

SASAKIAN SUBMANIFOLDS OF CODIMENSION 2 IN A SASAKIAN MANIFOLD WITH HARMONIC CURVATURE

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0. Introduction

Let N be a Sasakian manifold with the structure tensor (F, G, v) . If M is a submanifold immersed in N , M is said to be an *invariant* submanifold provided that the tangent space to M at each point of the submanifold is invariant under the action F . It is well known that an invariant submanifold tangent to the structure vector field v of a Sasakian manifold is also a Sasakian manifold. The study of invariant C -Einstein submanifolds of codimension 2 in a Sasakian manifold, which is called a problem of Nomizu-Smyth, were made by Endo [3], Kon [8], Pak and Oh [10], Yano and Ishihara [13] and so on. One of which, done by Yano and Ishihara [13], asserts that any invariant Einstein submanifold of codimension 2 immersed in a Sasakian manifold of constant curvature is totally geodesic. However, Pak and Oh [10] obtained the same result replacing the Sasakian manifold of constant curvature by that with vanishing C -Bochner curvature tensor.

The main purpose of the present paper is to investigate invariant submanifolds of codimension 2 immersed in an Einstein Sasakian manifold.

1. Invariant submanifolds of codimension 2 in a Sasakian manifold

Let N be a $(2n+1)$ -dimensional Sasakian manifold with Sasakian structure (F, G, v) covered by a system of coordinate neighborhoods $\{U ; x^A\}$, where here and in the sequel the indices A, B, C, \dots run over the range $\{1, 2, \dots, 2n+1\}$. We denote by F_B^A , G_{BA} and v^A components of the $(1, 1)$ -tensor F , of the Riemannian metric tensor G and of the

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structure vector field v respectively. We then have

$$(1.1) \quad \begin{aligned} F_C^B F_B^A &= -\delta_C^A + v_C v^A, \quad F_C^A v^C = 0, \quad v_A F_C^A = 0, \\ G_{BA} v^B v^A &= 1, \quad F_D^B F_C^A G_{BA} = G_{DC} - v_D v_C, \end{aligned}$$

where $v_C = G_{CE} v^E$. Denoting by ∇_A the operator of the covariant differentiation with respect to the fundamental tensor G_{BA} , we have

$$(1.2) \quad \nabla_C v_B = F_{CB}, \quad \nabla_C F_{EB} = -G_{CE} v_B + G_{CB} v_E.$$

From the last equation of (1.2) and the Ricci formula for F_{CB} , we find

$$(1.3) \quad \begin{aligned} R_{DCBA} F_E^A &= -R_{DCE}^A F_{AB} - G_{CB} F_{DE} + G_{DB} F_{CE} \\ &\quad + G_{CE} F_{DB} - G_{DE} F_{CB}, \end{aligned}$$

where R_{DCB}^A denotes components of the Riemannian curvature tensor of N . Moreover, we have

$$(1.4) \quad R_{DA} v^A = 2n v_D,$$

$$(1.5) \quad R_{DE} F_B^E + R_{BE} F_D^E = 0,$$

R_{DA} being components of the Ricci tensor of N .

Let M be an invariant submanifold of codimension 2 in N covered by a system of coordinate neighborhoods $\{V; y^h\}$, where here and in the sequel the indices h, i, j, \dots run over the range $\{1, 2, \dots, 2n-1\}$. And let M be immersed isometrically in N by the immersion $i: M \rightarrow N$. We represent the immersion i locally by $x^A = x^A(y^h)$ and put $B_j = (B_j^A)$ are $(2n-1)$ -linearly independent local tangent vector fields of M . We denote by C^A and D^A two mutually orthogonal unit normals to M . Then the induced Riemannian metric g_{ji} on M is given by

$$(1.6) \quad g_{ji} = G_{CB} B_j^C B_i^B$$

because the immersion is isometric.

Denoting by ∇_j the operator of van der Waerden-Botolotti covariant differentiation formed with g_{ji} , The equations of Gauss and Weingarten for M are respectively obtained:

$$(1.7) \quad \begin{cases} \nabla_j B_i^A = h_{ji} C^A + k_{ji} D^A, \\ \nabla_j C^A = -h_j^r B_r^A + l_j D^A, \\ \nabla_j D^A = -k_j^r B_r^A - l_j C^A, \end{cases}$$

where $h_j^r = h_{ji} g^{ir}$, $k_j^r = k_{ji} g^{ir}$ are components of the second fundamental tensors, l_j those of the third fundamental tensor and g^{ji} being contravariant components of g_{ji} . As to the transformations of B_j^A , C^A and D^A by F_B^A we have respectively equations of the form

$$(1.8) \quad F_B^A B_i^B = f_i^j B_j^A,$$

$$(1.9) \quad F_B^A C^B = D^A, \quad F_B^A D^B = -C^A,$$

where we have put $f_{ji} = G(FB_j, B_i)$. The structure vector field v is also represented by

$$(1.10) \quad v^A = p^i B_i^A,$$

where $p_i = G(B_i, v)$, p^i being contravariant components of p_i . From the last three equations, it follows that

$$(1.11) \quad \begin{cases} f_j^r f_r^h = -\delta_j^h + p_j p^h, & p^r f_r^h = 0, \\ g_{rs} f_j^r f_i^s = g_{ji} - p_j p_i, & p^r p_r = 1. \end{cases}$$

Differentiating (1.8) covariantly along N and making use of (1.7), (1.8) and (1.9), we have

$$(1.12) \quad \nabla_j p_i = f_{ji}, \quad \nabla_j f_i^h = -g_{ji} p^h + \delta_j^h p_i.$$

Then it is shown that the set (f, g, p) defines a Sasakian structure ([12, 14]). Similarly differentiating (1.10) covariantly and using (1.7) and (1.11), we have

$$(1.13) \quad h_{ji} = k_{jt} f_i^t, \quad k_{ji} = -h_{jt} f_i^t,$$

which imply

$$(1.14) \quad \begin{aligned} h_{j,r} p^r &= 0, & k_{j,r} p^r &= 0, \\ h_i^t &= k_i^t = 0. \end{aligned}$$

Thus, the submanifold of codimension 2 M is minimal.

From (1.13) we can easily see that

$$(1.15) \quad k_j, h_i^r + k_i, h_j^r = 0,$$

$$(1.16) \quad k_{ji}^2 = h_{ji}^2, \quad k_2 = h_2,$$

$$(1.17) \quad k_3 = h_3 = 0,$$

where we have defined $h_{ji}^2 = h_j, h_i^r$, $k_{ji}^2 = k_j, k_i^r$, $h_2 = h_{ji} h^{ji}$ and $h_3 = h_j, h_s^r h^{sj}$.

On the other hand, Gauss, Codazzi and Ricci equations for M are given respectively by

$$(1.18) \quad R_{DCBA} B_k^D B_j^C B_i^B B_h^A = R_{kjih} - (h_{kh} h_{ji} - h_{ki} h_{jh} + k_{kl} k_{ji} - k_{ki} k_{jh}),$$

$$(1.19) \quad R_{DCBA} B_k^D B_j^C B_i^B C^A = \nabla_k h_{ji} - \nabla_j h_{ki} - (l_k k_{ji} - l_j k_{ki}),$$

$$(1.20) \quad R_{DCBA} B_k^D B_j^C B_i^B D^A = \nabla_k l_j - \nabla_j l_k + h_{kr} k_j^r - h_{jr} k_k^r,$$

$$(1.21) \quad R_{DCBA} B_k^D B_j^C C^B D^A = \nabla_k l_j - \nabla_j l_k + h_{kr} k_j^r - h_{jr} k_k^r,$$

where $R_{k_j i h}$ denote covariant components of the Riemannian curvature tensor of M .

Putting $A_{kj} = \nabla_k l_j - \nabla_j l_k$ and utilizing (1.15), the equation (1.21) reduces to

$$(1.22) \quad R_{DCBA} B_k^D B_j^C C^B D^A = A_{kj} + 2h_{kr} k_j^r.$$

2. Sasakian submanifolds of codimension 2

Let M be an invariant submanifold of codimension 2 of a Sasakian manifold N . Transvecting (1.18) by g^{ji} and using (1.16), we find

$$R_{DA} B_k^D B_h^A - R_{DCBA} B_k^D B_h^A (C^C C^B + D^C D^B) = R_{kh} + 2h_{kr} k_h^r,$$

where R_{ji} denote components of the Ricci tensor of M . Transvecting f_j^h , we get

$$(2.1) \quad R_{kr} f_j^r - 2h_{kr} k_j^r = R_{DA} B_k^D f_j^r B_r^A - R_{DCBA} F_E^A B_j^E B_k^D (C^C C^B + D^C D^B)$$

On the other hand, from (1.3) we have

$$\begin{aligned} & R_{DCBA} F_E^A B_k^D B_j^E (C^C C^B + D^C D^B) \\ &= R_{DCEA} F_B^A B_k^D B_j^E C^C C^B + R_{DCEA} F_B^A B_k^D B_j^E D^C D^B + 2F_{ED} B_k^D B_j^E. \end{aligned}$$

Thus, using (1.8), (1.9) and (1.22), it follows that

$$R_{DCBA} F_E^A B_k^D B_j^E (C^C C^B + D^C D^B) = A_{kj} + 2h_{kr} k_j^r - 2f_{kj}.$$

Therefore (2.1) turns out to be

$$R_{DA} B_k^D f_j^r B_r^A = R_{kr} f_j^r + A_{kj} - 2f_{kj}.$$

Transvecting f_i^j and taking account of (1.11), we get

$$R_{DA} B_k^D (-\delta_i^r + p_i p^r) B_r^A = R_{kr} (-\delta_i^r + p_i p^r) + A_{kr} f_i^r - 2(g_{ki} - p_k p_i),$$

which together with (1.4) and (1.10) yields

$$R_{DA} B_j^D B_i^A = R_{ji} + 2g_{ji} - A_{jr} f_i^r.$$

LEMMA 1. *Let N be a $(2n+1)$ -dimensional Sasakian manifold with harmonic curvature.*

Proof. Differentiating (1.4) covariantly along N and using (1.1), we find

$$(\nabla_C R_{DA}) v^A + R_{DA} F_C^A = 2n F_{CD}.$$

Since N has harmonic curvature, namely, $\nabla_C R_{DA} - \nabla_D R_{CA} = 0$, it follows that

$$R_{DA} F_C^A - R_{CA} F_D^A = 4n F_{CD},$$

which together with (1.5) yields

$$(2.3) \quad R_{DA}F_C^A = 2nF_{CD}.$$

Transvecting (2.3) by F_B^C and making use of (1.1) and (1.4), we see that N is Einstein. This completes the proof.

Since M is also Sasakian manifold, we see that

$$(2.4) \quad f_j^r R_{ir} = f^{lk} R_{lijk} + (2n-3)f_{ji}.$$

Thus, if M is of harmonic curvature, then, by Lemma 1, M is Einstein, i. e. $R_{ji} = 2(n-1)g_{ji}$. Therefore (2.4) turns out to be

$$f^{lk} R_{lijk} = f_{ji}.$$

Transvecting (1.22) with p^j and using (1.10) and (1.14), we find

$$R_{DCBA}B_k^D v^C C^B D^A = A_{kj} p^j,$$

However, we have $R_{DCBA}v^A = v_D G_{CB} - v_C G_{DB}$, which is a direct consequence of (1.2), we get

$$R_{BADC}B_k^D v^C C^B D^A = 0.$$

Therefore we have

$$(2.6) \quad A_{jr} p^r = 0.$$

LEMMA 2. *Let M be an invariant submanifold of codimension 2 in a Sasakian manifold. Then we have*

$$(2.7) \quad \nabla^l \nabla_j h_{il} = (\nabla_l \nabla_j k_{ik}) f^{lk} + (2n-3)h_{ji}.$$

Proof. From (1.14), we have respectively

$$(\nabla_k k_{jr}) p^r + k_{jr} f_k^r = 0, \quad (\nabla_k h_{jr}) p^r + h_{jr} f_k^r = 0$$

because of (1.12). By using (1.13), it follows that

$$(2.8) \quad (\nabla_k k_{jr}) p^r = -h_{kj}, \quad (\nabla_k h_{jr}) p^r = k_{jk}.$$

Differentiating (1.13) covariantly along M and taking account of (1.12), we find respectively

$$(2.9) \quad \nabla_k h_{ji} = (\nabla_k k_{jr}) f_i^r + k_{jk} p_i, \quad \nabla_k k_{ji} = -(\nabla_k h_{jr}) f_i^r - h_{jk} p_i.$$

Differentiating (2.9) covariantly and using (1.12) we obtain

$$\nabla_l \nabla_k h_{ji} = (\nabla_l \nabla_k k_{jr}) f_i^r + (\nabla_k k_{jr}) (-g_{li} p^r + g_{lr} p_i) + (\nabla_l k_{jk}) p_i + k_{kj} f_{li},$$

or, making use of (2.8),

$$\nabla_l \nabla_k h_{ji} = (\nabla_l \nabla_k k_{jr}) f_i^r + g_{li} h_{kj} + (\nabla_k k_{jl}) p_i + (\nabla_l k_{jk}) p_i + k_{kj} f_{li}.$$

If we transvect g^{li} and use (2.8), then we obtain the equation (2.7) which completes the proof.

3. Invariant submanifolds of an Einstein manifold

Suppose that N is a $(2n+1)$ -dimensional Einstein manifold. Then we have $R_{DA}=2nG_{DA}$. It means that

$$R_{DA}B_j^DB_i^A=2ng_{ji}$$

Thus (2.2) reduces to

$$(3.1) \quad R_{ji}=2(n-1)g_{ji}+A_{jr}f_i^r$$

Substituting (3.1) into (2.4) and using (2.6), we find

$$f^{lk}R_{ljjk}=f_{ji}+A_{ji}$$

By the properties of the Sasakian structure, it follows that

$$f^{lk}R_{lkji}=-2(f_{ji}+A_{ji})$$

On the other hand, from the Ricci identity for k_{ji} , we obtain

$$\nabla_l\nabla_k k_{ji}-\nabla_k\nabla_l k_{ji}=-R_{lkjr}k_i^r-R_{lkir}k_j^r$$

Transvecting the above equation with f^{lk} and taking account of (1.13) and (3.2), it reduces to

$$(3.3) \quad f^{lk}\nabla_l\nabla_k k_{ji}=2h_{ji}+A_{jr}k_i^r+A_{ir}k_j^r$$

Thus, it follows that

$$(3.4) \quad h^{ji}f^{lk}\nabla_l\nabla_k k_{ji}=2h_2+A_{jr}k_i^r h^{ji}$$

PROPOSITION 3. *Let N be a Sasakian with harmonic curvature. If M is an invariant submanifold of codimension 2 in N , then the following assertions are true:*

(1) *M is an Einstein manifold if and only if the normal connection of M is flat.*

(2) *M is C-Einstein manifold if and only if $A_{ji}=-bf_{ji}$ for some constant b .*

Proof. (1) From Lemma 1 we have (3.1). Thus it is easily seen that $R_{ji}=2(n-1)g_{ji}$ is equivalent to $A_{ji}=0$ by taking account of (2.6).

(2) "If part" is evidently true because of (3.1).

Suppose that M is of C-Einstein, i. e. $R_{ji}=ag_{ji}+bp_jp_i$. Then from (3.1) we have

$$-b(g_{ji}-p_jp_i)=A_{jr}f_i^r$$

Differentiating the above equation covariantly and (2.6), we get

$$b(f_{kj}+f_{ki}p_j)=(\nabla_k A_{jr})f_i^r+A_{jk}p_i$$

Transvecting with p^i , we find $bf_{kj}=A_{jk}$. Thus we complete the proof.

THEOREM 4. *Let N be a $(2n+1)$ -dimensional Sasakian manifold with harmonic curvature and M be a compact C-Einstein submanifold of codimension 2 in N . If the second fundamental form is of Codazzi type and the scalar curvature of M is non-negative, then M is totally geodesic.*

Proof. Since h_{ji} is of Codazzi type, Lemma 2 tells us that

$$(3.5) \quad \Delta h_{ji} = (\nabla_j \nabla_k k_{ji}) f^{jk} + (2n-3) h_{ji},$$

where $\Delta = \nabla^i \nabla_i$ denotes the operator of Laplacian, which and (3.4) imply

$$(3.6) \quad h^{ji} \Delta h_{ji} = (2n-1) h_2 + A_{jr} k_r^i h^{ji}.$$

Since M is C-Einstein manifold, by Proposition 3, we see that $A_{jr} = -bf_{jr}$. Thus (3.6) reduces to

$$(3.7) \quad h^{ji} \Delta h_{ji} = (2n-1-b) h_2$$

because of (1.13). From (3.1) we have

$$R = 2(n-1)(2n-1-b) \geq 0$$

because the scalar curvature of M is non-negative is assumed. Therefore (3.7) means

$$h^{ji} \Delta h_{ji} = \frac{R}{2(n-1)} h_2.$$

Therefore we have the following identity:

$$(3.8) \quad \frac{1}{2} \Delta h_2 = \frac{R}{2(n-1)} h_2 + \|\nabla_k h_{ji}\|^2 \geq 0.$$

Since M is compact, we see, according to the Green's Theorem, that $h_2 = k_2 = 0$ because of (3.5). Thus M is totally geodesic because of (1.16).

Now, we prove the following theorem:

THEOREM 5. *Let M be a compact invariant submanifold of codimension 2 with harmonic curvature in a Sasakian manifold. If the second fundamental form is of Codazzi type, then M is totally geodesic.*

Proof. Since M is of also a Sasakian manifold with harmonic curvature, by Lemma 1, it follows that M is Einstein, that is,

$$R_{ji} = 2(n-1) g_{ji}.$$

Thus (2.5) is valid. Hence (3.3) becomes

$$f^{lk} \nabla_k \nabla_l k_{ji} = 2h_{ji}.$$

Therefore (3.5) reduces to

$$(3.9) \quad \Delta h_{ji} = (2n-1)h_{ji}$$

because h_{ji} is of Codazzi type. M being compact, combining (3.8) and (3.9), it is clear that $h_{ji} = k_{ji} = 0$. Thus M is totally geodesic.

REMARK 1. If we replace the compactness condition in Theorem 4 and Theorem 5 by $h_2 = \text{constant}$. Then we obtain the same result that M is totally geodesic.

REMARK 2. Let N be a Sasakian space form, then it is clear that $h_2 = \text{constant}$ and h_{ji} is of Codazzi type. Thus it follows that if M is an invariant submanifold of codimension 2 in a Sasakian space form $N(c)$, then M is totally geodesic (cf. [10]).

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