

# PERFORMANCE OF MULTILAYER CERAMIC ACTUATOR BY CONSIDERING THE SHAPE EFFECT

S. B. Wee<sup>\*</sup>, S. J. Jeong<sup>\*\*</sup>, J. S. Song<sup>\*\*</sup>

<sup>\*</sup> Korea University of Technology and Education

<sup>\*\*</sup> Korea Electrotechnology Research Institute

## Abstract

In the present study, the piezoelectricity and polarization of multilayer ceramic actuator, being designed to stack PMN-PZ-PT ceramic layers and Ag-Pd electrode layers alternatively, were investigated under a consideration of geometric factor, the volume ratio of the ceramic to the electrode layers.

The actuators were fabricated by tape casting of  $0.2\text{Pb}(\text{Mg}_{1/3}\text{Nb}_{2/3})\text{O}_3-0.38\text{PbZrO}_3-0.42\text{PbTiO}_3$  followed by lamination and burnout & co-firing processes. The actuators of  $10 \times 10 \times 0.62 \text{ mm}^3$  in size were formed in a way that 60–200  $\mu\text{m}$  thick ceramics were stacked alternatively with 5  $\mu\text{m}$  thick electrode layer. Increases in polarization and electric field-induced displacement with thickness of the ceramic layer were attributed to change of 90°/180° domain ratio, which was affected by interlayer internal stress. The piezoelectricity and actuation behaviors were found to depend upon the volume ratio (or thickness ratio) of ceramic to electrode layer.

## Introduction

Recently, multilayer ceramic actuators (hereafter called MCA) have been extensively used in controlling moving electric machines such as micro-mirror, micro-sized machining tool, micro-pipets and so on [1]. The design of MCA has been carried out on a basis of low field piezoelectric constant of the piezoelectric materials. In practice, the high field-actuation behavior of the MCA was observed to be different from the calculated strain based on the piezoelectric constant [2]. According to previous studies [3, 4], bulk-type actuators subjected to relative high electric fields exhibited the larger displacement than the value estimated from the  $d$ -coefficient measured using the resonance method.

Besides the piezoceramics' properties, the high field strain behavior and its related domain motion for MCA are also dependent upon the geometry. The actuators are designed to stack the piezoelectric ceramic layer and electrode layer alternatively. In the MCA the electrode Ag-Pd layer exists as inactive part with strong elastic modulus and acts as a resistance to

deformation of the actuator. On the actuation mode where an electric field is applied along one direction, the electrode layers tend to act a resistance to deformation along the direction and compression along perpendicular to the direction. Accordingly, the field-induced deformation is affected by the relative thickness of two ceramic and electrode layers. The purpose of the present study is to understand electric-induced deformation of multilayer ceramic actuator with regard to the relative ceramic layer thickness. The electric and piezoelectric properties were investigated with a consideration of geometric factor, thickness fraction of ceramic to electrode layers.

## Experimental Procedure

Ceramic powder used was  $0.42\text{PbTiO}_3-0.38\text{PbZrO}_3-0.2\text{Pb}(\text{Mg}_{1/3}\text{Nb}_{2/3})\text{O}_3$  (PT-PZ-PMN). Various thick green sheets were made by passing the slurry below a doctor blade and drying. By printing Ag-30Pd paste on the sheet, electrode layers were made in  $10 \times 10 \text{ mm}^2$ . The stacking of 10 layers was carried

out. The actuators were poled at 3 kV/mm in an electric field at 120°C for 30 min.

The basic piezoelectric coefficients  $d_{31}$ ,  $d_{33}$  and  $k_p$  of the ceramic material (PZ-PT-PMN) used in the actuator were measured in a circular plate (diameter 18 mm, thickness 1 mm) by the resonance method, using an impedance analyzer (HP 4194, Hewlett-Packard Co.), as listed in Table 1. The electric field-induced strain of the poled actuators was measured in the longitudinal direction, using a laser-based displacement measurement system (OFV 303 vibrometer scanning head, Polytech Co.) at room temperature.

**Table 1.** Piezoelectric and electric properties of the piezoelectric ceramics used.

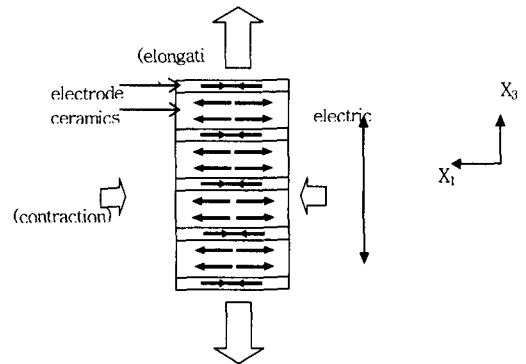
D33 (pC/N)	d31 (pC/N)	Kp	Qm	Zr (at 1kHz)	33/o	E11 (GPa)
450	-230	0.58	75	196	2500	22 GPa

To analyze the deformation mechanism, in-situ XRD patterns were collected for the poled actuator under various electric field applications. The diffraction experiment was performed at an applied electric field of 2 kV/mm with step scanning at 45°, where (200) and (002) diffracted peaks are placed.

### Composite Model

The multilayer actuator can be considered to be basically the same geometrical structure as composite. In the actuator, the ceramic layer and electrode layer are connected in series along  $x_3$  axis and in parallel along  $x_1$  axis, as shown in Figure 1. Since the two layers are in series along  $x_3$  axis, they experience the same stress. This assumes that the two layers do not exert forces on one another and hence generate no internal stress. In the  $x_3$  axis of the multilayer actuator, the interlayer stress must be taken into consideration. Thus, there are two contributions of  $d_{33}$  of the multilayer: those arising from electric field  $E_3$  along  $x_3$  direction

and those arising from internal stress



**Fig. 1.** Schematic diagram showing the internal stress configuration in the inner structure of multilayer actuator subjected to an electric field along  $x_3$  axis.

Considering only the external electric field  $E_3$ , the displacement appearing along the polar direction is given by the following equation

$$P_3 = \epsilon_{33} E_3 = \epsilon_{33}(C) E_3 V(C) \quad (1)$$

, where  $P_3$  is polarization along  $x_3$  axis,  $\epsilon_{33}(C)$  the relative permittivity of ceramics,  $E_3$  the applied field along  $x_3$  axis,  $V(C)$  the volume fraction of ceramic layers.

However, if internal stress (i) is considered as shown in the figure 1, a correction factor should be included. The correction arises from piezoelectric  $d_{31}$  coefficient. Thus, the expression can be explained by,

$$P_3' = \epsilon_{33}(C) E_3 V(C) + d_{31}(i) \sigma_1 V(C) \quad (2)$$

, when the actuator is stretched along  $x_3$ , it contracts along  $x_1$ . This contraction is controlled by the elastic compliance. If the two constituents contract equally, an internal stress is generated. The magnitude of the internal stress can be estimated by assuming that the strains are equal along  $x_1$  ( $\epsilon_1(C) = \epsilon_1(E)$ ) and that the sum of internal stress over the actuator structure is zero

$$(\sigma_1 V(C) + \sigma_1(E) V(E) = 0).$$

Under these assumptions, it can be shown that the internal stress on the ceramic layer is given by

$$\sigma_1(C) = -d_{31} E_3 / (S_{11}(C) + S_{11}(E) V(C) / V(E))$$

(3)

The internal stress  $\sigma_3$  produces a piezoelectric effect by coupling through coefficient  $d_{31}$ . If both the electric field  $E_3$  and the internal stress  $\sigma_3$  are acting, the polarization along  $x_3$  is given by

$$P_3 = \epsilon_{33}(C)E_3(C) - d_{31}E_3 / (S_{11}(C) + S_{11}(E)) + S_{11}(E) / V(E) \quad (4)$$

The first term on the right is the electric field induction contribution and the second term is caused by the internal stress contribution occurred between ceramic and electrode layers. Coefficient  $d_{33}$  of the actuator is given by

$$\begin{aligned} d_{33}' &= 3/E_3 = Q_{33}P_3^2/E_3 \\ &= Q_{33}(\epsilon_{33}(C)E_3V(C))^2/E_3 [1 - d_{31}^2 / (\epsilon_{33}(C) \\ & \quad (S_{11}(C) + S_{11}(E) + S_{11}(E)/V(E)))]^2 \\ &= d_{33}(\text{bulk})V(C)^2 [1 - d_{31}^2 / (\epsilon_{33}(C) (S_{11}(C) \\ & \quad + S_{11}(E) + S_{11}(E)/V(E)))]^2 \quad (5) \end{aligned}$$

### Experimental Results and Discussion

Figure 2 represents polarization vs. electric field curves of multilayer actuators, designed by various thick ceramic layers. As can be seen in the (a) (c), the actuators with the thicker ceramic sheet have the increased spontaneous polarization ( $P_s$ ) from 23 C/cm<sup>2</sup> for 60m-thick layer to 38 C/cm<sup>2</sup> for 200m-thick layer.

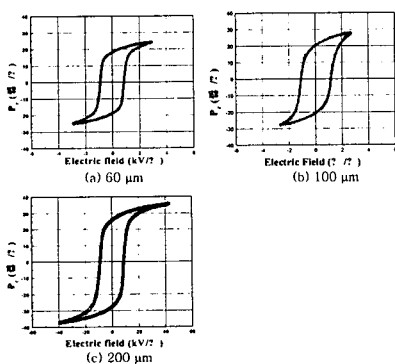


Fig. 2. Polarization vs. Electric field on the multilayer ceramic actuators with (a) 60 m, (b) 100 m, (c) 200 m thick-ceramic layers.

Figure 3 shows the X-ray patterns of the actuators after the sintering process and the reflected X-ray of (200) relative to (002). As can be seen in (a), only (200) peak was detected in zero-electric field application. In order to observe the relationship [5] between the polarization process and domain switching in the actuator, the X-ray diffraction experiments of the actuators with various thick layers were carried out under an electric field application of 2 kV/mm and the results were shown in the Figure 3 (b) (d). In the case of the MC

with 60, 100 and 200 m-thick ceramic layers, the intensity ratio of X-ray peaks (002) to

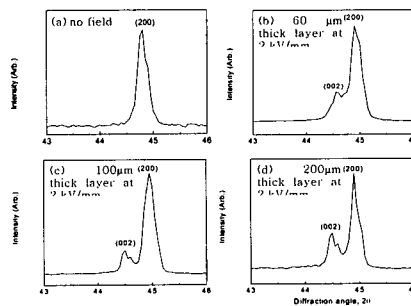


Fig. 3. (002) and (200) X-ray diffraction peaks taken on (a) the multilayer actuator without electric field application, and (b) 60m thick, (c) 100 m thick and (d) 200 m thick ceramic layer-actuators under an applied electric field of 2 kV/mm.

(200) under the electric field increases with the ceramic thickness, indicating the increased ratio of 90° domain relative to 180° domain [6].

Figure 4 is the plots of strain vs. ceramic layer thickness of the MCAs subjected to electric fields of 300 and 600 V/mm. As can be seen in the figure, the MCA containing thick ceramic layer shows the larger strain.

It can be shown from Eq. (5) that  $d_{33}$  is considerably decreased due to internal stress

and its resultant resistance to contraction along  $x_1$  and elongation along  $x_3$ . The calculations were performed on a basis of the data listed in Table 1. The relative amount of 90° domain.

and to elongate along  $x_1$  axis. Decrease of  $d_{33}$  coefficient relative to bulk type specimen coefficient  $d_{33}(\text{bulk})$  is shown by the internal stress effect for the case of volume ratio of ceramic layer. Comparing the calculated with the experimental as shown in the Figure 5,

the spontaneous polarization and  $d_{33}$  as a function of ceramic volume (thickness) fraction is in fairly agreement with the measured values from the Figure 4.

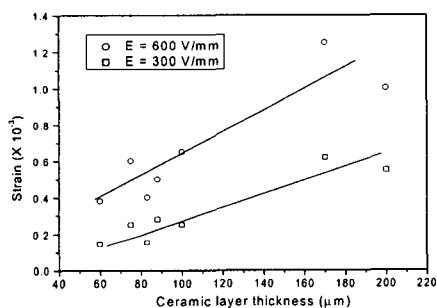


Fig. 4. Strain with respect to ceramic layer thickness of MCA subjected to electric fields of 300 and 600 V/mm.

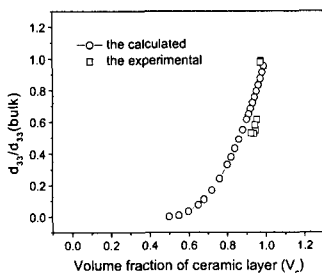


Fig. 5. Piezoelectric  $d_{33}$ -coefficient ratio of multilayer actuator ceramics relative to bulk type as a function of volume fraction of ceramic layer in the MCA

## Conclusions

The piezoelectricity and polarization of multilayer actuator were investigated under a consideration of stacking conditions including the thickness of the ceramic layer. The increase in polarization and electric field-displacement with thickness of the ceramic layer was attributed to the interlayer internal stress.

## References

- [1] C. Schuh, K. Lubitz, Th. Steinkopff, and A. Wolff: *Advances in Science, Technology and Applications*, 2000, Kluwer Academic Publishers, p. 391.
- [2] M. Marutak: *J. Phys. Soc. Japan* Vol.11(1956), p. 807.
- [3] H. Fujii: *Jpn. J. Appl. Phys. Vol. 24*[3 Suppl.](1985), p. 103.
- [4] E.I. Bondarenko, V. Yu. Topolov, A.V. Turik: *Ferroelectrics* Vol. 110(1990), p. 53.
- [5] G. Li, E. Furman, G.H. Haertling: *J. Am. Ceram. Soc. Vol. 80*(1997), p. 1382.
- [6] J. Mendiola and L. Pardo: *Ferroelectrics* Vol.54(1984), p. 199.