

Free Vibrations of Non-Circular Arches with Elastic Supports

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Key Words: Non-Circular Arch(), Elastic Support(), Free Vibration(), Axial Deformation(), Rotatory Inertia(), Shear Deformation()

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The differential equations governing free, in-plane vibrations of non-circular arches with the translational (radial and tangential directions) and rotational springs at the ends, including the effects of rotatory inertia, shear deformation and axial deformation, are solved numerically using the corresponding boundary conditions. The lowest four natural frequencies for the parabolic geometry are calculated over a range of non-dimensional system parameters: the arch rise to span length ratio, the slenderness ratio, and the translational and rotational spring parameters.

1.

가 (1-4) (ρ, ψ, β)

Fig. 1 가

가

(1) (3)

(5.6) 가

$$\rho^{-1} \psi' + \rho^{-1} \psi = 0, \quad \psi' - \rho \psi = 0 \quad (1, 2)$$

$$\rho^{-1} \psi' - \psi + T = 0 \quad (3)$$

가 T , $() = d/d\phi$

(4) (6)

$$= -E \rho^{-1} \psi', \quad = EA \rho^{-1} (\psi' + \psi) + E \rho^{-2} \psi' \quad (4, 5)$$

$$= kA \beta = kA \rho^{-1} (\psi' - \rho \psi) \quad (6)$$

2.

E

, A , k

Fig. 1

l ,

$y(x)$, ρ , ϕ

가 가

(7) (9)

$$r = -\gamma A \omega^2, \quad t = -\gamma A \omega^2, \quad T = -\gamma \omega^2 \psi \quad (7-9)$$

γ

, ω

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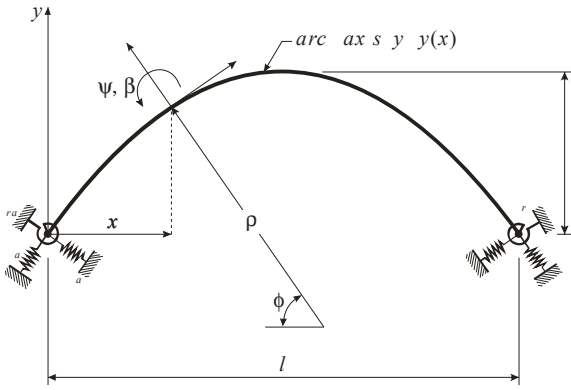


Fig. 1 Non-circular arch with elastically constrained ends.

$$f = \omega l, \quad s = l / \sqrt{\gamma A}, \quad \mu = k / E \quad (10-12)$$

$$\xi = x/l, \quad \eta = y/l, \quad \zeta = \rho/l \quad (13-15)$$

$$\delta = f/l, \quad \lambda = \omega/l \quad (16, 17)$$

$$= \omega l^2 \sqrt{\gamma A / (E)}, \quad \omega = 1, 2, 3, 4, \dots \quad (18)$$

f, s, μ
(rise to span length ratio), (slenderness ratio)
(shear parameter),
(frequency parameter),
(1) (3) (4) (9), (10) (18)

$$\delta'' = \zeta^{-1} \zeta' \delta' + \mu^{-1} (1 - \zeta^2 s^{-2}) \delta + (1 + \mu^{-1}) \lambda' - \zeta^{-1} \zeta' \lambda + (\zeta + \mu^{-1} \zeta^{-1} s^{-2}) \psi' \quad (19)$$

$$\lambda'' = \zeta^{-1} \zeta' \lambda' + (\mu - \zeta^2 s^{-2}) \lambda - (1 + \mu) \delta' + \zeta^{-1} \zeta' \delta - \zeta^{-1} s^{-2} \psi'' + 2 \zeta^{-2} \zeta' s^{-2} \psi' + \mu \zeta \psi \quad (20)$$

$$\psi'' = \zeta^{-1} \zeta' \psi' + (\mu s^2 - s^{-2}) \zeta^2 \psi - \zeta \mu s^2 \delta' + \zeta \mu s^2 \lambda \quad (21)$$

$$\eta = -4f\xi(\xi - 1), \quad 0 \leq \xi \leq 1 \quad (22)$$

$$\zeta = (1/8f) [1 + 16f^2(2\xi - 1)^2]^{3/2} \quad (23)$$

$$\zeta' = [3(2\xi - 1)/2] [1 + 16f^2(2\xi - 1)^2]^{3/2} \quad (24)$$

$$\phi = \pi/2 - \tan^{-1}[-4f(2\xi - 1)] \quad (25)$$

Fig. 1

$$-E \rho^{-1} \psi' = k_{ra} \psi \quad (26)$$

$$EA \rho^{-1} (\psi' + \dots) + E \rho^{-2} \psi' = -k_a \quad (27)$$

$$kA \rho^{-1} (\psi' - \dots - \rho \psi) = -k_a \quad (28)$$

(29)

$$\psi' + \zeta k_{ra} \psi = 0 \quad (29a)$$

$$\zeta^{-1} s^2 \lambda' + k_a \lambda + \zeta^{-1} s^2 \delta + \zeta^{-2} \psi' = 0 \quad (29b)$$

$$\zeta^{-1} \mu s^2 \delta' + k_a \delta - \zeta^{-1} \mu s^2 \lambda - \mu s^2 \psi = 0 \quad (29c)$$

가

(30)

$$\psi' - \zeta k_r \psi = 0 \quad (30a)$$

$$\zeta^{-1} s^2 \lambda' - k_a \lambda + \zeta^{-1} s^2 \delta + \zeta^{-2} \psi' = 0 \quad (30b)$$

$$\zeta^{-1} \mu s^2 \delta' - k_a \delta - \zeta^{-1} \mu s^2 \lambda - \mu s^2 \psi = 0 \quad (30c)$$

(29), (30) $k_{ra}, k_r, k_a, k, k_a, k$
(spring parameter)

(31) (36)

$$k_{ra} = k_{ra} l / (E), \quad k_r = k_r l / (E) \quad (31, 32)$$

$$k_a = k_a l^3 / (E), \quad k = k l^3 / (E) \quad (33, 34)$$

$$k_a = k_a l^3 / (E), \quad k = k l^3 / (E) \quad (35, 36)$$

3.

$$6 \quad 1 \quad (19) \quad (21)$$

$$\text{Runge-Kutta}, \quad (30)$$

Regula-Falsi

(22)

4

2 10

Fig. 2 4

$s = 60,$

$\mu = 0.3$

Fig.

Fig. 5 7

$f = 0.2,$

$\mu = 0.3$

Fig. 2 Fig. 5 $k_a = k_a = k = k = 10^7$

$k_{ra} = k_r = 0, 10, 100, 10^7$

$k_{ra} = k_r$ 가 0 10^7

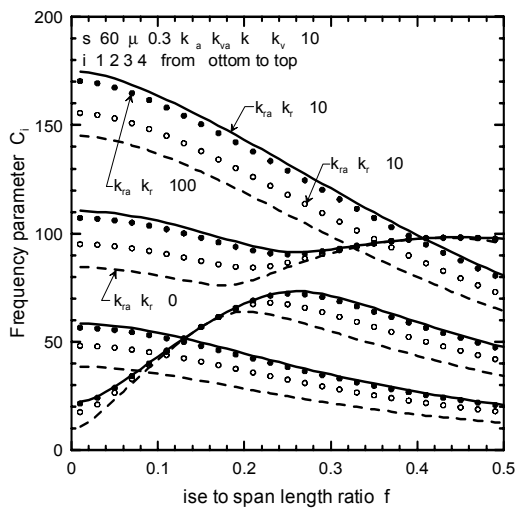


Fig. 2 Effect of f on frequency. $s=60$; $\mu=0.3$; $k_a = k_{ra} = k_r = 10^7$; $k_{ra} = k_r = 0, 10, 100$ and 10^7 .

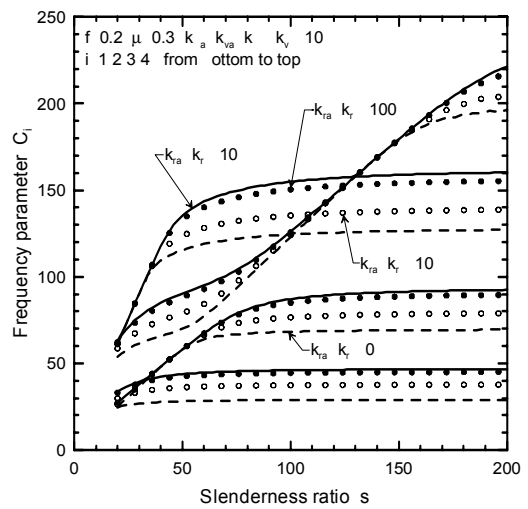


Fig. 5 Effect of s on frequency. $f=0.2$; $\mu=0.3$; $k_a = k_{ra} = k_r = 10^7$; $k_{ra} = k_r = 0, 10, 100$ and 10^7 .

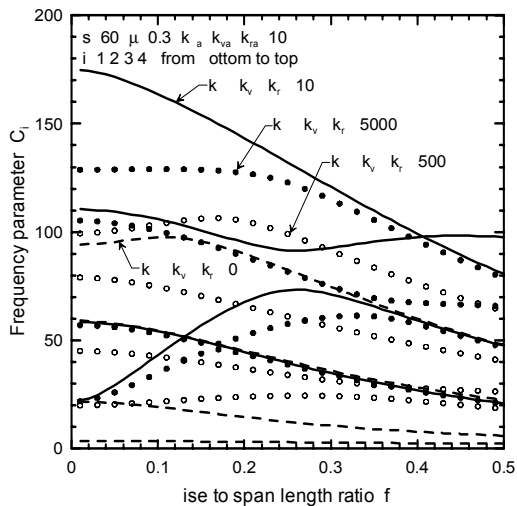


Fig. 3 Effect of f on frequency. $s=60$; $\mu=0.3$; $k_a = k_{ra} = 10^7$; $k = k_r = 0, 500, 5000$ and 10^7 .

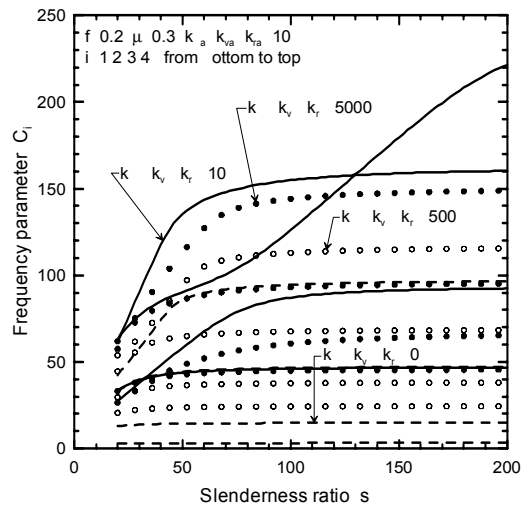


Fig. 6 Effect of s on frequency. $f=0.2$; $\mu=0.3$; $k_a = k_{ra} = 10^7$; $k = k_r = 0, 500, 5000$ and 10^7 .

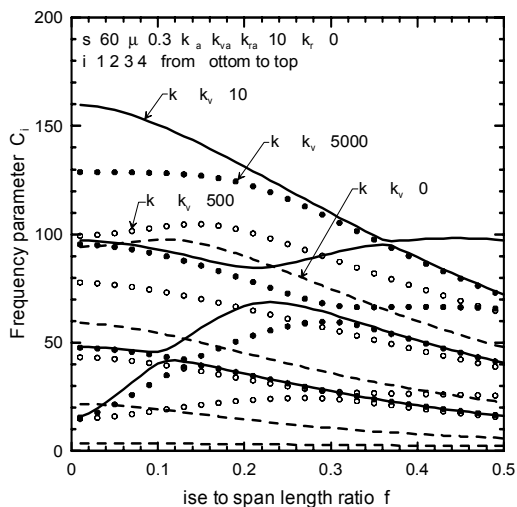


Fig. 4 Effect of f on frequency. $s=60$; $\mu=0.3$; $k_a = k_{ra} = 10^7$; $k_r = 0$; $k = k = 0, 500, 5000$ and 10^7 .

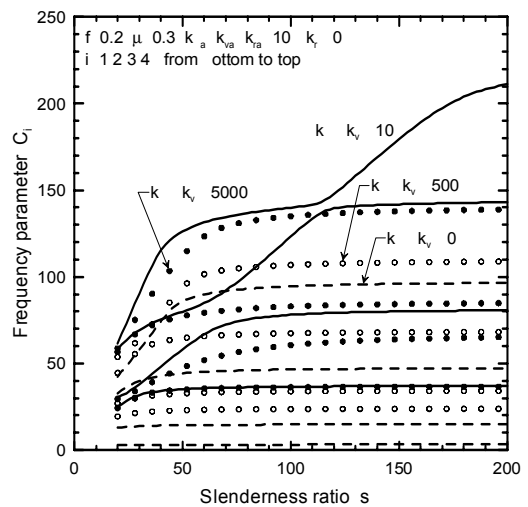


Fig. 7 Effect of s on frequency. $f=0.2$; $\mu=0.3$; $k_a = k_{ra} = 10^7$; $k_r = 0$; $k = k = 0, 500, 5000$ and 10^7 .

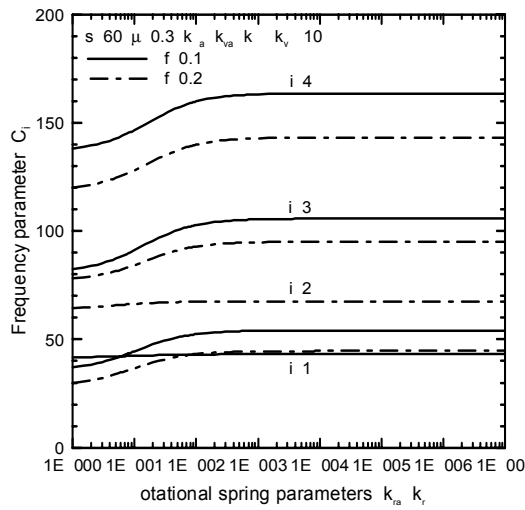


Fig. 8 Effect of $k_{ra}=k_r$ on frequency. $s=60$; $\mu=0.3$; $k_a=k_a=k_{ra}=k_r=10^7$; $f=0.1$ and 0.2 .

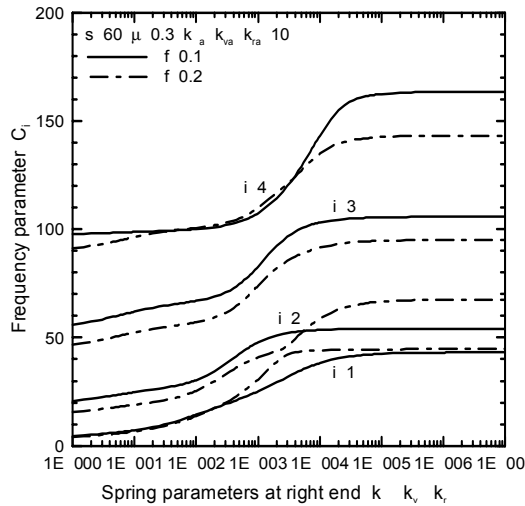


Fig. 9 Effect of $k=k=k_r$ on frequency. $s=60$; $\mu=0.3$; $k_a=k_a=k_{ra}=10^7$; $f=0.1$ and 0.2 .

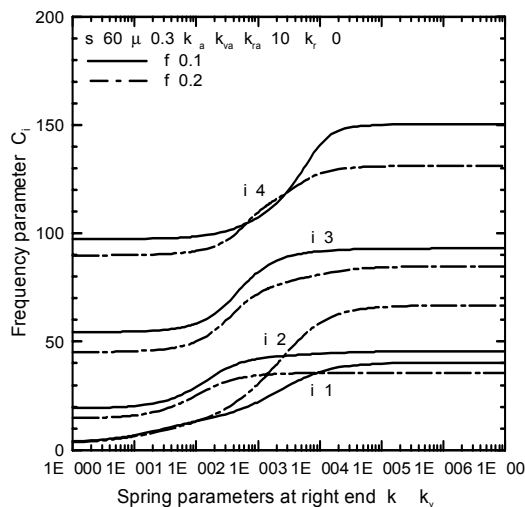


Fig. 10 Effect of $k=k$ on frequency. $s=60$; $\mu=0.3$; $k_a=k_a=k_{ra}=10^7$; $k_r=0$; $f=0.1$ and 0.2 .

Fig. 3 Fig. 6 $k_a=k_a=k_{ra}=10^7$, $k=k_r=0, 500, 5000, 10^7$, Fig. 4

Fig. 7 $k_a=k_a=k_{ra}=10^7$, $k_r=0$, $k=k=0, 500, 5000, 10^7$. Fig. 3

Fig. 6 $k=k=k_r$ 가 0 10^7

, Fig. 4 Fig. 7 $k=k$ 가 0 10^7

. Fig. 2 7

Fig. 8 10 $s=60$, $\mu=0.3$

$k_{ra}=k_r$ ($k_a=k_a=k_r=10^7$), $k=k=k_r$ ($k_a=k_a=k_{ra}=10^7$), $k=k$ ($k_a=k_a=k_{ra}=10^7$, $k_r=0$)

$f=0.1$,

$f=0.2$

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