

Lagrange Stability and Poisson Stability in Transformation Groups

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1. Introduction

Let (X, T) be a transformation group. A point x of X is said to be *Lagrange stable* if the orbit closure \overline{xT} of x is compact. Suppose that the phase group T is noncompact. Given a point x of X , the limit set $L(x)$ of x is defined to be the intersection of $\overline{xK^c}$ for all compact subsets K of T . A point x of X is said to be *Poisson stable* if x belongs to $L(x)$. In this paper some properties of the above concepts are discussed. These results are the generalization of those in flows.

2. Preliminaries

Definition 2.1. A transformation group is a triple (X, T, ϕ) where X is a topological space called the phase space, T is a topological group called the phase group and $\phi : X \times T \rightarrow X, (x, t) \rightarrow xt$ is a continuous map such that for all $x \in X, s, t \in T, xe = x, (xs)t = x(st)$ where e is the identity of T .

It will be convenient to suppress the map ϕ and then denote the transformation group (X, T, ϕ) simply as (X, T) .

Definition 2.2. Let (X, T) be a transformation group. T is said to act freely on X if for each point x of X the map $\phi_x : T \rightarrow X, t \rightarrow xt$ is injective.

Definition 2.3. Let (X, T) be a transformation group. A subset M of X is said to be invariant if Mt is contained in M for all $t \in T$.

Definition 2.4. Let (X, T) and (Y, T) be transformation groups. A continuous map $f : X \rightarrow Y$ is called a homomorphism if $f(xt) = f(x)t$ for all $x \in X, t \in T$.

Definition 2.5. A topological space X is said to be hemicompact if there exists a sequence (K_n) of compact subsets of X such that if K is any compact subset of X , then K is contained in K_{n_0} for some n_0 .

In this paper we only deal with a transformation group whose phase space is Hausdorff and phase group is noncompact.

3. Limit sets

Definition 3.1. Let (X, T) be a transformation group and x a point of X . The limit set $L(x)$ of x is defined by the intersection of $\overline{xK^c}$ for all compact subsets K of T .

For a net (t_α) in $T, t_\alpha \rightarrow \infty$ is to mean that (t_α) is ultimately outside each compact subset of T .

Theorem 3.2. Let (X, T) be a transformation group. For all points x, y of $X, y \in L(x)$ if and

only if there exists a net (t_α) in T such that $t_\alpha \rightarrow \infty$, $xt_\alpha \rightarrow y$.

Proof. (\Rightarrow) Let (K_α) be the family of all compact subsets of T with the inclusion order and (U_β) the family of all neighborhoods of y with the reverse inclusion order. Define $(\alpha_1, \beta_1) \leq (\alpha_2, \beta_2)$ by $\alpha_1 \leq \alpha_2$ and $\beta_1 \leq \beta_2$. For any (α, β) , since $U_\beta \cap xK_\alpha^c \neq \phi$, there exists $t_{(\alpha, \beta)} \in K_\alpha^c$ such that $xt_{(\alpha, \beta)} \in U_\beta$. It is not hard to show that $t_{(\alpha, \beta)} \rightarrow \infty$, $xt_{(\alpha, \beta)} \rightarrow y$.

(\Leftarrow) Given any compact subset K of T , there exists α_0 such that $t_\alpha \in K^c$ for all $\alpha \geq \alpha_0$. For each neighborhood U of y , there exists α_1 such that $xt_\alpha \in U$ for all $\alpha \geq \alpha_1$. There exists α_2 such that $\alpha_0, \alpha_1 \leq \alpha_2$. Clearly $xt_{\alpha_2} \in U \cap xK^c$ and so $U \cap x\overline{K}^c \neq \phi$. Thus $y \in x\overline{K}^c$, consequently $y \in L(x)$.

Theorem 3.3. Let (X, T) be a transformation group. For any point x of X , $\overline{xT} = xT \cup L(x)$.

Proof. Clearly, $xT \cup L(x) \subset \overline{xT}$. Suppose that $xT \cup L(x) \neq \overline{xT}$. There exists $y \in \overline{xT} - (xT \cup L(x))$. Since $y \notin L(x)$, there exists a compact subset K of T such that $y \in x\overline{K}^c$. Thus $U \cap xK^c = \phi$ for some neighborhood U of y . Clearly, xK is a closed subset of X . Since $y \notin xT$, $y \notin xK$. Take $V = U \cap (xK)^c$. Then V is a neighborhood of y and $V \cap xT = \phi$. Thus $y \notin \overline{xT}$. This is a contradiction. Hence $\overline{xT} = xT \cup L(x)$.

Theorem 3.4. Let (X, T) be a transformation group. For any point x of X , $L(x)$ is invariant.

Proof. Let y be a point of $L(x)$ and t an element of T . There exists a net (t_α) in T such that $t_\alpha \rightarrow \infty$, $xt_\alpha \rightarrow y$. It is not hard to show that $t_\alpha t \rightarrow \infty$. Since $xt_\alpha t \rightarrow yt$, $yt \in L(x)$. Thus $L(x)$ is invariant.

Theorem 3.5. Let (X, T) be a transformation group and x a point of X . For any point y of xT , $L(y) = L(x)$.

Proof. $y = xt$ for some $t \in T$. Let $z \in L(y)$. Then there exists a net (t_α) in T such that $t_\alpha \rightarrow \infty$, $yt_\alpha = xtt_\alpha \rightarrow z$. It is not hard to show that $tt_\alpha \rightarrow \infty$. Thus $z \in L(x)$. Let $z \in L(x)$. Then there exists a net (t_α) in T such that $t_\alpha \rightarrow \infty$, $xt_\alpha = xtt_\alpha^{-1}t_\alpha = yt^{-1}t_\alpha \rightarrow z$. Clearly, $t^{-1}t_\alpha \rightarrow \infty$ and so $z \in L(y)$. Hence $L(y) = L(x)$.

Theorem 3.6. Let $f: (X, T) \rightarrow (Y, T)$ be a homomorphism of transformation groups. For any point x of X , $f(L(x)) \subset L(f(x))$.

Proof. Let $y \in f(L(x))$. $y = f(z)$ for some $z \in L(x)$. There exists a net (t_α) in T such that $t_\alpha \rightarrow \infty$, $xt_\alpha \rightarrow z$. $f(xt_\alpha) = f(x)t_\alpha \rightarrow f(z) = y$. Thus $y \in L(f(x))$. Hence $f(L(x)) \subset L(f(x))$.

4. Lagrange stability

Definition 4.1. Let (X, T) be a transformation group. A point x of X is said to be *Lagrange stable* if the orbit closure \overline{xT} is compact.

Theorem 4.2. Let (X, T) be a transformation group. If a point x of X is Lagrange stable, then $L(x)$ is nonempty.

Proof. Let (K_α) be the family of all compact subsets of T . We will prove that $(x\overline{K_\alpha^c})$ has the finite intersection property $\bigcap_{i=1}^n x\overline{K_{\alpha_i}^c} \supset \bigcap_{i=1}^n xK_{\alpha_i}^c \supset x\bigcap_{i=1}^n K_{\alpha_i}^c$. Since T is noncompact, $\bigcap_{i=1}^n K_{\alpha_i}^c \neq \phi$. Thus

$\bigcap_{i=1}^n \overline{xK_{\alpha_i}^c} \neq \phi$. Since \overline{xT} is compact, $\bigcap \overline{xK_{\alpha}^c} = L(x) \neq \phi$.

Corollary 4.3. *Let (X, T) be a transformation group. If a point x of X is Lagrange stable, then $L(x)$ is compact.*

Theorem 4.4. *Let (X, T) be a transformation group. If a point x of X is Lagrange stable, then for each neighborhood U of $L(x)$, there exists a compact subset K of T such that $xK^c \subset U$.*

Proof. By theorem 4.2 $L(x) \neq \phi$. Let (K_{α}) be the family of all compact subsets of T with the inclusion order. Suppose that there exists a neighborhood U of $L(x)$ such that $xK_{\alpha}^c \subset U$ for all α . For each α , there exists $t_{\alpha} \in K_{\alpha}^c$ such that $xt_{\alpha} \in U$. (xt_{α}) is a net in \overline{xT} . Since \overline{xT} is compact, (xt_{α}) has a convergent subnet. Let $xt_{\alpha} \rightarrow y \in \overline{xT}$. It is not hard to show that $t_{\alpha} \rightarrow \infty$. Thus $y \in L(x)$ and so U is a neighborhood of y . Since $xt_{\alpha} \rightarrow y$, there exists α_0 such that $xt_{\alpha} \in U$ for all $\alpha \geq \alpha_0$. This is a contradiction. Hence the theorem holds.

Theorem 4.5. *Let (X, T) be a transformation group whose phase space is locally compact. Given a point x of X , if $L(x) \neq \phi$ is compact and for each neighborhood U of $L(x)$, there exists a compact subset K of T such that $xK^c \subset U$, then x is Lagrange stable.*

Proof. Since X is locally connected and $L(x)$ is compact, there exists a neighborhood U of $L(x)$ such that \bar{U} is compact. By assumption, there exists a compact subset K of T such that $xK^c \subset U$. $xT = xK \cup xK^c \subset xK \cup U$, $\overline{xT} \subset \overline{xK} \cup U = xK \cup \bar{U}$. $xK \cup \bar{U}$ is compact. Thus \overline{xT} is compact.

Theorem 4.6. *Let (X, T) be a transformation group whose phase space is locally compact and phase group is hemicompact. There exists a sequence (K_n) of compact subsets of T such that if K is any compact subset of T , then $K \subset K_{n_0}$ for some n_0 . Suppose that K_n^c is connected for all n . Given a point x of X , if $L(x) \neq \phi$ is compact, then x is Lagrange stable.*

Proof. Suppose that there exists a neighborhood U of $L(x)$ such that $xK_n^c \subset U$ for all n . Since X is locally compact and $L(x)$ is compact, there exists a neighborhood V of $L(x)$ such that $\bar{V} \subset U$ and \bar{V} is compact. For each n , there exists $t_n \in K_n^c$ such that $xt_n \in U$ so that $xt_n \in \bar{V}$. Since $L(x) \neq \phi$, there exists $y \in L(x)$. V is a neighborhood of y . For each n , since $y \in \overline{xK_n^c}$, $V \cap xK_n^c \neq \phi$ so there exists $S_n \in K_n^c$ such that $xS_n \in V$. For each n , since K_n^c is connected, there exists $r_n \in K_n^c$ such that $xr_n \in \partial V$. (xr_n) is a sequence in ∂V . Since ∂V is compact, (xr_n) has a convergent subsequence. Let $xr_n \rightarrow z \in \partial V$. It is not hard to show that $r_n \rightarrow \infty$. Since $z \in L(x) \subset V$, $V \cap \partial V \neq \phi$ and this is a contradiction. Thus for any neighborhood U of $L(x)$, there exists n_0 such that $xK_{n_0}^c \subset U$. By theorem 4.5, x is Lagrange stable.

Theorem 4.7. *Let (X, T) be a transformation group whose phase space is first countable, phase group is hemicompact. For all points x, y of X , $y \in L(x)$ if and only if there exists a sequence (t_n) in T such that $t_n \rightarrow \infty$, $xt_n \rightarrow y$.*

Proof. (\Rightarrow) Since T is hemicompact, there exists a sequence (K_n) of compact subsets of T such that if K is any compact subset of T , then $K \subset K_{n_0}$ for some n_0 . We can assume that (K_n) has the inclusion order. Let (U_m) be a countable basis at y with the reverse inclusion order. Define $(n_1, m_1) \leq (n_2, m_2)$ by $n_1 \leq n_2$, $m_1 \leq m_2$.

For each (n, m) , $Um \cap xKn^c \neq \emptyset$ so there exists $t_{(n,m)} \in Kn^c$ such that $xt_{(n,m)} \in Um$. Take $t_n = t_{(n,n)}$. It is not hard to show that $t_n \rightarrow \infty$ and $xt_n \rightarrow y$.

(\Leftarrow) By theorem 3.2, it is obvious.

Theorem 4.8. *Let (X, T) be a transformation group whose phase space is locally compact, first countable and phase group is hemicompact. There exists a sequence (Kn) of compact subsets of T such that if K is any compact subset of T , then $K \subset Kn_0$ for some n_0 . Suppose that Kn^c is connected for all n . If $x \in X$ is Lagrange stable, then $L(x)$ is connected.*

Proof. Suppose that $L(x)$ is disconnected. $L(x) = A \cup B$ for some disjoint nonempty closed subsets A, B of X . B^c is a neighborhood of A . Since $L(x)$ is compact, A is compact. Since X is locally compact, there exists a neighborhood U of A such that $\bar{U} \subset B^c$ and \bar{U} is compact. There exist $a \in A, b \in B$ for A, B are nonempty. By theorem 4.7, there exist sequences $(t_m), (s_k)$ in T such that $t_m, s_k \rightarrow \infty, xt_m \rightarrow a, xs_k \rightarrow b$. Since U is a neighborhood of a and \bar{U}^c is a neighborhood of b , there exist m_0, k_0 such that $xt_m \in U, xs_k \in \bar{U}^c$ for all $m \geq m_0, k \geq k_0$. For each n , there exist $m(n), k(n)$ such that $t_m, s_n \in Kn^c$ for all $m \geq m(n), k \geq k(n)$. Let $l_1 = \max(m_0, k_0, m(1), k(1)), l_{i+1} = \max(i+1, k(i+1), l_i+1)$. Clearly, $l_1 < l_2 < \dots, tl_i, sl_i \in K_i^c, xt_{l_i} \in U, xs_{l_i} \in \bar{U}^c$ for all i . For each i , since K_i^c is connected, there exists $r_{l_i} \in K_i^c$ such that $xr_{l_i} \in \partial U$. (xr_{l_i}) is a sequence in ∂U . Since ∂U is compact, (xr_{l_i}) has a convergent subsequence. Let $xr_{l_i} \rightarrow y \in \partial U, y \notin A \cup B = L(x)$. It is not hard to show that $r_{l_i} \rightarrow \infty$. Thus $y \in L(x)$, this is a contradiction. Hence $L(x)$ is connected.

Theorem 4.9. *Let (X, T) be a transformation group. If a point x of X is Lagrange stable, then any point y of $L(x)$ is Lagrange stable.*

Proof. Since $y \in L(x), \overline{yT} \subset L(x)$. Thus \overline{yT} is compact.

5. Poisson stability

Definition 5.1. Let (X, T) be a transformation group. A point x of X is said to be *Poisson stable* if $x \in L(x)$.

It is not hard to show that the following three statements are equivalent

$$x \in L(x), L(x) = \overline{xT}, xT \cap L(x) \neq \emptyset$$

Theorem 5.2. *Let $f: (X, T) \rightarrow (Y, T)$ be a homomorphism of transformation groups. If $x \in X$ is Poisson stable, then $f(x)$ is Poisson stable.*

Proof. Since $x \in L(x), f(x) \in f(L(x)) \subset L(f(x))$.

Theorem 5.3. *Let (X, T) be a transformation group. Suppose that X is first countable, T is hemicompact and T acts freely on X . If $x \in X$ is not Poisson stable, then $\phi_x: T \rightarrow xT$ is a homeomorphism.*

Proof. Clearly, ϕ_x is a continuous bijection. Let A be a closed subset of T . $\phi_x(A) = xA$. Let y belong to the closure of xA in xT . Since X is first countable, there exists a sequence (t_m) in A such that $xt_m \rightarrow y$. Since T is hemicompact, there exists a sequence (K_n) of compact subsets of T such that if K is any compact subset of T , then $K \subset Kn_0$ for some n_0 . Let us show that there exists n_0 such that for each m , there exists $m_0 \geq m$ such that $t_m \in Kn_0$. Suppose that for each n , there exists m_0 such that $t_m \in Kn^c$ for all $m \geq m_0$. It is not hard to show that $t_m \rightarrow \infty$. By theorem 3.2, $y \in L(x)$. Thus $y \in xT \cap L(x)$ and $x \in L(x)$. This is a contradiction for x is not Poisson stable. Take $m_1 = 1$

For each k , there exists $m_{k+1} \geq m_k + 1$ such that $t_{m_{k+1}} \in Kn_0$. (t_{m_k}) is a sequence in Kn_0 . Since Kn_0 is compact, (t_{m_k}) has a convergent subsequence. Let $t_{m_k} \rightarrow t \in Kn_0$. Clearly, $xt_{m_k} \rightarrow xt$. (t_{m_k}) is also a sequence in A . Thus $t \in \bar{A} = A$ and $yt \in xA$. Since (xt_{m_k}) is a subsequence of (xt_m) , $xt_{m_k} \rightarrow y$, $y = xt \in xA$ for X is Hausdorff. Thus the closure of xA in xT contained in xA and so xA is a closed subset of xT . Hence ϕ_x^{-1} is continuous. Consequently, ϕ_x is a homeomorphism.

Let (X, T) be a transformation group. If $x \in X$ is not Poisson stable, then $xT \cap L(x) = \phi$ by definition. Since $\overline{xT} = xT \cup L(x)$, $L(x) = \overline{xT} - xT$. So $L(x) = \overline{xT - xT}$. But if x is Poisson stable, this does not hold in general.

Theorem 5.4. *Let (X, T) be a transformation group. Suppose that X is locally compact, T is hemicompact and T acts freely on X . If $x \in X$ is Poisson stable, then $L(x) = \overline{xT} - xT$.*

Proof. It is clear that $\overline{xT} - xT \subset L(x)$.

Let $y \in L(x)$. Given any neighborhood U of y , we will show that $U \cap (L(x) - xT) \neq \phi$. Since X is locally compact, there exists a neighborhood V of y such that $\bar{V} \subset U$ and \bar{V} is compact. Since T is hemicompact, there exists a sequence (K_n) of compact subsets of T such that if K is any compact subset of T , then $K \subset K_{n_0}$ for some n_0 . It is not hard to show that $L(x) = \bigcap_{n=1}^{\infty} \overline{xK_n^c}$. $V \cap xK_1^c \neq \phi$. Thus there exists $t_1 \in K_1^c$ such that $xt_1 = y_1 \in V$. Since T acts freely on X , $xK_1 \cap xK_1^c = \phi$ so $y_1 \notin xK_1$. Thus $V \cap (xK_1)^c$ is a neighborhood of y_1 . There exists a neighborhood V_1 of y_1 such that $\bar{V}_1 \subset V \cap (xK_1)^c$. Since $y_1 = xt_1 \in xT \subset \overline{xT} = L(x)$, $V_1 \cap xK_2^c \neq \phi$ so there exists $t_2 \in K_2^c$ such that $xt_2 = y_2 \in V_1$. Since $xK_2 \cap xK_2^c = \phi$, $y_2 \notin xK_2$. So $V_1 \cap (xK_2)^c$ is a neighborhood of y_2 . There exists a neighborhood V_2 of y_2 such that $\bar{V}_2 \subset V_1 \cap (xK_2)^c$. We proceed in this way repeatedly. Clearly $V_n \cap xK_n^c \neq \phi$ for all n , and $\bar{V}_1 \supset \overline{V_1 \cap xK_1^c} \supset \overline{V_2 \cap xK_2^c} \supset \dots$. Since \bar{V} is compact, $\phi \neq \bigcap_{n=1}^{\infty} \overline{V_n \cap xK_n^c} \subset \bigcap_{n=1}^{\infty} (\overline{V_n \cap xK_n^c}) = \bigcap_{n=1}^{\infty} \bar{V}_n \cap \bigcap_{n=1}^{\infty} \overline{xK_n^c} = \bigcap_{n=1}^{\infty} \bar{V}_n \cap L(x)$ so there exists $z \in \bigcap_{n=1}^{\infty} \bar{V}_n \cap L(x)$. Since $z \in \bar{V}_1 \subset V \subset U$ and $\bar{V}_1 \cap xK_1 = \phi$, $z \notin xK_1$. Thus $z \notin xT$. Therefore $z \in U \cap (L(x) - xT)$. This means that $y \in \overline{L(x) - xT}$. Consequently, $L(x) = \overline{xT - xT}$.

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