

## A CONSTRUCTION OF PIECEWISE SOLENOIDAL VECTOR FIELDS

HYUN YOUNG LEE

### 1. Introduction

Let  $\Omega$  be a bounded domain in  $R^N$  with  $N = 2$  or  $N = 3$ , and whose boundary  $\partial\Omega$  is smooth. We consider the boundary value problem of the stationary Stokes equations: Seek a vector valued function  $\vec{u} = (u_1, u_2, \dots, u_N)$  (the velocity) and a scalar function  $p$  (the pressure) satisfying

$$(1) \quad \begin{cases} -\nu\Delta\vec{u} + \text{grad } p = \vec{f} & \text{in } \Omega, \\ \text{div } \vec{u} = 0 & \text{in } \Omega, \\ \vec{u} = 0 & \text{on } \partial\Omega; \end{cases}$$

where  $\nu > 0$  is the kinematic viscosity and  $\vec{f} = (f_1, f_2, \dots, f_N)$  is a given vector valued function.

For results concerning existence, uniqueness and regularity of (weak) solutions of (1), we refer to [6].

In constructing Galerkin discretization for the Stokes problem, one encounters a major difficulty in incorporating the incompressibility condition into the finite element space (cf.[5]). Various techniques have been developed to avoid this difficulty. One such method consists in using a Lagrange multiplier technique (cf.[3,4]). In [1], they introduced the finite dimensional approximating spaces  $V_k^N$  consisting of piecewise polynomial functions of degree  $\leq k$ ,  $k \geq 1$  for the velocity  $\vec{u}$  that are piecewise solenoidal i.e. the constituent functions satisfy the incompressibility condition (strongly) on each triangle in the subdivision of the domain  $\Omega$ . And they proved that these functions possess optimal approximating properties on the domains with curved boundaries.

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In this paper, we compute the dimension of  $V_k^N$  and construct the basis of  $V_k^N$  to provide an opportunity to use computer codes for real computations. In this paper, we will denote the set of polynomials of degree  $\leq k$  by  $P_k$  i.e.

$$P_k = \left\{ \sum \gamma_{\alpha_1 \alpha_2 \dots \alpha_N} x_1^{\alpha_1} x_2^{\alpha_2} \dots x_N^{\alpha_N} \mid \sum_{l=1}^N \alpha_l \leq k, \gamma_{\alpha_1 \alpha_2 \dots \alpha_N} \in \mathbb{R} \right\}$$

We know that (see [2])

$$\dim P_k = \binom{N+k}{k}.$$

## 2. The dimension of $V_k^N$

**THEOREM 1.**  $V_k^N = \{p \in (P_k)^N \mid \text{div } p = 0\}$ . Then

$$\dim V_k^N = N \binom{N+k}{k} - \binom{N+k-1}{k-1}.$$

*Proof.* Let  $A_k = \{x_1^{r_1} x_2^{r_2} \dots x_N^{r_N} \mid 0 \leq r_i \leq k, \sum_{i=1}^N r_i = k\}$ . Then  $P_k$  is the collection of all the possible finite linear combination of elements in  $A_0 \cup \dots \cup A_k$ , so we can say  $P_k = \text{Span}\{A_0 \cup A_1 \cup \dots \cup A_k\}$ . Obviously,

$$A_{k+1} = \bigcup_{i=1}^N \{x_i a_k \mid a_k \in A_k\}.$$

First we'll show that for each  $1 \leq i \leq N$ ,

$$\text{Span}(A_k) = \left\{ \frac{\partial}{\partial x_i} a_{k+1} \mid a_{k+1} \in \text{Span}(A_{k+1}) \right\}.$$

Choose  $x_1^{r_1} x_2^{r_2} \dots x_N^{r_N} \in A_k$ . If  $r_i = 0$ , then  $x_i(x_1^{r_1} x_2^{r_2} \dots x_N^{r_N}) \in A_{k+1}$  and

$$\frac{\partial}{\partial x_i} [x_i(x_1^{r_1} x_2^{r_2} \dots x_N^{r_N})] = x_1^{r_1} x_2^{r_2} \dots x_N^{r_N}.$$

If  $r_i \neq 0$ , then  $(x_1^{r_1} x_2^{r_2} \dots x_i^{r_i+1} \dots x_N^{r_N}) / (r_i + 1) \in \text{Span}(A_{k+1})$ , and

$$\frac{\partial}{\partial x_i} [(x_1^{r_1} x_2^{r_2} \dots x_i^{r_i+1} \dots x_N^{r_N}) / (r_i + 1)] = x_1^{r_1} x_2^{r_2} \dots x_i^{r_i} \dots x_N^{r_N}.$$

Therefore  $A_k \subset \left\{ \frac{\partial}{\partial x_i} a_{k+1} \mid a_{k+1} \in \text{Span}(A_{k+1}) \right\}$ , which implies

$$\text{Span}(A_k) \subset \left\{ \frac{\partial}{\partial x_i} a_{k+1} \mid a_{k+1} \in \text{Span}(A_{k+1}) \right\}.$$

To prove the reverse inclusion, choose  $x_1^{r_1} x_2^{r_2} \dots x_N^{r_N} \in A_{k+1}$ , then there exist  $i_0$  and  $a_k \in A_k$  such that

$$x_{i_0} a_k = x_{i_0} (x_1^{s_1} x_2^{s_2} \dots x_N^{s_N}), \text{ where } 0 \leq s_i \leq k \text{ and } \sum_{i=1}^N s_i = k.$$

If  $i = i_0$ ,

$$\begin{aligned} \frac{\partial}{\partial x_i} (x_{i_0} a_k) &= a_k + \left( \frac{\partial}{\partial x_i} a_k \right) x_{i_0} \\ &= a_k + s_i a_k \\ &= (1 + s_i) a_k \end{aligned}$$

which is in  $\text{Span}(A_k)$ .

If  $i \neq i_0$ ,

$$\begin{aligned} \frac{\partial}{\partial x_i} (x_{i_0} a_k) &= x_{i_0} \frac{\partial}{\partial x_i} (a_k) \\ &= s_i x_{i_0} x_1^{s_1} \dots x_i^{s_i-1} \dots x_N^{s_N} \end{aligned}$$

which is in  $\text{Span}(A_k)$ . Therefore we showed,

$$\left\{ \frac{\partial}{\partial x_i} a_{k+1} \mid a_{k+1} \in \text{Span}(A_{k+1}) \right\} \subset \text{Span}(A_k).$$

Next, we will prove that  $\text{div}$  is a linear mapping from  $(P_k)^N$  onto  $P_{k-1}$ , which implies the result

$$\begin{aligned} \dim V_k^N &= \dim(\ker(\text{div})) \\ &= \dim (P_K)^N - \dim P_{k-1} \\ &= N \binom{N+k}{k} - \binom{N+k-1}{k-1}. \end{aligned}$$

First we take div to the polynomial in  $(P_k)^N$ .

$$\begin{aligned} & \{ \operatorname{div}(p_1, p_2, \dots, p_N) \mid p_i \in P_k \text{ for all } 1 \leq i \leq N \} \\ &= \left\{ \sum_{i=1}^N \frac{\partial p_i}{\partial x_i} \mid p_i \in P_k, 1 \leq i \leq N \right\} \\ &= \left\{ \sum_{i=1}^N \frac{\partial p_i}{\partial x_i} \mid p_i \in \operatorname{Span}(A_0 \cup A_1 \cup \dots \cup A_k), 1 \leq i \leq N \right\}. \end{aligned}$$

Now choose  $p_i \in A_{k_i}$  for some  $1 \leq k_i \leq k$ . Then

$$\begin{aligned} \frac{\partial p_i}{\partial x_i} &\in \operatorname{Span}(A_0 \cup A_1 \cup \dots \cup A_{k^*-1}) \\ &\subset P_{k-1} \end{aligned}$$

for  $1 \leq i \leq N$ , where  $k^* = \max\{k_1, k_2, \dots, k_N\} \leq k$ . Let's show the reverse inclusion,

$$\begin{aligned} P_{k-1} &= \operatorname{Span}(A_0 \cup A_1 \cup \dots \cup A_{k-1}) \\ &= \operatorname{Span}A_0 \oplus \operatorname{Span}A_1 \oplus \dots \oplus \operatorname{Span}A_{k-1} \\ &= \left\{ \frac{\partial a_1}{\partial x_1} \mid a_1 \in \operatorname{Span}(A_1) \right\} \\ &\oplus \left\{ \frac{\partial a_2}{\partial x_1} \mid a_2 \in \operatorname{Span}(A_2) \right\} \\ &\vdots \\ &\oplus \left\{ \frac{\partial a_k}{\partial x_1} \mid a_k \in \operatorname{Span}(A_k) \right\} \\ &= \left\{ \frac{\partial p}{\partial x_1} \mid p \in P_k \right\} \\ &= \left\{ \sum_{i=1}^N \frac{\partial}{\partial x_i} p_i \mid p_i \in P_k \text{ and } p_i = 0, \text{ if } i \neq 1 \right\} \\ &\subset \{ \operatorname{div}(p_1, p_2, \dots, p_N) \mid p_i \in P_k \}. \end{aligned}$$

Therefore we proved div is a linear mapping from  $(P_k)^N$  onto  $P_{k-1}$ .

**3. The construction of a basis of  $V_k^N$**

Case I :  $N = 2$ .

(i)  $k = 1$

Theorem 1 gives  $\dim V_1^2 = 5$ . The basis is the following:

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 0 \\ x \end{pmatrix} \quad \begin{pmatrix} y \\ 0 \end{pmatrix} \quad \begin{pmatrix} x \\ -y \end{pmatrix}.$$

(ii)  $k = 2$

The basis is the following:

The vector polynomials for  $k = 1$ , and

$$\begin{pmatrix} x^2 \\ -2xy \end{pmatrix} \quad \begin{pmatrix} -2xy \\ y^2 \end{pmatrix} \quad \begin{pmatrix} y^2 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ x^2 \end{pmatrix}.$$

(iii)  $k = n$

The basis is the set of vector polynomials for  $k = n - 1$ , and

$$\begin{pmatrix} 0 \\ x^n \end{pmatrix} \quad \begin{pmatrix} 0 \\ y^n \end{pmatrix} \quad \begin{pmatrix} x^n \\ -nx^{n-1}y \end{pmatrix} \quad \begin{pmatrix} 2x^{n-1}y \\ -(n-1)x^{n-2}y^2 \end{pmatrix} \\ \begin{pmatrix} 3x^{n-2}y^2 \\ -(n-2)x^{n-3}y^3 \end{pmatrix} \quad \dots \quad \begin{pmatrix} -nxy^{n-1} \\ y^n \end{pmatrix}.$$

Case II :  $N = 3$ .

(i)  $k = 1$

Theorem 1 gives  $\dim V_1^3 = 11$ .

The basis is the following:

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 0 \\ x \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ x \end{pmatrix} \quad \begin{pmatrix} y \\ 0 \\ 0 \end{pmatrix} \\ \begin{pmatrix} 0 \\ 0 \\ y \end{pmatrix} \quad \begin{pmatrix} z \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ z \\ 0 \end{pmatrix} \quad \begin{pmatrix} x \\ 0 \\ -z \end{pmatrix} \quad \begin{pmatrix} 0 \\ y \\ -z \end{pmatrix}.$$

(ii)  $k = 2$

The basis is the set of the vector polynomials for  $k = 1$  and

$$\begin{pmatrix} 0 \\ x^2 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ x^2 \end{pmatrix} \quad \begin{pmatrix} y^2 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ y^2 \end{pmatrix} \quad \begin{pmatrix} z^2 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ z^2 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x^2 \\ 0 \\ -2xz \end{pmatrix} \begin{pmatrix} -2xz \\ 0 \\ z^2 \end{pmatrix} \begin{pmatrix} 0 \\ y^2 \\ -2yz \end{pmatrix} \begin{pmatrix} 0 \\ -2yz \\ z^2 \end{pmatrix} \begin{pmatrix} xy \\ 0 \\ -yz \end{pmatrix} \\ \begin{pmatrix} 0 \\ xy \\ -xz \end{pmatrix} \begin{pmatrix} yz \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ xz \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ xy \end{pmatrix}.$$

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Department of Mathematics  
 Kyungsung University  
 Pusan 609-736, Korea