

*A certain submanifold of codimension 2
of a Kählerian manifold*

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§ 0. Introduction.

It is well known that a submanifold of codimension 2 of an almost Hermitian manifold or a hypersurface of an almost contact metric manifold carries an (f, g, u, v, λ) -structure ([1], [9]).

Let E be an even-dimensional Euclidean space, it can be regarded as a flat Kählerian manifold. The submanifolds M of E carrying such a structure with certain conditions have studied in [5], [7], [9].

In [5], [9], K. Yano and M. Okumura proved:

THEOREM A. *Let M be a complete differentiable submanifold of codimension 2 of an even-dimensional Euclidean space and C and D be two normals to M . (1) If the connection induced in the normal bundle of M is trivial and the (f, g, u, v, λ) -structure induced on M is normal or (2) $\lambda \neq \text{constant}$, H and K commute with f , then M is a plane, a sphere or a product of a sphere and a plane, where H and K are the Weingarten maps with respect to C and D respectively.*

In the present paper, we study a submanifold M of codimension 2 of a Kählerian manifold \tilde{M} whose tangent space is invariant under the curvature transformation of \tilde{M} .

In section 1, we recall the properties of submanifold of codimension 2 in a Kählerian manifold.

In section 2, we find differential equations the induced (f, g, u, v, λ) -structure satisfies and some relations under the condition (2) in Theorem A.

In the last section 3, we give a complete classification of the submanifold.

In the sequel we assume that $\lambda \neq \text{constant}$ on the submanifold M . Our main result appears in Theorem 3.2.

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§ 1. Submanifolds of codimension 2 of a Kählerian manifold.

Let \tilde{M} be a $(2n+2)$ -dimensional Kählerian manifold covered by a system of coordinate neighborhoods $\{U; y^\alpha\}$, where here and in the sequel the indices $\kappa, \lambda, \mu, \nu, \dots$ run over the range $\{1, 2, \dots, 2n+2\}$ and let $(F_\lambda^\kappa, G_{\mu\lambda})$ be the Kählerian structure, that is.

$$(1.1) \quad F_\mu^\kappa F_\lambda^\mu = -\delta_\lambda^\kappa,$$

and $G_{\mu\lambda}$ a Riemannian metric such that

$$(1.2) \quad G_{\gamma\beta} F_\mu^\gamma F_\lambda^\beta = G_{\mu\lambda},$$

and

$$(1.3) \quad \nabla_\mu F_\lambda^\kappa = 0,$$

where we denote by $\{F_\lambda^\kappa\}$ and ∇_μ the Christoffel symbols formed with $G_{\mu\lambda}$ and the opera-

tor of covariant differentiation with respect to $\{\mu^\lambda\}$ respectively.

Let M be a $2n$ -dimensional differentiable manifold which is covered by a system of coordinate neighborhoods $\{U; x^h\}$, where here and in the sequel the indices h, i, j, \dots run over the range $\{1, 2, \dots, 2n\}$ and which is differentiably immersed in \tilde{M} as a submanifold of codimension 2 by the equations

$$(1.4) \quad y^\kappa = y^\kappa(x^h).$$

We put

$$(1.5) \quad B_i^\kappa = \partial_i y^\kappa, \quad (\partial_i = \partial/\partial x^i),$$

then B_i^κ is, for each i , a local vector field of \tilde{M} tangent to M and the vectors B_i^κ are linearly independent in each coordinate neighborhood. B_i^κ is, for each κ , a local 1-form of M .

We choose two mutually orthogonal unit vectors C^κ and D^κ of \tilde{M} normal to M in such a way that $2n+2$ vectors $B_i^\kappa, C^\kappa, D^\kappa$ give the positive orientation of \tilde{M} .

The transforms $F_\lambda^\kappa B_i^\lambda$ of B_i^λ by F_λ^κ can be expressed

$$(1.6) \quad F_\lambda^\kappa B_i^\lambda = f_i^h B_h^\kappa + u_i C^\kappa + v_i D^\kappa,$$

where f_i^h is a tensor field of type $(1, 1)$ and u_i, v_i are 1-forms of M . Similarly the transform $F_\lambda^\kappa C^\lambda$ of C^λ by F_λ^κ and the transform $F_\lambda^\kappa D^\lambda$ of D^λ by F_λ^κ can be written as

$$(1.7) \quad \begin{aligned} F_\lambda^\kappa C^\lambda &= -u^i B_i^\kappa + \lambda D^\kappa, \\ F_\lambda^\kappa D^\lambda &= -v^i B_i^\kappa - \lambda C^\kappa, \end{aligned}$$

where

$$u^i = u_i g^{ii}, \quad v^i = v_i g^{ii},$$

g_{ji} being the Riemannian metric on M induced from that of \tilde{M} , and λ is a function on M . We can easily verify that λ is a function globally defined on M .

From (1.2), (1.6) and (1.7) we have ([8])

$$(1.8) \quad \begin{aligned} f_j^i f_i^h &= -\delta_j^h + u_j u^h + v_j v^h, \\ f_j^i f_i^h g_{ii} &= g_{ji} - u_j u_i - v_j v_i, \\ f_i^h u_i &= \lambda v_i \quad \text{or} \quad f_i^h u^i = -\lambda v^h, \\ f_i^h v_i &= -\lambda u_i \quad \text{or} \quad f_i^h v^i = \lambda u^h, \\ u_i u^i &= v_i v^i = 1 - \lambda^2, \quad u_i v^i = 0. \end{aligned}$$

If we put

$$f_{ji} = f_j^i g_{ii},$$

then we can easily verify that f_{ji} is skew-symmetric.

§2. Structure equations of submanifold of codimension 2.

We denote by $\{^h_i\}$ and ∇_i the Christoffel symbols formed with g_{ji} and the operator of covariant differentiation with respect to $\{^h_i\}$ respectively. Then the equations of Gauss and Weingarten are respectively

$$(2.1) \quad \nabla_j B_i^\kappa = \partial_j B_i^\kappa + \{^{\mu\lambda}_i\} B_j^\mu B_i^\lambda - B_h^\kappa \{^h_i\} = h_{ji} C^\kappa + k_{ji} D^\kappa,$$

$$(2.2) \quad \nabla_j C^\kappa = \partial_j C^\kappa + \{^{\mu\lambda}_i\} B_j^\mu C^\lambda = -h_j^i B_i^\kappa + l_j D^\kappa,$$

$$\nabla_j D^\kappa = \partial_j D^\kappa + \{^{\mu\lambda}_i\} B_j^\mu D^\lambda = -k_j^i B_i^\kappa - l_j C^\kappa,$$

where h_{ji} and k_{ji} are the second fundamental tensors with respect to the normals C^κ and D^κ respectively, h_j^i and k_j^i define the corresponding Weingarten maps H and K and are given by

$$h_j^h = h_{ji} g^{ih}, \quad k_j^h = k_{ji} g^{ih},$$

l_j is the third fundamental tensor.

Differentiating (1.6) covariantly along M and taking account of (1.3), (2.1) and (2.2), we get ([2])

$$(2.3) \quad \nabla_j f_i^h = -h_{ji} u^h + h_j^h u_i - k_{ji} v^h + k_j^h v_i,$$

$$(2.4) \quad \nabla_j u_i = -h_{ji} f_i^t - \lambda k_{ji} + l_j v_i,$$

$$(2.5) \quad \nabla_j v_i = -k_{ji} f_i^t + \lambda h_{ji} - l_j u_i.$$

Similarly, from (1.7) we find

$$(2.6) \quad \nabla_j \lambda = k_{ji} u^i - h_{ji} v^i.$$

Now, we consider a submanifold M of codimension 2 of a Kählerian manifold satisfying the following conditions:

$$(2.7) \quad f_j^i h_i^h = h_j^i f_i^h \quad \text{and} \quad f_j^i k_i^h = k_j^i f_i^h.$$

From (2.7), we can find

$$(2.8) \quad h_{ji} u^i = \alpha u_j, \quad h_{ji} v^i = \alpha v_j,$$

$$(2.9) \quad k_{ji} u^i = \bar{\alpha} u_j, \quad k_{ji} v^i = \bar{\alpha} v_j,$$

and

$$(2.10) \quad \bar{\alpha} h_{ji} = \alpha k_{ji},$$

where α and $\bar{\alpha}$ are functions on M [2].

We here assume that, for a submanifold M of codimension 2 of a Kählerian manifold \tilde{M} , all curvature transformations preserve the tangent space $T_p(x(M))$ at each point p of $x(M)$, where x is an immersion $M \rightarrow \tilde{M}$, that is, the tangent space of M is invariant under the curvature transformation of \tilde{M} [10].

Then the equations of Codazzi are

$$(2.11) \quad \nabla_k h_{ji} - \nabla_j h_{ki} = l_k k_{ji} - l_j k_{ki},$$

$$(2.12) \quad \nabla_k k_{ji} - \nabla_j k_{ki} = l_j h_{ki} - l_k h_{ji}.$$

§ 3. Submanifolds of codimension 2 of a Kählerian manifold such that the curvature transformation is invariant.

In this section, we assume that, for a submanifold M of codimension 2 of a Kählerian manifold \tilde{M} , (1) the tangent space of M is invariant under the curvature transformation of \tilde{M} and (2) the conditions (2.7) are satisfied.

Differentiating the first equation of (2.8) covariantly, we find

$$(\nabla_k h_{ji}) u^i + h_{ji} \nabla_k u^i = (\nabla_k \alpha) u_j + \alpha \nabla_k u_j,$$

from which, using (2.4) and (2.11)

$$\begin{aligned} (l_k k_{ji} - l_j k_{ki}) u^i + h_{ji} (-h_{ki} f_i^t - \lambda k_{ki} + l_k v^i) - h_{ki} (-h_{ji} f_i^t - \lambda k_{ji} + l_j v^i) \\ = (\nabla_k \alpha) u_j - (\nabla_j \alpha) u_k + \alpha (-h_{ki} f_j^t + h_{ji} f_k^t + l_k v_j - l_j v_k), \end{aligned}$$

or, using (2.7), (2.8) and (2.9)

$$(3.1) \quad -2h_{ji} h_{ki} f_i^t - \lambda (h_{ji} k_{ki} - h_{ki} k_{ji}) = (\nabla_k \alpha - \bar{\alpha} l_k) u_j - (\nabla_j \alpha - \bar{\alpha} l_j) u_k - 2\alpha h_{ki} f_j^t.$$

Transvecting (3.1) with u^i , we find

$$\nabla_k \alpha - \bar{\alpha} l_k = \mu u_k,$$

for a function μ .

Starting from the second equation of (2.8), we have

$$\nabla_k \alpha - \bar{\alpha} l_k = \mu' v_k.$$

From the last two equations, we have

$$(3.2) \quad \nabla_k \alpha = \bar{\alpha} l_k$$

by virtue of the orthogonality of u_k and v_k .

Substituting (3.2) into (3.1) and using (2.7), we find

$$2(h_{ki}h_i' - \alpha h_{ki})f_{j'} = \lambda(h_{ki}k_{j'} - h_{ji}k_k'),$$

from which, transvecting $f_{k'}$ and using (1.8) and (2.8),

$$(3.3) \quad 2(h_{ki}h_k' - \alpha h_{kh}) = \lambda(h_{ki}k_i' - h_{ii}k_k')f_{h'}.$$

In the same way, we can find from (2.9)

$$(3.4) \quad \nabla_k \bar{\alpha} = -\alpha l_k$$

and

$$(3.5) \quad 2(k_{ki}k_k' - \bar{\alpha} h_{kh}) = \lambda(h_{ki}k_i' - h_{ii}k_k')f_{h'}.$$

We now prove

LEMMA 3.1 *Let M be a submanifold of codimension 2 of a Kählerian manifold \bar{M} whose tangent space is invariant under the curvature transformation of \bar{M} . If the conditions (2.7) are satisfied, then*

(1) *the connection of the normal bundle of M is trivial,*

(2) *the mean curvature of M is constant,*

and consequently

(3) *the mean curvature vector of M does not vanish everywhere on M .*

Proof. Differentiating (3.4) covariantly and substituting (3.2) into the resulting equation, we find

$$\nabla_k \nabla_j \bar{\alpha} = -\bar{\alpha} l_k l_j - \alpha \nabla_k l_j,$$

from which

$$\alpha(\nabla_k l_j - \nabla_j l_k) = 0.$$

In the same way,

$$\bar{\alpha}(\nabla_k l_j - \nabla_j l_k) = 0.$$

Since $\nabla_j \lambda = \bar{\alpha} u_j - \alpha v_j$ and $\lambda \neq \text{const.}$, α and $\bar{\alpha}$ are not always zero.

Thus the connection of the normal bundle of M is trivial. So, we can choose the unit normals C^r and D^s in such a way that $l_j = 0$. In this case α and $\bar{\alpha}$ are both constants because of (3.2) and (3.4).

From (2.10) and $(\alpha, \bar{\alpha}) \neq (0, 0)$, we see that

$$h_{ki}k_j' = k_{ki}h_j'.$$

Therefore, (3.3) and (3.5) can be respectively written as

$$(3.6) \quad h_{ji}h_k' = \alpha h_{jk},$$

and

$$(3.7) \quad k_{ji}k_k' = \bar{\alpha} k_{jk}.$$

(3.6) shows that h_j^i has only two constant eigenvalues α and 0. Similarly k_j^i has $\bar{\alpha}$ and 0. Now, let r and s be multiplicities of α of h_j^i and of $\bar{\alpha}$ of k_j^i respectively, then

$$h_i^i = r\alpha = \text{const.}, \quad k_i^i = s\bar{\alpha} = \text{const.}$$

Substituting these into the equation giving the mean curvature of the submanifold M ;

$$H^2 = \frac{1}{4n^2} \{ (h_i^i)^2 + (k_i^i)^2 \},$$

we have $H = \text{const.}$

Suppose that the submanifold M is minimal.

Then, from (3.6) and (3.7) we have

$$h_j h^{ji} = 0, \quad k_j k^{ji} = 0,$$

from which

$$h_j = 0, \quad k_j = 0.$$

Thus, the equation (2.6) shows that λ is constant. This contradicts to the assumption. From the equation giving the mean curvature vector of M ;

$$(3.8) \quad H^s = -\frac{1}{2n} (h_i^i C^s + k_i^i D^s),$$

we see that H^s does not vanish everywhere on M . This completes the proof of the lemma.

From $H^s \neq 0$ on M , we can choose the first unit normal C^s along the direction of H^s and choose the second unit normal D^s in such a way that B_i^s, C^s, D^s form the positive orientation of the Kählerian manifold \tilde{M} . Then, from (3.8), we see that

$$k_i^i = 0,$$

which implies that

$$k_j k^{ji} = 0,$$

because of (3.7). Thus we have

$$(3.9) \quad k_{ji} = 0,$$

from which, using (2.12),

$$h_i^i l^i = h_i^i l^i,$$

which shows that l^i is an eigenvector of h_j^i corresponding to the eigenvalue h_i^i . So we have

$$h_i^i = 0 \quad \text{or} \quad h_i^i = \alpha.$$

The submanifold M not being minimal, we have $h_i^i = \alpha$. This implies that l^i vanishes identically on M because of (2.8).

Thus the equations (2.1) and (2.2) can be respectively written as

$$(3.10) \quad \nabla_j B_i^s = h_j C^s,$$

and

$$(3.11) \quad \nabla_j C^s = -h_j^i B_i^s, \quad \nabla_j D^s = 0.$$

We here prove the following

THEOREM 3.2. *Let M be a complete connected submanifold of codimension 2 of a Kählerian manifold \tilde{M} whose tangent space is invariant under the curvature transformation of \tilde{M} . If H and K commute with f and $\lambda \neq \text{const.}$, then M is a sphere or a product of a sphere and a totally geodesic submanifold, when H and K are defined in section 2.*

Proof. M not being minimal, we can see that from (3.6) M is totally umbilical (i.e. $h_{ji} = \alpha g_{ji}$, $\alpha \neq 0$) or h_j^i has exactly two distinct constant eigenvalues α and 0, where $\alpha \neq 0$

has multiplicity r .

In the first case M is a sphere S^{2n} , in fact, (2.5) and (2.6) become

$$(3.12) \quad \nabla_j v_i = \lambda h_{ji} = \alpha \lambda g_{ji},$$

$$(3.13) \quad \nabla_j \lambda = -\alpha v_j$$

by virtue of (3.9) and $l_j = 0$.

Differentiating (3.13) covariantly and using (3.12), we have

$$\nabla_j \nabla_i \lambda = -\alpha^2 \lambda g_{ji}, \quad \alpha = \text{const.}$$

This implies that the submanifold M is isometric to S^{2n} [4].

In the second case, the correspondences a point $P \in M$ to

$$D_\alpha(P) = \{w^i \in T(M) \mid h_j^i w^j = \alpha w^i\},$$

and to

$$D_0(P) = \{w^i \in T(M) \mid h_j^i w^j = 0\},$$

define two mutually orthogonal distributions of dimension r and $2n-r$ respectively. Since α is constant, by virtue of Codazzi-equation;

$$(3.14) \quad \nabla_k h_{ji} - \nabla_j h_{ki} = 0,$$

we know that both distributions are integrable and the integrable submanifolds are totally geodesic in M [8]. Moreover, from (3.14) we can see that the distributions D_0 and D_α are parallel [8]. So, using de Rham's decomposition theorem [6], we have M is a product of M_α and M_0 , M_α corresponding to the integral manifold D_α and M_0 to that of D_0 .

Thus, it is sufficient to show that M_α is a sphere in \tilde{M} and M_0 is a totally geodesic submanifold in \tilde{M} .

We represent M_α by

$$x^h = x^h(u^a),$$

where u^a are local coordinates on M_α .

Thus we have

$$y^s = y^s(x(u)),$$

from which

$$(3.15) \quad B_b^s = B_b^h B_h^s,$$

where

$$B_b^s = \partial_b y^s, \quad B_b^h = \partial_b x^h, \quad (\partial_b = \partial / \partial u^b).$$

Differentiating (3.15) covariantly along M_α , we find

$$\nabla_c B_b^s = B_c^j B_b^i \nabla_j B_i^s$$

because of $\nabla_c B_b^i = 0$, from which, using (3.10)

$$(3.16) \quad \nabla_c B_b^s = h_{ji} B_c^j B_b^i C^s.$$

On the other hand, from (1.7) we see that

$$(3.17) \quad \lambda = -G_{\alpha i} F_\mu^\lambda D^\mu C^s.$$

Differentiating (3.17) covariantly along M_α and taking account of (1.3) and (3.11), we find

$$\nabla_b \lambda = G_{\alpha i} (F_\mu^\lambda D^\mu) B_b^j B_h^s h_j^h,$$

from which, using (1.7),

$$\nabla_b \lambda = G_{ai}(-v^i B_i^\lambda - \lambda C^\lambda) h_j^a B_h^e B_b^j = -\alpha v_j B_b^j$$

by virtue of (1.2) and (2.8).

From this we find

$$\nabla_c \nabla_b \lambda = -\alpha B_b^i B_c^j (\nabla_j v_i),$$

or, using (2.5), (3.9) and $l_j = 0$,

$$\nabla_c \nabla_b \lambda = -\alpha^2 \lambda g_{cb}$$

because B_b^j are eigenvectors of h^h with eigenvalue α . Thus, M_α is isometric with sphere in \tilde{M} .

Similarly, for M_0 we can see that $\nabla_c B_b^e = 0$ because of (3.16), from which, M_0 is totally geodesic in \tilde{M} .

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