

inhomogeneous feature. This has effectively diminished the impact of the static displacement and improved the inversion accuracy.

AMT acquire four horizontal components of magnetotelluric field: E_x , E_y , H_x , H_y with observation frequency range of 10000Hz~10Hz. It is synchronized by GPS among multi-acquisition units to realize remote reference acquisition to improve quality of acquired data. Figure 1 shows sketch map of the configuration of AMT survey.

3. Data analysis

VES and IP data analysis

The inversion result of line 8 (Figure 2) is showed as a VES resistivity contour section, whose characteristics are as follows: the west and east portion of the line are of resistivity high, the rest presents gentle and low resistivity between 100~420 Ω m in deep segment. It grows gradually from its lower to upper. Figure 3 shows plane contour of $AB/2=180$ m, whose characteristics are as follows: the west portion presents relatively high resistivity and dense contour, which is probably caused by different lithology of its two sides due to faults.

Figure 4 shows compound index with IP method, which is characterized by gentle Z_s curves with maximum value of 2. We infer that there exists a formation weakly enriched in water, regarded as fracture water containing in karst.

In general, only fault position is confirmed according to VES data, but belt where karst is richly developed is not clearly reflected, this is probably caused by deep burial and small scale and low resolution in vertical direction for VES.

AMT data analysis

2D inversion section of line 8 presents low resistivity at the depth of upper 40~60m, which is referred as Quaternary and weathered zone of basement. It presents a suite of low resistivity at the depth of 200~300m, which is referred as cavern, fracture, and weathered crust containing water at the top of limestone, because it is impossible that variation of resistivity on large scale is caused by variation of lithology or mineral components within limestone er. Drilling hole located at site 370 of line 8 indicates that the segment at the depth of 21~63.5m are severely weathered with richly developed fractures and karsts, which is filled with arenaceous rock; while segment at the depth of 208~308.6m develops karst and fracture with water enrichment. The rest presents no karst and fracture. Log data indicates that water is mainly produced at the segment of depth of 255~273m. All above evidences show that AMT 2D inversion results are consistent with real data and AMT is sensitive to underlying formation with low resistivity beneath high resistivity.

4. Conclusions

Due to poor topography with criss-cross ridge and gouge in work area, the quality and reliability of VES data are affected. Moreover, exploration depth of VES is limited because of $AB/2_{max}=560$ m. But AMT is sensitive to conductive underlying bed beneath poor conductive bed, and characterized by high resolution within exploration depth of 1000m. So AMT is an effective means to detect water contained in karsts and in fractures for karst area.

References

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- Wannamaker, P.E., 1989, PW2D's User Documentation-Finite Element Program for Solution of Magnetotelluric Responses and Sensitivities for Two-Dimensional Earth Resistivity Structure: University of Utah Research Institute, ESL-89043-TR.

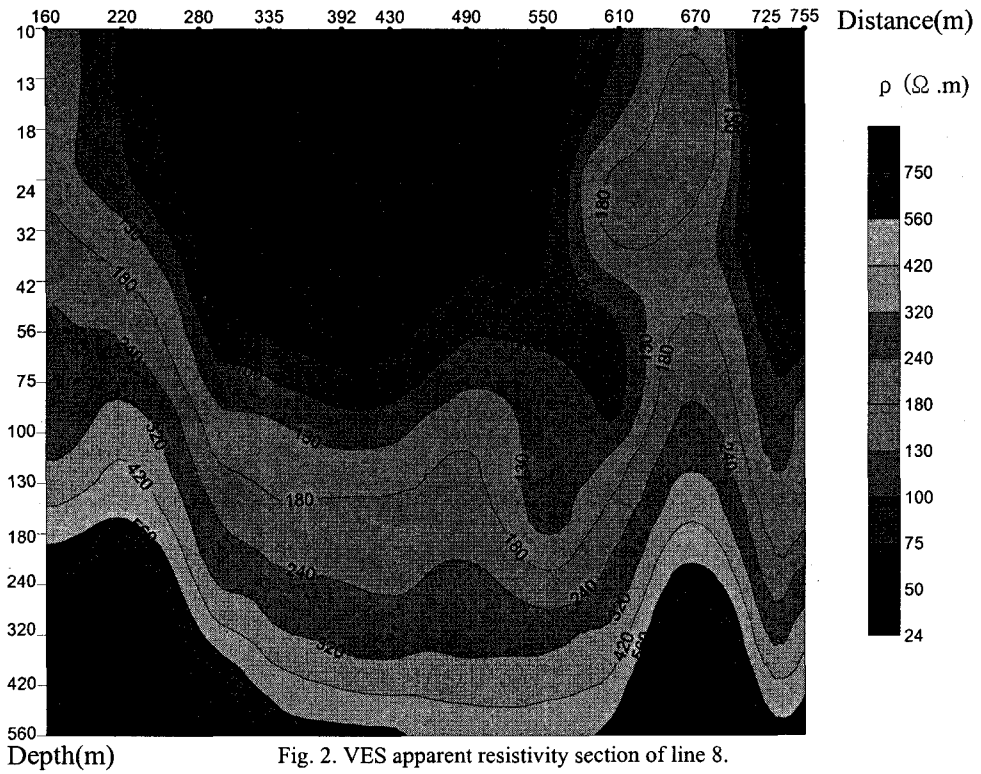


Fig. 2. VES apparent resistivity section of line 8.

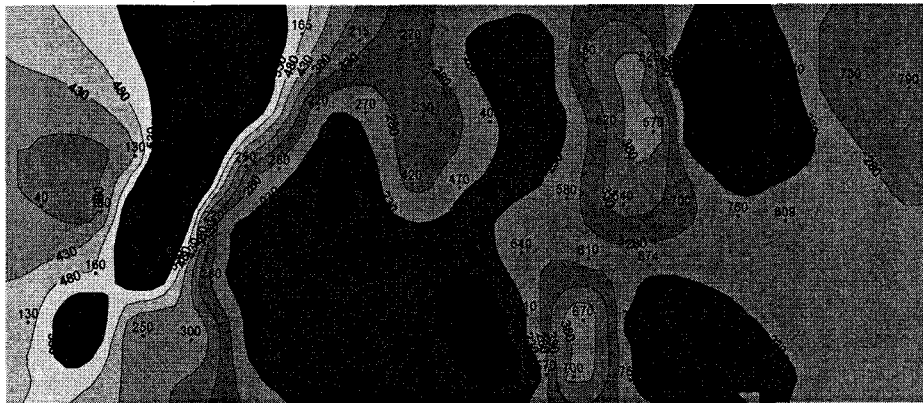


Fig. 3. contour plane of apparent resistivity with $AB/2=180m$.

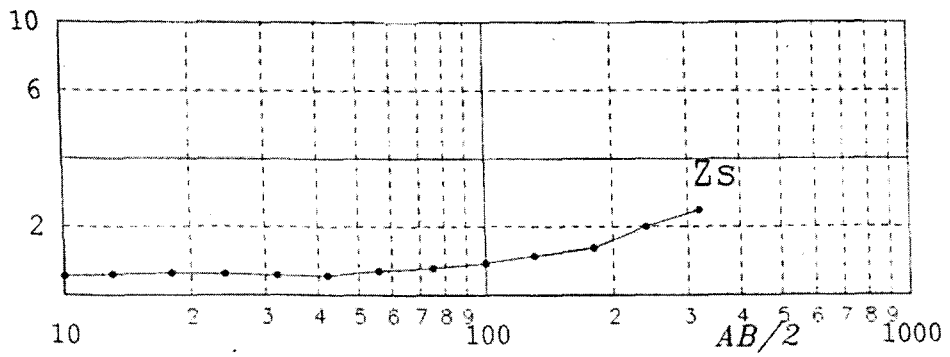


Fig. 4. IP sounding curve.

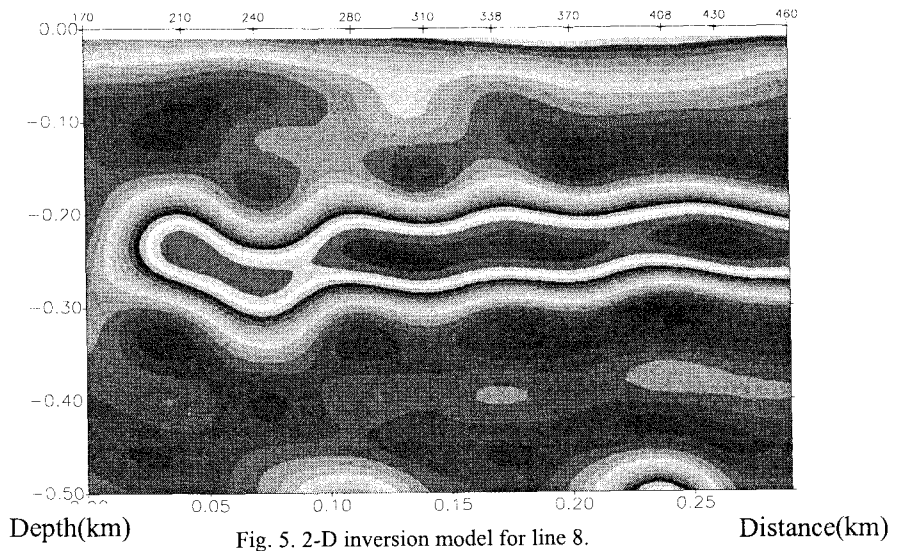


Fig. 5. 2-D inversion model for line 8.