TOPOLOGIES ON GENERALIZED SEMI-INNER PRODUCT ALGEBRAS, LATTICES, AND SPACES

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1. Introduction

In his paper [2], Lumer has introduced the concept of semi-inner product space. This concept has led Husain and Malviya [1] to introduce and study, what they call, semi-inner product algebras. In a different direction Nath [4] has used Lumer's concept to introduce, what he calls, generalized semi-inner product spaces, and has studied strong topologies on such spaces. These strong topologies have earlier been studied on generalized inner product spaces by Prugovecki [6].

In this paper we introduce, what we call, generalized semi-inner product (in short g.s.i.p.) algebras, and lattices, and show that a g.s.i.p. algebra (lattice) with strong topology is locally convex algebra (lattice). We also show that a g.s.i.p. algebra with strong topology under a restriction is locally m-convex algebra. Finally, we show that it is possible to introduce, as in [6], weak topologies in g.s.i.p. spaces, and it turns out that a g.s.i.p. space with weak topology is a Hausdorff locally convex space.

Throughout in this paper, we have used N to denote the set of natural numbers.

2. g.s.i.p. algebras

G. Lumer [2] calls a complex (real) vector space X a semi-inner product space (abbreviated to s. i. p. space) if to every pair of of elements $x, y \in X$ there corresponds a complex (real) number, written as [x,y], with the following properties:

(i)
$$[x+y,z] = [x,z] + [y,z],$$
 $[\lambda x,y] = \lambda [x,y], x,y,z \in X, \lambda : complex (real),$ (ii) $[x,x] > 0$ for $x \neq 0$, and

(iii) $|[x,y]|^2 \le [x,x][y,y].$

REMARK 2.1. With $||x|| = [x, x]^{1/2}$, a s.i.p. space becomes a normed space.

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It is clear from (i) and (ii) that [x, y] = 0 for all $y \in X$ iff x = 0, Moreover, if either of x, y is zero, then [x, y] = 0.

DEFINITION 2.2. A vector space A is called a s.i.p. algebra if (a) A is a normed algebra, and (b) A is a s.i.p. space with the same norm as that of the normed algebra A,

REMARK 2.3. Our definition of a s.i.p. algebra is different from that given in [1].

DEFINITON 2.4. A vector space A is called a generalized semi-inner product algebra (abbreviated to g.s.i.p. algebra) if

- (i) A is an algebra,
- (ii) there is a subspace M of A which is a s.i.p. algebra, and
- (iii) there is a set ζ of linear multiplicative operators on A satisfying (a) $\zeta A \subset M$, i.e. each member of ζ maps A into M, and (b) Tx=0 for all $T \subset \zeta$, implies x=0.

We denote such a g.s. i. p. algebra by the triple (A, ζ, M) .

EXAMPLE 2.5. Let A be the space of all measurable functions on a compact topological group G with Haar measure. A is a vector space if

$$(f+g)(x)=f(x)+f(y)$$
 and $(\lambda f)(x)=\lambda f(x), f, g \in A, \lambda \text{ scalar.}$

Clearly A is an algebra. Now, consider the vector subspace $M = L^p(G)$, $2 \le p < \infty$, of A; then M is a s.i.p. algebra if

$$(fg)(x) = \int_C f(xy^{-1})g(y)dy$$

and

$$[f, g] = \frac{1}{\|g\|_{p}^{p-2}} \int_{G} f(x) |g(x)|^{p-1} \operatorname{sgn}(g(x)) dx,$$

where

$$\|g\|_p = \left(\int_G |g(x)|^p dx\right)^{1/p}$$

and sgn is the signum function. Let ζ be the family of operators $E^{p-1}(S)$ defined by

 $(E^{p-1}(S)(\alpha f + \beta g))(x) = \chi_S(x)(|f(x)|^{p-2} + |g(x)|^{p-2})(\alpha f(x) + \beta g(x)),$ where χ_S is the characteristic function of S and S is a subset of A whose Haar measure is non-zero. Clearly each $E^{p-1}(S)$ is linear. It can easily be verified that

 $\zeta A \subset M$ and Tx=0 for all $T \in \zeta$ implies x=0. Since

$$\chi_S = \chi_S \chi_S$$
,

it follows that each $E^{p-1}(S)$ is multiplicative. Thus, (A, ζ, M) is a g.s.i.p. algebra. But it is not a s.i.p. algebra.

3. Strong topology

Let (A, ζ, M) be a g.s.i.p. algebra. We introduce "strong topology" in A as follows:

DEFINITION 3.1. For each $x \in A$, define

$$V(x; T_1, \dots, T_n; \varepsilon) = \{y \in A; [T_i(y-x), T_i(y-x)]^{1/2} < \varepsilon, 1 \le i \le n\}$$

for all $\varepsilon > 0$, T_1 , ..., $T_n \in \zeta$ and $n \in N$. The family $\{V(x; T_1, ..., T_n; \varepsilon): T_1, ..., T_n \in \zeta$, $\varepsilon > 0$, $n \in N$ forms a neighbourhood basis at x, for each $x \in A$, for a topology on A which we call "strong topology".

REMARK 3.2. It is known, from [4], that (i) each $V(0; T_1, \dots, T_n; \varepsilon)$ is circled and convex, and that (ii) the topology on A for which the sets $V(x; T; \varepsilon)$ are neighbourhoods of x for all $\varepsilon > 0$, $T \in \zeta$ is Hausdorff.

Michael [3] calls a subset of an algebra m-convex (multiplicatively convex if V is convex and idempotent (i.e. $VV \subset V$).

LEMMA 3.3. Let (A, ζ, M) be a g.s.i.p. algebra. Then each $V(0; T_1, \dots, T_n; \varepsilon)$, $0 < \varepsilon \le 1$, is m-convex.

PROOF. Clearly $V(0; T_1, \dots, T_n; \varepsilon)$ is convex by 3.2. We show that it is idempotent i.e. $V(0; T_1, \dots, T_n; \varepsilon)V(0; T_1, \dots, T_n; \varepsilon) \subset V(0; T_1, \dots, T_n; \varepsilon)$ $(0 < \varepsilon \le 1)$. Let $x, y \in V(0; T_1, \dots, T_n; \varepsilon)$. Then,

$$\begin{split} [T_k(xy), \ T_k(xy)]^{1/2} &= [T_k(x)T_k(y), \ T_k(x)T_k(y)]^{1/2}, \ 1 \leq k < n \\ &\leq [T_k(x), \ T_k(x)]^{1/2} [T_k(y), \ T_k(y)]^{1/2} < \varepsilon^2 \leq \varepsilon. \end{split}$$

This implies that $xy \in V(0; T_1, \dots, T_n; \varepsilon)$ for all $x, y \in V(0; T_1, \dots, T_n; \varepsilon)$, $0 < \varepsilon \le 1$, and this establishes the idempotentness of $V(0; T_1, \dots, T_n; \varepsilon)$, $0 < \varepsilon \le 1$. Hence it is m-convex.

A locally convex algebra is an algebra and a Hausdorff locally convex space such that the multiplication is continuous in each variable separately ([3], page 3). A locally convex algebra is called locally *m*-convex algebra if there exists a neighbourhood basis of 0 consisting of *m*-convex sets ([3], page 6).

THEOREM 3.4. A g.s.i.p. algebra (A, ζ, M) equipped with the strong topology, as defined in 3.1, is a locally convex algebra.

PROOF. In view of ([4], 3.3), (A, ζ, M) is a Hausdorff locally convex space. To complete the proof we show that for any $V(x_0x; T_1, \dots, T_n; \varepsilon)$, there exists

$$V\left(x; T_{1}, \cdots, T_{n}; \frac{\varepsilon}{\lambda}\right), \lambda = \max_{1 \leq k \leq n}(\lambda_{k}),$$

$$\lambda_{k} = \left[T_{k}(x_{0}), T_{k}(x_{0})\right]^{1/2}, k = 1, \cdots, n, \text{ such that}$$

$$x_{0}V\left(x; T_{1}, \cdots, T_{n}; \frac{\varepsilon}{\lambda}\right) \subset V(x_{0}x; T_{1}, \cdots, T_{n}; \varepsilon).$$

Let $y \in V(x; T_1, \dots, T_n; \frac{\varepsilon}{\lambda})$; then

$$[T_k(y-x), T_k(y-x)]^{1/2} < \frac{\varepsilon}{\lambda}, k=1, 2, \dots, n.$$

Now,

$$\begin{split} \left[T_{k}(x_{0}y-x_{0}x), \ T_{k}(x_{0}y-x_{0}x)\right]^{1/2} &= \left[T_{k}x_{0}(y-x), \ T_{k}x_{0}(y-x)\right]^{1/2} \\ &= \left[T_{k}(x_{0})T_{k}(y-x), \ T_{k}(x_{0})T_{k}(y-x)\right]^{1/2} \\ &\leq \left[T_{k}(x_{0}), T_{k}(x_{0})\right]^{1/2} \left[T_{k}(y-x), \ T_{k}(y-x)\right]^{1/2} \\ &< \lambda \frac{\varepsilon}{\lambda} = \varepsilon. \end{split}$$

This implies that $x_0 y \in V(x_0 x; T_1, \dots, T_n; \varepsilon)$, for all $y \in V(x; T_1, \dots, T_n; \varepsilon/\lambda)$, and this proves that

$$x_0V(x; T_1, \dots, T_n; \varepsilon/\lambda) \subset V(x_0x; T_1, \dots, T_n; \varepsilon).$$

Similarly, we can show that

$$V(x; T_1, \dots, T_n; \varepsilon/\lambda)x_0 \subset V(xx_0; T_1, \dots, T_n; \varepsilon).$$

This shows that (A, ζ, M) is a locally convex algebra under the strong topology.

COROLLARY 3.5. A g.s.i.p. algebra (A, ζ, M) equipped with the strong topology for which the family $\{V(x; T_1, \dots, T_n; \varepsilon); T_1, \dots, T_n \in \zeta, 0 < \varepsilon \le 1, n \in N\}$ forms a neighbourhood basis of x, for each $x \in A$, is a locally m-convex algebra.

PROOF. The result follows from 3.3 and 3.4 if λ , as defined in 3.4, is greater than or equal to 1. If $\lambda < 1$ then the result follows from 3.3, because we can show that for any $V(x_0x; T_1, \dots, T_n; \varepsilon)$, there exists $V(x; T_1, \dots, T_n; \varepsilon)$ such that

$$x_0V(x; T_1, \dots, T_n; \varepsilon) \subset V(x_0x; T_1, \dots, T_n; \varepsilon).$$

THEOREM 3.6. A g.s.i.p. algebra (A, ζ, M) with strong topology is metrizable

if there is a countable subset C of ζ which has the property that for any $T \in \zeta$ there is a $P \in N$, where N is the linear manifold generated by C, such that $[Tx, Tx]^{1/2} \leq [Px, Px]^{1/2}$ for all $x \in A$.

PROOF. Same as that of ([4], 3.4).

4. g. s. i. p. lattices

In this section, we consider only the real vector spaces.

DEFINITION 4.1. An ordered vector space X is called a semi-inner product lattice (in short s.i.p. lattice) if (a) X is a normed lattice, and (b) X is a s.i.p. space with the same norm as that of the normed lattice X.

A subset B of a vector lattice X is solid if $|x| \le |y|$, $y \in B$ implies $x \in B$, where $|x| = \sup \{-x, x\}$. A vector subspace M of X is a lattice ideal if M is a solid subset of X. Every lattice ideal M in a vector lattice X is a sublattice of X ([5], page 35). Every solid set is circled.

A linear map from a vector lattice into a vector lattice is called a lattice homomorphism if it preserves lattice operations. (For more details, see [5]).

DEFINITION 4.2. An ordered vector space X is called a generalized semi-inner product (in short g.s.i.p.) lattice if

- (i) X is a vector lattice,
- (ii) there is a lattice ideal M of X which is a s.i.p. lattice, and
- (iii) there is a set τ of lattice homomorphisms on X such that (a) $\tau X \subset M$, i.e. each member of τ maps X into M, and (b) hx=0 for all $h\in \tau$ implies x=0.

We denote such a g.s.i.p. lattice by the triple (X, τ, M) . The example given in [4] is in fact a g.s.i.p. lattice.

As in section 2, we define

 $V(x; h_1, \dots, h_n; \varepsilon) = \{y \in X; [h_i(y-x), h_i(y-x)]^{1/2} < \varepsilon, 1 \le i \le n\}, \text{ for all } \varepsilon > 0, h_1, \dots, h_n \in \tau \text{ and } n \in \mathbb{N}.$

LEMMA 4.3. Each $V(0; h_1, \dots, h_n; \varepsilon)$ is solid.

PROOF. Let $|x| \le |y|$ and $y \in V(0; h_1, \dots, h_n; \varepsilon)$. Then (*) $[h_i(y), h_i(y)]^{1/2} < \varepsilon$, $1 \le i \le n$. Since each h_i is a lattice homomorphism, $|x| \le |y|$ implies that $|h_i(x)| \le |h_i(y)|$. But then, since M is a normed lattice, we have

$$||h_i(x)|| \leq ||h_i(y)||$$

i.e.
$$[h_i(x), h_i(x)]^{1/2} \le [h_i(y), h_i(y)]^{1/2} < \varepsilon$$
, by (*).

This implies that $x \in V(0; h_1, \dots, h_n; \varepsilon)$, and hence each $V(0; h_1, \dots, h_n; \varepsilon)$ is solid.

An ordered locally convex space which is a vector lattice is called a locally convex lattice if there is a neighbourhood basis of 0 consisting of solid sets ([5], page 103).

THEOREM 4.4. A g.s.i.p. lattice (X, τ, M) equipped with the strong topology for which the family $\{V(x; h_1, \dots, h_n; \varepsilon) : \varepsilon > 0, h_1, \dots, h_n \in \tau, n \in \mathbb{N}\}$ forms a neighbourhood basis at x, for each $x \in X$, is a locally convex lattice.

PROOF. In view of ([4], 3.3), (X, τ, M) is a Hausdorff locally convex space; hence it is an ordered locally convex space, because X is an ordered vector space ([5], page 63). The result now follows from 4.3.

The sets of the form

$$V(x; h_1, h_2, \dots; \varepsilon) = \bigcap_{k=1}^{\infty} V(x; h_k; \varepsilon), h_k \in \tau, \varepsilon > 0,$$

constitute a neighbourhood basis at x, for each $x \in X$, for a topology on X called ultra-strong topology.

Clearly ultra-strong topology is finer than the strong topology, and hence Hausdorff.

REMARK 4.5. Since the intersection of solid sets is solid, it follows that each $V(0; h_1, h_2, \dots; \varepsilon)$ is solid. Also it is convex.

THEOREM 4.6. A g.s.i.p. lattice (X, τ, M) equipped with ultra-strong topology is a locally convex lattice.

PROOF. (x, τ, M) is a Hausdorff locally convex space [4], and hence ordered locally convex space. The result now follows from 4.5.

5. Weak topology

A vector space X is a g.s.i.p. space if

- (i) there is a subspace M of X which is a s.i.p. space,
- (ii) there is a (non-empty) set ζ of linear operations on X satisfying (a) $\zeta X \subset M$, i.e. each element of ζ maps X into M, and (b) Tx=0 for all $T \in \zeta$ implies x=0 [4].

LEMMA 5.1. Let (X, ζ, M) be a g.s.i.p. space and $x \in X$. If [Tx, x] = 0 for

all $y \in M, T \in \zeta$, then x = 0.

PROOF. In view of (ii) (b), we have Tx=0 for all $T \in \zeta$. But then, by 2.4, it follows that x=0.

LEMMA 5.2. Let (X, ζ, M) be a g.s.i.p. space and $x \in X$. If [Tx, Tx] = 0 for all $T \in \zeta$, then x = 0.

PROOF. First we observe that Tx=0; because if $Tx\neq 0$, then by the definition of semi-inner product Space, it follows that [Tx, Tx] > 0 which contradicts the hypothesis. Since Tx=0 for all $T\in \zeta$, it follows from (ii)(b) that x=0.

DUAL SPACE 5.3. Let (X, ζ, M) be a g.s.i.p. space. For each $T \in \zeta$ and each $y \in M$, we define.

$$F(x; T, y) = [Tx, y]$$
 on X.

Clearly F is linear functional on X, Let L_0 be the family of all such functionals; it is not a vector space, in general. Denote by L the vector space (over the same field as that of X) spanned by L_0 .

PROPOSITION 5.4. L and X constitute a dual pair.

PROOF. If F(x)=0 for all $F \in L$, then [Tx, y]=0 for all $y \in M$ and all $T \in \zeta$. But then, in view of 5.1, x=0.

Conversely if for a given $F_0 \in L$ we have that $F_0(x) = 0$ for all $x \in X$; then, by definition, F_0 is the zero element of L.

NOTATION 5.5. $\langle x, F \rangle = F(x)$, $x \in X$, $F \in L$. Clearly $\langle x, F \rangle$ is a bilinear function on X and L.

PROPOSITION 5.6. Each $F \subseteq L$ is continuous on X in the strong topology.

PROOF. Let $\varepsilon > 0$.

$$|F(x; T, y) - F(x_0; T, y)| = |[Tx, y] - [Tx_0, y]|$$

$$= |[T(x - x_0), y]|$$

$$\leq [T(x - x_0), T(x - x_0)]^{1/2} [y, y]^{1/2} < \varepsilon$$

whenever

$$[T(x-x_0), T(x-x_0)]^{1/2} < \frac{\varepsilon}{[y,y]^{1/2}},$$

because [y, y] > 0 for $y \neq 0$, i.e. for all $x \in V(x_0; T, \frac{\varepsilon}{[y, y]^{1/2}})$. Thus each element of L is a continuous linear functional on E equipped with strong topology.

Hence the continuity of an arbitrary element of L follows.

REMARK 5.7. The above proposition says that L is contained in the vector space conjugate to X with strong topology.

DEFINITION 5.8. The coarsest topology on X for which all the linear functionals from L are continuous is called the weak topology.

The family of all subsets of X of the form,

$$U(x ; F_1, \dots, F_n) = \{y \in X: |F_i(y-x)| < 1, 1 \le i \le n\}$$

for all F_1 , ..., $F_n \subseteq L$, $n \subseteq N$, is a neighbourhood basis at x.

Since L_0 generates L, the family of all neighbourhoods,

$$U(0; y_1, T_1, \dots, y_n, T_n) = \{x \in X: | [T_i x, y_i] | < 1, 1 \le i \le n\}$$

corresponding to all y_1 , ..., $y_n \in M$, T_1 , ..., $T_n \in \zeta$, n=1,2..., is also a neighbourhood basis of 0.

As X and L are dual pairs, X is a Hausdorff topological space in the weak topology.

From the general properties of weak topologies we have the following result:

PROPOSITION 5.9. A g.s.i.p. space (X, ζ, M) is a Hausdorff locally convex space in the weak topology.

DEFINITION 5.10. The sets of the form

$$U(x; F_1, \dots, F_n, \dots) = \{y \in X: |F_i(y-x)| < 1, i=1, 2, \dots, n, \dots\}$$

for all sequences F_1 , F_2 , ..., F_n , ... $\in \zeta$, contsitute a neighbourhood basis at x, for each $x \in X$, for a topology on X which we call infra-weak topology.

Cleary infra-weak topology is finer than the weak topology and hence Hausdorff. Also each $U(x; F_1, \dots, F_n, \dots)$ is convex. It is a routine matter to establish the truth of the following result.

PROPOSITION 5.11. A g.s.i.p. space (X, ζ, M) with the infra-weak topology is a Hausdorff locally convex space.

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