

## A NONLINEAR BEAM EQUATION WITH NONLINEARITY CROSSING AN EIGENVALUE

Q-HEUNG CHOI<sup>1</sup> AND HYEWON NAM

ABSTRACT. We investigate the existence of solutions of the nonlinear beam equation under the Dirichlet boundary condition on the interval  $(-\frac{\pi}{2}, \frac{\pi}{2})$  and periodic condition on the variable  $t$ ,  $Lu + bu^+ - au^- = f(x, t)$ , when the jumping nonlinearity crosses the first positive eigenvalue.

### 0. Introduction

In this paper, we investigate multiplicity of solutions  $u(x, t)$  for a piecewise linear perturbation  $-(bu^+ - au^-)$  of the beam operator  $L$  under the Dirichlet boundary condition on the interval  $(-\frac{\pi}{2}, \frac{\pi}{2})$  and periodic condition on the variable  $t$ ,

$$(0.1) \quad \begin{aligned} Lu + bu^+ - au^- &= f(x, t) && \text{in } (-\frac{\pi}{2}, \frac{\pi}{2}) \times \mathbf{R}, \\ u(\pm \frac{\pi}{2}, t) &= u_{xx}(\pm \frac{\pi}{2}, t) = 0, \\ u(x, t) &= u(-x, t) = u(x, -t) = u(x, t + \pi), \end{aligned}$$

where  $L$  denote the beam operator  $Lu = u_{tt} + u_{xxxx}$ . The eigenvalues of  $L$  under the Dirichlet boundary condition and periodic condition on the variable  $t$  are given by  $\lambda_{mn} = (2n + 1)^4 - 4m^2$  ( $m, n = 0, 1, 2, \dots$ ).

Let  $Q$  be the square  $(-\frac{\pi}{2}, \frac{\pi}{2}) \times (-\frac{\pi}{2}, \frac{\pi}{2})$  and  $H$  be the Hilbert space defined by

$$H = \{u \in L^2(Q) \mid u \text{ is even in } x \text{ and } t\}.$$

Then equation (0.1) is represented by

$$(0.2) \quad Lu + bu^+ - au^- = f \quad \text{in } H.$$

---

Received January 27, 1997.

1991 Mathematics Subject Classification: 35B10, 35Q40.

Key words and phrases: eigenvalue, beam equation, multiplicity of solutions.

<sup>1</sup>Research supported in part by Inha Univ. fund and BSRI-96-1436.

In [2,10], Choi and McKenna investigated multiplicity of solutions of a semilinear equation (0.2) when the nonlinearity  $-bu^+$  crosses an eigenvalue  $\lambda_{10}$  and the forcing term  $f$  is supposed to be  $1 + \varepsilon h(\|h\|)$ . In [5], Choi and Jung investigated multiplicity of solutions of a semilinear equation (0.2) when the nonlinearity  $-(bu^+ - au^-)$  crosses two eigenvalues  $\lambda_{00}, \lambda_{10}$  and the source term  $f$  is generated by  $\phi_{00}$  and  $\phi_{10}$ , and when the nonlinearity  $-(bu^+ - au^-)$  crosses an eigenvalue  $\lambda_{10}$  and the source term  $f$  is generated by  $\phi_{00}$  and  $\phi_{10}$ .

Our concern is to investigate multiplicity of solutions of (0.2) when  $-17 < a < -1 < b < 3$  and the source term  $f$  is generated by two eigenfunctions  $\phi_{00}, \phi_{10}$ . In particular, we investigate multiplicity of solutions of (0.2).

In Section 1, we suppose that the nonlinearity  $-(bu^+ - au^-)$  crosses the eigenvalue  $\lambda_{00}$  and the source term  $f$  is generated by  $\phi_{00}$  and  $\phi_{10}$ . And we use the variational reduction method to reduce the problem from an infinite dimensional one to a finite dimensional one. Let  $Q = (-\frac{\pi}{2}, \frac{\pi}{2}) \times (-\frac{\pi}{2}, \frac{\pi}{2})$  and  $V$  be the subspace of  $L^2(Q)$  spanned by  $\phi_{00}$  and  $\phi_{10}$ . Let  $P$  be the orthogonal projection  $L^2(Q)$  onto  $V$ . Then the beam equation (0.1) is reduced to a equation in  $V$ .

In Section 2, we define a map  $\Phi$  by

$$\Phi(v) = Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-), \quad v \in V$$

and we investigate the properties of the map  $\Phi$  and we reveal a relation between multiplicity of solutions and source terms in equation (0.2) when  $f$  belongs to the two-dimensional space  $V$ . We also determine the region of source terms in which (0.2) has no solution.

### 1. A variational reduction method

We consider the beam equation under the Dirichlet boundary condition on the interval  $(-\frac{\pi}{2}, \frac{\pi}{2})$  and periodic condition on the variable  $t$

$$\begin{aligned}
 (1.1) \quad & u_{tt} + u_{xxxx} + bu^+ - au^- = f(x, t) \quad \text{in } (-\frac{\pi}{2}, \frac{\pi}{2}) \times \mathbf{R}, \\
 & u(\pm \frac{\pi}{2}, t) = u_{xx}(\pm \frac{\pi}{2}, t) = 0, \\
 & u(x, t) = u(-x, t) = u(x, -t) = u(x, t + \pi).
 \end{aligned}$$

Here we suppose that  $-\lambda_{41} = -17 < a < -\lambda_{00} = -1 < b < -\lambda_{10} = 3$ .

Let  $L$  be the differential operator  $Lu = u_t + u_{xxxx}$ . Then the eigenvalue problem

$$\begin{aligned}
 (1.2) \quad & Lu = \lambda u \quad \text{in } \left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \times R, \\
 & u\left(\pm\frac{\pi}{2}, t\right) = u_{xx}\left(\pm\frac{\pi}{2}, t\right) = 0, \\
 & u(x, t) = u(-x, t) = u(x, -t) = u(x, t + \pi)
 \end{aligned}$$

has infinitely many eigenvalues  $\lambda_{mn}$  and corresponding eigenfunctions  $\phi_{mn} (m, n \geq 0)$  given by

$$\begin{aligned}
 \lambda_{mn} &= (2n + 1)^4 - 4m^2, \\
 \phi_{mn} &= \cos 2mt \cos(2n + 1)x \quad (m, n = 0, 1, 2, \dots).
 \end{aligned}$$

Let  $Q$  be the square  $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \times \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$  and  $H$  be the Hilbert space defined by

$$H = \{u \in L^2(Q) \mid u \text{ is even in } x \text{ and } t\}.$$

Then the set  $\{\phi_{mn} \mid m, n = 0, 1, 2, \dots\}$  forms an orthogonal set in  $H$ .

Equation (1.1) is equivalent to

$$(1.3) \quad Lu + bu^+ - au^- = f \quad \text{in } H,$$

where we assume that  $f = s_1\phi_{00} + s_2\phi_{10} (s_1, s_2 \in R)$ .

**THEOREM 1.1.** *If  $s_1 < 0$ , then (1.3) has no solution.*

*Proof.* We rewrite (1.3) as

$$(L - \lambda_{00})u + (b + \lambda_{00})u^+ - (a + \lambda_{00})u^- = s_1\phi_{00} + s_2\phi_{10} \quad \text{in } H.$$

Multiply across by  $\phi_{00}$  and integrate over  $Q$ . Since  $L$  is self-adjoint and  $(L - \lambda_{00})\phi_{00} = 0$ ,  $((L - \lambda_{00})u, \phi_{00}) = 0$ . Thus we have

$$\begin{aligned}
 \int_Q \{(b + \lambda_{00})u^+ - (a + \lambda_{00})u^-\} \phi_{00} &= (s_1\phi_{00} + s_2\phi_{10}, \phi_{00}) \\
 &= s_1 \int_Q \phi_{00}^2 \\
 &= \frac{\pi}{2} s_1.
 \end{aligned}$$

We know that  $(b + \lambda_{00})u^+ - (a + \lambda_{00})u^- \geq 0$  for all real valued function  $u$ . Also  $\phi_{00} > 0$  in  $Q$ . Therefore  $\int_Q \{(b + \lambda_{00})u^+ - (a + \lambda_{00})u^-\} \phi_{00} \geq 0$ . Hence there is no solution of (1.3) if  $s_1 < 0$ . □

Let  $V$  be the subspace of  $H$  spanned by  $\{\phi_{00}, \phi_{10}\}$  and  $W$  be the orthogonal complement of  $V$  in  $H$ . Let  $P$  be the orthogonal projection of  $H$  onto  $V$ . Then every  $u \in H$  can be written as  $u = v + w$ , where  $v = Pu$  and  $w = (I - P)u$ . Hence equation (1.3) is equivalent to a system

$$(1.4) \quad Lw + (I - P)(b(v + w)^+ - a(v + w)^-) = 0,$$

$$(1.5) \quad Lv + P(b(v + w)^+ - a(v + w)^-) = s_1\phi_{00} + s_2\phi_{10}.$$

LEMMA 1.2. *For a fixed  $v \in V$ , (1.4) has a unique solution  $w = \theta(v)$ . Furthermore,  $\theta(v)$  is Lipschitz continuous in  $v$ .*

*Proof.* Let  $\delta = \frac{a+b}{2}$ . Rewrite (1.4) as

$$(1.6) \quad (-L - \delta)w = (I - P)(b(v + w)^+ - a(v + w)^- - \delta(v + w)),$$

or equivalently,

$$w = (-L - \delta)^{-1}(I - P)g_v(w),$$

where

$$g_v(w) = b(v + w)^+ - a(v + w)^- - \delta(v + w).$$

Since

$$|g_v(w_1) - g_v(w_2)| \leq \max\{|b - \delta|, |\delta - a|\}|w_1 - w_2|,$$

we have

$$\|g_v(w_1) - g_v(w_2)\| \leq \max\{|b - \delta|, |\delta - a|\}|w_1 - w_2\|.$$

The operator  $(-L - \delta)^{-1}(I - P)$  is a self-adjoint compact linear map from  $W$  into itself. Its eigenvalues in  $W$  are  $(-\lambda_{mn} - \delta)^{-1}$ , where  $\lambda_{mn} \neq 1$ . Therefore its  $L^2$  norm is  $\max\{\frac{1}{| -17 - \delta |}, \frac{1}{| 3 - \delta |}\}$ . Since  $\max\{|b - \delta|, |\delta - a|\} < \min\{| -17 - \delta |, | 3 - \delta | \}$ , for fixed  $v \in V$ , the right hand

side of (1.6) defines a Lipschitz mapping of  $W$  into itself with Lipschitz constant  $\gamma < 1$ .

By the contraction mapping principle, for each  $v \in V$ , there is a unique  $w \in W$  which satisfies (1.4).

By the standard argument principle,  $\theta(v)$  is Lipschitz continuous in  $v$ . □

By Lemma 1.2, the study of the multiplicity of solutions of (1.3) is reduced to that of an equivalent problem

$$(1.7) \quad Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-) = s_1\phi_{00} + s_2\phi_{10}$$

defined on  $V$ .

**PROPOSITION.** *If  $v \geq 0$  or  $v \leq 0$ , then  $\theta(v) = 0$ .*

*Proof.* Let  $v \geq 0$ . Then  $\theta(v) = 0$  and equation (1.4) is reduced to

$$L0 + (I - P)(bv^+ - av^-) = 0$$

because  $v^+ = v, v^- = 0$  and  $(I - P)v = 0$ . Similarly if  $v \leq 0$ , then  $\theta(v) = 0$ . □

Since  $V = span\{\phi_{00}, \phi_{10}\}$  and  $\phi_{00}$  is a positive eigenfunction, there exists a cone  $C_1$  defined by

$$C_1 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_1 \geq 0, |c_2| \leq c_1\}$$

so that  $v \geq 0$  for all  $v \in C_1$ , and a cone  $C_3$  defined by

$$C_3 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_1 \leq 0, |c_2| \leq |c_1|\}$$

so that  $v \leq 0$  for all  $v \in C_3$ . Thus  $\theta(v) \equiv 0$  for  $v \in C_1 \cup C_3$ .

Now we set

$$C_2 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_2 \geq 0, |c_1| \leq c_2\}$$

$$C_4 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_2 \leq 0, |c_1| \leq |c_2|\}.$$

Then the union of  $C_1, C_2, C_3,$  and  $C_4$  is the space  $V$ .

We define a map  $\Phi : V \rightarrow V$  by

$$\Phi(v) = Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-), \quad v \in V.$$

Then  $\Phi$  is continuous on  $V$  and we have the following lemma.

LEMMA 1.3.  $\Phi(cv) = c\Phi(v)$  for  $c \geq 0$  and  $v \in V$ .

*Proof.* Let  $c \geq 0$ . If  $v$  satisfies

$$L\theta(v) + (I - P)(b(v + \theta(v))^+ - a(v + \theta(v))^-) = 0,$$

then

$$L(c\theta(v)) + (I - P)(b(cv + c\theta(v))^+ - a(cv + c\theta(v))^-) = 0$$

and hence  $\theta(cv) = c\theta(v)$ . Therefore

$$\begin{aligned} \Phi(cv) &= L(cv) + P(b(cv + \theta(cv))^+ - a(cv + \theta(cv))^-) \\ &= L(cv) + P(b(cv + c\theta(v))^+ - a(cv + c\theta(v))^-) \\ &= c\Phi(v) \end{aligned}$$

□

We investigate the image of the cones  $C_1, C_3$  under  $\Phi$ .

First, we consider the image of  $C_1$ . If  $v = c_1\phi_{00} + c_2\phi_{10} \geq 0$ ,

$$\begin{aligned} \Phi(v) &= Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-) \\ &= c_1\phi_{00} - 3c_2\phi_{10} + b(c_1\phi_{00} + c_2\phi_{10}) \\ &= (b + 1)c_1\phi_{00} + (b - 3)c_2\phi_{10}. \end{aligned}$$

Thus images of the rays  $c_1\phi_{00} \pm c_1\phi_{10} (c_1 \geq 0)$  are

$$(b + 1)c_1\phi_{00} + (b - 3)c_1\phi_{10} \quad (c_1 \geq 0).$$

Therefore  $\Phi$  maps  $C_1$  onto the cone

$$R_1 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, |d_2| \leq \frac{-b + 3}{b + 1} d_1 \right\}.$$

Second, we consider the image of  $C_3$ . If  $v = -c_1\phi_{00} + c_2\phi_{10} \leq 0 (c_1 \geq 0, |c_2| \leq c_1)$ ,

$$\begin{aligned} \Phi(v) &= Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-) \\ &= -c_1\phi_{00} - 3c_2\phi_{10} + a(-c_1\phi_{00} + c_2\phi_{10}) \\ &= (-a - 1)c_1\phi_{00} + (a - 3)c_2\phi_{10}. \end{aligned}$$

Thus images of the rays  $-c_1\phi_{00} \pm c_1\phi_{10}$  ( $c_1 \geq 0$ ) are

$$(-a - 1)c_1\phi_{00} \pm (a - 3)c_1\phi_{10} \quad (c_1 \geq 0).$$

Therefore  $\Phi$  maps  $C_3$  onto the cone

$$R_3 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, |d_2| \leq \frac{a-3}{a+1}d_1 \right\}.$$

We have three cases  $R_1 \subsetneq R_3, R_3 \subsetneq R_1$ , and  $R_1 = R_3$ . The relation  $R_1 \subsetneq R_3$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b > \frac{a+3}{a-1}$ . The relation  $R_3 \subsetneq R_1$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b < \frac{a+3}{a-1}$ . The relation  $R_1 = R_3$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b = \frac{a+3}{a-1}$ .

### 2. Multiplicity results

We consider the restrictions  $\Phi|_{C_i}$  ( $1 \leq i \leq 4$ ) of  $\Phi$  to the cones  $C_i$ . Let  $\Phi_i = \Phi|_{C_i}$ , i.e.,  $\Phi_i : C_i \rightarrow V$ .

First, we consider  $\Phi_1$ . It maps  $C_1$  onto  $R_1$ . Let  $l_1$  be the segment defined by

$$l_1 = \left\{ \phi_{00} + d_2\phi_{10} \mid |d_2| \leq \frac{-b-3}{b+1} \right\}.$$

Then the inverse image  $\Phi_1^{-1}(l_1)$  is the segment

$$L_1 = \left\{ \frac{1}{b+1}(\phi_{00} + c_2\phi_{10}) \mid |c_2| \leq 1 \right\}.$$

By Lemma 1.3,  $\Phi_1 : C_1 \rightarrow R_1$  is bijective.

Second, we consider  $\Phi_3$ . It maps  $C_3$  onto  $R_3$ . Let  $l_3$  be the segment defined by

$$l_3 = \left\{ \phi_{00} + d_2\phi_{10} \mid |d_2| \leq \frac{a-3}{a+1} \right\}.$$

Then the inverse image  $\Phi_3^{-1}(l_3)$  is the segment

$$L_3 = \left\{ \frac{1}{a+1}(\phi_{00} + c_2\phi_{10}) \mid |c_2| \leq 1 \right\}.$$

By Lemma 1.3,  $\Phi_3 : C_3 \rightarrow R_3$  is bijective.

**2.1 The nonlinearity  $-(bu^+ - au^-)$  satisfies  $b > \frac{a+3}{a-1}$**

The relation  $R_1 \subsetneq R_3$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b > \frac{a+3}{a-1}$ . We investigate the images of the cones  $C_2, C_4$  under  $\Phi$ , where

$$C_2 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_2 \geq 0, |c_1| \leq c_2\},$$

$$C_4 = \{v = c_1\phi_{00} + c_2\phi_{10} \mid c_2 \leq 0, |c_1| \leq |c_2|\}.$$

By Theorem 1.1 and Lemma 1.2, the image of  $C_2$  under  $\Phi$  is a cone containing

$$R_2 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, \frac{-a+3}{a+1}d_1 \leq d_2 \leq \frac{b-3}{b+1}d_1 \right\}$$

and the image of  $C_4$  under  $\Phi$  is a cone containing

$$R_4 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, \frac{-b+3}{b+1}d_1 \leq d_2 \leq \frac{a-3}{a+1}d_1 \right\}.$$

We consider the restrictions  $\Phi_2$  and  $\Phi_4$ . Define the segments  $l_2, l_4$  as follows;

$$l_2 = \left\{ \phi_{00} + d_2\phi_{10} \mid \frac{-a+3}{a+1} \leq d_2 \leq \frac{b-3}{b+1} \right\},$$

$$l_4 = \left\{ \phi_{00} + d_2\phi_{10} \mid \frac{-b+3}{b+1} \leq d_2 \leq \frac{a-3}{a+1} \right\}.$$

We investigate the inverse images  $\Phi_2^{-1}(l_2)$  and  $\Phi_4^{-1}(l_4)$ . We note that  $\Phi_i(C_i)$  contains  $R_i$ , for  $i = 2, 4$ , respectively.

**LEMMA 2.1.1.** *For  $i = 2, 4$ , let  $\gamma$  be any simple path in  $R_i$  with end points on  $\partial R_i$ , where each ray in  $R_i$  (starting from the origin) intersects only one point of  $\gamma$ . Then the inverse image  $\Phi_i^{-1}(\gamma)$  of  $\gamma$  is also a simple path in  $C_i$  with end points on  $\partial C_i$ , where any ray in  $C_i$  (starting from the origin) intersects only one point of this path.*



*Proof.* Since  $\Phi$  is continuous and  $\gamma$  is closed in  $V$ ,  $\Phi_i^{-1}(\gamma)$  is closed. Suppose that there is a ray (starting from the origin) in  $C_i$ , which intersects two points of  $\Phi_i^{-1}(\gamma)$ , say  $p$  and  $\alpha p$  ( $\alpha > 1$ ). Then  $\Phi(\alpha p) = \alpha \Phi(p)$ , which implies  $\Phi(p) \in \gamma$  and  $\Phi(\alpha p) \in \gamma$ . This contradicts the assumption that each ray (starting from the origin) in  $C_i$  intersects only one point of  $\gamma$ .

We regard a point  $p \in V$  as a radius vector in the plan  $V$ . Define the argument  $\arg p$  to be the angle from the positive  $\phi_{00}$ -axis to  $p$ .

We claim that  $\Phi_i^{-1}(\gamma)$  meets all the rays (starting from the origin) in  $C_i$ . If not,  $\Phi_i^{-1}(\gamma)$  is disconnected in  $C_i$ . Since  $\Phi_i^{-1}(\gamma)$  is closed and meets at most one point of any ray in  $C_i$ , there are two points  $p_1$  and  $p_2$  in  $C_i$  such that  $\Phi_i^{-1}(\gamma)$  does not contain a point  $p \in C_i$  with  $\arg p_1 < \arg p < \arg p_2$ . Let  $l$  be the segment with end points  $p_1$  and  $p_2$  then  $\Phi_i(l)$  is a path in  $R_i$ , where  $\Phi_i(p_1)$  and  $\Phi_i(p_2)$  belong to  $\gamma$ . Choose a point  $q \in \Phi_i(l)$  such that  $\arg q$  is between  $\arg \Phi_i(p_1)$  and  $\arg \Phi_i(p_2)$ . Then there exist a point  $q'$  of  $\gamma$  such that  $q' = \beta q$  for some  $\beta > 0$ . Hence  $\Phi_i^{-1}(q)$  and  $\Phi_i^{-1}(q')$  are on the same ray (starting from the origin) in  $C_i$  and  $\arg p_1 < \arg \Phi_i^{-1}(q') < \arg p_2$ , which is a contradiction. This completes the proof.  $\square$

Lemma 2.1.1 implies that  $\Phi_i$  ( $i = 2, 4$ ) is surjective. Hence we have the following theorem.

**THEOREM 2.1.2.** *For  $1 \leq i \leq 4$ , the restriction  $\Phi_i$  maps  $C_i$  onto  $R_i$ . Therefore,  $\Phi$  maps  $V$  onto  $R_3$ . In particular,  $\Phi_1$  and  $\Phi_3$  are bijective.*

The above theorem also implies the following result.

**THEOREM 2.1.3.** *Suppose  $-17 < a < -1 < b < 3$  and  $b > \frac{a+3}{a-1}$ . Let  $f = s_1\phi_{00} + s_2\phi_{10} \in V$ . Then we have :*

- (1) *If  $f \in \text{Int}R$ , then (1.3) has exactly two solutions, one of which is positive and the other the other is negative.*
- (2) *If  $f \in \text{Int}R_2 \cup \text{Int}R_4$ , then (1.3) has a negative solution and at least one sign changing solution.*
- (3) *If  $f \in \partial R_3$ , then (1.3) has a negative solution.*
- (4) *If  $f \in R_3^c$ , then (1.3) has no solution.*

**2.2 The nonlinearity  $-(bu^+ - au^-)$  satisfies  $b < \frac{a+3}{a-1}$**

The relation  $R_3 \subsetneq R_1$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b < \frac{a+3}{a-1}$ . We investigate the images of the cones  $C_2, C_4$  under  $\Phi$ . By Theorem 1.1 and Lemma 1.2, the image of  $C_2$  under  $\Phi$  is a cone containing

$$R_2' = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, \frac{b-3}{b+1}d_1 \leq d_2 \leq \frac{-a+3}{a+1}d_1 \right\}$$

and the image of  $C_4$  under  $\Phi$  is a cone containing

$$R_4' = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, \frac{a-3}{a+1}d_1 \leq d_2 \leq \frac{-b+3}{b+1}d_1 \right\}$$

We consider the restrictions  $\Phi_2$  and  $\Phi_4$ . Define the segments  $l_2', l_4'$  as follows;

$$l_2' = \left\{ \phi_{00} + d_2\phi_{10} \mid \frac{b-3}{b+1} \leq d_2 \leq \frac{-a+3}{a+1} \right\}$$

$$l_4' = \left\{ \phi_{00} + d_2\phi_{10} \mid \frac{a-3}{a+1} \leq d_2 \leq \frac{-b+3}{b+1} \right\}$$

We investigate the inverse images  $\Phi_2^{-1}(l_2')$  and  $\Phi_4^{-1}(l_4')$ . We note that  $\Phi_i(C_i)(i = 2, 4)$  contains  $R_i'(i = 2, 4)$ .

LEMMA 2.2.1. *For  $i = 2, 4$ , let  $\gamma'$  be any simple path in  $R_i'$  with end points on  $\partial R_i'$ , where each ray in  $R_i'$  (starting from the origin) intersects only one point of  $\gamma'$ . Then the inverse image  $\Phi_i^{-1}(\gamma')$  of  $\gamma'$  is also a simple path in  $C_i$  with end points on  $\partial C_i$ , where any ray in  $C_i$  (starting from the origin) intersects only one point of this path.*

*Proof.* The proof is similar to the proof given in Lemma 2.1.1. □

Lemma 2.2.1 implies that  $\Phi_i(i = 2, 4)$  is surjective. Hence we have the following theorem.

THEOREM 2.2.2. *For  $i = 2, 4$ , the restriction  $\Phi_i$  maps  $C_i$  onto  $R_i'$ . And  $\Phi_1$  and  $\Phi_3$  are bijective. Therefore,  $\Phi$  maps  $V$  onto  $R_1$ .*

Above the theorem also implies the following results.

**THEOREM 2.2.3.** *Suppose  $-17 < a < -1 < b < 3$  and  $b < \frac{a+3}{a-1}$ . Let  $f = s_1\phi_{00} + s_2\phi_{10} \in V$ . Then we have :*

- (1) *If  $f \in \text{Int}R$ , then (1.3) has exactly two solutions, one of which is positive and the other the other is negative.*
- (2) *If  $f \in \text{Int}R_2' \cup \text{Int}R_4'$ , then (1.3) has a positive solution and at least one sign changing solution.*
- (3) *If  $f \in \partial R_1$ , then (1.3) has a positive solution.*
- (4) *If  $f \in R_1^c$ , then (1.3) has no solution.*

**2.3 The nonlinearity  $-(bu^+ - au^-)$  satisfies  $b = \frac{a+3}{a-1}$**

The relation  $R_1 = R_3$  holds if and only if the nonlinearity  $-(bu^+ - au^-)$  satisfies  $b = \frac{a+3}{a-1}$ .

We considered the map  $\Phi : V \rightarrow V$  defined by

$$\Phi(v) = Lv + P(b(v + \theta(v))^+ - a(v + \theta(v))^-), \quad v \in V,$$

where  $-17 < a < -1 < b < 3$  and  $b = \frac{a+3}{a-1}$ .

We investigate the images of  $C_2$  and  $C_4$  under  $\Phi$ . For fixed  $v$ , we define a map  $\Phi_v : (-1, 3) \rightarrow V$  as follows

$$\Phi_v(b) = Lv + P(b(v + w)^+ - a(v + w)^-), \quad b \in (-1, 3),$$

where  $v \in V$  and  $a$  are fixed.

**LEMMA 2.3.1.**  *$\Phi_v$  is continuous at  $b_0 = \frac{a+3}{a-1}$ , where  $-17 < a < -1 < b_0 < 3$  and  $a$  is fixed.*

*Proof.* Let  $\delta = \frac{a+b_0}{2}$  and  $-1 < b < 3$ . Rewrite (1.4) as

$$(2.3.1) \quad (-L - \delta)w = (I - P)(b(v + w)^+ - a(v + w)^- - \delta(v + w)),$$

or equivalently,

$$(2.3.2) \quad w = (-L - \delta)^{-1}(I - P)h(b, u),$$

where

$$h(b, w) = b(v + w)^+ - a(v + w)^- - \delta(v + w).$$

By Lemma 1.2, (2.3.2) has a unique solution  $w = \theta_b(v)$  for fixed  $b$  with  $-1 < b < 3$ . Let  $w_0 = \theta_{b_0}(v)$ . Then we have

$$\begin{aligned} w - w_0 &= (-L - \delta)^{-1}(I - P)[h(b, w) - h(b_0, w_0)] \\ &= (-L - \delta)^{-1}(I - P)[h(b, w) - h(b, w_0)] \\ &\quad + (-L - \delta)^{-1}(I - P)[h(b, w_0) - h(b_0, w_0)]. \end{aligned}$$

Since

$$\|h(b, w) - h(b, w_0)\| \leq \max\{|b - \delta|, |\delta - a|\} \|w - w_0\|$$

and

$$\gamma = \max\left\{\frac{1}{|-17 - \delta|}, \frac{1}{|3 - \delta|}\right\} \max\{|b - \delta|, |\delta - a|\} < 1,$$

we have

$$\|w - w_0\| \leq \gamma \|w - w_0\| + \max\left\{\frac{1}{|-17 - \delta|}, \frac{1}{|3 - \delta|}\right\} \|v + w_0\| |b - b_0|.$$

Hence

$$\|w - w_0\| \leq \max\left\{\frac{1}{|-17 - \delta|}, \frac{1}{|3 - \delta|}\right\} \frac{\|v + w_0\|}{(1 - \gamma)} |b - b_0|,$$

which shows that  $\theta_b(v)$  is continuous at  $b_0 = \frac{a+3}{a-1}$ . Therefore  $\Phi_v(b)$  is continuous at  $b_0 = \frac{a+3}{a-1}$ .  $\square$

First, we investigate the images of the cones  $C_2$  under  $\Phi$ . Let  $p_1 = \phi_{00} + \frac{-a+3}{a+1}\phi_{10}$  and  $p_2 = \phi_{00} + \frac{b-3}{b+1}\phi_{10}$ . We fix  $a$ . Define

$$\theta = \begin{cases} \arg p_1 - \arg p_2, & \text{if } b > \frac{a+3}{a-1}; \\ \arg p_2 - \arg p_1, & \text{if } b < \frac{a+3}{a-1}. \end{cases}$$

Then  $0 \leq \theta \leq \frac{\pi}{2}$  and

$$\tan \theta = \frac{|-ab + a + b + 3|}{-2a - 2b + 4}.$$

When  $b$  converges to  $\frac{a+3}{a-1}$ ,  $\tan \theta$  converges to 0. Then  $\theta$  converges to 0 since  $0 \leq \theta \leq \frac{\pi}{2}$ . We note that  $\Phi_2$  maps  $C_2$  onto  $R_2$  when  $b > \frac{a+3}{a-1}$  and that  $\Phi_2$  maps  $C_2$  onto  $R_2'$  when  $b < \frac{a+3}{a-1}$ . When  $b$  converges to  $\frac{a+3}{a-1}$ , the angle of two lines consisting  $\partial R_2$  or  $\partial R_2'$  converges to 0. Since  $\Phi_2$  is continuous at  $\frac{a+3}{a-1}$ ,  $\Phi_2$  maps  $C_2$  onto the ray

$$S_2 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, d_2 = \frac{b-3}{b+1}d_1 \right\}$$

when  $b = \frac{a+3}{a-1}$ .

Second, we investigate the images of the cones  $C_4$  under  $\Phi$ .

Let  $q_1 = \phi_{00} + \frac{a-3}{a+1}\phi_{10}$  and  $q_2 = \phi_{00} + \frac{-b+3}{b+1}\phi_{10}$ . We fix  $a$ . Define

$$\theta' = \begin{cases} \arg q_1 - \arg q_2, & \text{if } b > \frac{a+3}{a-1}; \\ \arg q_2 - \arg q_1, & \text{if } b < \frac{a+3}{a-1}. \end{cases}$$

Then  $0 \leq \theta' \leq \frac{\pi}{2}$  and

$$\tan \theta' = \frac{|-ab + a + b + 3|}{-2a - 2b + 4}.$$

When  $b$  converges to  $\frac{a+3}{a-1}$ ,  $\tan \theta'$  converges to 0. Then  $\theta'$  converges to 0, since  $0 \leq \theta' \leq \frac{\pi}{2}$ . We note that  $\Phi_4$  maps  $C_4$  onto  $R_4$  when  $b > \frac{a+3}{a-1}$  and that  $\Phi_4$  maps  $C_4$  onto  $R_4'$  when  $b < \frac{a+3}{a-1}$ . When  $b$  converges to  $\frac{a+3}{a-1}$ , the angle of two lines consisting  $\partial R_4$  or  $\partial R_4'$  converges to 0. Since  $\Phi_4$  is continuous at  $\frac{a+3}{a-1}$ ,  $\Phi_4$  maps  $C_4$  onto the ray

$$S_4 = \left\{ d_1\phi_{00} + d_2\phi_{10} \mid d_1 \geq 0, d_2 = \frac{-b+3}{b+1}d_1 \right\}$$

when  $b = \frac{a+3}{a-1}$ .

Hence we have the following theorem.

**THEOREM 2.3.2.** *For  $i = 2, 4$ , the restriction  $\Phi_i$  maps  $C_i$  onto  $S_i$ . And  $\Phi_1$  and  $\Phi_3$  are bijective. Therefore,  $\Phi$  maps  $V$  onto  $R$ , where  $R = R_1 = R_3$ .*

The above theorem also implies the following result.

**THEOREM 2.3.3.** Suppose  $-17 < a < -1 < b < 3$  and  $b = \frac{a+3}{a-1}$ . Let  $f = s_1\phi_{00} + s_2\phi_{10} \in V$ . Then we have :

- (1) If  $f \in \text{Int}R$ , then (1.3) has exactly two solutions, one of which is positive and the other the other is negative.
- (2) If  $f \in \partial R$ , then (1.3) has a positive solution, a negative solution, and infinitely many sign changing solutions.
- (3) If  $f \in R^c$ , then (1.3) has no solution.

## References

- [1] A. Ambrosetti and G. Prodi, *A primer of nonlinear analysis*, vol. **34**, Cambridge, University Press, Cambridge Studies in Advanced Math., 1993.
- [2] Q. H. Choi, T. S. Jung and P. J. McKenna, *The study of a nonlinear suspension bridge equation by a variational reduction method*, *Applicable Analysis* **50** (1993), 73-92.
- [3] Q. H. Choi and T. S. Jung, *An application of a variational reduction method to a nonlinear wave equation*, *J. Differential Equations* **117** (1995), 390-410.
- [4] Q. H. Choi and T. S. Jung, *Multiplicity of solutions of nonlinear wave equations with nonlinearities crossing eigenvalues*, *Hokkaido Math. J.* **24** (1995), 53-62.
- [5] Q. H. Choi and T. S. Jung, *Multiplicity of solutions and source terms in a semilinear beam equation*, Preprint.
- [6] K. Hoffman and R. Kunze, *Linear Algebra*, Prentice-Hall., Inc., 1971.
- [7] E. Kreyszig, *Introductory Functional Analysis with Applications*, John Wiley and Sons Inc., 1978.
- [8] A. C. Lazer and P. J. McKenna, *A symmetry theorem and applications to nonlinear partial differential equations*, *J. Differential Equations* **72** (1988), 95-106.
- [9] J. E. Marsden and M. J. Horrmann, *Elementary classical analysis*, W. H. Freeman and Company, 1993.
- [10] P. J. McKenna and W. Walter, *Nonlinear Oscillations in a Suspension Bridge*, *Archive for Rational Mechanics and Analysis* **98** (1987), 167-177.
- [11] B. Narici, *Functional Analysis*, Academic Press., Inc., 1996.
- [12] W. Rudin, *Functional Analysis*, McGraw-Hill Book Co., 1991.
- [13] J. Schröder, *Operator Inequalities*, Academic Press, New York, 1980.
- [14] L. A. Segel and G. H. Handelman, *Mathematics to Applied to Continuum Mechanics*, Macmillan Publishing Co., Inc., New York, 1977.

Department of Mathematics  
Inha university  
Incheon 402-751, Korea