

*A certain submanifold of codimension 2  
of a Kählerian manifold*

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**§ 0. Introduction.**

It is well known that a submanifold of codimension 2 of an almost Hermitian manifold or a hypersurface of an almost contact metric manifold carries an  $(f, g, u, v, \lambda)$ -structure ([1], [9]).

Let  $E$  be an even-dimensional Euclidean space, it can be regarded as a flat Kählerian manifold. The submanifolds  $M$  of  $E$  carrying such a structure with certain conditions have studied in [5], [7], [9].

In [5], [9], K. Yano and M. Okumura proved:

**THEOREM A.** *Let  $M$  be a complete differentiable submanifold of codimension 2 of an even-dimensional Euclidean space and  $C$  and  $D$  be two normals to  $M$ . (1) If the connection induced in the normal bundle of  $M$  is trivial and the  $(f, g, u, v, \lambda)$ -structure induced on  $M$  is normal or (2)  $\lambda \neq \text{constant}$ ,  $H$  and  $K$  commute with  $f$ , then  $M$  is a plane, a sphere or a product of a sphere and a plane, where  $H$  and  $K$  are the Weingarten maps with respect to  $C$  and  $D$  respectively.*

In the present paper, we study a submanifold  $M$  of codimension 2 of a Kählerian manifold  $\tilde{M}$  whose tangent space is invariant under the curvature transformation of  $\tilde{M}$ .

In section 1, we recall the properties of submanifold of codimension 2 in a Kählerian manifold.

In section 2, we find differential equations the induced  $(f, g, u, v, \lambda)$ -structure satisfies and some relations under the condition (2) in Theorem A.

In the last section 3, we give a complete classification of the submanifold.

In the sequel we assume that  $\lambda \neq \text{constant}$  on the submanifold  $M$ . Our main result appears in Theorem 3.2.

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**§ 1. Submanifolds of codimension 2 of a Kählerian manifold.**

Let  $\tilde{M}$  be a  $(2n+2)$ -dimensional Kählerian manifold covered by a system of coordinate neighborhoods  $\{U; y^\alpha\}$ , where here and in the sequel the indices  $\kappa, \lambda, \mu, \nu, \dots$  run over the range  $\{1, 2, \dots, 2n+2\}$  and let  $(F_\lambda^\kappa, G_{\mu\lambda})$  be the Kählerian structure, that is.

$$(1.1) \quad F_\mu^\kappa F_\lambda^\mu = -\delta_\lambda^\kappa,$$

and  $G_{\mu\lambda}$  a Riemannian metric such that

$$(1.2) \quad G_{\gamma\beta} F_\mu^\gamma F_\lambda^\beta = G_{\mu\lambda},$$

and

$$(1.3) \quad \nabla_\mu F_\lambda^\kappa = 0,$$

where we denote by  $\{F_\lambda^\kappa\}$  and  $\nabla_\mu$  the Christoffel symbols formed with  $G_{\mu\lambda}$  and the opera-

tor of covariant differentiation with respect to  $\{\mu^\lambda\}$  respectively.

Let  $M$  be a  $2n$ -dimensional differentiable manifold which is covered by a system of coordinate neighborhoods  $\{U; x^h\}$ , where here and in the sequel the indices  $h, i, j, \dots$  run over the range  $\{1, 2, \dots, 2n\}$  and which is differentiably immersed in  $\tilde{M}$  as a submanifold of codimension 2 by the equations

$$(1.4) \quad y^\kappa = y^\kappa(x^h).$$

We put

$$(1.5) \quad B_i^\kappa = \partial_i y^\kappa, \quad (\partial_i = \partial/\partial x^i),$$

then  $B_i^\kappa$  is, for each  $i$ , a local vector field of  $\tilde{M}$  tangent to  $M$  and the vectors  $B_i^\kappa$  are linearly independent in each coordinate neighborhood.  $B_i^\kappa$  is, for each  $\kappa$ , a local 1-form of  $M$ .

We choose two mutually orthogonal unit vectors  $C^\kappa$  and  $D^\kappa$  of  $\tilde{M}$  normal to  $M$  in such a way that  $2n+2$  vectors  $B_i^\kappa, C^\kappa, D^\kappa$  give the positive orientation of  $\tilde{M}$ .

The transforms  $F_\lambda^\kappa B_i^\lambda$  of  $B_i^\lambda$  by  $F_\lambda^\kappa$  can be expressed

$$(1.6) \quad F_\lambda^\kappa B_i^\lambda = f_i^h B_h^\kappa + u_i C^\kappa + v_i D^\kappa,$$

where  $f_i^h$  is a tensor field of type  $(1,1)$  and  $u_i, v_i$  are 1-forms of  $M$ . Similarly the transform  $F_\lambda^\kappa C^\lambda$  of  $C^\lambda$  by  $F_\lambda^\kappa$  and the transform  $F_\lambda^\kappa D^\lambda$  of  $D^\lambda$  by  $F_\lambda^\kappa$  can be written as

$$(1.7) \quad \begin{aligned} F_\lambda^\kappa C^\lambda &= -u^i B_i^\kappa + \lambda D^\kappa, \\ F_\lambda^\kappa D^\lambda &= -v^i B_i^\kappa - \lambda C^\kappa, \end{aligned}$$

where

$$u^i = u_i g^{ii}, \quad v^i = v_i g^{ii},$$

$g_{ji}$  being the Riemannian metric on  $M$  induced from that of  $\tilde{M}$ , and  $\lambda$  is a function on  $M$ . We can easily verify that  $\lambda$  is a function globally defined on  $M$ .

From (1.2), (1.6) and (1.7) we have ([8])

$$(1.8) \quad \begin{aligned} f_j^i f_i^h &= -\delta_j^h + u_j u^h + v_j v^h, \\ f_j^i f_i^h g_{ii} &= g_{ji} - u_j u_i - v_j v_i, \\ f_i^h u_i &= \lambda v_i \quad \text{or} \quad f_i^h u^i = -\lambda v^h, \\ f_i^h v_i &= -\lambda u_i \quad \text{or} \quad f_i^h v^i = \lambda u^h, \\ u_i u^i &= v_i v^i = 1 - \lambda^2, \quad u_i v^i = 0. \end{aligned}$$

If we put

$$f_{ji} = f_j^i g_{ii},$$

then we can easily verify that  $f_{ji}$  is skew-symmetric.

## §2. Structure equations of submanifold of codimension 2.

We denote by  $\{^h_i\}$  and  $\nabla_i$  the Christoffel symbols formed with  $g_{ji}$  and the operator of covariant differentiation with respect to  $\{^h_i\}$  respectively. Then the equations of Gauss and Weingarten are respectively

$$(2.1) \quad \nabla_j B_i^\kappa = \partial_j B_i^\kappa + \{^{\mu\lambda}_i\} B_j^\mu B_i^\lambda - B_h^\kappa \{^h_i\} = h_{ji} C^\kappa + k_{ji} D^\kappa,$$

$$(2.2) \quad \nabla_j C^\kappa = \partial_j C^\kappa + \{^{\mu\lambda}_i\} B_j^\mu C^\lambda = -h_j^i B_i^\kappa + l_j D^\kappa,$$

$$\nabla_j D^\kappa = \partial_j D^\kappa + \{^{\mu\lambda}_i\} B_j^\mu D^\lambda = -k_j^i B_i^\kappa - l_j C^\kappa,$$

where  $h_{ji}$  and  $k_{ji}$  are the second fundamental tensors with respect to the normals  $C^\kappa$  and  $D^\kappa$  respectively,  $h_j^h$  and  $k_j^h$  define the corresponding Weingarten maps  $H$  and  $K$  and are given by

$$h_j^h = h_{ji} g^{ih}, \quad k_j^h = k_{ji} g^{ih},$$

$l_j$  is the third fundamental tensor.

Differentiating (1.6) covariantly along  $M$  and taking account of (1.3), (2.1) and (2.2), we get ([2])

$$(2.3) \quad \nabla_j f_i^h = -h_{ji} u^h + h_j^h u_i - k_{ji} v^h + k_j^h v_i,$$

$$(2.4) \quad \nabla_j u_i = -h_{ji} f_i^t - \lambda k_{ji} + l_j v_i,$$

$$(2.5) \quad \nabla_j v_i = -k_{ji} f_i^t + \lambda h_{ji} - l_j u_i.$$

Similarly, from (1.7) we find

$$(2.6) \quad \nabla_j \lambda = k_{ji} u^i - h_{ji} v^i.$$

Now, we consider a submanifold  $M$  of codimension 2 of a Kählerian manifold satisfying the following conditions:

$$(2.7) \quad f_j^i h_i^h = h_j^i f_i^h \quad \text{and} \quad f_j^i k_i^h = k_j^i f_i^h.$$

From (2.7), we can find

$$(2.8) \quad h_{ji} u^i = \alpha u_j, \quad h_{ji} v^i = \alpha v_j,$$

$$(2.9) \quad k_{ji} u^i = \bar{\alpha} u_j, \quad k_{ji} v^i = \bar{\alpha} v_j,$$

and

$$(2.10) \quad \bar{\alpha} h_{ji} = \alpha k_{ji},$$

where  $\alpha$  and  $\bar{\alpha}$  are functions on  $M$  [2].

We here assume that, for a submanifold  $M$  of codimension 2 of a Kählerian manifold  $\tilde{M}$ , all curvature transformations preserve the tangent space  $T_p(x(M))$  at each point  $p$  of  $x(M)$ , where  $x$  is an immersion  $M \rightarrow \tilde{M}$ , that is, the tangent space of  $M$  is invariant under the curvature transformation of  $\tilde{M}$  [10].

Then the equations of Codazzi are

$$(2.11) \quad \nabla_k h_{ji} - \nabla_j h_{ki} = l_k k_{ji} - l_j k_{ki},$$

$$(2.12) \quad \nabla_k k_{ji} - \nabla_j k_{ki} = l_j h_{ki} - l_k h_{ji}.$$

### § 3. Submanifolds of codimension 2 of a Kählerian manifold such that the curvature transformation is invariant.

In this section, we assume that, for a submanifold  $M$  of codimension 2 of a Kählerian manifold  $\tilde{M}$ , (1) the tangent space of  $M$  is invariant under the curvature transformation of  $\tilde{M}$  and (2) the conditions (2.7) are satisfied.

Differentiating the first equation of (2.8) covariantly, we find

$$(\nabla_k h_{ji}) u^i + h_{ji} \nabla_k u^i = (\nabla_k \alpha) u_j + \alpha \nabla_k u_j,$$

from which, using (2.4) and (2.11)

$$\begin{aligned} (l_k k_{ji} - l_j k_{ki}) u^i + h_{ji} (-h_{ki} f_i^t - \lambda k_{ki} + l_k v^i) - h_{ki} (-h_{ji} f_i^t - \lambda k_{ji} + l_j v^i) \\ = (\nabla_k \alpha) u_j - (\nabla_j \alpha) u_k + \alpha (-h_{ki} f_j^t + h_{ji} f_k^t + l_k v_j - l_j v_k), \end{aligned}$$

or, using (2.7), (2.8) and (2.9)

$$(3.1) \quad -2h_{ji} h_{ki} f_i^t - \lambda (h_{ji} k_{ki} - h_{ki} k_{ji}) = (\nabla_k \alpha - \bar{\alpha} l_k) u_j - (\nabla_j \alpha - \bar{\alpha} l_j) u_k - 2\alpha h_{ki} f_j^t.$$

Transvecting (3.1) with  $u^i$ , we find

$$\nabla_k \alpha - \bar{\alpha} l_k = \mu u_k,$$

for a function  $\mu$ .

Starting from the second equation of (2.8), we have

$$\nabla_k \alpha - \bar{\alpha} l_k = \mu' v_k.$$

From the last two equations, we have

$$(3.2) \quad \nabla_k \alpha = \bar{\alpha} l_k$$

by virtue of the orthogonality of  $u_k$  and  $v_k$ .

Substituting (3.2) into (3.1) and using (2.7), we find

$$2(h_{ki}h_i' - \alpha h_{ki})f_{j'} = \lambda(h_{ki}k_{j'} - h_{ji}k_k'),$$

from which, transvecting  $f_{k'}$  and using (1.8) and (2.8),

$$(3.3) \quad 2(h_{ki}h_k' - \alpha h_{kh}) = \lambda(h_{ki}k_i' - h_{ii}k_k')f_{h'}.$$

In the same way, we can find from (2.9)

$$(3.4) \quad \nabla_k \bar{\alpha} = -\alpha l_k$$

and

$$(3.5) \quad 2(k_{ki}k_k' - \bar{\alpha} h_{kh}) = \lambda(h_{ki}k_i' - h_{ii}k_k')f_{h'}.$$

We now prove

LEMMA 3.1 *Let  $M$  be a submanifold of codimension 2 of a Kählerian manifold  $\bar{M}$  whose tangent space is invariant under the curvature transformation of  $\bar{M}$ . If the conditions (2.7) are satisfied, then*

(1) *the connection of the normal bundle of  $M$  is trivial,*

(2) *the mean curvature of  $M$  is constant,*

and consequently

(3) *the mean curvature vector of  $M$  does not vanish everywhere on  $M$ .*

*Proof.* Differentiating (3.4) covariantly and substituting (3.2) into the resulting equation, we find

$$\nabla_k \nabla_j \bar{\alpha} = -\bar{\alpha} l_k l_j - \alpha \nabla_k l_j,$$

from which

$$\alpha(\nabla_k l_j - \nabla_j l_k) = 0.$$

In the same way,

$$\bar{\alpha}(\nabla_k l_j - \nabla_j l_k) = 0.$$

Since  $\nabla_j \lambda = \bar{\alpha} u_j - \alpha v_j$  and  $\lambda \neq \text{const.}$ ,  $\alpha$  and  $\bar{\alpha}$  are not always zero.

Thus the connection of the normal bundle of  $M$  is trivial. So, we can choose the unit normals  $C^r$  and  $D^s$  in such a way that  $l_j = 0$ . In this case  $\alpha$  and  $\bar{\alpha}$  are both constants because of (3.2) and (3.4).

From (2.10) and  $(\alpha, \bar{\alpha}) \neq (0, 0)$ , we see that

$$h_{ki}k_j' = k_{ki}h_j'.$$

Therefore, (3.3) and (3.5) can be respectively written as

$$(3.6) \quad h_{ji}h_k' = \alpha h_{jk},$$

and

$$(3.7) \quad k_{ji}k_k' = \bar{\alpha} k_{jk}.$$

(3.6) shows that  $h_j^i$  has only two constant eigenvalues  $\alpha$  and 0. Similarly  $k_j^i$  has  $\bar{\alpha}$  and 0. Now, let  $r$  and  $s$  be multiplicities of  $\alpha$  of  $h_j^i$  and of  $\bar{\alpha}$  of  $k_j^i$  respectively, then

$$h_i^i = r\alpha = \text{const.}, \quad k_i^i = s\bar{\alpha} = \text{const.}$$

Substituting these into the equation giving the mean curvature of the submanifold  $M$ ;

$$H^2 = \frac{1}{4n^2} \{ (h_i^i)^2 + (k_i^i)^2 \},$$

we have  $H = \text{const.}$

Suppose that the submanifold  $M$  is minimal.

Then, from (3.6) and (3.7) we have

$$h_j h^{ji} = 0, \quad k_j k^{ji} = 0,$$

from which

$$h_j = 0, \quad k_j = 0.$$

Thus, the equation (2.6) shows that  $\lambda$  is constant. This contradicts to the assumption. From the equation giving the mean curvature vector of  $M$ ;

$$(3.8) \quad H^\epsilon = -\frac{1}{2n} (h_i^i C^\epsilon + k_i^i D^\epsilon),$$

we see that  $H^\epsilon$  does not vanish everywhere on  $M$ . This completes the proof of the lemma.

From  $H^\epsilon \neq 0$  on  $M$ , we can choose the first unit normal  $C^\epsilon$  along the direction of  $H^\epsilon$  and choose the second unit normal  $D^\epsilon$  in such a way that  $B_i^\epsilon, C^\epsilon, D^\epsilon$  form the positive orientation of the Kählerian manifold  $\bar{M}$ . Then, from (3.8), we see that

$$k_i^i = 0,$$

which implies that

$$k_j k^{ji} = 0,$$

because of (3.7). Thus we have

$$(3.9) \quad k_{ji} = 0,$$

from which, using (2.12),

$$h_i^i l^i = h_i^i l^i,$$

which shows that  $l^i$  is an eigenvector of  $h_j^i$  corresponding to the eigenvalue  $h_i^i$ . So we have

$$h_i^i = 0 \quad \text{or} \quad h_i^i = \alpha.$$

The submanifold  $M$  not being minimal, we have  $h_i^i = \alpha$ . This implies that  $l^i$  vanishes identically on  $M$  because of (2.8).

Thus the equations (2.1) and (2.2) can be respectively written as

$$(3.10) \quad \nabla_j B_i^\epsilon = h_j C^\epsilon,$$

and

$$(3.11) \quad \nabla_j C^\epsilon = -h_j^i B_i^\epsilon, \quad \nabla_j D^\epsilon = 0.$$

We here prove the following

**THEOREM 3.2.** *Let  $M$  be a complete connected submanifold of codimension 2 of a Kählerian manifold  $\bar{M}$  whose tangent space is invariant under the curvature transformation of  $\bar{M}$ . If  $H$  and  $K$  commute with  $f$  and  $\lambda \neq \text{const.}$ , then  $M$  is a sphere or a product of a sphere and a totally geodesic submanifold, when  $H$  and  $K$  are defined in section 2.*

*Proof.*  $M$  not being minimal, we can see that from (3.6)  $M$  is totally umbilical (i.e.  $h_{ji} = \alpha g_{ji}$ ,  $\alpha \neq 0$ ) or  $h_j^i$  has exactly two distinct constant eigenvalues  $\alpha$  and 0, where  $\alpha \neq 0$

has multiplicity  $r$ .

In the first case  $M$  is a sphere  $S^{2n}$ , in fact, (2.5) and (2.6) become

$$(3.12) \quad \nabla_j v_i = \lambda h_{ji} = \alpha \lambda g_{ji},$$

$$(3.13) \quad \nabla_j \lambda = -\alpha v_j$$

by virtue of (3.9) and  $l_j = 0$ .

Differentiating (3.13) covariantly and using (3.12), we have

$$\nabla_j \nabla_i \lambda = -\alpha^2 \lambda g_{ji}, \quad \alpha = \text{const.}$$

This implies that the submanifold  $M$  is isometric to  $S^{2n}$  [4].

In the second case, the correspondences a point  $P \in M$  to

$$D_\alpha(P) = \{w^i \in T(M) \mid h_j^i w^j = \alpha w^i\},$$

and to

$$D_0(P) = \{w^i \in T(M) \mid h_j^i w^j = 0\},$$

define two mutually orthogonal distributions of dimension  $r$  and  $2n-r$  respectively. Since  $\alpha$  is constant, by virtue of Codazzi-equation;

$$(3.14) \quad \nabla_k h_{ji} - \nabla_j h_{ki} = 0,$$

we know that both distributions are integrable and the integrable submanifolds are totally geodesic in  $M$  [8]. Moreover, from (3.14) we can see that the distributions  $D_0$  and  $D_\alpha$  are parallel [8]. So, using de Rham's decomposition theorem [6], we have  $M$  is a product of  $M_\alpha$  and  $M_0$ ,  $M_\alpha$  corresponding to the integral manifold  $D_\alpha$  and  $M_0$  to that of  $D_0$ .

Thus, it is sufficient to show that  $M_\alpha$  is a sphere in  $\tilde{M}$  and  $M_0$  is a totally geodesic submanifold in  $\tilde{M}$ .

We represent  $M_\alpha$  by

$$x^h = x^h(u^a),$$

where  $u^a$  are local coordinates on  $M_\alpha$ .

Thus we have

$$y^s = y^s(x(u)),$$

from which

$$(3.15) \quad B_b^s = B_b^h B_h^s,$$

where

$$B_b^s = \partial_b y^s, \quad B_b^h = \partial_b x^h, \quad (\partial_b = \partial / \partial u^b).$$

Differentiating (3.15) covariantly along  $M_\alpha$ , we find

$$\nabla_c B_b^s = B_c^j B_b^i \nabla_j B_i^s$$

because of  $\nabla_c B_b^i = 0$ , from which, using (3.10)

$$(3.16) \quad \nabla_c B_b^s = h_{ji} B_c^j B_b^i C^s.$$

On the other hand, from (1.7) we see that

$$(3.17) \quad \lambda = -G_{\alpha i} F_\mu^\lambda D^\mu C^s.$$

Differentiating (3.17) covariantly along  $M_\alpha$  and taking account of (1.3) and (3.11), we find

$$\nabla_b \lambda = G_{\alpha i} (F_\mu^\lambda D^\mu) B_b^j B_h^s h_j^h,$$

from which, using (1.7),

$$\nabla_b \lambda = G_{ai}(-v^i B_i^\lambda - \lambda C^\lambda) h_j^a B_h^e B_b^j = -\alpha v_j B_b^j$$

by virtue of (1.2) and (2.8).

From this we find

$$\nabla_c \nabla_b \lambda = -\alpha B_b^i B_c^j (\nabla_j v_i),$$

or, using (2.5), (3.9) and  $l_j = 0$ ,

$$\nabla_c \nabla_b \lambda = -\alpha^2 \lambda g_{cb}$$

because  $B_b^j$  are eigenvectors of  $h^h$  with eigenvalue  $\alpha$ . Thus,  $M_\alpha$  is isometric with sphere in  $\tilde{M}$ .

Similarly, for  $M_0$  we can see that  $\nabla_c B_b^e = 0$  because of (3.16), from which,  $M_0$  is totally geodesic in  $\tilde{M}$ .

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