

**GLOBAL EXISTENCE OF  
HOLOMORPHIC SOLUTIONS OF  
DIFFERENTIAL EQUATIONS WITH  
COMPLEX PARAMETERS–II**

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**1. Introduction and the Main Theorem**

As early as in 1956 L. Ehrenpreis[1] discoursed on an application of the sheaf theory to differential equations and gave a criterion for the existence of global solutions of differential equations  $Tf = g$  in a domain  $D$  when the existence of local solutions are assured. The first author[2] applied Ehrenpreis' method to linear ordinary differential equations with meromorphic coefficients and gave a necessary and sufficient condition for the global existence in the meromorphic category. In the holomorphic category the condition is that  $D$  is either simply connected or doubly connected without non trivial global single-valued holomorphic homogeneous solutions.

H. Suzuki[11] stated that the global existence of differential equation  $\partial u/\partial x_1 = f$  with complex parameter depends on the Steinness of the sets of cuts over the parameter space. The first author and Y. Mori[7] connected [2] and [11] and discussed the global existence of more general ordinary differential equations with complex parameters. The authors[8] generalized those to the case of Stein parameter spaces.

Concerning partial differential equations, the first author[3]-[6] discussed several concrete cases. In the former paper K. H. Shon[10] reported promptly the main theorem and showed sheaf-theoretically a route of its proof. The main of this series is to give complete analytical foundations to it. In the previous paper[9], we gave a necessary and

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Received April 3, 1993

\*Research was supported by Grant-in-Aid for General Scientific Research (B) no 04452005 from the Ministry of Education, Science and Culture of Japan, 1992

\*\*Research was supported by Pusan National University Research Fund

sufficient condition for the global existence in case of polycylindrical domains as follows:

Let  $m$  be a positive integer and, for each integer  $j$  with  $1 \leq j \leq m$ ,  $D_j$  be a domain in the complex plane  $\mathbb{C}$ . We put

$$(1.1) \quad D = D_1 \times D_2 \times \cdots \times D_m.$$

The set  $D$  is a domain of holomorphy in the complex  $m$ -space  $\mathbb{C}^m$ . Let  $M$  be a Stein manifold. We use the manifold  $M$  as a parameter space, denote by  $r$  a point of  $M$  and regard it as a complex parameter. We consider the product manifold  $D \times M$ .

For each  $i$  with  $1 \leq i \leq m$ , let  $a^i = (a_{jk}^i(z, r))$  be a square matrix of degree  $m$  whose each  $(j, k)$  element  $a_{jk}^i(z, r)$  is holomorphic function in  $D \times M$ . For each  $i$  with  $1 \leq i \leq m$ , let  $T_i$  be a differential operator defined by

$$(1.2) \quad T_i = \frac{\partial}{\partial z_i} + a^i.$$

Let  $\mathcal{O}_{D \times M}$  be the sheaf of germs of all holomorphic function on  $D \times M$ . Then each differential operator  $T_i$  defines a sheaf homomorphism

$$(1.3) \quad T_i : (\mathcal{O}_{D \times M})^m \longrightarrow (\mathcal{O}_{D \times M})^m$$

as

$$(1.4) \quad T_i u = \begin{pmatrix} \frac{\partial u_1}{\partial z_i} + \sum_{k=1}^m a_{1k}^i(z, r) u_k \\ \frac{\partial u_2}{\partial z_i} + \sum_{k=1}^m a_{2k}^i(z, r) u_k \\ \vdots \\ \frac{\partial u_m}{\partial z_i} + \sum_{k=1}^m a_{mk}^i(z, r) u_k \end{pmatrix}$$

for any germ

$$u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix}$$

of  $(\mathcal{O}_{D \times M})^m$ . We put

$$(1.5) \quad T = T_1 T_2 \cdots T_m.$$

Let

$$(1.6) \quad H(D \times M) = H^0(D \times M, (\mathcal{O}_{D \times M})^m)$$

be the set of global sections of  $(\mathcal{O}_{D \times M})^m$  over  $D \times M$ .  $H^0(D \times M, \mathcal{O}_{D \times M})$  is the  $\mathbb{C}$ -module of all holomorphic functions on  $D \times M$ .  $H(D \times M)$  is the  $H^0(D \times M, \mathcal{O}_{D \times M})$ -module of all  $m$ -column vector valued holomorphic functions on  $D \times M$ .

Let  $\text{Ker } T$  and  $\text{Im } T$  be, respectively, the kernel and image of the homomorphism

$$(1.7) \quad T : H(D \times M) \longrightarrow H(D \times M).$$

As Theorem 3<sub>m</sub>, we have proved the following theorem in the previous paper of the authors[9].

**PREPARATION THEOREM.** *The necessary and sufficient condition for  $H(D \times M) = T(H(D \times M))$  is that, for  $i = 1, 2, \dots, m$ ,  $D_i$  is either a simply connected domain or a doubly connected domain in  $\mathbb{C}$  with  $H^0(D_i, \text{Ker } T_i) = 0$ .*

In the present paper, we let each cross domain  $D(r)$  varies as polycylinder valued function of the parameter  $r \in M$  and instead of the product manifold, we consider a domain  $\Omega$  in the product manifold  $\mathbb{C}^m \times M$  of type

$$(1.8) \quad \Omega := \{(z, r) \in \mathbb{C}^m \times M; z \in D(r), r \in M\}$$

where  $D(r)$  is a polycylinder, product

$$(1.9) \quad D(r) := D_1(r) \times D_2(r) \times \dots \times D_m(r)$$

of open sets  $D_1(r), D_2(r), \dots$  and  $D_m(r)$ , not necessarily connected, in the complex plane  $\mathbb{C}$ . For each  $i$  with  $1 \leq i \leq m$ , let  $a^i = (a_{j,k}^i(z, r))$  be a square matrix of degree  $m$  whose each  $(j, k)$ -element  $a_{j,k}^i(z, r)$  is a holomorphic function in  $\Omega$ . Let  $M$  be a Stein manifold and  $m$  be a positive integer. For any point  $r$  of  $M$  and each integer  $j$  with  $1 \leq j \leq m$ , let  $D_j(r)$  be an open set, which may depends on  $r$  and which is not necessarily connected, in the complex plane  $\mathbb{C}$ . We put

$$(1.10) \quad D(r) := D_1(r) \times D_2(r) \times \dots \times D_m(r).$$

For each point  $r$  of  $M$ , each connected component of the open set  $D(r)$  is a domain of holomorphy in the complex  $m$ -space  $\mathbb{C}^m$ . We assume that the subset

$$(1.11) \quad \Omega := \{(z, r) \in \mathbb{C}^m \times M; z \in D(r), r \in M\}$$

of the product Stein manifold  $\mathbb{C}^m \times M$  forms a Stein domain in  $\mathbb{C}^m \times M$ . For each  $i$  with  $1 \leq i \leq m$ , we put

$$(1.12) \quad D^i(r) := D_1(r) \times D_2(r) \times \cdots \times D_{i-1}(r) \times D_{i+1}(r) \times \cdots \times D_m(r),$$

$$(1.13) \quad \Omega^i := \{(z', r) \in \mathbb{C}^{m-1} \times M; z' \in D^i(r), r \in M\}.$$

For each  $i$  with  $1 \leq i \leq m$  and for any point  $(z', r) := (z_1, z_2, \dots, z_{i-1}, z_{i+1}, \dots, z_m, r)$  of  $\Omega^i$ , we introduce in the set  $\Omega$  an equivalence relation  $\approx$  by regarding each connected component of  $\{z_1\} \times \{z_2\} \times \cdots \times \{z_{i-1}\} \times D_i(r) \times \{z_{i+1}\} \times \cdots \times \{z_m\} \times \{r\}$  as a point. Let  $\widetilde{\Omega}^i := \Omega / \approx$  be the factor space of  $\Omega$  by this equivalence relation and  $\varphi^i : \widetilde{\Omega}^i \rightarrow \Omega^i \subset \mathbb{C}^{m-1} \times M$  be the canonical mapping which is a local homeomorphism.

Let  $a^i = (a_{j,k}^i(z, r))$  be a square matrix of degree  $m$  whose each  $(j, k)$  element  $a_{j,k}^i(z, r)$  is a holomorphic function in  $\Omega$ . For each  $i$  with  $1 \leq i \leq m$ , let  $T_i$  be a differential operator defined by (1.2).

Let  $\mathcal{O}_\Omega$  be the sheaf of germs of all holomorphic functions on  $\mathcal{O}_\Omega$ . Then each differential operator  $T_i$  defines a sheaf homomorphism

$$(1.14) \quad T_i : (\mathcal{O}_\Omega)^m \rightarrow (\mathcal{O}_\Omega)^m$$

similarly as (1.4). We put

$$(1.15) \quad T = T_1 T_2 \cdots T_m.$$

Let

$$(1.16) \quad H(\Omega) = H^0(\Omega, (\mathcal{O}_\Omega)^m)$$

be the set of global sections of  $(\mathcal{O}_\Omega)^m$  over  $\Omega$ .

Under the above notations, the main results of the present paper is as follows:

**MAIN THEOREM.** *The necessary condition for  $H^1(\Omega, Ker T) = 0$  is that, for any  $i = 1, 2, \dots, m$ , each connected component of  $D_i(r)$  is either, simultaneously for any  $r \in M$ , a simply connected domain in  $\mathbb{C}$  or, simultaneously for any  $r \in M$ , a doubly connected domain in  $\mathbb{C}$  for any  $r \in M$  with  $H^0(D_i(r), Ker T) = 0$ . For  $i = 1, 2, \dots, m$  such that each connected component of  $D_i(r)$  is simultaneously simply connected for any  $r \in M$ , we assume additionally that the coefficients  $a_{j,k}^i(z, r)$ 's are holomorphic in a cylindrical neighborhood  $E$  of  $\Omega$ . Then the necessary and sufficient condition for  $H^1(\Omega, Ker T) = 0$  is that, for  $i = 1, 2, \dots, m$ , the factor space  $\widetilde{\Omega}^i$  of  $\Omega$  is a Hausdorff space, that, for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a simply connected domain in  $\mathbb{C}$  for any  $r \in M$ , the domain  $(\widetilde{\Omega}^i, \varphi^i)$  is a Stein domain over  $\mathbb{C}^{m-1} \times M$  and that for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a doubly connected domain in  $\mathbb{C}$  for any  $(z', r) \in \mathbb{C}^{m-1} \times M$ , there holds  $H^0(\{z'\} \times D_i(r) \times M, Ker T_i) = 0$ .*

## 2. Proof of the main theorem

Let  $r$  be a point of the base space  $M$  and  $g(z)$  be any element of  $H^0(D(r), (\mathcal{O}_{D(r)})^m)$ , that is, any vector-valued holomorphic function on the cylindrical open set  $D(r)$  which is regarded as an analytic subset of the Stein manifold  $M$ , by the theorem of Oka-Cartan-Serre, there exists a holomorphic function  $G(z, r)$  on the whole  $\Omega$  such that restriction of  $G(z, r)$  to the section  $D(r)$  coincides with  $g(z)$ . The assumption that  $H^1(\Omega, Ker T) = H(\Omega)/T(H(\Omega)) = 0$  implies the existence of a solution  $F \in H(\Omega)$  of the partial differential equation  $TF = G$ . The restriction  $f$  of  $F$  to  $D(r)$  is a solution of the partial differential equation  $Tf = g$  because the partial differentiations of  $T$  is done only for the variables of  $z$ . Hence we have  $H^1(D(r), Ker T) = H(D(r))/T(H(D(r))) = 0$ . By the preparation theorem, that is, Main Theorem at page 181 of the previous paper [8], for any  $r \in M$  and for any  $i = 1, 2, \dots, m$  each connected component of  $D_i(r)$  is either a simply connected domain with  $H^0(D_i(r), Ker T_i) = 0$  in  $\mathbb{C}$  or a doubly connected domain in  $\mathbb{C}$ . Moreover, by the argument from page 102 till page 105 and the inductive argument from page 175 till page 177 of the previous paper [9], and for any  $i = 1, 2, \dots, m$  each connected component of  $D_i(r)$  is simul-

taneously either a simply connected domain in  $\mathbb{C}$  or simultaneously a doubly connected domain in  $\mathbb{C}$  for all  $r \in M$ .

Under the assumption that  $H^1(\Omega, Ker T) = 0$ , for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a simply connected domain in  $\mathbb{C}$  for any  $r \in M$ , we put the additional assumption that the coefficients  $a_{j,k}^i(z, r)$ 's are holomorphic in a cylindrical neighborhood  $E$  of  $\Omega$  and we can prove by inductual method from page 174 till page 180 of the previos paper[9] that the first cohomology group of the topological space  $\widetilde{\Omega}^i$  over  $\mathbb{C}^{m-1} \times M$  with coefficients in the sheaf of germs of holomorphic function over  $\widetilde{\Omega}^i$  vanishes and, therefore, we can prove by the arguments from page 108 till page 114 of the former paper[8] that  $\widetilde{\Omega}^i$  is a Hausdorff space and, with respect to the complex structure induced canonically by the local homeomorphism  $\varphi^i$ , the complex manifold  $\widetilde{\Omega}^i$  is Stein. Hence the domain  $(\widetilde{\Omega}^i, \varphi^i)$  is a Stein domain over  $\mathbb{C}^{m-1} \times M$ .

Under the assumption that  $H^1(\Omega, Ker T) = 0$ , for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a doubly connected domain in  $\mathbb{C}$  for any  $r \in M$ , we can prove by the arguments from page 105 till 107 of the former paper[8] the  $T_2$ -ness of the topological space  $\widetilde{\Omega}^i$ .

We can also establish the validity of the converse part of the main theorem because, for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a simply connected domain in  $\mathbb{C}$ , the condition given for the converse allows us to use the vanishment of the locally free analytic sheaf of sections of vector bundles formed by germs of homogeneous solutions  $f$  of  $T_i f = 0$  and because, for any  $i$  such that each connected component of  $D_i(r)$  is simultaneously a doubly connected domain in  $\mathbb{C}$ , the condition given for the converse  $H^0(\{z'\} \times D_i(r) \times M, Ker T_i) = 0$  gives us the unity of the homogeneous solution  $f$  of  $T_i f = 0$  in the cut  $\{z'\} \times D_i(r) \times M$ . Thus, we can prove  $H^1(\Omega, Ker T_i) = H(\Omega)/T_i(H(\Omega)) = 0$  for any  $i$  and we can prove the validity of converse by induction with respect to  $i$ .

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