The overall accuracy of the CPCS depends on the accuracy of these constants[1][2].

The Core Operating Limit Supervisory System (COLSS) which is a part of plant monitoring system consists of process measurements and algorithms used to continuously monitor the following LCO's : LHR margin, DNBR margin, azimuthal tilt and ASI. COLSS also assists the operator in maintaining core power equal to or below the licensed power. To implement the requirements, COLSS is required to perform the following functions :

- Compute the DNBR and LHR power operating limits
- Compute the azimuthal tilt and monitor it with respect to the LCO
- Compute the ASI and Monitor it with respect to the LCO
- Compute the plant power and power distribution.
- Compute the margin to the licensed power, LHR and DNBR power operating limits.
- Initiate appropriate alarm sequences and informative messages when any monitored margin or parameter exceeds its LCO.

LHR power operating limit is calculated as follows :

the temperature dependent KW/FT limit is calcu-

lated based on the inlet temperature as

$$KLIM = FLIMO + (FLIMI - FLIMO) * \frac{TCMIN - TLIMO}{TLIMI - TLIMO} \quad (5)$$

IF $TCMIN \leq TLIMO$

THEN $KLIM = FLIMO$

IF $TCMIN \geq TLIMI$

THEN $KLIM = FLIMI$

where

$KLIM$: Temperature dependent linear heat rate (KW/FT) limit

$TCMIN$: Minimum compensated coldleg temperature

$TLIMO$: Minimum temperature in the proportional limit region

$TLIMI$: Maximum temperature in the proportional limit region

$FLIMO$: Linear heat rate (KW/FT) limit at $TLIMO$

$FLIMI$: Linear heat rate (KW/FT) limit at $TLIMI$

The following calculations are performed for $I = 1$ to 40 axial nodes.

$$KWFT(I) = T41 * TDPEAK(I) * (1 + AZTILT) * UNCERT * PP/100.0 \quad (6)$$

$$KWPFPL = (KLIM/KWFT(I)) * PP * T42 \quad (7)$$

Select the minimum value of $KWPFPL(I)$ and set it equal to $KWPFPL$

$$KWPFPL = \text{MIN}[KWPFPL(I) \text{ for } I=1 \text{ to } 40] \quad (8)$$

where

$KWFT(I)$: linear heat rate at node I

$T41$: Core average linear heat rate at rated power, constant

$TDPEAK(I)$: Three-D peaking factor

$AZTILT$: Azimuthal tilt

PP : Plant power, percent

$KLIM$: Temperature dependent linear heat rate limit

$KWPFPL(I)$: Core power operation limit at node I

$T42$: Adjustment factor for linear heat rate limit

$UNCERT$: Adjustment factor for calculation of linear heat rate

$KWPFPL$: LHR power operating limit

$DNBPOLC$: power operating limit

The main parts of COLSS are power level calculation algorithm, core power distribution algorithm and DNBR & LHR power operating limit calculation algorithm. In core power calculation algorithm, it selects the highest power among the secondary calorimetric power, turbine power and core ΔT power. In core power distribution algorithm, it determines 1-D and 3-D power distribution, azimuthal tilt and ASI by five level fixed in core detectors and CEA positions. The DNBR & LHR power operating limit algorithms determine the DNBR and LHR margins. COLSS

should have always some required power margin to meet fuel design criteria even if any AOO occurs. This margin is called the Required Over Power Margin(ROPM). COLSS checks every second whether the present plant status is within the COLSS LCO's using the ROPM and measured state parameters. If any COLSS LCO is exceeded, COLSS alarms and operator action is taken per the Technical Specifications[3].

III. CPC/COLSS model configuration of simulator

The simulator for the YGN#3,4 is a full scope replica type to be used for training plant operators. The CPC/COLSS on the simulator was also designed to provide the same features as those installed in the actual plant. In order to accomplish this, hardware identical to the plant Main Control Room(MCR) was installed. The hardware installed included the same operator module such as the Plasma Display Unit(PDU), CRT and function keyboards. The simulation host computer was a Silicon Graphics Challenge L and Indy Workstations operating under Real-Time UNIX OS. Table 1 shows the configuration of the actual plant and that of the simulator.

Table 1. The configuration of the actual plant and that of the simulator.

Real Plant CPC/COLSS	Simulator CPC/COLSS
Process(Pipe, Pump, Core, Instrumentation...)	Process Modeling Programs
Main Control Room (Example: CRT, PDU)	Main Control Room (Example : CRT, PDU)
Computer Systems for Calculation, Display (3205/3280MPS)	Simulation Computer Systems (CHALLENGE L, INDY)

IV. Development of CPC/COLSS model of simulator

1. Development process

The first step in the development of the CPC/COLSS simulation model is the generation of the Software Requirement Specifications(SRS). The SRS is generated by compiling performance requirement and specifications from plant operators and plant data. The SRS defines the scope of simulation for the simulator for each specific system. The next process is the development of Detailed Design Specifications(DDS). During the DDS phase, the modeling of algorithm and system interfaces are developed. The design data used for this is the CPC/COLSS functional design requirement which is provided by the vendor. After the completion of the DDS, the developed system model is put through a Stand-alone Test and Non-Integrated Systems Test(NIST). The system model is then integrated with the simulator and put

through an Integration Test. Finally, after the Integration Test is completed, the software model is integrated with the H/W and tested by plant operators during the Factory Acceptance Test(FAT) and Site Acceptance Test(SAT). Figure 1 shows the development process[8].

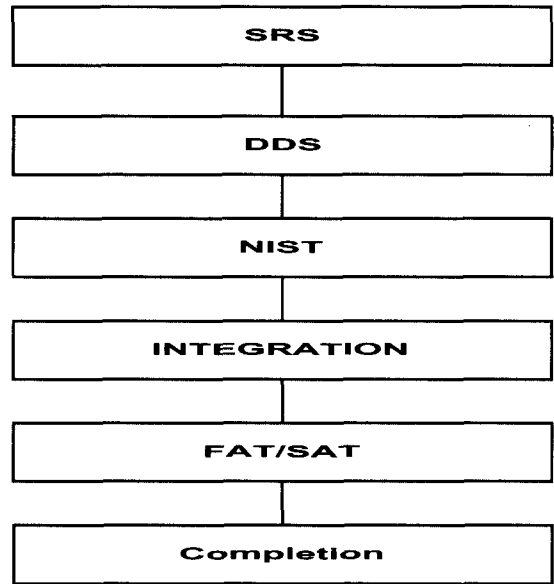


Fig. 1. The development process.

2. CPC/COLSS model program structure and process flow

2.1 CPC/COLSS commonly used software

The computerized systems such as CPC/COLSS developed commonly used software collectively so that changes can be easily made and implemented throughout the simulator. The main task of common S/W development are Data Gathering Task, Communication Manager, Scanning Task, Timer Task.

2.2 CPC/COLSS display task and program module

The display task receives information such as Symbols(pump, valves..), Value(temperature, pressure, level...), text(Point ID, description...) from Current Value Table(CVT) and displays this data on the PDU and CRT in the MCR. The display task also receives operator input and processes the input command.

2.3 CPC program module

The plant CPC is designed to perform rapid and accurate calculations to maintain certain plant safety parameters to within specified safety limits. In order to comply with this design requirement, the calculation algorithm was installed on the simulation host computer. The CPC program module is set in a top-down configuration with segment modules placed in a hierarchial sequence. The structure allows for the independent compiling of the modules. Figure 2 shows the configuration of the CPC model program.

2.3.1 Control module

The control module has the highest place in the

program heirarchy. The control module calls submodules(segments, component, subroutines...) for simulation and sets the calculation cycle rate for the various submodules.

2.3.2 Segment module

The segment module is comprised of mathematical equations which models the CPC based on the FDR(Functional Design Requirements). The segment module calls on subroutines and component modules for calculating the following functions.

- Coolant Mass Flow Program(FLOW)
- DNBR and Power Density Update Program(UPDATE)
- Power Distribution Program(POWER)
- Static DNBR and Power Density Program(STATIC)
- Trip Sequence Subroutine(TRIPSEQ)
- CEA Penalty Factor Calculation Program(CEAC)

2.3.3 Component

The component modules simulate the control logics of various components in the acutal power plant. The component modules are a type of a subroutine with component level malfunction feature included in them.

2.3.4 Subroutine

The subroutines used for repeated functions. The Subroutines maybe called by control modules, segments, components, and other subroutines.

2.3.5 Functions

The functions maybe called by control modules, segments, components, and other functions. They are used to calculate and return one value.

2.3.6 Block data

The block data is used to store constants which are not actually stroed in the CPC/COLSS program itself. These include constants such as Reload Data Block and Addressable constants.

2.4 COLSS program module

COLSS program being a mounted program is installed separately on a W/S instead of the simulation host computer itself. The COLSS program consists of 5 modules with 20 calculation algorithm written in C programming language.

2.5 CPC/COLSS execution flow

The CPC algorithm is executed by the simulation host computer and the variables calculated are displayed on the operator displays. The communication between the simulation host computer and CPC/COLSS workstations are executed by accessing data from the global memory and sending the information via a Send Server of the communication manager to the receive servers on the workstations.

These data are read by the scan task and updated to the shared memory(CVT). Finally the display task scans the data in the CVT and displays it on the operator display. The COLSS algorithm calculates the various variables from the data stored in the

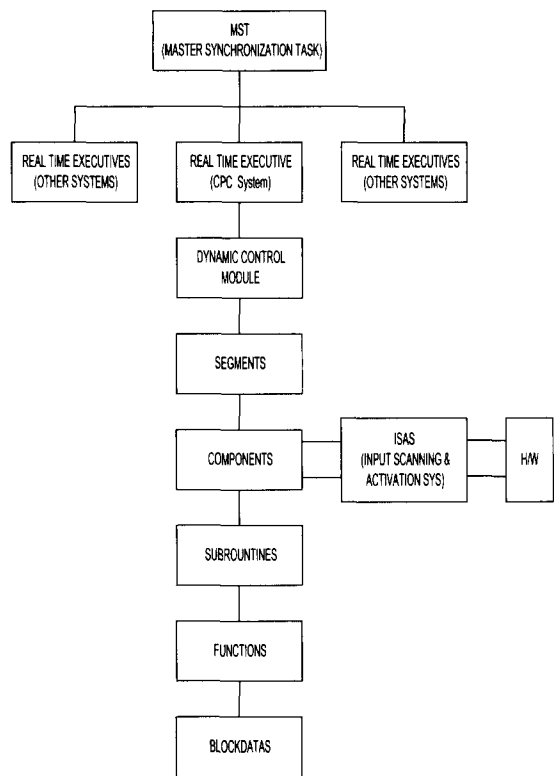


Fig. 2. The configuration of the CPC model program.

workstation CVT. The scan task accesses the CVT and sends the information to the operator display terminal. Figure 3 shows the execution & data flow of the CPC/COLSS model program[8].

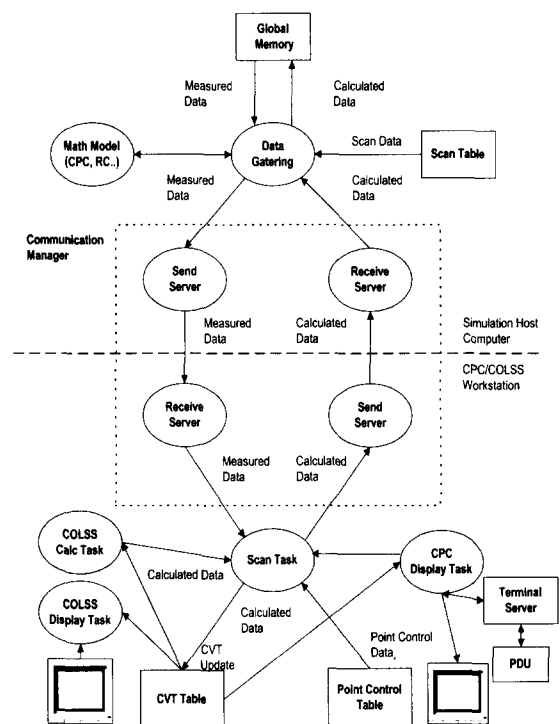


Fig. 3. The execution & data flow of the CPC/COLSS model program.

V. Test, verification and validation(V/V)

Objectives of verification and validation (V/V) of the CPC/COLSS calculation of DNBR and LPD are to verify that the CPC/ COLSS calculated values of DNBR and LPD are consistent with the values calculated by the CPC/COLSS Fortran Code. The V/V of YGN#3,4 simulator CPC/COLSS was performed by comparing the on-line calculated variables(DNBR, LPD...) from the actual plant to those calculated by the simulator model. The data used for V/V was from the data gathered during YGN#3 Start-up Test operation[9][10].

1. CPC simulation model and analysis result

The operation test of the plant is performed at 20%, 50%, 80%, and at 100% full power plant operations. The calculated values for the CPC DNBR, LPD... are compared to those calculated from an identical algorithm off-line called the CEDIPS which is provided by the CPC Vendor for the test of CPC system. CEDIPS accepts the minimum and maximum values of the CPC inputs observed during startup testing as the input. CEDIPS is performed to set up 2⁷ static cases, in which the input data are permuted, and one dynamic case, during which the CPC input signals fluctuate with uniform distributions between the maximum and minimum sensor values provided in the input. the minimum and maximum DNBR and LPD values are produced to support the CPC/COLSS Operability Test[11]. The calculated values for these parameters from the simulator were compared in an identical procedure to that of the actual power plant. The requirement is that the plant and simulator CPC output values should be within the maximum and minimum values calculated by CEDIPS[9]. The second requirement is that the simulator CPC output values should be within ±1% of the plant output values[12]. The values of constants used for the two calculations are from the actual plant database. Table 2,3 and Figure 4,5 show the 20%, 50%, 80%, and at 100% full power plant operations. All of the CPC calculated DNBR and LPD values were bounded by the corresponding CEDIPS ranges of values.

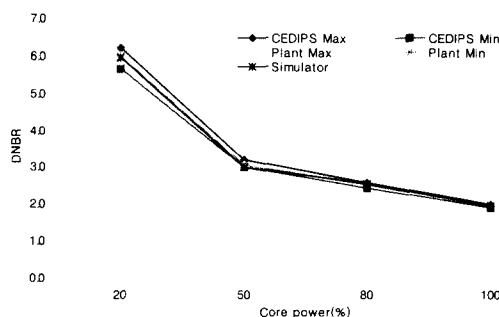


Fig. 4. CEDIPS/plant CPC/simulator CPC comparison of DNBR(for Ch. A).

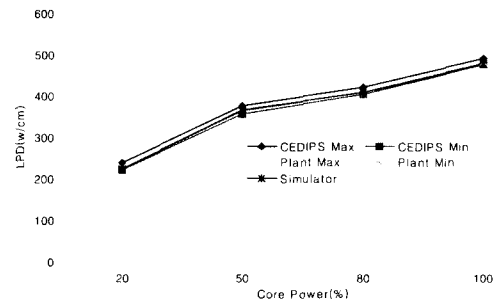


Fig. 5. CEDIPS/plant CPC/simulator CPC comparison of LPD(for Ch. A).

Table 2. CEDIPS/plant CPC/simulator CPC comparison of DNBR(For Channel A).

Power Level	CEDIPS		Plant CPC		Simulator CPC Output
	Maximum	Minimum	Maximum	Minimum	
20%	6.1905	5.6463	6.0325	5.9631	5.93586
50%	3.1937	2.9748	3.0967	3.0552	2.98230
80%	2.5797	2.4219	2.5355	2.5023	2.54811
100%	1.9816	1.8857	1.9632	1.9331	1.95401

Table 3. CEDIPS/plant CPC/simulator CPC comparison of LPD(W/cm)(For Channel A).

Power Level	CEDIPS		Plant CPC		Simulator CPC Output
	Maximum	Minimum	Maximum	Minimum	
20%	239.58	221.78	225.78	225.07	225.82
50%	378.56	358.42	366.55	365.24	367.82
80%	423.47	405.10	410.25	409.42	409.97
100%	491.60	476.80	482.43	480.62	480.97

2. COLSS simulation model and analysis result.

The COLSS operations test is performed by operating the COLSS independently using a test case provided by the vendor. Afterwards the detailed print from the plant is compared to the results from the COLSS verification program called the COLSS FORTRAN simulator. The simulator COLSS was also tested using the identical procedure. Table 4 is the compilation of detailed printout results. Table 5 and 6 are compilation of 40 test case results.

VI. Conclusion

The analysis of the simulator CPC/COLSS output was verified to be within the design performance limit of YGN#3,4 and demonstrates the accuracy of the simulation model developed for the YGN#3,4 simulator.

