## LOW TYPE PSEUDO-RIEMANNIAN SUBMANIFOLDS

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ABSTRACT. We study low type submanifolds in pseudo-Euclidean space which is especially of 2-type pseudo-umbilical. We also determine full null 2-type surfaces with parallel mean curvature vector in 4-dimensional Minkowski space-time.

#### 1. Introduction

The general notion of finite type submanifolds of Euclidean space was introduced by B.-Y. Chen about ten years ago ([1]). Later on, he extended this notion to a pseudo-Riemannian version ([2], [3]) as follows: Let  $E_s^{m+1}$  be an (m+1)-dimensional pseudo-Euclidean space with metric tensor given by

$$\tilde{g} = -\sum_{i=1}^{s} dx_i^2 + \sum_{i=s+1}^{m+1} dx_i^2,$$

where  $(x_1, x_2, \dots, x_{m+1})$  is a Cartesian coordinate system of  $E_s^{m+1}$ . Let M be a connected n-dimensional pseudo-Riemannian submanifold of  $E_s^{m+1}$  with signature (r, n-r). Then we have the Laplacian  $\Delta$  of M acting on the space of smooth functions defined on M. M is said to be of k-type if the position vector x of M in  $E_s^{m+1}$  can be decomposed in the following way

(1.1) 
$$x = x_0 + x_{i_1} + \dots + x_{i_k}, \quad \Delta x_{i_j} = l_{ij} x_{ij}, l_{i_1} < \dots < l_{i_k}$$

Received November 14, 1996.

<sup>1991</sup> Mathematics Subject Classification: 53C40.

Key words and phrases: pseudo-Riemannian submanifolds, pseudo-Euclidean spaces, finite-type, pseudo-umbilical submanifolds.

Supported by NON DIRECT RESEARCH FUND, Korea Research Foundation. partially supported by TGRC-KOSEF.

for some natural number k, where  $x_0$  is a constant map and  $x_{i_1}, \dots, x_{i_k}$  are non-constant maps. A k-type submanifold is said to be of null k-type if one of  $l_{i_1}, \dots, l_{i_k}$  is zero. Since it is well known that  $\Delta x = -nH$  where H is the mean curvature vector of M in  $E_s^{m+1}$ , the submanifold M is of null 1-type if and only if M is minimal in  $E_s^{m+1}$ .

We now introduce typical pseudo-Riemannian manifolds. Let  ${\bf c}$  be a point in  $E_s^{m+1}$  and r>0. We put

$$S_s^m(\mathbf{c}, r) = \{ x \in E_s^{m+1} | \langle x - \mathbf{c}, x - \mathbf{c} \rangle = r^2 \},$$

$$H_{s-1}^m(\mathbf{c}, r) = \{ x \in E_s^{m+1} | \langle x - \mathbf{c}, x - \mathbf{c} \rangle = -r^2 \}$$

where  $\langle,\rangle$  denotes the indefinite scalar product on  $E_s^{m+1}$ . It is well known that  $S_s^m(\mathbf{c},r)$  and  $H_{s-1}^m(\mathbf{c},r)$  are complete pseudo-Riemannian manifolds with constant sectional curvatures  $\frac{1}{r^2}$  and  $-\frac{1}{r^2}$  respectively. Such  $S_s^m(\mathbf{c},r)$  and  $H_{s-1}^m(\mathbf{c},r)$  are respectively called the pseudo-Riemannian sphere and the pseudo-hyperbolic space and  $\mathbf{c}$  is called the center. B.-Y. Chen ([2]) classified 1-type submanifolds of pseudo-Euclidean space  $E_s^{m+1}$ .

In this article, we study 2-type pseudo-umbilical pseudo-Riemannian submanifolds of  $E_s^{m+1}$  and null 2-type surfaces with unit parallel mean curvature vector. Throughout this paper, submanifolds of pseudo-Euclidean space are always assumed to be pseudo-Riemannian.

## 2. Preliminaries

Let M be a submanifold of a pseudo-Euclidean space  $E_s^{m+1}$  with indefinite scalar product  $\langle,\rangle$ . Let X be a vector in  $E_s^{m+1}$ . X is called spacelike if  $\langle X,X\rangle\geq 0$  (respectively, timelike or null if  $\langle X,X\rangle<0$  or  $\langle X,X\rangle=0$  and  $X\neq 0$ ). We denote by  $A,h,\nabla,D$  and  $\tilde{\nabla}$  the Weingarten map, the second fundamental form, the Levi-Civita connection of M, the normal connection and the Levi-Civita concection of  $E_s^{m+1}$ , respectively. A submanifold M is said to be pseudo-umbilical if  $A_H=\rho I$  for some smooth function  $\rho$  on M and  $\langle H,H\rangle\neq 0$ . For the second fundamental form h, we define its covariant derivative, denoted by  $\nabla h$ , as follows:

$$(2.1) \qquad (\bar{\nabla}_X h)(Y, Z) = D_X h(Y, Z) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z)$$

for vector fields X, Y and Z tangent to M.

Let  $e_1, e_2, \dots, e_n$  be an orthonormal basis of the tangent bundle TM. If  $\phi$  is an endomorphism of  $T_xM$ , then the trace of  $\phi$  is defined by

(2.2) 
$$tr\phi = \sum_{i=1}^{n} \epsilon_i \langle \phi e_i, e_i \rangle, \quad \epsilon_i = \langle e_i, e_i \rangle = \pm 1.$$

Thus, the mean curvature vector H of M is given by

(2.3) 
$$H = \frac{1}{n} trh = \frac{1}{n} \sum_{i=1}^{n} \epsilon_i h(e_i, e_i).$$

Let  $e_{n+1}, e_{n+2}, \dots, e_{m+1}$  be an orthonormal normal basis of the normal bundle  $T^{\perp}M$ . B.-Y. Chen ([3]) gave the formula for  $\Delta H$ :

(2.4) 
$$\Delta H = \Delta^{D} H + \frac{n}{2} grad \langle H, H \rangle + 2 tr A_{DH} + \sum_{r=n+1}^{m+1} \epsilon_{r} tr(A_{H} A_{e_{r}}) e_{r},$$

where  $\Delta^D$  denotes the Laplacian of the normal bundle given by  $\Delta^D = -\sum_{i=1}^n \epsilon_i (D_{e_i} D_{e_i} - D_{\nabla_{e_i} e_i})$  and  $A_r$  stands for the shape operator associated with  $e_r$ . Let  $\omega^A$  be the dual 1-form of  $e_A$   $(A = 1, 2, \dots, m+1)$  defined by  $\omega^A(X) = \epsilon_A \langle e_A, X \rangle$ . The connection forms  $\omega_A^B$  are defined by

(2.5) 
$$de_A = \sum_B \omega_A^B e_B, \qquad \omega_A^B + \epsilon_A \epsilon_B \omega_B^A = 0.$$

Then, the structure equations of  $E_s^{m+1}$  are obtained as follows:

(2.6) 
$$d\omega^A = \sum_{B=1}^{m+1} \omega^B \wedge \omega_B^A,$$

(2.7) 
$$d\omega_B^A = \sum_{C=1}^{n+1} \omega_B^C \wedge \omega_C^A.$$

We now define the curvature forms  $\Omega_i^i$  and  $\Omega_t^s$  on M:

$$\Omega_j^i = \frac{1}{2} \sum_{k,l} R_{jkl}^i \omega^k \wedge \omega^l, \quad \Omega_t^s = \frac{1}{2} \sum_{k,l} R_{tkl}^s \omega^k \wedge \omega^l,$$

where  $R_{jkl}^i = \epsilon_i \langle R(e_k, e_l) e_j, e_i \rangle$  and

(2.8) 
$$R_{tkl}^{s} = \epsilon_{t} \sum_{i} (h_{ik}^{t} h_{il}^{s} - h_{il}^{t} h_{ik}^{s})$$

with  $h_{ij}^t = \langle h(e_i, e_j), e_t \rangle$  where  $i, j, k, l \in \{1, 2, \dots, n\}$  and  $t, s \in \{n + 1, \dots, m + 1\}$ . The equation (2.8) is called the equation of Ricci. We then have the structure equations for M

(2.9) 
$$d\omega^{i} = \sum_{j=1}^{n} \omega^{j} \wedge \omega_{j}^{i}, \quad \omega_{j}^{i} + \epsilon_{j} \epsilon_{i} \omega_{i}^{j} = 0,$$

(2.10) 
$$d\omega_j^i = \sum_{k=1}^n \omega_j^k \wedge \omega_k^i + \Omega_j^i,$$

(2.11) 
$$d\omega_t^s = \sum_{u=n+1}^{m+1} \omega_t^u \wedge \omega_u^s + \Omega_t^s.$$

Fore later uses, we introduce some examples of null 2-type.

Example 1 ([ 5 ]). Let  $f: E_1^3 \to R$  be a real function defined by

$$f(x, y, z) = -\delta_1 x^2 + y^2 + \delta_2 z^2.$$

where  $\delta_1$  and  $\delta_2$  belong to the set  $\{0,1\}$  and they do not vanish at the same time. Taking r>0 and  $\epsilon=\pm 1$ , the set  $f^{-1}(\epsilon r^2)$  is a surface in  $E_1^3$  provided that  $(\delta_1,\delta_2,\epsilon)\neq (0,1,-1)$ . Then, the unit normal vector is given by  $\frac{1}{r}(\delta_1 x,y,\delta_2 z)$  and the principal curvatures are easily derived as  $-\frac{\delta_1}{r}$  and  $-\frac{\delta_2}{r}$ . According to the choice of numbers 0, 1 and -1 for  $\delta_1,\delta_2$  and  $\epsilon$ , we have several examples of null 2-type surfaces:  $E_1^1\times S^1(r)$  for  $(\delta_1,\delta_2,\epsilon)=(0,1,1)$ ,  $R\times H^1(r)$  for  $(\delta_1,\delta_2,\epsilon)=(1,0,-1)$  and  $S_1^1\times R$  for  $(\delta_1,\delta_2,\epsilon)=(1,0,1)$ .

EXAMPLE 2 (B-SCROLL IN  $E^3$ , [6]). Let  $\gamma(s)$  be a null curve in Minkowski 3-space  $E_1^3$  with Cartan frame  $\{A, B, C\}$ , that is, A, B, C are vector fields along  $\gamma(s)$  satisfying the following:

$$\langle A, A \rangle = \langle B, B \rangle = 0,$$
  $\langle A, B \rangle = -1,$   $\langle A, C \rangle = \langle B, C \rangle = 0,$   $\langle C, C \rangle = 1,$ 

and

$$\dot{x} = A,$$

$$\dot{A} = k(s)C,$$

 $\dot{B} = a_0 C, a_0$  being a nonzero constant,

$$\dot{C} = a_0 A + k(s) B.$$

If we consider an immersion x(s,t) = x(s) + tB(s), then x defines a Lorentz surface called a B-scroll. In this surface, we can have the unit normal vector field  $N = -a_0tB(s) - C(s)$  and the mean curvature vector  $H = a_0N$ . It is a null 2-type surface in  $e_1^3$  with minimal polynomial  $(x - a_0)^2$ .

EXAMPLE 3 (EXTENDED B-SCROLL IN  $E_1^4$ ). Let  $\gamma$  be a null curve in  $E_1^4$  and let A(s), B(s), C(s), D(s) be a Cartan frame along  $\gamma$  such that

$$\begin{split} \langle A,A\rangle &= \langle B,B\rangle = 0, \qquad \langle A,B\rangle = -1, \\ \langle A,C\rangle &= \langle A,D\rangle = \langle B,C\rangle = \langle B,D\rangle = 0, \\ \langle C,C\rangle &= \langle D,D\rangle = 1, \qquad \langle C,D\rangle = 0, \qquad \dot{\gamma}(s) = A(s). \end{split}$$

Let X(s) be the matrix of (A(s) B(s) C(s) D(s)) consisting of column vectors of A, B, C, D with respect to standard coordinates of  $E_1^4$ . Then, X(s) satisfies

$$X^t(s)EX(s) = T(s),$$

where E = diag(-1, 1, 1, 1) and

$$T = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

where  $X^{t}(s)$  denotes the transpose of X(s).

We now consider a system of ordinary differential equations:

$$\begin{split} \dot{A}(s) &= k_1(s)A(s) - k_2(s)C(s) - k_3(s)D(s), \\ \dot{B}(s) &= -k_1(s)B(s) - aC(s), \\ \dot{C}(s) &= -aA(s) - k_2(s)B(s), \\ \dot{D}(s) &= -k_3(s)B(s), \end{split}$$

where  $k_1(s), k_2(s)$  and  $k_3(s)$  are smooth functions and a is a constant. In other words, we may write

$$\dot{X}(s) = X(s)M(s),$$

where

$$M(s) = \begin{pmatrix} k_1(s) & 0 & -a & 0\\ 0 & -k_1(s) & -k_2(s) & -k_3(s)\\ -k_2(s) & -a & 0 & 0\\ -k_3(s) & 0 & 0 & 0 \end{pmatrix}.$$

For a given X(0) = (A(0) B(0) C(0) D(0)) satisfying  $X^t(0)EX(0) = T$ , or, equivalently  $X(0)TX^t(0) = E$ , there is a unique solution to above matrix equation with initial condition X(0). Since T is symmetric and MT is skew-symmetric,  $\frac{d}{ds}(X(s)TX^t(s)) = 0$  and hence  $X(s)TX^t(s) = E$  which is equivalent to

$$X^t(s)EX(s) = T.$$

Therefore, A(s), B(s), C(s), D(s) form the null frame along a null curve  $\gamma$  in  $E_1^4$ .

Let  $x(s,t) = \gamma(s) + tB(s)$ . Then, it defines a Lorentz surface M in  $E_1^4$ . The mean curvature vector field H is given by

$$H(s,t) = -ta^2B(s) + aC(s),$$

which implies

$$\Delta H = 2a^2H.$$

If  $a \neq 0$ , then we can easily see that M is of null 2-type. And, the shape operator  $A_H$  associated with the mean curvature vector field H has the form

$$\begin{pmatrix} a^2 & 0 \\ ak_2 & a^2 \end{pmatrix}$$

in the coordinate frame  $\{x_s, x_t\}$ .

## 3. 2-type pseudo-umbilical submanifolds

In this section we deal with 2-type pseudo-umbilical submanifolds of  $E_s^{m+1}$ . First of all, if we follow the similar argument in [7], we have

LEMMA 3.1 ([7]). Let M be a pseudo-umbilical submanifold of  $E_s^{m+1}$ . Then we have

- (1)  $\sum_{r} \epsilon_r tr(A_H A_r) e_r = n \epsilon \alpha^2 H$ ,
- (2)  $trA_{DH} = \frac{2-n}{2}grad\langle H, H \rangle$ , where  $\epsilon = sgn\langle H, H \rangle$  and  $\alpha = |\langle H, H \rangle|^{\frac{1}{2}}$ .

LEMMA 3.2. Let M be an n-dimensional pseudo-umbilical submanifold of  $E_s^{m+1}$ . Then,  $(\Delta H)^T$  vanishes if and only if the mean curvature is constant or n=4, where  $(\Delta H)^T$  denotes the tangential component of  $\Delta H$ .

*Proof.* By Lemma 3.1, (2.4) can be reduced to

$$\Delta H = \Delta^D H + n\epsilon\alpha^2 H + \frac{4-n}{2} grad\langle H, H \rangle.$$

Thus,  $(\Delta H)^T = \frac{4-n}{2} grad \langle H, H \rangle$  which gives the lemma.

LEMMA 3.3. Let M be an n-dimensional submanifold of  $E_s^{m+1}$ . If M is of 2-type, then  $(\Delta H)^T$  vanishes if and only if one of the following occurs

- (a) M lies in a pseudo-Riemannian sphere, a pseudo-hyperbolic space or a null cone.
- (b) M is of null 2-type.

*Proof.* Since M is of 2-type, the position vector x of M can be decomposed into

(3.1) 
$$x = x_0 + x_p + x_q, \quad \Delta x_p = \lambda x_p, \quad \Delta x_q = \mu x_q$$

for some constants  $\lambda$  and  $\mu$ . Then we have

$$(3.2) \Delta^2 x + b\Delta x + c(x - x_0) = 0$$

where  $b=-(\lambda+\mu)$  and  $c=\lambda\mu$ . Since  $\Delta x=-nH$ , (3.2) can be rewritten as

(3.3) 
$$\Delta^{D}H + \frac{n}{2}grad\langle H, H \rangle + 2trA_{DH} + \sum \epsilon_{r}tr(A_{H}A_{\epsilon_{r}})e_{r}$$
$$= -bH + \frac{c}{n}(x - x_{0}).$$

Therefore,  $(\Delta H)^T$  vanishes if and only if c = 0 or  $x - x_0$  is normal to M. If c = 0, M is of null 2-type. Suppose  $x - x_0$  is normal to M. Let X be a vector field tangent to M. Then,

$$X\langle x - x_0, x - x_0 \rangle = \langle X, x - x_0 \rangle = 0,$$

that is,  $\langle x-x_0, x-x_0 \rangle$  is constant. Thus, M lies in a pseudo-Riemannian sphere, a pseudo-hyperbolic space or a null cone depending upon  $\langle x-x_0, x-x_0 \rangle > 0$ , < 0 or equals zero.

THEOREM 3.4. Let M be an  $n(\neq 4)$ -dimensional 2-type pseudo-umbilical submanifold of  $E_s^{m+1}$ . Then, M has constant mean curvature if and only if one of the following holds:

- (a) M lies in a pseudo-Riemannian sphere, a pseudo-hyperbolic space or a null cone.
- (b) M is of null 2-type.

*Proof.* If M has a constant mean curvature, then Lemma 3.2 and Lemma 3.3 give (a) or (b). Conversely, if (a) or (b) holds, then  $(\Delta H)^T$  vanishes if we take account of (3.3). Then, Lemma 3.2 implies that the mean curvature is constant.

THEOREM 3.5. Let M be a 4-dimensional 2-type pseudo-umbilical submanifold of  $E_s^{m+1}$ . Then, (a) or (b) described in Theorem 3.4 holds.

*Proof.* By Lemma 3.2,  $(\Delta H)^T$  always vanishes. If we make use of (3.3) and the argument developed in Lemma 3.3, we obtain the theorem.

# 4. Null 2-type surfaces with unit parallel mean curvature vector

A surface M of pseudo-Euclidean space  $E_s^{m-1}$  is said to have the unit parallel mean curvature vector if the mean curvature vector H is non-null and its normalized vector field is parallel in the normal bundle. In this section we assume that the surface M of pseudo-Euclidean space  $E_s^{m+1}$  have the unit parallel mean curvature vector and is of null 2-type. We choose a local adapted orthonormal frame  $e_1, e_2, e_3, \cdots, e_{m+1}$  such that  $H = \alpha e_3$ . Then the last term of (2.4) can be rewritten as

$$\sum_{r=3}^{m+1} \epsilon_r tr(A_H A_r) e_r = \epsilon_3 \alpha tr A_3^2 e_3 + \alpha a(H)$$

where a(H) stands for the allied mean curvature vector field of H defined by  $a(H) = \sum_{r=4}^{m+1} \epsilon_r tr(A_3 A_r) e_r$ . A submanifold in  $E_s^{m+1}$  is called Chen submanifold if the allied mean curvature vector field a(H) vanishes identically. As is well known we have the following proposition.

PROPOSITION 4.1 ([4]). Let M be a null 2-type submanifold of  $E_s^m$ . Then

$$(4.1) tr\bar{\nabla}A_H = tr\nabla A_H + trA_{DH} = 0$$

and

(4.2) 
$$\Delta^D H + \sum_{i=1}^n \epsilon_i h(A_H e_i, e_i) = \lambda H$$

for some nonzero constant  $\lambda$ , where  $tr\nabla A_H = \sum_{i=1}^2 \epsilon_i(\nabla_{e_i} A_H)e_i$ .

LEMMA 4.2. Let M be a surface of  $E_s^{m+1}$  with unit parallel mean curvature vector. If M is of null 2-type, then M is a Chen surface and on the open subset  $\mathcal{U} = \{p \in M | (\nabla \alpha)(p) \neq 0\}$  we have

$$A_3 \nabla \alpha = -\epsilon_3 \alpha \nabla \alpha$$

and

$$\Delta \alpha = (\lambda - \epsilon_3 tr A_3^2) \alpha,$$

where  $\nabla \alpha$  stands for the gradient of  $\alpha$ .

*Proof.* Sine  $e_3$  is parallel in the normal bundle, (4.2) implies

$$(\Delta \alpha)e_3 + \epsilon_3 \alpha tr A_3^2 e_3 + \alpha a(H) = \lambda \alpha e_3.$$

It follows that a(H) = 0 and thus M is a Chen surface. We also have  $\Delta \alpha = (\lambda - \epsilon_3 tr A_3^2) \alpha$ . Since  $tr A_{DH} = A_3 \nabla \alpha$ , we obtain from (2.4) and (4.1)

$$A_3 \nabla \alpha = -\epsilon_3 \alpha \nabla \alpha$$

on  $\mathcal{U}$ .

LEMMA 4.3. Under the same hypothesis of Lemma 4.2, the mean curvature vector field H is parallel in the normal bundle.

*Proof.* We choose a local orthonormal frame  $\{e_1, e_2, e_3, \dots, e_{m+1}\}$  of  $E_s^{m+1}$  such that  $e_1$  and  $e_2$  are tangent to M,  $e_3, \dots, e_{m+1}$  are normal to M and  $H = \alpha e_3$ . Suppose the open subset  $\mathcal{U} = \{p \in M | (\nabla \alpha)(p) \neq 0\}$  is not empty. By Lemma 4.2, we see that  $-\epsilon_3 \alpha$  is a principal curvature of  $A_3$  on  $\mathcal{U}$  and thus the other principal curvature is  $3\epsilon_3 \alpha$  on  $\mathcal{U}$ .

If M is spacelike, we choose  $e_1$  in the direction of  $\nabla \alpha$  on  $\mathcal{U}$ . We now show that  $\nabla \alpha$  cannot be null even if M is Lorentzian. Let M be Lorentzian. Then, the Weingarten map  $A_3$  has one of the following forms ([9]):

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}, \quad \begin{pmatrix} \mu & 0 \\ 1 & \mu \end{pmatrix}, \quad \begin{pmatrix} a & b \\ -b & a \end{pmatrix}$$

for some functions  $\lambda_1, \lambda_2, \mu, a$  and b, where the first and the last representations are induced by an orthonormal frame and the second one is obtained by an pseudo-orthonormal frame  $\{e_1, e_2\}$  on M satisfying  $\langle e_1, e_1 \rangle = \langle e_2, e_2 \rangle = 0$ ,  $\langle e_1, e_2 \rangle = 1$ . Since one principal curvature of M is  $-\epsilon_3 \alpha$ ,  $A_3$  cannot have the second and third forms. Hence, M is diagonalizable on  $\mathcal{U}$ . Thus, we may assume that the unit vector field  $e_1$  tangent to M is parallel to  $\nabla \alpha$  on  $\mathcal{U}$  if M is spacelike or Lorentzian. Therefore, we may put

(4.3) 
$$\omega_3^1 = \epsilon_3 \alpha \omega^1, \qquad \omega_3^2 = -3\epsilon_3 \alpha \omega^2,$$

$$(4.4) d\alpha = (e_1 \alpha) \omega^1.$$

Taking the exterior differentiation of the first equation of (4.3) and making use of the structure equations, we obtain

$$(4.5) \quad d\omega_3^1 = \omega_3^2 \wedge \omega_2^1 + \sum_{r=4}^{m+1} \omega_3^r \wedge \omega_r^1 = -3\epsilon_3 \alpha \omega^2 \wedge \omega_2^1 = -3\epsilon_3 \alpha d\omega^1.$$

If we use (4.4), we have

$$d(\alpha\omega^1) = \alpha d\omega^1.$$

The last two equations give

$$d\omega^1 = 0.$$

By the Poincaré lemma,  $\omega^1$  can be locally written as

$$(4.6) \omega^1 = du$$

where u is a smooth function. Similarly, by taking the exterior differentiation of the second equation of (4.3) and using  $De_3 = 0$ , we may get

(4.7) 
$$\omega_1^2(e_2) = -\frac{(3e_1\alpha)}{4\alpha}.$$

We also have from (4.6)

$$(4.8) \omega_2^1(e_1) = 0.$$

On the other hand, we see from (4.4) and (4.6)

$$(4.9) d\alpha \wedge du = 0.$$

Thus,  $\alpha$  is a function of u, that is,  $\alpha = \alpha(u)$ . Therefore, (4.4) and (4.7) give rise to

(4.10) 
$$d\alpha = \alpha'(u)du, \qquad e_1(\alpha) = \alpha'$$

and

$$(4.11) 4\alpha\omega_1^2 = -3\alpha'\omega^2.$$

Taking the exterior differentiation of (4.11), we get

(4.12) 
$$21(\alpha')^2 - 48\epsilon_1 \epsilon_3 \alpha^4 + 16\epsilon_2 \alpha^2 K - 12\alpha \alpha'' = 0$$

where K denotes the Gaussian curvature of M. Since  $H = \alpha e_3$  and M is a Chen surface by Lemma 4.2, we have

$$trA_r = 0$$
 and  $trA_3A_r = 0$   $(r = 4, \dots, m+1).$ 

It follows that

$$(4.13) h_{11}^r = h_{22}^r = 0$$

where we have put  $A_r = (h_{ij}^r)$  for  $r = 4, \dots, m+1$ .

On the other hand, the equation (2.8) of Ricci is rewritten as

$$\langle K^N(X,Y)e_r,e_s\rangle = \langle [A_r,A_s]X,Y\rangle$$

for  $r, s = 3, 4, \dots, m + 1$ , where  $K^N$  denotes the normal curvature tensor field associated with the normal connection D and X, Y are tangent vector fields to M. Since  $De_3 = 0$ , we have from the last equation

$$[A_3, A_r] = 0$$

for all  $r = 3, \dots, m + 1$ . If we make use of (4.3), (4.13) and (4.14), then we obtain

$$h_{12}^r = 0$$

for  $r=4,\cdots,m+1$ . Thus we have  $A_r=0$  for  $r=4,\cdots,m+1$  and

$$K = \sum_{j=1}^{m+1} det(h_{ij}^r) = det(h_{ij}^3) = -3\alpha^2.$$

Consequently, (4.12) becomes

(4.15) 
$$7(\alpha')^2 - 16\alpha^4(\epsilon_1 \epsilon_3 + \epsilon_2) - 4\alpha\alpha'' = 0.$$

Let  $y = (\alpha')^2$ . Then the equation (4.15) is reduced to the following ordinary differential equation of first order:

$$(4.16) 7y - 16\alpha^4(\epsilon_1\epsilon_3 + \epsilon_2) - 2\alpha y' = 0.$$

where y' stands for the derivative of y with respect to the variable  $\alpha$ . Then, the solution of this differential equation is given by

$$(4.17) y = (\alpha')^2 = C\alpha^{\frac{\pi}{2}} - 16\alpha^4(\epsilon_1 \epsilon_3 + \epsilon_2)$$

where C is a constant.

Lemma 4.2 and (4.3) imply

(4.18) 
$$\Delta \alpha = (\lambda - 10\epsilon_3 \alpha^2)\alpha.$$

On the other hand, if we use the definition of  $\Delta \alpha$  together with (4.4), (4.7) and (4.8), we can obtain

$$(4.19) 4\alpha\Delta\alpha = -4\epsilon_1\alpha\alpha'' + 3\epsilon_1(\alpha')^2.$$

Combining (4.18) and (4.19), we get

$$(4.20) 4\epsilon_1 \alpha \alpha'' - 3\epsilon_1 (\alpha')^2 + 4\alpha^2 (\lambda - 10\epsilon_3 \alpha^2) = 0.$$

Together with (4.15) and (4.20) we get

$$(4.21) \epsilon_1(\alpha')^2 + \alpha^2(\lambda - 10\epsilon_3\alpha^2) - 4\epsilon_1\alpha^4(\epsilon_1\epsilon_3 + \epsilon_2) = 0.$$

Comparing (4.17) and (4.21), we can conclude that  $\alpha$  is constant on each component of  $\mathcal{U}$  which is contrary to our assumption. Therefore, the open subset  $\mathcal{U}$  is empty and hence the mean curvature of M is constant. Automatically, the mean curvature vector H is parallel in the normal bundle. It completes the proof.

We now prove

THEOREM 4.4. Let M be a surface of  $E_1^4$ . If M is of null 2-type with unit parallel mean curvature vector, then M is an open portion of a B-scroll in  $E_1^3$ ,  $E_1^1 \times S^1(r)$ ,  $S_1^1(r) \times R$ ,  $H^1(r) \times R$  or an extended B-scroll in  $E_1^4$ .

*Proof.* Let M be Lorentzian in  $E_1^4$ . As before, we choose one of unit normal vector fields  $e_3$  as  $H = \alpha e_3$  which is the mean curvature vector field of M in  $E_1^4$ . Suppose that the shape operator  $A_3$  associated with  $e_3$  is diagonalizable. Thus, we may choose an orthonormal frame  $\{e_1, e_2\}$  so that

$$A_3 = \begin{pmatrix} eta & 0 \\ 0 & \gamma \end{pmatrix}, \qquad A_4 = \begin{pmatrix} \mu & \delta \\ -\delta & -\mu \end{pmatrix},$$

where  $A_4$  is the shape operator of M associated with the normal vector field  $e_4$  orthogonal to  $e_3$ . We obtain from the above  $A_3$  and  $A_4$ 

$$\begin{split} &\omega_3^1 = -\beta\omega^1, \quad \omega_3^2 = -\gamma\omega^2, \\ &\omega_4^1 = -\mu\omega^1 - \delta\omega^2, \quad \omega_4^2 = \delta\omega^1 + \mu\omega^2. \end{split}$$

Since  $e_3$  is parallel, we have

$$(\beta - \gamma)\delta = 0.$$

Suppose that an open subset  $\mathcal{O} = \{p \in M | (\beta - \gamma)(p) \neq 0\} \neq \phi$ . Then,  $\delta = 0$  on  $\mathcal{O}$ . Since M is of null 2-type,  $\Delta H = \lambda H$  for some real number  $\lambda \neq 0$ . That implies

$$\lambda = \beta^2 + \gamma^2$$
 and  $\mu = 0$ .

Consequently,  $A_4$  is identically zero on  $\mathcal{O}$ . Thus, the reduction theorem can be applied in such a way that  $\mathcal{O}$  lies in  $E_1^3$ . According to Theorm 3.1 in [6], one of  $\beta$  and  $\gamma$  must be zero. Hence, each component of  $\mathcal{O}$  lies in  $E_1^1 \times S^1(r)$  or  $S_1^1(r) \times \mathbb{R}$  for some constant r. By continuity, a component C of  $\mathcal{O}$  must be M if  $C \neq \phi$ .

If  $\mathcal{O} = \phi$ , that is,  $\beta = \gamma = \alpha$ , then M is pseudo-umbilical in  $E_1^4$ . Since the mean curvature vector is parallel in the normal bundle, M is minimal in a hypersphere  $S_1^3(c,r)$  for some  $c \in E_1^4$  and r > 0 due

to B.-Y. Chen ([ 2 ]). Therefore, M is of 1-type and hence this case cannot occur.

We now suppose that there is a point  $p \in M$  such that  $A_3$  is not diagonalizable at p. The, we can choose a pseudo-orthonormal frame  $\{A, B\}$  on a neighborhood W of p so that  $A_3$  takes the form

$$\begin{pmatrix} \alpha & 0 \\ k & \alpha \end{pmatrix} \quad (k \neq 0).$$

We put

$$e_1 = \frac{A+B}{\sqrt{2}}, \quad e_2 = \frac{A-B}{\sqrt{2}}.$$

Then,  $\{e_1, e_2\}$  is an orthonormal frame on W.  $A_3$  and  $A_4$  take the form

$$A_3 = \begin{pmatrix} \alpha + rac{k}{2} & rac{k}{2} \\ -rac{k}{2} & \alpha - rac{k}{2} \end{pmatrix}$$
 and  $A_4 = \begin{pmatrix} eta & \gamma \\ -\gamma & -eta \end{pmatrix}$ 

in the frame  $\{e_1, e_2\}$  for some functions  $\beta$  and  $\gamma$  on W. Since the normal connection is flat, we may assume that  $\beta = \gamma$ .

Since  $\nabla_A B$  and  $\nabla_B A$  are parallel to B and A respectively, the equation of Codazzi

$$\nabla_B(A_3A) - A_3\nabla_BA = \nabla_A(A_3B) - A_3\nabla_AB$$

gives

$$k\nabla_B B = A_3 \nabla_B A - \alpha \nabla_B A - B(k)B$$

which is parallel to B. Therefore, we have

$$\tilde{\nabla}_B B = \nabla_B B = fB$$

for some function f because of  $\langle A_3B,B\rangle=\langle A_4B,B\rangle=0$ . Thus, the integral curves of B are straight lines. Let  $\gamma(s)$  be an integral curve of A and let  $C(s)=e_3(\gamma(s))$  and  $D(s)=e_4(\gamma(s))$ . Since the normal connection is flat, we get

$$\dot{A}(s) = k_1(s)A(s) - kC(s) - 2\beta(s)D(s),$$
$$\dot{B}(s) = -k_1(s)B(s) - \alpha C(s)$$

$$\dot{C}(s) = \tilde{\nabla}_A e_3 = -\alpha A(s) - kB(s)$$

and

$$\dot{D}(s) = \tilde{\nabla}_A e_4 = -2\beta(s)B(s).$$

Therefore,  $x(s,t) = \gamma(s) + tB(s)$  is a parametrization of each connected component of W which is an extended B-scroll in  $E_1^4$ .

For the space-like surface of null 2-type with unit parallel mean curvature vector in  $E_1^4$ , M is given by an open portion of  $H^1(r) \times R$  if we use the result of [5]. It completes our proof.

From this theorem, we have

THEOREM 4.5. The only full null 2-type surface with unit parallel mean curvature vector in 4-dimensional Minkowski space-time is an open portion of an extended B-scroll.

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