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# NOTE ON COMPACT HYPERSURFACES IN A UNIT SPHERE $S^{2n+1}$

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#### § 0. Introduction

Recently, K. Yano and M. Okumura [5] have defined the concept of an (f, g, f) $u, v, \lambda$ )-structure in an even-dimensional Riemannian manifold. Hypersurfaces in an almost contact metric manifold or submanifolds of codimension 2 in an almost Hermitian manifold admit an  $(f, g, u, v, \lambda)$ -structure (cf. [5] etc.). H. Suzuki [4] studied the integrability conditions of this structure. In terms of this structure, D.E. Blair, G.D. Ludden and K. Yano [1], and M. Nakagawa and I. Yokote [3] have proved

THEOREM 0.1. If  $M^{2n}$  is a complete orientable submanifold with constant scalar curvature satisfying Kf+fK=0 and  $\lambda\neq$  constant, where K denotes the second fundamental tensor on  $M^{2n}$ , then  $M^{2n}$  is a natural sphere  $S^{2n}$  or  $S^n \times S^n$ .

In the present paper we investigate the necessary and sufficient condition of antinormal (f, g, u, v,  $\lambda$ )-structure in a Sasakian manifold and study compact hypersurfaces with antinormal  $(f, g, u, v, \lambda)$ -structure in a unit sphere.

### §1. Preliminaries

We consider a  $C^{\infty}$  differentiable manifold M with an (f, g, u, v,  $\lambda$ )-structure, that is, a Riemannian manifold with metric tensor g which admits a tensor field f of type (1, 1), two 1-forms u and v (or two vector fields associated with them), and a function  $\lambda$  satisfying

$$f_{j}^{t}f_{t}^{h} = -\delta_{j}^{h} + u_{j}u^{h} + v_{j}v^{h}, \qquad f_{j}^{t}f_{i}^{s}g_{is} = g_{ji} - u_{j}u_{i} - v_{j}v_{i},$$
(1.1)  $u_{t}f_{i}^{t} = \lambda v_{i} \text{ or } f_{i}^{h}u^{i} = -\lambda v^{h}, \qquad v_{t}f_{i}^{t} = -\lambda u_{i} \text{ or } f_{i}^{h}v^{i} = \lambda u^{h},$ 
 $u_{i}u^{i} = v_{i}v^{i} = 1 - \lambda^{2}, \qquad u_{i}v^{i} = 0.$ 

Such an M is even-dimensional ([5]).

## Jae Kyu Lim and Yeong-Wu Choe 220 We put $[f,f]_{ji} = f_j^{t} \nabla_t u_i - f_i^{t} \nabla_t u_j - (\nabla_j f_i^{t} - \nabla_i f_j^{t}) u_t + \lambda (\nabla_j v_i - \nabla_i v_j),$ (1.2) $\nabla_i$ denoting the operator of covariant differentiation with respect to the Rie-

mannian connection. If the tensor  $[f, f]_{ii}$  vanishes, the  $(f, g, u, v, \lambda)$ -structure is said to be antinormal (cf. [4]).

#### §2. Hypersurfaces in a Sasakian manifold

Let M be an orientable hypersurface of a Sasakian manifold  $\widetilde{M}^{2n+1}$ . Then there is an  $(f, g, u, v, \lambda)$ -structure induced in M, which has the following properties;

(2.1)  $\nabla_{i}f_{i}^{h} = -g_{i}u^{h} + \delta_{i}^{h}u_{i} - k_{i}v^{h} + k_{j}^{h}v_{i}$ (2.2)  $\nabla_i u_i = f_{ii} - \lambda k_{ji}$ (2.3)  $\nabla_i v_i = -k_{it} f_i^{t} + \lambda g_{it}$  $(2.4) \quad \nabla_i \lambda = k_{it} u^t - v_{i},$ 

where  $k_{ii}$  is the component of second fundamental tensor of the hypersurface M relative to  $\widetilde{M}^{2n+1}$  ([1], [5]). Since (2.2) implies that  $\{x \in M; \lambda^2(x)=1\}$  is bordered set, we may only consider  $1-\lambda^2 \neq 0$  on M.

Substituting  $(2.1) \sim (2.4)$  into (1.2), we find (2.5)  $[f,f]_{ii} = (\nabla_i \lambda) v_i - (\nabla_i \lambda) v_i.$ 

Thus, we have

LEMMA 2.1. Let M be an orientable hypersurface of a Sasakian manifold. In order that the induced (f, g, u, v,  $\lambda$ )-structure be antinormal it is necessary and sufficient that it satisfies  $\nabla_j \lambda = Av_j$ , A being certain differentiable function on M.

We now assume that

$$(2.6) \quad \nabla_j \lambda = A v_j,$$

A being non-zero differentiable function on M. Then we have from (2.4)

(2.7) 
$$k_{jt}u^{t} = (A+1)v_{j}$$
.

Differentiating (2.6) covariantly and using (2.3), we find

$$\nabla_k \nabla_j \lambda = (\nabla_k A) v_j - A(-k_{kl} f_j^{t} + \lambda g_{kj}),$$

from which,

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(2.8) 
$$(\nabla_k A)v_j - (\nabla_j A)v_k + A(k_{jt}f_k^{\ t} - k_{kt}f_j^{\ t}) = 0.$$
  
Transvecting (2.8) with  $v^j$  and using (1.1) and (2.7), we get  
(2.9)  $(1 - \lambda^2)\nabla_k A = (v^t \nabla_t A)v_k + \lambda A(A+1)v_k - Ak_{st}v^s f_k^{\ t}.$   
Substituting (2.9) into (2.8), we obtain

$$(2.10) \quad (1-\lambda)(R_{jt}J_k - R_{kt}J_j) = R_{st}v(v_jJ_k - v_kJ_j)$$

because of  $A \neq 0$ .

Transvecting (2.10) with  $f_i^k$  and using (2.7), we find

$$(1-\lambda^{2})\left\{-k_{ji}-(k_{ji}v^{t})v_{i}-k_{st}f_{i}^{s}f_{j}^{t}\right\}=-(k_{it}v^{t})v_{j}+(k_{st}v^{s}v^{t})v_{j}v_{i}+\lambda k_{st}v^{s}f_{j}^{t}u_{i}$$

from which, taking the skew-symmetric part,

$$(1-\lambda^2)\{(k_{jt}v^t)v_i - (k_{it}v^t)v_j\} = -(k_{it}v^t)v_j + (k_{jt}v^t)v_i + \lambda k_{st}v^s(f_j^t u_i - f_i^t u_j).$$

Transvecting this with v and using  $\lambda \neq 0$  and (2.7), we find

(2.11) 
$$k_{jt}v^{t} = (A+1)u_{j} + Bv_{j}$$

where  $B = (k_{st} v^s v^t) / (1 - \lambda^2).$ 

Substituting (2.11) into (2.9) and (2.10), we have respectively

(2.12) 
$$\nabla_{j}A = Cu_{j} + Dv_{j},$$
  
(2.13)  $(1 - \lambda^{2})(k_{jt}f_{k}^{t} - k_{kt}f_{j}^{t}) = \lambda B(u_{j}v_{k} - u_{k}v_{j}),$ 

where, we have put

(2.14) 
$$C = \frac{\lambda AB}{1 - \lambda^2}, \qquad D = \frac{v' \nabla_t A}{1 - \lambda^2}$$

Differentiating (2.12) covariantly and taking account of (2.2) and (2.3), we find

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$$\nabla_k \nabla_j A = (\nabla_k C) u_j + (\nabla_k D) v_j + C(f_{kj} - \lambda k_{kj}) + D(-k_{kl} f_j' + \lambda g_{kj}),$$

from which, substituting (2.13), (2.15)  $(\nabla_k C)u_j - (\nabla_j C)u_k + (\nabla_k D)v_j - (\nabla_j D)v_k + 2Cf_{kj} + \frac{\lambda B}{1 - \lambda^2}(u_j v_k - u_k v_j) = 0.$ Transvecting (2.15) with  $u^k v^j$  and  $f^{kj}$ , we have respectively

$$-v^{t}\nabla_{t}C+u^{t}\nabla_{t}D-\lambda B-2C\lambda=0,$$

 $\lambda(v^{t}\nabla_{t}C-u^{t}\nabla_{t}D+\lambda B)+2C(n-1+\lambda^{2})=0.$ 

Thus, last two equations imply C=0 and consequently  $\lambda AB=0$ . So we have B=0 because of  $A\neq 0$  and (2.6). Therefore (2.11), (2.12) and (2.13) become

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respectively (2.16)  $\nabla_{j}A = Dv_{j},$ (2.17)  $k_{jt}v^{t} = (A+1)u_{j},$ (2.18)  $k_{jt}f_{k}^{t} - k_{kt}f_{j}^{t} = 0.$ 

Conversely, if (2.18) satisfied on M, by transvecting  $f_i^k$ , we find

$$k_{jt}(-\delta_i^{t} + u_i u^{t} + v_i v^{t}) - k_{st} f_i^{s} f_j^{t} = 0.$$

Taking the skew-symmetric part of this equation, we have

(2.19) 
$$(k_{jt}u^{t})u_{i} - (k_{it}u^{t})u_{j} + (k_{jt}v^{t})v_{i} - (k_{it}v^{t})v_{j} = 0.$$

Transvecting (2.19) with  $u^i$  and putting  $\overline{A}(1-\lambda^2) = k_{ts}u^t u^s$ ,  $\overline{B}(1-\lambda^2) = k_{ts}u^t v^s$ , we get

$$(2.20) k_{jt}u^{t} = \overline{A}u_{j} + \overline{B}v_{j}$$

Differentiating (2.20) covariantly and using (2.2) and (2.3), we find  $(\nabla_k k_{jt}) u^t + k_{jt} (f_k^{\ t} - \lambda k_k^{\ t}) = (\nabla_k \overline{A}) u_j + (\nabla_k \overline{B}) v_j + \overline{A} (f_{kj} - \lambda k_{kj}) + \overline{B} (-k_{kt} f_j^{\ t} + \lambda g_{kj}),$ 

from which, taking the skew-symmetric part with respect to k and j,

(2.21) 
$$(\nabla_k k_{jt} - \nabla_j k_{kt}) u^t = (\nabla_k \overline{A}) u_j - (\nabla_j \overline{A}) u_k + (\nabla_k \overline{B}) u_j - (\nabla_j \overline{B}) v_k + 2\overline{A} f_{kj}$$
  
because of (2.18).

On the other hand, differentiating (2.4) covariantly and substituting (2.3),

we get

$$\nabla_k \nabla_j \lambda = (\nabla_k k_{jt}) u^t - (\lambda g_{kj} - k_{kt} f_j^t),$$

from which, using (2.18),

$$(\nabla_k k_{jt} - \nabla_j k_{kt}) u^t = 0.$$

Thus, (2.21) becomes

(2.22) 
$$(\nabla_k \overline{A})u_j - (\nabla_j \overline{A})u_k + (\nabla_k \overline{B})v_j - (\nabla_j \overline{B})v_k + 2\overline{A}f_{kj} = 0.$$
  
Transvecting (2.22) with  $u^j v^k$  and  $f^{kj}$ , we have respectively  $(1 - \lambda^2)(v^t \nabla_t \overline{A} - u^t \nabla_t \overline{B}) + 2\overline{A}\lambda(1 - \lambda^2) = 0$ 

and

$$\lambda(v^t \nabla_t \overline{A} - u^t \nabla_t \overline{B}) + \overline{A} \{2n - 2(1 - \lambda^2)\} = 0,$$

from which,  $\overline{A}=0$ . Consequently (2.4) and (2.20) imply that  $\nabla_j \lambda = (\overline{B}+1)v_j$ . Hence, using Lemma 2.1, we have

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THEOREM 2.2. Let M be an orientable hypersurface of a Sasakian manifold such that the function  $\lambda$  is not constant. In order that the induced  $(f, g, u, v, \lambda)$ -structure be antinormal it is necessary and sufficient that Kf+fK=0, where K is the second fundamental tensor of M with respect to Sasakian manifold.

#### §3. Compact hypersurface in a unit sphere

Let M be a hypersurface immersed in a unit sphere  $S^{2n+1}(1)$  with canonical almost contact structure. Then there is an  $(f, g, u, v, \lambda)$ -structure induced in M, which satisfies  $(2.1) \sim (2.4)$ .

We now denote by  $R_{kji}^{h}$ ,  $R_{ji}$  and R components of the Riemannian curvature tensor, the Ricci tensor and the scalar curvature of M. The equation of Gauss for the hypersurface M is written as

(3.1) 
$$R_{kji}^{\ \ h} = \delta_k^{\ \ h} g_{ji} - \delta_j^{\ \ h} g_{ki} + k_k^{\ \ h} k_{ji} - k_j^{\ \ h} k_{ki},$$
  
and the equation of Codazzi is given by  
(3.2) 
$$\nabla_k k_{ii} - \nabla_i k_{ki} = 0.$$

From (3.1) it follows easily that

(3.3) 
$$R_{ji} = (2n-1)g_{ji} + k_t^{t}k_{ji} - k_{jt}k_i^{t},$$

(3.4) 
$$R = 2n(2n-1) + (k_t^{t})^2 - k_{st}k^{st}.$$

We prove the following (cf. [3])

THEOREM 3.1. Let M be a compact hypersurface with antinormal  $(f, g, u, v, \lambda)$ -structure in a unit sphere  $S^{2n+1}$  (1). If  $\lambda$  is not constant, then M is congruent to  $S^{2n}(1)$  or  $S^n\left(\frac{1}{\sqrt{2}}\right) \times S^n\left(\frac{1}{\sqrt{2}}\right)$  imbedded naturally in  $S^{2n+1}(1)$ .

**PROOF.** Since M has antinormal  $(f, g, u, v, \lambda)$ -structure, (2.7), (2.16), (2.17) and (2.18) are valid on M. From (2.18) we can easily prove that

(3.5) 
$$k_t^{t} = 0.$$

Differentiating (2.17) covariantly, we find

$$(\nabla_k k_{jt})v^t + k_{jt} \nabla_k v^t = (\nabla_k A)u_j + (A+1)\nabla_k u_j,$$

from which, using (2.2), (2.3), (2.18) and (3.2),

(3.6) 
$$2k_k^{t}k_{ts}f_j^{s} = (\nabla_k A)u_j - (\nabla_j A)u_k + 2(A+1)f_{kj}.$$

Transvecting (3.6) with u' and taking account of (2.7), (2.16) and (2.17),

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we have

(3.7) 
$$(1-\lambda^2)\nabla_k A = -2\lambda(A+1)(A+2)v_k$$
.

Substituting (3.7) into (3.6), we get  $(1-\lambda^2)k_k^{t}k_{ts}f_{j}^{s} = \lambda(A+1)(A+2)(v_ju_k - v_ku_j) + (1-\lambda^2)(A+1)f_{kj},$ from which, transvecting  $f^{kj}$  and using (2.7) and (2.17), (3.8)  $k_{st}k^{st} = 2(A+1)(A+2-n).$ 

Since M is compact, from (3.2), (3.5), (3.6) and (3.7), we can prove that (A+1)(A+2)=0 (See [2], [3]). Thus, (3.5) and (3.8) imply that R is constant. Taking account of Theorem 0.1, Theorem 3.1 is proved.

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