

ABSTRACT FUNCTIONAL DIFFERENTIAL EQUATIONS IN BANACH SPACES

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ABSTRACT. The existence of a unique local generalized solution for the abstract functional evolution problem of the type

$$(\text{FDE}:\phi) \quad x'(t) + A(t, x_t)x(t) \ni G(t, x_t), \quad t \in [0, T], \quad x_0 = \phi$$

in a general Banach spaces is considered. It is shown that (FDE: ϕ) could be considered with well-known fixed point theory and recent results for the functional differential equations involving the operator $A(t)$.

1. Introduction and preliminaries

Let X be a real Banach space with norm $\|\cdot\|$. We let C denote the space of all continuous functions $f : [-r, 0] \rightarrow X$ for a fixed $r > 0$. For $f \in C$, $\|f\|_C = \sup_{-r \leq s \leq 0} \|f(s)\|$.

We consider the abstract nonlinear functional differential equation of the type

$$(\text{FDE} : \phi) \quad \begin{aligned} x'(t) + A(t, x_t)x(t) &\ni G(t, x_t), & t \in [0, T], \\ x_0 = \phi, & & -r \leq t \leq 0 \end{aligned}$$

in a general Banach space, where for a function $f : [-r, T] \rightarrow X$, $f_t(s) = f(t + s)$, $t \in [0, T]$, $s \in [-r, 0]$ with a positive constant T .

An operator $A : D \subset X \rightarrow 2^X$ is called “accretive” if

$$\|x_1 - x_2\| \leq \|x_1 - x_2 + \lambda(y_1 - y_2)\|$$

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for every $\lambda > 0$ and every $[x_1, y_1], [x_2, y_2] \in A$. It is called “ m -accretive” if it is accretive and $R(I + \lambda A) = X$ for all $\lambda > 0$. If A is m -accretive, we set

$$|Ax| = \lim_{\lambda \downarrow 0} \|A_\lambda x\|, \quad x \in X,$$

where $A_\lambda = (I - J_\lambda)/\lambda$ with $J_\lambda = (I + \lambda A)^{-1}$. We also set

$$\hat{D} = \{x \in X : |Ax| < \infty\}.$$

It is known that $D(A) \subset \hat{D}(A) \subset \overline{D(A)}$. For other properties of these operators, the reader is referred to Barbu [1], Crandall [2], Crandall and Pazy [3] and Evans [4].

Tanaka [12] has recently obtained the existence of a unique limit solution of the abstract nonlinear functional evolution equation of the type

$$x'(t) + A(t)x(t) \ni G(t, x_t), \quad t \in [0, T], \quad x_0 = \phi$$

in a general Banach space by constructing the “lines” which satisfy certain approximate discrete scheme. The solution is obtained from the uniform limit of the “lines”. Kartsatos and Parrott [10] also have the similar results with different method. For the operator $A(t, x_t)$, Kartsatos and Parrott [8], Kartsatos [7] have studied by use of fixed point theory and Crandall and Pazy’s result [3].

The following conditions will be used in the sequel.

(A.1) For each $(t, \psi) \in [0, T] \times C$, $A(t, \psi) : D(A(t, \psi)) \subset X \rightarrow 2^X$ is m -accretive in X , where $D(A(t, \psi))$ is only dependent on t . We denote $D(A(t, \psi)) = D(t)$.

(A.2) For each $t, s \in [0, T]$, $\psi_1, \psi_2 \in C$, and $v \in X$,

$$\begin{aligned} & \|A_\lambda(t, \psi_1)v - A_\lambda(s, \psi_2)v\| \\ & \leq L_0(\|v\|)[|t - s|(1 + \|A_\lambda(s, \psi_2)v\|) + \|\psi_1 - \psi_2\|_C] \end{aligned}$$

where $L_0 : \mathcal{R}^+ \rightarrow \mathcal{R}^+ = [0, \infty)$ is increasing, continuous function.

(A.3) For $t, s \in [0, T]$, and $\psi, \psi_1, \psi_2 \in C$,

$$\begin{aligned} \|G(t, \psi_1) - G(t, \psi_2)\| & \leq k_1 \|\psi_1 - \psi_2\|_C, \\ \|G(t, \psi) - G(s, \psi)\| & \leq L_1(\|\psi\|_C)|t - s|, \end{aligned}$$

where k_1 is a positive constant and $L_1 : \mathcal{R}^+ \rightarrow \mathcal{R}^+$ is nondecreasing, continuous function.

(A.4) ϕ is a given Lipschitz function with Lipschitz constant k_0 on $[-r, 0]$.

By virtue of (A.2), it is known that $\hat{D}(A(t, \psi))$ is independent of $(t, \psi) \in [0, T] \times C$. (See Evans [4].) We denote by $\hat{D} \equiv \hat{D}(A(t, \psi))$.

The main purpose of this paper is to obtain a “generalized solution” of (FDE: ϕ) with more simple method. When the functional term in A and G is fixed, (FDE: ϕ) is converted a very well known evolution problem. Then we employ the Banach contraction principle to get a local generalized solution.

We define a set E by

$$E = \{u : [-r, T] \rightarrow X \mid u(t) \text{ is continuous, } u(t) = \phi(t) \text{ for } t \in [-r, 0] \text{ and } \|u(t_1) - u(t_2)\| \leq M|t_1 - t_2| \text{ for } t_1, t_2 \in [0, T]\},$$

where $M \geq k_0$ is a constant. Clearly, $E \neq \phi$ since the function $u(t)$ defined by $u(t) = \phi(t)$ for $t \in [-r, 0]$, and $u(t) = \phi(0)$ for $t \in [0, T]$ belongs to E . Moreover, the set E is a Banach space with supremum norm. (cf. Ha, Shin and Jin [6]).

2. Main results

In the following discussion, we assume that the hypotheses (A.1)–(A.4) hold and $\phi(0) \in \hat{D}$. Let $u \in E$ be arbitrary but fixed. We shall first consider a more simple evolution problem which is converted from (FDE: ϕ) by employing the above $u \in E$.

By fixing the functional term with u , we consider (EE: ϕ, u) from (FDE: ϕ) by the type of

$$\begin{aligned} \text{(EE : } \phi, u) \quad & x'(t) + A(t, u_t)x(t) \ni G(t, u_t), \quad t \in [0, T], \\ & x_0 = \phi(0). \end{aligned}$$

For the simplicity, we put $B(t) \equiv A(t, u_t)$ and $g(t) \equiv G(t, u_t)$ for $t \in [0, T]$. Then our hypotheses (A.1)–(A.4) are converted as follows.

(B.1) For each $t \in [0, T]$, $B(t) : D(t) \subset X \rightarrow 2^X$ is m -accretive.

(B.2) For each $t, s \in [0, T]$ and $v \in X$,

$$\begin{aligned} \|B_\lambda(t)v - B_\lambda(s)v\| &\leq L_0(\|v\|)|t - s|(1 + M)(1 + \|B_\lambda(s)v\|) \\ &\equiv \tilde{L}_0(\|v\|)|t - s|(1 + \|B_\lambda(s)v\|) \end{aligned}$$

where $\tilde{L}_0 : \mathcal{R}^+ \rightarrow \mathcal{R}^+$ is again nondecreasing continuous function with $\tilde{L}_0(p) = (1 + M)L_0(p)$ and $B_\lambda(t)$ is the Yosida approximation of $B(t)$.

(B.3) For $t, s \in [0, T]$

$$\begin{aligned} \|g(t) - g(s)\| &\leq \|G(t, u_t) - G(t, u_s)\| + \|G(t, u_s) - G(s, u_s)\| \\ &\leq k_1\|u_t - u_s\|_C + L_1(\|u_s\|_C)|t - s| \\ &\leq (k_1M + L_1(\|u_s\|_C))|t - s| \\ &\leq (k_1M + L_1(\|\phi\|_C + MT))|t - s| \\ &\equiv \tilde{L}_1|t - s| \end{aligned}$$

where \tilde{L}_1 is a constant.

By (B.1)–(B.3), it is easy to show that there exist constants $C_1 = C_1(\phi)$ and $C_2 = C_2(\phi)$ such that for $t \in [0, T]$

$$|B(t)\phi(0)| = |A(t, u_t)\phi(0)| \leq C_1, \quad \|g(t)\| = \|G(t, u_t)\| \leq C_2.$$

Let $\{t_j^n\}_{j=0}^n$ be a partition of the interval $[0, T]$ for fixed n , where $t_j^n = jT/n$, $j = 0, 1, \dots, n$. And we let $g_j^n = g(t_j^n)$. When we put $x_0^n = \phi(0)$, we construct a sequence $\{x_j^n\}_{j=0}^n$ of elements of X satisfying

$$\frac{x_j^n - x_{j-1}^n}{t_j^n - t_{j-1}^n} + B(t_j^n)x_j^n \ni g_j^n, \quad j = 1, 2, \dots, n$$

by m -accretiveness of B . The step function

$$x_n(t) = \begin{cases} x_0^n, & t = 0, \\ x_j^n, & t \in (t_{j-1}^n, t_j^n], \quad j = 1, 2, \dots, n \end{cases}$$

is called an approximate solution of (EE: ϕ, u). If the approximate solution converge to some continuous function uniformly on $[0, T]$, we call it the limit solution of (EE: ϕ, u) on $[0, T]$.

Since the conditions (B.1)–(B.3) satisfy the conditions (A) and (C.2) in Theorem 2 of Evans [4], we follow the steps to get constants $R_1 = R_1(\phi)$, $R_2 = R_2(\phi)$ satisfying

$$\sup_n \left\{ \max_{0 \leq j \leq n} \|x_j^n\| \right\} \leq R_1, \text{ and } \sup_n \left\{ \max_{0 \leq j \leq n} \frac{\|x_j^n - x_{j-1}^n\|}{t_j^n - t_{j-1}^n} \right\} \leq R_2$$

for $\phi(0) \in \hat{D}$. Therefore, by similar method of Evans [4], we have constant $K = 2R_2$ to show that

$$\|x_n(t) - x_n(s)\| \leq K(|t - s| + T/n)$$

for sufficiently large n . Consequently, in considering (EE: ϕ, u) for fixed $u \in E$, we note that our hypotheses (B.1)–(B.3) implies there exist a limit solution $x_u(t)$ which is converged from approximate solutions $x_n(t)$ uniformly on $[0, T]$. More precisely, we have the following theorem.

THEOREM 1. (Evans [4]) *Let (A.1)–(A.4) hold and $\phi(0) \in \hat{D}$. Then there exist a limit solution $x_u(t)$ of (EE: ϕ, u) on $[0, T]$ for fixed $u \in E$. Moreover, x_u is Lipschitz continuous with Lipschitz constant K on $[0, T]$.*

Now we show the relation between the limit solutions of (EE: ϕ, u) and (EE: ϕ, v) for $u, v \in E$. Using this, we have the existence of a limit solution for (EE: ϕ) by the Banach contraction principle.

THEOREM 2. *Let $x_u(t)$ and $y_v(t)$ be the limit solutions of (EE: ϕ, u) and (EE: ϕ, v) in Theorem 1, respectively. Then there exists a constant C_4 such that*

$$\begin{aligned} \|x_u(t) - y_v(t)\| &\leq \|x_u(\tau) - y_v(\tau)\| + C_4 T \|u - v\|_\infty \\ &\quad + \int_\tau^t [x_u(\eta) - y_v(\eta), G(\eta, (x_u)_\eta) - G(\eta, (y_v)_\eta)]_+ d\eta \end{aligned}$$

for $0 \leq \tau \leq t \leq T$.

Proof. Let x_u, y_v be the limit solutions of $(EE:\phi,u), (EE:\phi,v)$, respectively. By the definition of the limit solution of $(EE:\phi,u)$, there exists an approximate solution $x_n(t)$ such that

$$(2.1) \quad \frac{x_j^n - x_{j-1}^n}{h_n} + A(t_j^n, u_{t_j^n})x_j^n \ni G(t_j^n, u_{t_j^n}),$$

$x_n(0) = x_0^n = \phi(0)$ and $x_n(t) = x_k^n, t \in (t_{j-1}^n, t_j^n], j = 1, 2, \dots, n$, where $h_n = t_j^n - t_{j-1}^n$. Also, there exists an approximate solution $y_m(t)$ such that

$$(2.2) \quad \frac{y_k^m - y_{k-1}^m}{\hat{h}_m} + A(s_k^m, v_{s_k^m})y_k^m \ni G(s_k^m, v_{s_k^m}),$$

$y_m(0) = y_0^m = \phi(0)$ and $y_m(t) = y_k^m, t \in (s_{k-1}^m, s_k^m], k = 1, 2, \dots, m$, where $\hat{h}_m = s_k^m - s_{k-1}^m$. Let $\delta \in (0, T/2)$ and assume that n and m are sufficiently large such that $\max(h_n, \hat{h}_m) < \delta$. Then there is a positive constant C_4 such that for $p \in \{0, 1, \dots, n\}$ and $q \in \{0, 1, \dots, m\}$

$$(2.3) \quad \begin{aligned} \|x_j^n - y_k^m\| \leq & \|x_p^n - y_q^m\| + C_4 D_{j,k} + \sum_{i=p}^j \delta_i^n h_n + \sum_{i=q}^k \hat{\delta}_i^m \hat{h}_m \\ & + j h_n \{(\delta^{-1} \rho(T) + C_4)(D_{j,k} + |t_p^n - \hat{t}_q^m|) \\ & + \rho(2\delta) + C_4(h_n + \|u - v\|_\infty)\} \end{aligned}$$

for $j = p, \dots, n$ and $k = q, \dots, m$. Here the symbols used above are defined by

$$\delta_j^n = \left[x_j^n - y_v(t_j^n), G(t_j^n, u_{t_j^n}) - G(t_j^n, (y_v)_{t_j^n}) \right]_\lambda,$$

where $[x, y]_\lambda = \lambda^{-1}(\|x + \lambda y\| - \|x\|)$ for $\lambda > 0$,

$$\begin{aligned} \hat{\delta}_k^m &= \|G(s_k^m, u_{s_k^m}) - G(s_k^m, (y_v)_{s_k^m})\| + \frac{2}{\lambda} \|y_k^m - y_v(s_k^m)\|, \\ \rho(\hat{t}) &= \sup \left\{ \frac{2}{\lambda} \|y_v(t) - y_v(r)\| \right. \\ &\quad \left. + \|G(r, (y_v)_r) - G(t, (y_v)_t)\| : |t - r| \leq \hat{t} \right\}. \end{aligned}$$

and

$$D_{j,k} = \{((t_j^n - t_p^n) - (s_k^m - s_q^m))^2 + (t_j^n - t_p^n)h_n + (s_k^m - s_q^m)\hat{h}_m\}^{\frac{1}{2}} + \{((t_j^n - t_p^n) - (s_k^m - s_q^m))^2 + (t_j^n - t_p^n)t_n + (s_k^m - s_q^m)\hat{h}_m\}.$$

First, we prove that (2.3) holds. we let $\sigma = h_n \hat{h}_m / (h_n + \hat{h}_m)$. From (2.1) and (2.2), we have

$$A(t_j^n, u_{t_j^n})x_j^n \ni G(t_j^n, u_{t_j^n}) + \frac{x_{j-1}^n - x_j^n}{h_n},$$

$$A(s_k^m, v_{s_k^m})y_k^m \ni G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m}.$$

Choose $0 < \lambda < 1$. Then, with the similar steps in the paper of Ha, Shin and Jin [6],

$$J_{\sigma\lambda}(t_j^n, u_{t_j^n})(x_j^n + \sigma\lambda(G(t_j^n, u_{t_j^n}) + \frac{x_{j-1}^n - x_j^n}{h_n})) = x_j^n,$$

$$J_{\sigma\lambda}(s_k^m, v_{s_k^m})(y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m})) = y_k^m.$$

From (A.2)–(A.4),

$$\begin{aligned} & \|x_j^n - y_k^m\| \\ & \leq \|J_{\sigma\lambda}(t_j^n, u_{t_j^n})(x_j^n + \sigma\lambda(G(t_j^n, u_{t_j^n}) + \frac{x_{j-1}^n - x_j^n}{h_n})) \\ & \quad - J_{\sigma\lambda}(t_j^n, u_{t_j^n})(y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m}))\| \\ & \quad + \|J_{\sigma\lambda}(t_j^n, u_{t_j^n})(y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m})) \\ & \quad - J_{\sigma\lambda}(s_k^m, v_{s_k^m})(y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m}))\| \\ & \leq \|(x_j^n + \sigma\lambda(G(t_j^n, u_{t_j^n}) + \frac{x_{j-1}^n - x_j^n}{h_n})) \\ & \quad - (y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m}))\| \\ & \quad + \sigma\lambda L_0(\|y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m})\|)(|t_j^n - s_k^m|) \end{aligned}$$

$$\cdot (1 + \|A_{\sigma\lambda}(s_k^m, v_{t_k^m})(y_k^m + \sigma\lambda(G(s_k^m, v_{s_k^m}) + \frac{y_{k-1}^m - y_k^m}{\hat{h}_m}))\|) + \|u_{t_j^n} - v_{s_k^m}\|_C].$$

Let $A_{j,k} = \|x_j^n - y_k^m\|$. Then

$$\begin{aligned} A_{j,k} &\leq \frac{h_n}{h_n + \hat{h}_m} A_{j,k-1} + \frac{\hat{h}_m}{h_n + \hat{h}_m} A_{j-1,k} \\ &\quad + \frac{h_n \hat{h}_m}{h_n + \hat{h}_m} \{L_0(R_1)(1 + C_2 + R_2)|t_j^n - s_k^m| \\ &\quad + L_0(R_1)\|u_{t_j^n} - v_{s_k^m}\|_C + [x_j^n - y_k^m, G(t_j^n, u_{t_j^n}) - G(s_k^m, v_{s_k^m})]_+\} \\ &\leq \frac{h_n}{h_n + \hat{h}_m} A_{j,k-1} + \frac{\hat{h}_m}{h_n + \hat{h}_m} A_{j-1,k} \\ &\quad + \frac{h_n \hat{h}_m}{h_n + \hat{h}_m} \{L_0(R_1)(1 + C_2 + R_2)|t_j^n - s_k^m| \\ &\quad + L_0(R_1)\|u_{t_j^n} - v_{s_k^m}\|_C + \delta_j^n + \delta_k^m + \rho(|t_j^n - s_k^m|)\} \end{aligned}$$

by the fact that

$$\begin{aligned} &[x_j^n - y_k^m, G(t_j^n, u_{t_j^n}) - G(s_k^m, v_{s_k^m})]_+ \\ &\leq [x_j^n - y_v(t_j^n), G(t_j^n, u_{t_j^n}) - G(t_j^n, (y_v)_{t_j^n})]_{\lambda} \\ &\quad + \|G(s_k^m, u_{s_k^m}) - G(s_k^m, (y_v)_{s_k^m})\| \\ &\quad + \|G(s_k^m, (y_v)_{s_k^m}) - G(t_j^n, (y_v)_{t_j^n})\| \\ &\quad + \frac{2}{\lambda}\|y_k^m - y_v(s_k^m)\| + \frac{2}{\lambda}\|y_v(s_k^m) - y_v(t_j^n)\|. \end{aligned}$$

Since

$$\begin{aligned} |t_j^n - s_k^m| &\leq |(t_j^n - s_k^m) - h_n| + h_n \\ &\leq |(t_j^n - t_p^n) - (s_k^m - s_q^m) - h_n| + |t_p^n - s_q^m| + h_n \\ &\leq D_{j-1,k} + |t_p^n - s_q^m| + h_n, \end{aligned}$$

$$\begin{aligned} \rho(|t_j^n - s_k^m|) &\leq \delta^{-1}\rho(T)(|t_j^n - s_k^m| - h_n) + \rho(2\delta) \\ &\leq \delta^{-1}\rho(T)(D_{j-1,k} + |t_p^n - \hat{t}_q^m|) + \rho(2\delta), \end{aligned}$$

and

$$\begin{aligned} \|u_{t_j^n} - v_{s_k^m}\|_C &\leq \|u_{t_j^n} - u_{s_k^m}\|_C + \|u_{s_k^m} - v_{s_k^m}\|_C \\ &\leq M|t_j^n - s_k^m| + \|u_{s_k^m} - v_{s_k^m}\|_C \\ &\leq MD_{j-1,k} + M|t_p^n - s_q^m| + Mh_n + \|u_{s_k^m} - v_{s_k^m}\|_C, \end{aligned}$$

we have

$$\begin{aligned} A_{j,k} &\leq \frac{h_n}{h_n + \hat{h}_m} A_{j,k-1} + \frac{\hat{h}_m}{h_n + \hat{h}_m} A_{j-1,k} \\ &\quad + \frac{h_n \hat{h}_m}{h_n + \hat{h}_m} \{(R_4 + \delta^{-1} \rho(T))(D_{j-1,k} + |t_p^n - t_q^m|) \\ &\quad + R_4 h_n + \delta_j^n + \hat{\delta}_k^m + \rho(2\delta) + R_4 \|u - v\|_\infty\}. \end{aligned}$$

For $i = p + 1, \dots, n$,

$$\begin{aligned} \|x_i^n - x_p^n\| &\leq \|J_{h_n}(t_i^n, u_{t_i^n})(x_{i-1}^n + h_n G(t_i^n, u_{t_i^n})) - J_{h_n}(t_i^n, u_{t_i^n})x_p^n\| \\ &\quad + \|J_{h_n}(t_i^n, u_{t_i^n})x_p^n - x_p^n\| \\ &\leq \|x_{i-1}^n - x_p^n\| + h_n \|G(t_i^n, u_{t_i^n})\| + h_n |A(t_i^n, u_{t_i^n})x_p^n| \\ &\leq \|x_{i-1}^n - x_p^n\| + 2h_n C_3 + h_n L_0(\|x_p^n\|)|t_i^n - t_p^n|(1 + C_3 + M) \\ &\leq \|x_{i-1}^n - x_p^n\| + h_n C_4 |t_i^n - t_p^n| + C_4 h_n, \end{aligned}$$

where $C_4 = \max\{2C_3, R_4\}$ with the bound $C_3 \geq |A(t_j^n, u_{t_j^n})x_p^n|$. If we add this inequality for $i = p + 1, \dots, j$, we have

$$\begin{aligned} \|x_j^n - x_p^n\| &\leq C_4 h_n (j - p) + C_4 h_n \sum_{i=p+1}^j |t_i^n - t_p^n| \\ &\leq C_4 h_n (j - p) + C_4 (j - p)^2 h_n^2 \\ &= C_4 |t_j^n - t_p^n| + C_4 |t_j^n - t_p^n|^2 \\ &\leq C_4 D_{j,q}. \end{aligned}$$

For $p \leq j \leq n$ and $k = q$,

$$\begin{aligned} \|x_j^n - x_p^n\| &\leq C_4 (|t_j^n - t_p^n| + |t_j^n - t_p^n|^2) \\ &\leq C_4 D_{j,q}, \end{aligned}$$

which yields

$$\begin{aligned} \|x_j^n - y_k^m\| &\leq \|x_j^n - x_p^n\| + \|x_p^n - y_q^m\| \\ &\leq \|x_p^n - y_q^m\| + C_4 D_{j,q}. \end{aligned}$$

Similarly, the above inequality also holds for $j = p$ and $q \leq k \leq m$. Next, let $p + 1 \leq j \leq n$ and $q + 1 \leq k \leq m$, and suppose that (2.3) holds for the pair $(j - 1, k)$ and $(j, k - 1)$. Since $R_4 \leq C_4$, from (2.3),

$$\begin{aligned} A_{j,k} &\leq \frac{h_n}{h_n + \hat{h}_m} \left\{ \|x_p^n - y_q^m\| + C_4 D_{j,k-1} + \sum_{i=p}^j \delta_i^n h_n + \sum_{i=q}^{k-1} \hat{\delta}_i^m \hat{h}_m \right. \\ &\quad \left. + j h_n [(\delta^{-1} \rho(T) + C_4)(D_{j,k-1} + |t_p^n - \hat{t}_q^m|) + C_4 h_n + \rho(2\delta) \right. \\ &\quad \left. + C_4 \|u - v\|_\infty \right\} \\ &\quad + \frac{\hat{h}_m}{h_n + \hat{h}_m} \left\{ \|x_p^n - y_q^m\| + C_4 D_{j-1,k} + \sum_{i=p}^j \delta_i^n h_n + \sum_{i=q}^{k-1} \hat{\delta}_i^m \hat{h}_m \right. \\ &\quad \left. + (j - 1) h_n [(\delta^{-1} \rho(T) + C_4)(D_{j-1,k} + |t_p^n - \hat{t}_q^m|) + C_4 h_n + \rho(2\delta) \right. \\ &\quad \left. + C_4 \|u - v\|_\infty \right\} \\ &\quad + \frac{h_n \hat{h}_m}{h_n + \hat{h}_m} \left\{ (\delta^{-1} \rho(T) + C_4)(D_{j-1,k} + |t_p^n - \hat{t}_q^m|) + C_4 h_n + \rho(2\delta) \right. \\ &\quad \left. + \delta_j^n + \hat{\delta}_k^m + C_4 \|u - v\|_\infty \right\} \\ &= \|x_p^n - y_q^m\| + C_4 \left(\frac{h_n}{h_n + \hat{h}_m} D_{j,k-1} + \frac{\hat{h}_m}{h_n + \hat{h}_m} D_{j-1,k} \right) \\ &\quad + \sum_{i=p}^j \delta_i^n h_n + \sum_{i=q}^k \hat{\delta}_i^m \hat{h}_m + j h_n \left\{ (\delta^{-1} \rho(T) + C_4)(D_{j,k} + |t_p^n - \hat{t}_q^m|) \right. \\ &\quad \left. + C_4 h_n + \rho(2\delta) + C_4 \|u - v\|_\infty \right\} \\ &\leq \|x_p^n - y_q^m\| + C_4 D_{j,k} + \sum_{i=p}^j \delta_i^n h_n + \sum_{i=q}^k \hat{\delta}_i^m \hat{h}_m \\ &\quad + j h_n \left\{ (\delta^{-1} \rho(T) + C_4)(D_{j,k} + |t_p^n - \hat{t}_q^m|) \right. \\ &\quad \left. + C_4 h_n + \rho(2\delta) + C_4 \|u - v\|_\infty \right\} \end{aligned}$$

Here we have used

$$\frac{h_n}{h_n + \hat{h}_m} D_{j,k-1} + \frac{\hat{h}_m}{h_n + \hat{h}_m} D_{j-1,k} \leq D_{j,k}.$$

Thus it turns out that (2.3) holds for the pair (j, k) . Hence, we conclude that (2.3) holds for all $p \leq j \leq n$ and $q \leq k \leq m$.

Let $\tau \in (t_{p-1}^n, t_p^n] \cap (s_{q-1}^m, s_q^m]$ and $t \in (t_{j-1}^n, t_j^n] \cap (s_{k-1}^m, s_k^m]$. Letting $n, m \rightarrow \infty$ in (2.3),

$$\begin{aligned} (2.4) \quad & \|x_u(t) - y_v(t)\| \\ & \leq \|x_u(\tau) - y_v(\tau)\| + \limsup_{n \rightarrow \infty} \sum_{i=p}^j \delta_i^n h_n \\ & \quad + \limsup_{m \rightarrow \infty} \sum_{i=q}^k \hat{\delta}_i^m \hat{h}_m + T\rho(2\delta) + C_4 T \|u - v\|_\infty. \end{aligned}$$

Since

$$\lim_{n \rightarrow \infty} \sum_{i=p}^j \delta_i^n h_n = \int_\tau^t [x_u(\eta) - y_v(\eta) \cdot G(\eta, (x_u)_\eta) - G(\eta, (y_v)_\eta)] \lambda d\eta$$

and $\lim_{m \rightarrow \infty} \sum_{i=q}^k \hat{\delta}_i^m \hat{h}_m = 0$, letting $\delta \downarrow 0$ in (2.4)

$$\begin{aligned} \|x_u(t) - y_v(t)\| & \leq \|x_u(\tau) - y_v(\tau)\| + C_4 T \|u - v\|_\infty \\ & \quad + \int_\tau^t [x_u(\eta) - y_v(\eta) \cdot G(\eta, (x_u)_\eta) - G(\eta, (y_v)_\eta)] \lambda d\eta \end{aligned}$$

By letting $\lambda \downarrow 0$ for the above inequality, we finally have desired result.

THEOREM 3. *Let $\phi(0) \in \hat{D}$ and (A.1)–(A.4) hold. Then there exists $T_1 \in (0, T]$ such that (FDE: ϕ) has a limit solution on $[0, T_1]$.*

Proof. Let $T_1 \in (0, T]$ be sufficiently small so that $(C_4 + k_1)T_1 < 1$ and $K \leq M, \max\{k_0, 2(C_1 + C_2)\} < M$. Then by Theorem 2, for $t \in [0, T_1]$

$$\begin{aligned}
\|x_u(t) - y_v(t)\| &\leq C_4 T_1 \|u - v\|_\infty + \int_0^t \|G(\eta, (x_u)_\eta) - G(\eta, (y_v)_\eta)\| d\eta \\
&\leq C_4 T_1 \|u - v\|_\infty + \int_0^t k_1 \|x_u - y_v\|_\infty d\eta \\
&\leq C_4 T_1 \|u - v\|_\infty + k_1 T_1 \|x_u - y_v\|_\infty.
\end{aligned}$$

Therefore, $\|x_u - y_v\|_\infty < \|u - v\|_\infty$. Moreover, the limit solution satisfies $\|x_u(t) - x_u(s)\| \leq K|t - s| \leq M|t - s|$ for $t, s \in [-r, T_1]$ and for $u \in E$. Therefore, $x_u \in E$ for all $u \in E$. If we define an operator $F : E \rightarrow E$ by $u \mapsto x_u$, where $x_u(t)$ is the limit solution of (EE: ϕ, u), then F is a strict contraction on a complete metric space E . By the Banach fixed point theorem, there is a unique fixed point of F in E , say $x(t)$ for $t \in [-r, T_1]$. Then, $x(t)$ is the limit solution of (EE: ϕ) which is Lipschitz continuous on $[-r, T_1]$.

REMARK 1. It is obvious from the proof of the above theorems that the interval $[0, T]$ can be replaced by $[T_1, T]$. Then the solution $x(t)$ of (EE: ϕ) exists beyond T_1 . With this processing, we may conclude that there exists a maximal interval of existence of solutions of (FDE: ϕ) on $[0, T]$.

REMARK 2. Using the result of Theorem 2, we may have similar result of Ha, Shin and Jin [6] with the concept of integral solution defined by Benilan. It is quite interested in investigating the relation between two evolution operators generated by operators in (EE: ϕ) with different second terms. Also, for a just continuous perturbation $G(t, \cdot)$, we may apply the method in the paper of Kartsatos and Shin [11].

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